

Information Theory and Related Fields

Lecture 3: Channel Coding

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Online Short Course at Beijing Normal University

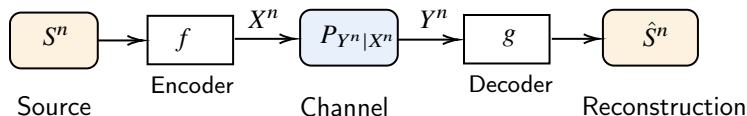
Outline

- 1 Channel Coding
- 2 Proof of Channel Coding Theorem
- 3 Channel Coding with Input Constraint
- 4 Source-Channel Coding
- 5 Summary, Extensions, and Open Problems

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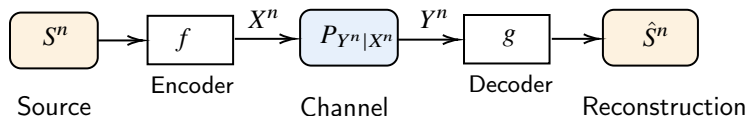
Recall: Source-Channel Coding Theorem



Theorem ([Shannon'48])

Consider discrete memoryless source S and discrete memoryless channel $P_{Y|X}$. There is a sequence of encoder-decoder pairs (f_n, g_n) such that $\mathbb{P}(S^n \neq \hat{S}^n) \rightarrow 0$ (as $n \rightarrow \infty$) if $H(S) < C(P_{Y|X})$, and only if $H(S) \leq C(P_{Y|X})$.

Recall: Source-Channel Coding Theorem

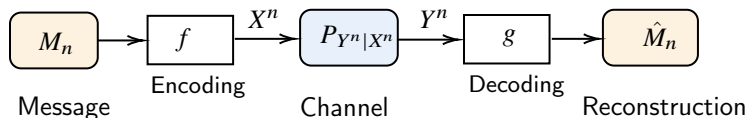


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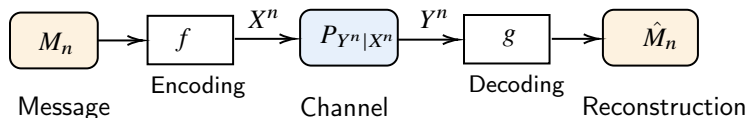
- Source coding (with noiseless rate- R channel) was proven in last lecture

Another Special Case: Channel Coding



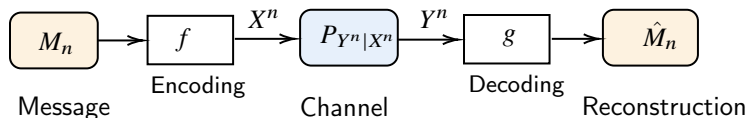
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- For this case, $f : [2^{nR}] \rightarrow \mathcal{X}^n$ and $g : \mathcal{Y}^n \rightarrow [2^{nR}]$ are respectively also called **channel encoder** and **channel decoder**, and R is also called the **rate of (f, g)** .

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- Essence of channel coding: Resist to noise interference in order to transmit the **rate- R message** almost with no error to the receiver, i.e., $\mathbb{P}(M \neq \hat{M}) \rightarrow 0$.
 - In other words, convert the noisy channel to an almost noiseless one

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is called *channel capacity*.

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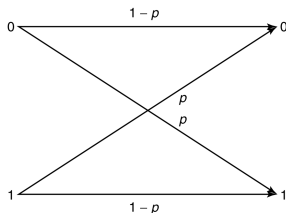
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We will prove this theorem in this lecture.

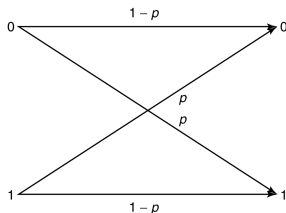
Example

Binary Symmetric Channel $\text{BSC}(p)$: $Y = X \oplus W$ with $W \sim \text{Bern}(p)$ independent of X where \oplus is XOR.



