

Acceptance Test Plan: v0.2

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This document outlines all of the tests required to deliver LFEV-Y5. The plan is presented as an overview with the ATP number next to the test. This refers to the document that describes the test procedure. The requirements are from the SoW for 2017



Lafayette College: Electrical and Computer Engineering

ATPs

None of these tests can be viewed as completed until appropriate documentation has been uploaded to the webpage.

| Item | i uploaded to th | Demonstrated | Verification | |
|--------|-------------------------|---|--|--------|
| Item | description | Requirements | Successful Test Criteria | Method |
| ATP-01 | Accumulator integration | R001a R001c R001d R001e R002a R002c R004a (TSV part) R005a R005b (Manual) | Packs power motor and all telemetry is recorded by VSCADA. Control by using the throttle. Verify by accelerating and looking at dash, pack screens, and log files remotely | Test |
| ATP-02 | Accumulator charging | R001b R001g R002b R002h | Packs charge by the charging port and open the safety loop VSCADA reacts correctly Verify by looking at the dash | Test |
| ATP-03 | CAN Bus link | R002a R002c R002d R002e R002f R002g R002j R002k R003a(8) R003d R004a (CAN Bus part) R005a (CAN Bus part) R005c (CAN Bus part) R007c R007d | DAQ by VSCADA of TSI, GLV, TSV, Cooling. Verify by looking at cell phone and looking at dash and remote computer in each mode of VSCADA | Test |
| ATP-04 | Safety loop | R001g R002b R002c R002d R002k | Fault by: Crashing BRB IMD Cooling | Test |

| | | R002m R003b R003c R003d R004a (Safety loop part) R005c (IMD fault) R007b | VSCADA limit Pack fault Throttle fault Brake fault User defined limit (warn) User defined limit (halt) Pack charging Verify by looking at the dash, the remote computer and the cellphone | |
|--------|--------------------------|--|---|------|
| ATP-05 | Cruise Control | R002l R005b (Software) | Motor can maintain desired speed Verify by checking motor speed compared to target | Test |
| ATP-06 | 24h endurance test | GPR006 | At the end of all other tests leave the car running for 24h | Test |
| ATP-07 | Shutdown | R002k R002i | VSCADA works after unexpected GLV shutdown All hardware in safe state Packs stop powering motor with GLV shutdown | Test |

Compliance Matrix

All requirements should also have a QA by each subsystem.

| Requirement | Test(s) to demonstrate acceptance |
|-------------|---|
| R001a | ATP-01 |
| R001b | ATP-02 OR https://sites.lafayette.edu/ece492- |
| | sp16/files/2016/05/QAR001b.pdf |
| R001c | ATP-01 |
| R001d | ATP-01 |
| R001e | ATP-01 |
| R001f | https://sites.lafayette.edu/ece492- |
| | sp16/files/2016/05/QAR001e.pdf |
| R001g | ATP-02 |
| R002a | ATP-01 or ATP-03 |
| R002b | ATP-02 |
| R002c | ATP-01 OR ATP-03 OR ATP-04 |

| R002d | ATP-01 OR ATP-03 OR ATP-04 |
|----------|------------------------------|
| R002e | ATP-03 |
| R002f | ATP-03 |
| R002g | ATP-03 |
| R002h | ATP-02 OR ATP-03 |
| R002i | ATP-02 |
| R002j | ATP-03 |
| R002k | ATP-03 |
| R0021 | ATP-08 |
| R002m | ATP-04 |
| R003a(1) | Any ATP |
| R003a(2) | QA by GLV |
| R003a(3) | QA by GLV |
| R003a(4) | QA by GLV |
| R003a(5) | QA by GLV |
| R003a(5) | QA by GLV |
| R003a(6) | QA by GLV |
| R003a(7) | QA by GLV |
| R003a(8) | ATP-03 |
| R003b | ATP-04 |
| R003c | QA by GLV |
| R003d | ATP-03 |
| R004a | ATP-01 AND ATP-03 AND ATP-04 |
| R004b | QA by Interconnect |
| R005a | ATP-01 AND ATP-03 |
| R005b | ATP-01 AND ATP-07 |
| R005c | ATP-04 |
| R005d | QA by TSI |
| R006 | Any ATP |
| R007a | QA by Cooling |
| R007b | ATP-04 |
| R007c | ATP-03 |
| R007d | ATP-03 |
| R007e | Waived |
| R007f | QA by Cooling |
| R007g | QA by Cooling |

