Problem 6

Find the principal values λ_0 and principal vectors v_i of the second order tensor

$$T = \hat{e}_1 \otimes \hat{e}_1 + 2(\hat{e}_1 \otimes \hat{e}_3) + \hat{e}_2 \otimes \hat{e}_2 + 2(\hat{e}_3 \otimes \hat{e}_4)$$

$$-2(\hat{e}_3 \otimes \hat{e}_3) = -2(\hat{e}_3 \otimes \hat{e}_3) = -2(\hat$$

Comment on the nature of the principal values and vectors. Confirm that is one independent, so that we can define a CS f. Is f cartesian? Express I in terms of the unit tensorial basis by in f and also find [I] f

Solution

Considering the given coordinate system $\{S, S, \hat{e}, \hat{f}, \text{ we can write the tensor } I \text{ as} \}$

Thus the matrix of I in & is (from given expression)

$$\begin{bmatrix} T \\ S \end{bmatrix} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & -2 \end{bmatrix}$$

Note that the matrix is symmetric.

we find the principal values from

$$\det \left\{ \left[\left[\right] \right] \right\} = 0$$

$$\det \left\{ \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & -2 \end{bmatrix} - \begin{bmatrix} \chi & 0 & 0 \\ 0 & \chi & 0 \\ 0 & 0 & \chi \end{bmatrix} \right\} = 0$$

which gives the characterise equation $(1-\lambda)(\lambda^2+\lambda-b)=0$

which gives the principal values.

$$\lambda_{1}=1 \qquad \lambda_{2}=-3 \qquad \lambda_{3}=2$$

Note that they are distinct and real

The corresponding principal vectors can tuen be determined as

then be determined
$$\begin{bmatrix} \hat{A} \end{bmatrix} = \begin{bmatrix} 0 \\ +1 \\ 0 \end{bmatrix}
\begin{bmatrix} \hat{12} \\ 2 \end{bmatrix} = \begin{bmatrix} -0.4472 \\ 0 \\ 0.8944 \end{bmatrix}
\begin{bmatrix} \hat{A}_3 \\ 0 \\ 0.4472 \end{bmatrix}$$

Note that they are normalized such that | v | = 1, the numbersing is chosen such that they form a right-hundred system

It can be easily checked that $\hat{\partial}_1 \cdot \hat{\partial}_2 = 0$ $\hat{\partial}_1 \cdot \hat{\partial}_3 = 0$ $\hat{\partial}_2 \cdot \hat{\partial}_3 = 0$

Thus they form an orthogonal basis and we can define a coordinate system & with these vectors as the basis. Thus we hatte

Sp. P. reg which is a Caxtedian Coordinate System.

Now let us express T in terms of the unit tensorial basis $\hat{\mathcal{Q}}_{\cdot} \otimes \hat{\mathcal{Q}}_{\cdot}$ in f.

ie $T = T_{\cdot} \hat{\mathcal{Q}}_{\cdot} \otimes \hat{\mathcal{V}}_{\cdot}$, we need to determine $T_{\cdot} = T_{\cdot} \hat{\mathcal{Q}}_{\cdot} \otimes \hat{\mathcal{V}}_{\cdot}$.

Since we have $T = tij e_i \otimes e_j$ let us see how we can relate the basis 2i with the basis \hat{e}_i

So we wish to write the relations as

$$\hat{e}_{1} = e_{11}\hat{v}_{1} + e_{12}\hat{v}_{2} + e_{13}\hat{v}_{3}$$

$$\hat{e}_2 = e_{21}\hat{v}_1 + e_{22}\hat{v}_2 + e_{23}\hat{v}_3$$

$$\hat{o} = e_{21}\hat{v}_1 + e_{22}\hat{v}_2 + e_{23}\hat{v}_3$$

where $e_{ij} = \hat{e}_i \cdot \hat{v}_j$

Evaluating the direction cosines, we can write,

$$\begin{bmatrix} \hat{e}_{1} \\ \hat{e}_{2} \\ \hat{e}_{3} \end{bmatrix} = \begin{bmatrix} 0 - 0.4472 & 0.8944 & \hat{v}_{0}, \\ 1 & 0 & 0 \\ 0 & 0.8944 & 0.4472 & \hat{v}_{3} \end{bmatrix}$$

Starting Foom

and substituting for \hat{e}_i and \hat{e}_j

This can also doe written as

$$=\begin{bmatrix} 1 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

It is a natrice with the principal values along the