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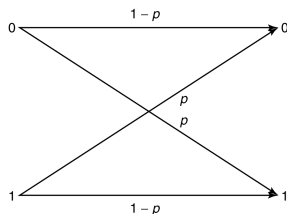
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- Any input distribution must be a **Bernoulli distribution**.
- If $X \sim \text{Bern}(q)$, then $Y \sim \text{Bern}(p * q)$ with $p * q := p(1 - q) + q(1 - p)$ denoting the **binary convolution**.

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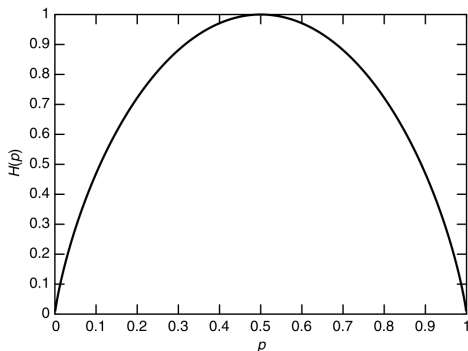
$$I(X; Y) = H(Y) - H(Y|X) = H_2(p * q) - H_2(p)$$

where $H_2(p) := p \log \frac{1}{p} + (1 - p) \log \frac{1}{1-p}$ is the binary entropy function.

Example (cont.)

So, we have

$$\begin{aligned} C(\text{BSC}(p)) &= \max_{q \in [0,1]} H_2(p * q) - H_2(p) \\ &= 1 - H_2(p), \quad \text{optimal } q = \frac{1}{2} \end{aligned}$$



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Achievability Part (“If” Part)

Definition

The (weakly) joint typical set $\mathcal{A}_\epsilon^{(n)}(P_{XY})$ (or shortly, $\mathcal{A}_\epsilon^{(n)}$) with respect to P_{XY} is the set of $(x^n, y^n) \in \mathcal{X}^n \times \mathcal{Y}^n$ such that

$$\begin{aligned} \left| -\frac{1}{n} \log P_X^{\otimes n}(x^n) - H(X) \right| &\leq \epsilon \\ \left| -\frac{1}{n} \log P_Y^{\otimes n}(y^n) - H(Y) \right| &\leq \epsilon \\ \left| -\frac{1}{n} \log P_{XY}^{\otimes n}(x^n, y^n) - H(X, Y) \right| &\leq \epsilon. \end{aligned}$$

Properties of Joint Typical Sets

Fact: [Cover–Thomas' book]

1. (Joint AEP) $P_{XY}^{\otimes n}(\mathcal{A}_\epsilon^{(n)}) \rightarrow 1$ as $n \rightarrow \infty$.
2. $|\mathcal{A}_\epsilon^{(n)}| \leq 2^{n(H(X,Y)+\epsilon)}$.
3. $|\mathcal{A}_\epsilon^{(n)}| \geq (1-\epsilon)2^{n(H(X,Y)-\epsilon)}$ for sufficiently large n .
4. Let $(X'^n, Y'^n) \sim P_X^{\otimes n} \otimes P_Y^{\otimes n}$. For sufficiently large n ,

$$(1-\epsilon)2^{-n(I(X;Y)+3\epsilon)} \leq \mathbb{P}\left\{(X'^n, Y'^n) \in \mathcal{A}_\epsilon^{(n)}\right\} \leq 2^{-n(I(X;Y)-3\epsilon)}.$$

Coding Scheme

- Let P_X attain $C = \max_{P_X} I(X; Y)$. Let R be any number $< I(X; Y) - 3\epsilon = C - 3\epsilon$.

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- **Generation of codebook:** Randomly generate 2^{nR} sequences (codewords) X^n drawn i.i.d. $\sim P_X^{\otimes n}$. Index them by $i \in [2^{nR}]$. Denote (random) **codebook** $C_n := \{X^n(1), X^n(2), \dots, X^n(2^{nR})\}$. Reveal this codebook to the encoder and decoder.

