# Axiomatic Attribution for Deep Networks

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Why did the network label this image as "fireboat"?

#### **Problem Statement**

# Attribute a <u>complex</u> deep network's prediction to its input features

E.g. Attribute an Object Recognition Network's prediction to its pixels

E.g. Attribute a diagnostic network's prediction to patient's symptoms, measurements, history

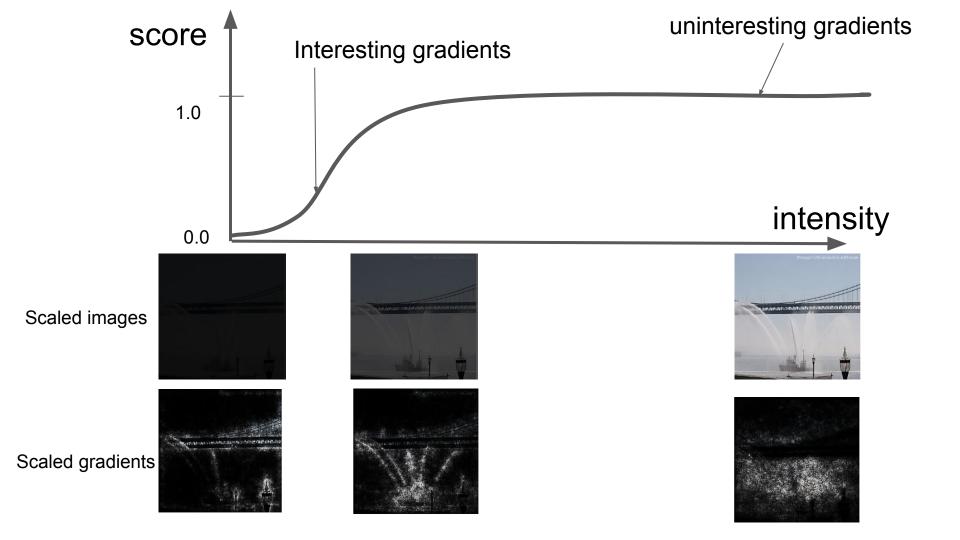
[DeepLift '17], [Layerwise relevance propagation '16], [DeConv nets '14], [Guided backprop '14]

#### Prior work

- Prior work is characterized by intuitive design+empirical eval
- Challenges with evaluation
  - Evals from prior work are specific to object recognition
  - Hard to separate model behavior, attribution errors, eval artifacts
    - Attributions may "look" incorrect because of unintuitive network behavior
    - Perturbations could change score for artifactual reasons like if they create a "new object" or a "crazy" input

#### Our approach: Axioms

- What makes for a good attribution method?
  - Inspired by economics literature [Aumann-Shapley 1974]
- Overview
  - List desirable criteria (axioms) for an attribution method
  - Establish a uniqueness result: X is the only method that satisfies these desirable criteria
    - X = Integrated Gradients (our method)
  - E.g. For  $f = x^*y + z$  and x,y,z=1,1,1, the "best" attribution is attr(x)=0.5, attr(y)=0.5, attr(z) = 1.0
- Surprisingly, the resulting method is simple



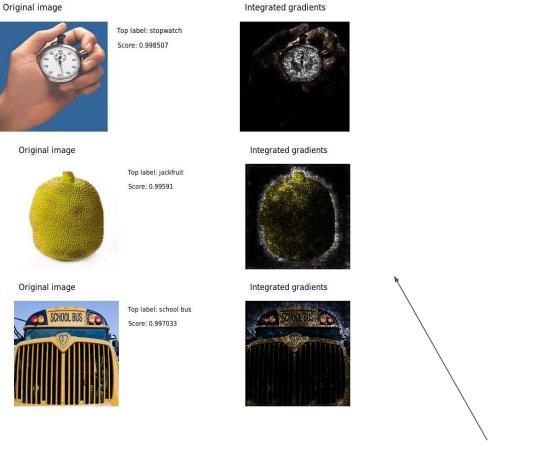
IG(input,base) = (input -baseline)\*
$$\int_{0.1} \nabla F(\alpha^* \text{input} + (1-\alpha)^* \text{baseline}) d\alpha$$





#### Easy to implement

```
def integrated gradients(inp, baseline, label, steps=range(50)):
  t input = input tensor() # input tensor
  t prediction = prediction tensor(label) # output tensor
  t gradients = tf.gradients(t prediction, t input)[0] # gradients
  path inputs = [baseline + (i/steps)*(inp-baseline) for i in steps]
  grads = run network(t gradients, path inputs)
  return (inp-baseline)*np.average(grads, axis=0) # integration
```



Attributions overlaid on the image

#### **Baselines**

- A baseline is an uninformative input used for comparison
  - E.g. Object recognition: black image, noise image
  - E.g. For  $f = x^*y + z$ , and attribution at x,y,z=1,1,1, natural baseline is 0,0,0

- Need for a baseline noted by [Deeplift '16], [Layerwise relevance propagation '16]
- Baselines are necessary for attributions [Kahneman-Miller 86]

### Axiom: Implementation Invariance

Two networks that compute identical functions <u>for all inputs</u> get identical attributions even if their architecture/parameters differ

