

Q1).

A disc D of radius $R = 0.3m$ rolls on a horizontal plane without slipping such that $v_0 = -3\hat{\mathbf{E}}_1 \text{ m/s}$ and $a_0 = -6\hat{\mathbf{E}}_1 \text{ m/s}^2$. Point P moves in a circular slot of radius $r = 0.2m$. At the instant shown in the figure, an observer sitting on the disc and rotating with it records the velocity and acceleration of point P to be $2\hat{\mathbf{E}}_1 \text{ m/s}$ and $-10\hat{\mathbf{E}}_1 \text{ m/s}^2$, respectively. Determine the absolute velocity and acceleration of P.

Hint: It does not matter where the observer sits, so choose a convenient point.

Sol)

Coordinate systems-

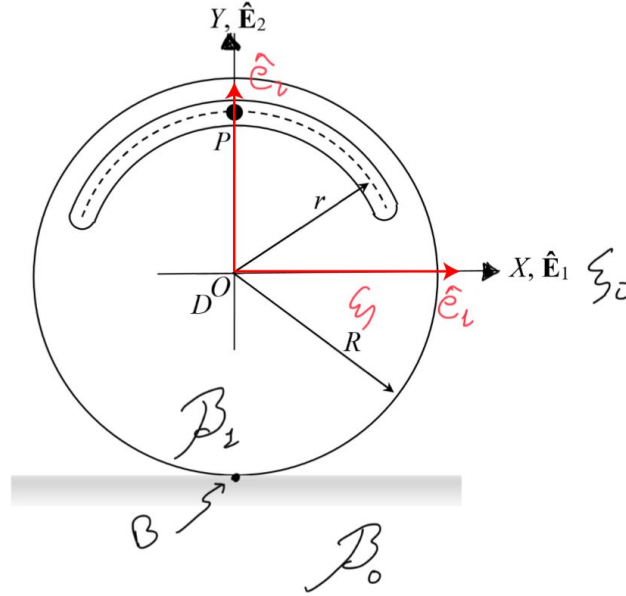


Figure 1: Schemating showing the coordinates systems

Ground frame- $\{ \mathcal{E}_0, O, \hat{\mathbf{E}}_i \}$

BFCS of disk - $\{ \mathcal{E}, O, \hat{\mathbf{e}}_i \}$

Velocity analysis

$$\mathbf{v}_{\mathcal{E}_0}^P = \mathbf{v}_{rel}^P + \boldsymbol{\omega}_{\mathcal{E}/\mathcal{E}_0} \times \mathbf{r}^{P/0} + \mathbf{v}_{\mathcal{E}_0}^0 \quad (1)$$

where, $\mathbf{v}_{rel}^P = 2\hat{\mathbf{E}}_1 \text{ m/s}$, $\mathbf{v}_{\mathcal{E}_0}^0 = -3\hat{\mathbf{E}}_1 \text{ m/s}$, and $\mathbf{r}^{P/0} = r\hat{\mathbf{E}}_2$.

No slip condition:-

Let point B_1 is attached to disc (body \mathcal{B}_1) and coincident with point of contact (B) and point B_0 is attached to ground (body \mathcal{B}_0).

$$\mathbf{v}_{\mathcal{E}_0}^{B_1} = \mathbf{v}_{\mathcal{E}_0}^{B_0}$$

Since, $\mathbf{v}_{\mathcal{E}_0}^{B_0} = 0$, hence, $\mathbf{v}_{\mathcal{E}_0}^{B_1} = 0$

Velocity of B_1 through point O is

$$\mathbf{v}^{B_1} = \boldsymbol{\omega}_{\mathcal{E}/\mathcal{E}_0} \times \mathbf{r}^{B_1/0} + \mathbf{v}^0 \quad (2)$$

Let $\boldsymbol{\omega}_{\mathcal{E}/\mathcal{E}_0} = \omega\hat{\mathbf{E}}_3$

here, $\mathbf{r}^{B_1/0} = R(-\hat{\mathbf{E}}_2)$

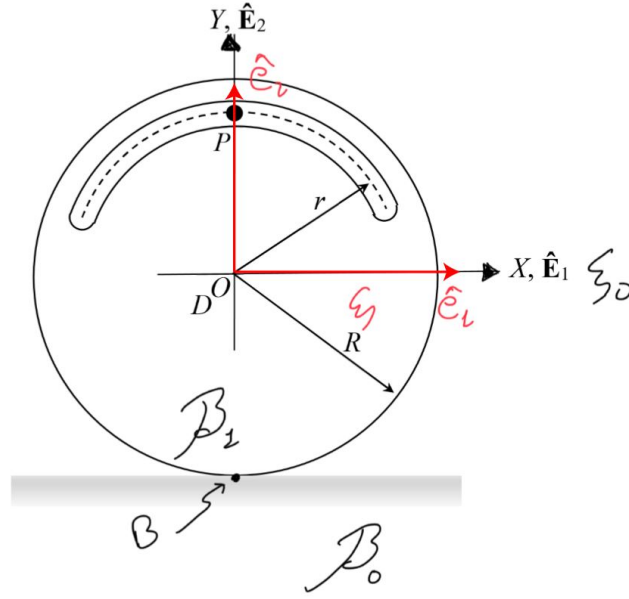


Figure 2: Schemating showing the coordinates systems

From Eqn (2)