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- **Encoding:** Given $M_n = m$, encode M_n by $X^n(m)$.
- **Decoding:** Declare the reconstruction of M_n as \hat{m} if $(X^n(\hat{m}), Y^n) \in \mathcal{A}_\epsilon^{(n)}$ and $(X^n(\hat{m}'), Y^n) \notin \mathcal{A}_\epsilon^{(n)}, \forall \hat{m}' \neq \hat{m}$. If there is no such \hat{m} or more than one such \hat{m} , let $\hat{m} = 1$.

Calculation of Probability of Error

Lemma ([Cover–Thomas' book])

If $R < I(X; Y) - 3\epsilon$, then $\mathbb{P}_{M_n, C_n}(M_n \neq \hat{M}_n) \rightarrow 0$ as $n \rightarrow \infty$.

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Intuition behind this lemma:

- Given $M_n = m$, by the joint AEP, $\mathbb{P}\left\{(X^n(m), Y^n) \in \mathcal{A}_\epsilon^{(n)}\right\} \rightarrow 1$. That is, with high probability (w.h.p.), $X^n(m)$ is jointly typical with Y^n .

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- Y^n is independent of $X^n(m')$, $m' \neq m$, since Y^n only depends on $X^n(m)$ and $X^n(m)$ is independent of $X^n(m')$, $m' \neq m$.
 - ▶ So, $\mathbb{P}\left\{(X^n(m'), Y^n) \in \mathcal{A}_\epsilon^{(n)}\right\} \approx 2^{-nI(X; Y)}$ for all $m' \neq m$.
 - ▶ The (expected) total number of codewords $X^n(m')$, $m' \neq m$ jointly typical with Y^n is $2^{n(R - I(X; Y))}$ which is exponentially small when $R < I(X; Y)$. That is, w.h.p., $X^n(m')$, $m' \neq m$ are not jointly typical with Y^n .

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Removing randomness of codebook: The lemma above holds on average over C_n , there must exist a sequence of fixed c_n such that $\mathbb{P}_{M_n}(M_n \neq \hat{M}_n | C_n = c_n) \rightarrow 0$.

Converse Part (“Only If” Part)

Recall that:

Lemma (Fano's inequality [Cover–Thomas' book])

Given two random variables X and Y , let $\hat{X} = g(Y)$ be any estimator of X given Y and let $\epsilon = \mathbb{P}(X \neq \hat{X})$ be the probability of error. Then

$$H(X|Y) \leq H(X|\hat{X}) \leq H_2(\epsilon) + \epsilon \log |\mathcal{X}|.$$

This inequality can be weakened to

$$H(X|Y) \leq H(X|\hat{X}) \leq 1 + \epsilon \log |\mathcal{X}|.$$

Converse Part (cont.)

Proof of Converse: For a pair of rate- R encoder-decoder (f_n, g_n) , denote $X^n = f_n(M_n)$ and $\hat{M}_n = g_n(Y^n)$. Obviously, $M_n \leftrightarrow X^n \leftrightarrow Y^n \leftrightarrow \hat{M}_n$. Denote $\epsilon_n = \mathbb{P}(M_n \neq \hat{M}_n)$. We then have

$$\begin{aligned}\log 2^{nR} &= H(M_n) \quad \text{uniform r.v.} \\ &= H(M_n | \hat{M}_n) + I(M_n; \hat{M}_n) \\ &\leq 1 + \epsilon_n \log 2^{nR} + I(M_n; \hat{M}_n) \quad \text{Fano's inequality} \\ &\leq 1 + \epsilon_n nR + I(X^n; Y^n) \quad \text{DPI} \\ &= 1 + \epsilon_n nR + \sum_{i=1}^n I(Y_i; X^n | Y^{i-1}) \quad \text{chain rule} \\ &= 1 + \epsilon_n nR + \sum_{i=1}^n H(Y_i | Y^{i-1}) - H(Y_i | X^n, Y^{i-1}) \\ &\leq 1 + \epsilon_n nR + \sum_{i=1}^n H(Y_i) - H(Y_i | X_i) \quad \left\{ \begin{array}{l} \text{conditioning reduces entropy} \\ \& \text{memorylessness of channel} \end{array} \right.\end{aligned}$$

Converse Part (cont.)