Waived or modified requirements and questions

| Requirement | Reason |
|-------------|---|
| R003a(4) | Cannot tell if GLV is from the battery or 24VDC |
| R002h | Cannot tell if GLV is from the battery or 24VDC |
| R007e | Waived |
| R005d | We've changed the switches |

ATP-01 intermediate steps

- 1. Packs provide 96V to motor
 - 1.1. Each pack provides 24VDC
 - 1.2. Packs can provide up to 200A.
 - 1.3. Each Pacman monitors pack status correctly
- 2. Throttle pedal controls motor
 - 2.1. Increasing throttle causes motor speed to increase
 - 2.2. Decreasing throttle leads to motor deceleration
- 3. VSCADA is aware about drive mode
 - 3.1. VSCADA view is the drive view
 - 3.2. VSCADA dashboard is updating appropriately
 - 3.2.1. Value for speed is updating continuously
 - 3.2.2. TSV SOC is updating periodically.
 - 3.2.3. Pack temperatures are updating periodically
- 4. Remote computer is aware about drive mode
 - 4.1. Remote computer display indicates drive mode
 - 4.2. Remote computer display of all parameters updates appropriately
- 5. Cell phone is aware about drive mode
 - 5.1. Cell phone displays appropriate drive mode view
 - 5.2. Drive mode parameters update on the screen appropriately

ATP-02 intermediate steps

- 1. Packs charge and perform safety checks
 - 1.1. Packs take charge, and are able to charge up to 100%
 - 1.2. Packs do not overcharge
 - 1.3. Safety loop opens when charging
- 2. VSCADA is aware about charging
 - 2.1. VSCADA charging view is set as the current view while charging
- 3. Remote computer is aware about charging
 - 3.1. Remote computer displays the charging view during charging
- 4. Cell phone is aware about charging
 - 4.1. Cell app defaults to the charging view during battery charging

ATP-03 intermediate steps

- 1. With CAN line connected to all systems, VSCADA acquires and reports the *same* values as reported on the individual system for all sensors.
- 2. With CAN line connected to individual sub-system only, VSCADA acquires and reports the *same* values as reported on the individual system

Sensor values to be monitored

| Test | Seen on VSCADA | Seen on Remote | Seen on Cell |
|------------------|----------------|----------------|--------------|
| Cell Temperature | | | |

| Cell Voltage | | | |
|--------------------|---|-----|--|
| Pack Current | | | |
| Pack SoC | | | |
| Pack Status | | | |
| Pack Voltage | | | |
| GLV Voltage | | | |
| GLV SoC | | | |
| GLV Current | | | |
| GLV Temperature | | | |
| Safety loop status | | | |
| RPM gauge | | | |
| (Dyno) | | | |
| Strain gauge | | | |
| Throttle position | | | |
| Brake status | | | |
| IMD status | | | |
| FWD/REV status | | | |
| Precharge status | | | |
| MC temp | | | |
| MC current | | | |
| Cooling temp in | | | |
| Cooling flow | \ | | |
| Cooling temp out | | | |
| TSI temp | | | |
| Speed | | 7 7 | |
| Safety loop status | | | |

ATP-04 intermediate steps

| Fault | Safety | Seen on | Seen on | Seen on |
|---------------------------|-----------|---------|---------|---------|
| | loop trip | VSCADA | Remote | Cell |
| Driver resettable BRB | | | | |
| Non driver resettable BRB | | | | |
| Crash protection | | | | |
| Over temperature cooling | | | | |
| Under flow cooling | | | | |
| IMD fault | | | | |
| Cell overtemp | | | | |
| Cell overcurrent | | | | |
| Cell overvoltage | | | | |
| Cell undervoltage | | | | |
| Brake overtravel | | | | |
| VSCADA defined violation | | | | |

ATP-05 intermediate steps

- 1. TSI has the hardware to control the throttle
- 2. Physics model simulated
- 3. Physics model implemented on TSI
- 4. TSI can hold a throttle position

ATP-06 intermediate steps

1. Run system for 24h

ATP-07 intermediate steps

- 1. VSCADA reboots after shutdown
- 2. Packs disengage from the motor with loss of power
- 3. VSCADA safely shuts down
- 4. Packs safely shutdown
- 5. Cooling safely shuts down
- 6. TSI safely shuts down
- 7. GLV safely shuts down