E.g.  $f1 = x^*y + z$  and  $f2 = y^*x + z$  should get the same attributions

Not satisfied by

[Deeplift '16], [Layerwise relevance propagation '16]

#### Failure of Implementation Invariance

- [DeepLift '17], [Layerwise relevance propagation '16] fail implementation invariance
- Methods redistribute prediction from output to the input over network structure
  - Chain rule is invalid for discrete gradients

# For all $x_1$ and $x_2$ : $F(x_1, x_2) == G(x_1, x_2)$

Integrated gradients 
$$x_1 = 1.5, x_2 = -0.5$$

$$x_1 = ReLU(x_1)$$

$$= 3$$

$$x_1 = 1.5, x_2 = -0.5$$

$$x_1 = 1.5, x_2 = -0.5$$

$$x_2 = ReLU(x_2)$$

$$= 1$$

$$x_1 = 1.5, x_2 = -0.5$$

$$x_1 = 1.5, x_2 = -0.5$$

$z_1 = ReLU(x_1 - 1)$ = 2	Integrated gradients	x <sub>1</sub> = 1.5, x <sub>2</sub> = -0.5
$G(x_1, x_2) = ReLU(z_1 - z_2)$ = 1 $z_2 = ReLU(x_2)$ = 1	DeepLift	$x_1 = 2,  x_2 = -1$
	LRP	$x_1 = 2,  x_2 = -1$

### **Axiom: Sensitivity**

- (a) If baseline and input have different scores, but differ in a single variable, then that variable gets some attribution.
- (b) If a variable has no influence on a function, then it gets no attribution.

- (a) not satisfied by:
  - Gradient at output
  - [Deconv nets '14]
  - [Guided back propagation '14]

# Axiom: Linearity preservation

Attributions(a\*f1 + B\*f2) = a\*Attributions(f1) + B\*Attributions(f2)

Rationale: Attributions have additive semantics. It is best to respect any existing linear structure.

E.g. For  $f = x^*y + z$ , the "optimal" attribution should assign blame independently to 'z' and 'x\*y'

### Axiom: Completeness

sum(attributions) = f(input) - f(baseline)

**Theorem** [Friedman 2004]

Every method that satisfies Linearity preservation, Sensitivity and Implementation invariance, and Completeness is a path integral of a gradient.

# **Axiom: Symmetry Preservation**

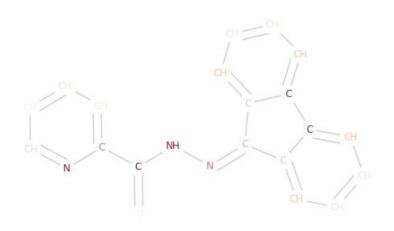
Symmetric variables with identical values get equal attributions

E.g. For  $f = x^*y + z$ , the "optimal" attribution at x,y,z=1,1,2 should be equal for x and y.

Theorem: [this work]

Integrated Gradients is the unique path method that satisfies these axioms. (there are other methods that take an average over a symmetric set of paths)

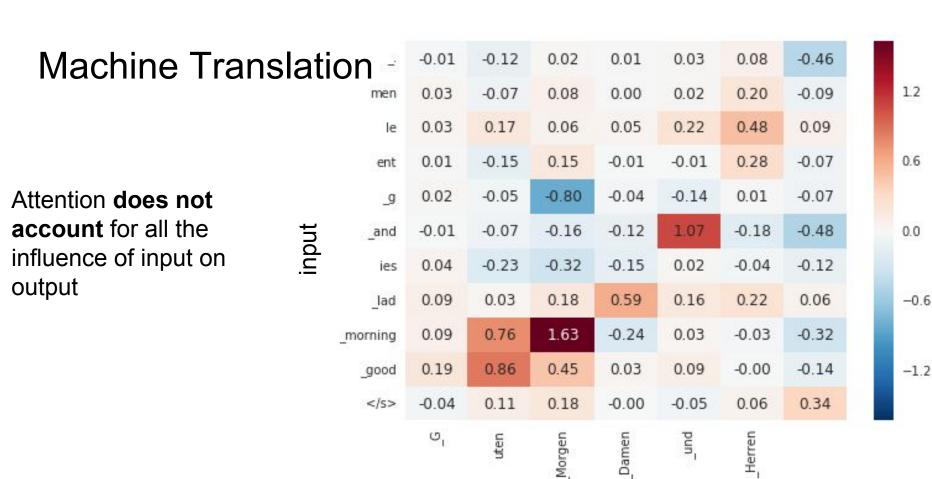
# Virtual Drug Screening



RED: +ve attribution

**BLUE: -ve attribtion** 

Baseline is zero embedding vector



output

#### Reductiveness of "Feature Attribution"

 Suppose that the network predicts TRUE if there are an even number of black pixels and FALSE otherwise.

The attributions to the base features will not tell us much.



# Why a vacuum?





#### Thanks!

We solve the problem of attributing a network's prediction to its base features

Our technique is called Integrated Gradients, is backed by an axiomatic theory, is <u>simple to</u> <u>implement</u>, and applies to a variety of deep networks

https://github.com/ankurtaly/Integrated-Gradients