Final Program

Name: UNT1TLED.BAS

Author: [select VIEW... EDITOR OPTIONS]

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Notes:

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DEFINE LOADER USED 1

DEFINE OSC 20

'LINE RESERVED FOR BOOTLOADER

'DEFINE OSCILLATOR

DEFINE LCD_DREG PORTD

Define LCD DBIT 4

DEFINE LCD RSREG PORTD

DEFINE LCD RSBIT 0

DEFINE LCD_EREG PORTD

DEFINE LCD_EBIT 2

DEFINE LCD RWREG PORTD

DEFINE LCD_BITS 4
DEFINE LCD_LINES 2

DEFINE LCD COMMANDUS 1500

DEFINE LCD_DATAUS 50
DEFINE ADC_BITS 8
DEFINE ADC_CLOCK 3
DEFINE ADC_SAMPLEUS 50

TRISA=%11111111
TRISB=°/000000000
TRISC=%00100000

V var byte
Z var byte
SWALL var byte
FWALL var byte
FLAME var byte
COUNTER var byte
COUNTER =0

'SET DEFINES

'SET PORTA TO INPUTS
'SET PORTB TO OUTPUTS
'SET PORTC.5 TO INPUT

'SET VARIABLES

PAUSE 500 LCDOUT \$FE, 1

'CLEAR LCD

main:

ADCON1 = 0 ADCIN 0, V

ADCIN 1, Z ADCIN 2, FLAME

SWALL = ((6787 / (V-3))-4)/5 FWALL = ((6787 / (Z-3))-4)/5

LCDOUT \$FE, \$80, "SW:"

LCDOUT \$FE, \$80 +4, DEC SWALL LCDOUT \$FE, \$80 +9, "FW: "

LCDOUT \$FE, \$80 +13, DEC FWALL

LCDOUT \$FE, \$CO3 "FL:" LCDOUT \$FE, \$CO +4, #FLAME LCDOUT \$FE, \$CO +9, "LN: "

LCDOUT \$FE, \$CO +13, DEC COUNTER

PAUSE 100

if counter =6 THEN GOSUB ROOM4
IF PORTC.5 =0 THEN GOSUB LINE
IF FLAME <50 THEN GOSUB FANON

GOSUB FANON

IF 12< SWALL < 14 THEN GOSUB STRAIGHT

PARAMETERS THEN GOSUB STRAIGHT

IF SWALL < 12 THEN GOSUB TURNRIGHT
THEN GOSUB TURNRIGHT

IF SWALL > 14 THEN GOSUB TURNLEFT THAN 14 THEN GOSUB TURNLEFT

IF FWALL < 12 THEN GOSUB FRONTWALL
12 THEN GOSUB FRONTWALL

GOTO MAIN

STRAIGHT:

'ASSIGN SIDE WALL VARIABLE
'ASSIGN FRONT WALL VARIABLE
'ASSIGN FLAME DISTANCE VARIABLE

'SIDE WALL CALCULATION
'FRONT WALL CALCULATION

'DISPLAY INFORMATION ON LCD

'IF BOT CROSSES LINE 6 TIMES GO TO ROOM4
'IF WHITE LINE IS DETECTED GOSUB LINE
'IF FLAME IS DETECTED WITHING 50 PARAMETER

'IF SIDE WALL DETECTS BETWEEN 12 AND 14

'IF SIDEWALL PARAMETERS ARE LESS THAN 12

'IF SIDEWALL PARAMETERS ARE GREATER

'IF FRONTWALL PARAMETERS ARE LESS THAN

PORTB=%00010100 'TURN RIGHT AND LEFT MOTOR FORWARD TO GO STRAIGHT

PAUSE 85 RETURN

TURNLEFT:

PORTB=%00010000 'TURN RIGHT MOTOR FORWARD TO TURN BOT TO THE LEFT

PAUSEus 20 RETURN

TURNRIGHT:

PAUSEus 20 RETURN

FRONT WALL:

PORTB=%00001010 'TURN LEFT AND RIGHT MOTOR BACKWARDS TO BACK BOT UP

PAUSE 450

PORTB=%00000100 'TURN LEFT MOTOR FORWARDS TO TURN BOT RIGHT

pause 666 Return

LINE:

COUNTER = COUNTER +1 'EACH TIME A WHITE LINE IS DETECTED ADD ONE TO

COUNTER RETURN

ROOM4:

PORTB=%00010100 'EXIT ROOM 3

PAUSE 100

PORTB=%00010010 'TURN LEFT

PAUSE 666

PORTB=%00010100 'GO STRAIGHT

PAUSE 5000

PORTB=°/000010000

PAUSE 666 'TURN INTO ROOM 4

RETURN

FANON:

PORTB=°/001000000 'TURN FAN ON FOR 5 SECONDS WHEN IR IS DETECTED

PAUSE 5000

return