Department of Intelligent Systems (DITS)

Academic year 2020/2021

Bachelor's Thesis Specification



Student: Ondris Ladislav
Programme: Information Technology

Title: Depth-Based Determination of a 3D Hand Position

Category: Image Processing

Assignment:

- 1. Study the literature on hand detection and determining its position from depth images.
- 2. Design a suitable algorithm for detecting the hand, determining its position, and accepting the gesture (e.g., outstretched and fingers far apart).
- 3. Implement the proposed algorithm from point 2.
- 4. Acquire a database of at least 100 records. Use this database to test your solution from point 3.
- 5. Summarize the achieved results and discuss possible extensions or improvements.

Recommended literature:

- SUPANČIČ, James Steven, et al. Depth-based hand pose estimation: methods, data, and challenges. *International Journal of Computer Vision*, 2018, 126.11: 1180-1198.
- EROL, Ali, et al. Vision-based hand pose estimation: A review. *Computer Vision and Image Understanding*, 2007, 108.1-2: 52-73.
- BARSOUM, Emad. Articulated hand pose estimation review. *arXiv preprint arXiv:1604.06195*, 2016.

Requirements for the first semester:

• Items and 2.

Detailed formal requirements can be found at https://www.fit.vut.cz/study/theses/

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Head of Department: Hanáček Petr, doc. Dr. Ing.

Beginning of work: November 1, 2020 Submission deadline: May 12, 2021

Approval date: November 11, 2020