$$\begin{aligned} nR &\leq 1 + \epsilon_n nR + \sum_{i=1}^n H(Y_i) - H(Y_i|X_i) && \text{copy from last slide} \\ &= 1 + \epsilon_n nR + \sum_{i=1}^n I(X_i; Y_i) \\ &\leq 1 + \epsilon_n nR + nC && \text{definition of capacity} \end{aligned}$$

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So,

$$R \leq C + \frac{1}{n} + \epsilon_n R.$$

Since $\epsilon_n \rightarrow 0$ as $n \rightarrow \infty$, taking $\lim_{n \rightarrow \infty}$, we then have

$$R \leq C.$$

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- Example: Squared-cost (or power) function $c(x) = x^2$
- The **cost of a sequence** x^n is defined by

$$c(x^n) = \frac{1}{n} \sum_{i=1}^n c(x_i).$$

Channel Coding with Input Constraint

- A rate-cost pair (R, P) is said to be **achievable** if there exists a sequence of rate- R encoder and decoder (f_n, g_n) such that $\mathbb{P}(M_n \neq \hat{M}_n) \rightarrow 0$ and

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- The (operational) **capacity-cost function** $C_{\text{op}}(P)$ is the supremum of rates R such that (R, P) is achievable.

Channel Coding Theorem

Theorem (Channel Coding with Input Constraint [Shannon'48])

Consider a memoryless channel $P_{Y|X}$ and a cost function c . Then,

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Proof is similar to the one for channel coding without input constraint.

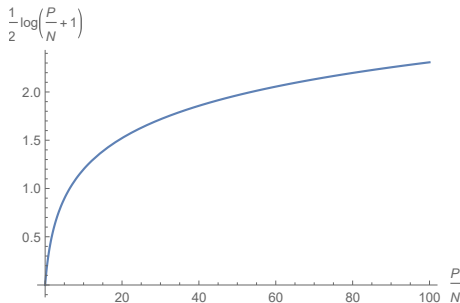
Example: Gaussian Channel with Power Constraint

Fact

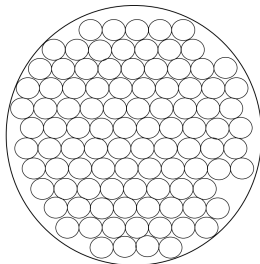
The capacity-cost function for a Gaussian channel $Y = X + Z$, $Z \sim \mathcal{N}(0, N)$ with power constraint is given by

$$C(P) = \frac{1}{2} \log \left(1 + \frac{P}{N} \right)$$

where the optimal P_X attaining $C(P)$ is $P_X = \mathcal{N}(0, P)$.

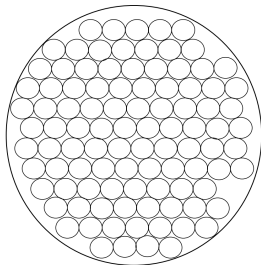


Intuition for Gaussian Channel



- By the AEP, the Gaussian noise Z^n is concentrated on a **thin spherical shell** (or a **ball**) of radius around \sqrt{nN}
- These balls are scattered throughout the space of received vectors. The received vectors have energy no greater than $n(P + N)$, so they lie in a ball of radius $\sqrt{n(P + N)}$.

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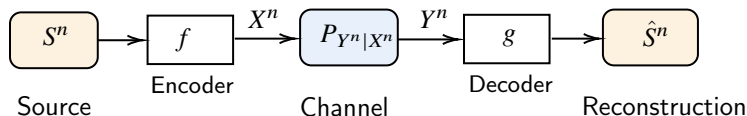


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- These balls are scattered throughout the space of received vectors. The received vectors have energy no greater than $n(P+N)$, so they lie in a ball of radius $\sqrt{n(P+N)}$.
- **Pack** a radius- $\sqrt{n(P+N)}$ ball by radius- \sqrt{nN} balls: The number of small balls packed is at most
$$\frac{\text{Vol}(\text{Ball}_{\sqrt{n(P+N)}})}{\text{Vol}(\text{Ball}_{\sqrt{nN}})} = \frac{\left(\sqrt{n(P+N)}\right)^n}{\left(\sqrt{nN}\right)^n} = 2^{n \cdot \frac{1}{2} \log\left(1 + \frac{P}{N}\right)}$$

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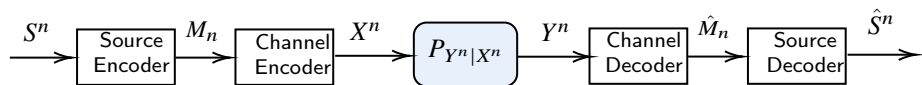
Turn Back to Source-Channel Coding



Theorem ([Shannon'48])

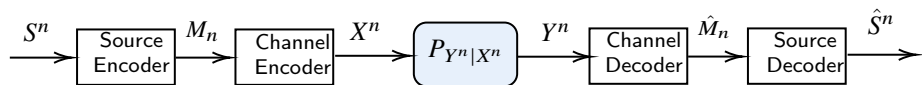
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Proof



Achievability: Separate source and channel coding.

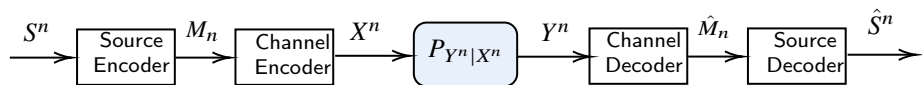
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- By channel coding theorem, $\mathbb{P}(\text{channel coding error}) \rightarrow 0$ (since $R < C(P_{Y|X})$)
- By source coding theorem, $\mathbb{P}(\text{source coding error}) \rightarrow 0$ (since $H(S) < R$)

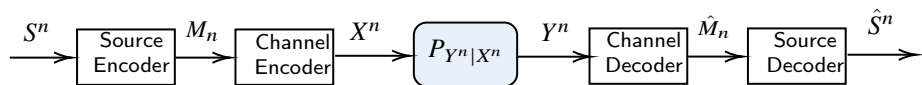
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- By channel coding theorem, $\mathbb{P}(\text{channel coding error}) \rightarrow 0$ (since $R < C(P_{Y|X})$)
- By source coding theorem, $\mathbb{P}(\text{source coding error}) \rightarrow 0$ (since $H(S) < R$)
- When no source and channel coding errors, we have $S^n = \hat{S}^n$. So, $\mathbb{P}(S^n \neq \hat{S}^n) \rightarrow 0$.

Proof



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Converse: Similar to the converse proof for channel coding

Theorem ([Shannon'48])

Consider a memoryless source S with bounded distortion function d , and a memoryless channel $P_{Y|X}$ with cost function c . There is a sequence of encoder-decoder pairs (f_n, g_n) such that

$$\limsup_{n \rightarrow \infty} \mathbb{E} d(S^n, \hat{S}^n) \leq D,$$

$$c(X^n) \leq P \text{ a.s.},$$

if $R(D) < C(P)$, and only if $R(D) \leq C(P)$. Recall that $R(D)$ is the rate-distortion function and $C(P)$ is the capacity-cost function.

Proof is similar to the lossless source-channel coding theorem.

Outline

- 1 Channel Coding
- 2 Proof of Channel Coding Theorem
- 3 Channel Coding with Input Constraint
- 4 Source-Channel Coding
- 5 Summary, Extensions, and Open Problems

- **Theoretical limits:**

- ▶ Simplify a practical problem and ask for the theoretically optimal solution, even if this solution is unrealistic.
- ▶ Information theory teaches us how to find a desirable solution, rather than gives us the desirable solution directly.
- ▶ Information theory gains our insights into the practical problem, especially on how far is the optimal performance from us.

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Key Ideas in Information Theory

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- **DPI:** Various DPI's have many applications in deriving bounds for many other problems, e.g., algorithms, statistical estimation, learning, etc.

Broadcast Channel

Network information theory: Communication systems with multi-senders and/or multi-reviewers

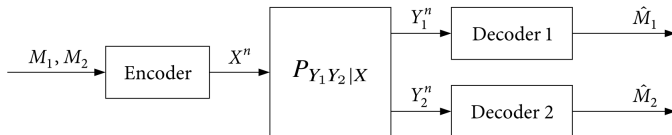
- There are many, many works in the literature on the network information theory; see [El Gamal–Kim's book]
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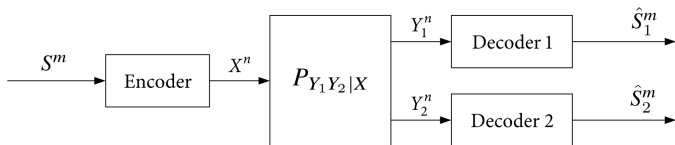
Open Problem 1: the capacity region of broadcast channel is still unknown.



Gaussian Source Broadcast

Open Problem 2: the distortion region for transmitting a Gaussian source over a Gaussian broadcast channel is still unknown when $m \neq n$.

- Interestingly, when $m = n$, symbol-by-symbol mapping is optimal, i.e.,
 $X = \alpha S$, $\hat{S}_i = \beta_i Y_i, i = 1, 2$



Second-order Coding Rate

Theorem ([Strassen'62])

Suppose that a discrete memoryless source S^n can be transmitted over a noiseless channel $M \mapsto M \in [2^b]$ within error probability ϵ (i.e., $\mathbb{P}(S^n \neq \hat{S}^n) \leq \epsilon$). Then, given $\epsilon \in (0, 1)$, the minimum b (number of bits) is

$$b^* = \begin{cases} nH(X) - \sqrt{nV(X)}\Phi^{-1}(\epsilon) - \frac{1}{2}\log n + O(1), & V(X) > 0 \\ nH(X) + O(1), & V(X) = 0 \end{cases}.$$

Here, $V(X)$ is the dispersion of the source (i.e., the variance of the self-information), which is given by

$$V(X) := \text{Var} \left(\log \frac{1}{P_X(X)} \right) = \sum_x P_X(x) \left(\log \frac{1}{P_X(x)} - H(X) \right)^2$$

Second-order Coding Rate (cont.)

Theorem ([Polyanskiy'10, Tomamichel–Tan'13])

Suppose that a message $M \sim \text{Unif}[2^b]$ can be transmitted over a discrete memoryless channel $P_{Y|X}$ within error probability ϵ (i.e., $\mathbb{P}(M \neq \hat{M}) \leq \epsilon$). If given $\epsilon \in (0, 1)$, $P_{Y|X}$ is non-singular (i.e., for some (x, x', y) , $P_{Y|X}(y|x)$ and $P_{Y|X}(y|x')$ are positive but not equal) and satisfies $V_\epsilon > 0$, then the maximum b (number of bits) is

$$b^* = nC + \sqrt{nV_\epsilon} \Phi^{-1}(\epsilon) + \frac{1}{2} \log n + O(1).$$

Here, V_ϵ is the ϵ -dispersion of the channel, which is given by

$$V_\epsilon := \begin{cases} \min_{P_X: I(X;Y)=C} V(X;Y), & \epsilon < \frac{1}{2} \\ \max_{P_X: I(X;Y)=C} V(X;Y), & \epsilon \geq \frac{1}{2} \end{cases}$$

where

$$V(X;Y) := \sum_{x,y} P_{XY}(x,y) \left(\log \frac{P_{XY}(x,y)}{P_X(x)P_Y(y)} - I(X;Y) \right)^2.$$

Sphere Packing and Covering (Zero-error Coding)

- Gaussian source coding is an approximate sphere covering problem, and Gaussian channel coding is an approximate sphere packing problem.
- Here “approximation” means the volume of uncovered region (for source coding) or overlapped region (for channel coding) is negligible, compared with the volume of the big sphere.

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- When no overlapped region is required, the rate of maximum number of small spheres is no longer $\log \frac{b}{a}$.

Sphere Packing (cont.)

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What is the asymptotic rate of the densest sphere packing in the n -dimensional Hamming space? — known as the coding problem, but also still open

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Thank you!