$$\begin{aligned}
 0 &= \omega \hat{\mathbf{E}}_3 \times R(-\hat{\mathbf{E}}_2) + (-3\hat{\mathbf{E}}_1) \\
 &= \omega R \hat{\mathbf{E}}_1 - 3\hat{\mathbf{E}}_1 \\
 \omega &= \frac{3}{R} \text{ rad/sec} \\
 \omega_{\mathcal{E}/\mathcal{E}_0} &= 10\hat{\mathbf{E}}_3 \text{ rad/sec}
 \end{aligned} \tag{3}$$

from eqn(1)

$$\begin{aligned}
 \mathbf{v}_{\mathcal{E}_0}^P &= 2\hat{\mathbf{E}}_1 + \frac{3}{R} \hat{\mathbf{E}}_3 \times \hat{\mathbf{E}}_2 + (-3\hat{\mathbf{E}}_1) \\
 &= 2\hat{\mathbf{E}}_1 + \frac{3r}{R}(-\hat{\mathbf{E}}_1) - 3\hat{\mathbf{E}}_1 \\
 \mathbf{v}_{\mathcal{E}_0}^P &= \left(-1 - \frac{3r}{R}\right) \hat{\mathbf{E}}_1 \\
 \mathbf{v}_{\mathcal{E}_0}^P &= -3\hat{\mathbf{E}}_1 \text{ m/s}
 \end{aligned} \tag{4}$$

Acceleration Analysis

$$\mathbf{a}_{\mathcal{E}_0}^P = \mathbf{a}_{rel}^P + \omega_{\mathcal{E}/\mathcal{E}_0} \times (\omega_{\mathcal{E}/\mathcal{E}_0} \times \mathbf{r}^{P/0}) + \alpha_{\mathcal{E}/\mathcal{E}_0} \times \mathbf{r}^{P/0} + 2\omega_{\mathcal{E}/\mathcal{E}_0} \times \mathbf{v}_{rel}^P + \mathbf{a}_{\mathcal{E}_0}^0 \tag{5}$$

here, $\mathbf{a}_{rel}^P = -10\hat{\mathbf{E}}_1$, $\omega_{\mathcal{E}/\mathcal{E}_0} = \frac{3}{R}\hat{\mathbf{E}}_3$, $r^{P/0} = r\hat{\mathbf{E}}_2$, $v_{rel}^P = 2\hat{\mathbf{E}}_1$, and $\mathbf{a}_{\mathcal{E}_0}^0 = -6\hat{\mathbf{E}}_1 \text{ m/s}^2$

no slip condition

Let $\hat{\mathbf{t}}$ be the tangential direction, here, $\hat{\mathbf{t}} = \hat{\mathbf{E}}_1$ then,

$$\begin{aligned}
 \mathbf{a}^{B_1} \cdot \hat{\mathbf{t}} &= \mathbf{a}^{B_0} \cdot \hat{\mathbf{t}} \\
 \text{since, } \mathbf{a}^{B_0} &= 0 \\
 \text{hence, } \mathbf{a}^{B_1} \cdot \hat{\mathbf{E}}_1 &= 0
 \end{aligned}$$

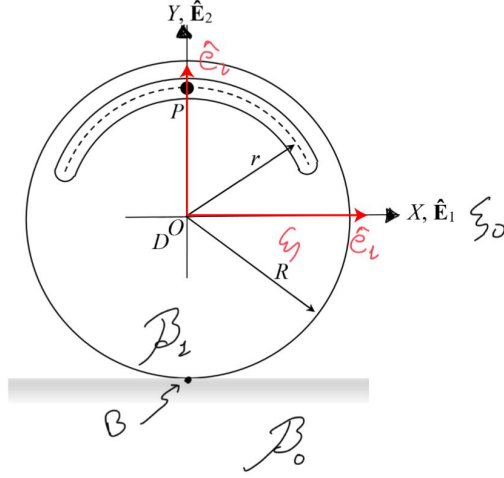


Figure 3: Schemating showing the coordinates systems

Acceleration of point B_1 through point O

relating acceleration of two point in a rigid body, B_1 and O.

$$\begin{aligned} \mathbf{a}_{\mathcal{E}_0}^{B_1} &= \mathbf{a}^O + \boldsymbol{\omega}_{\mathcal{E}/\mathcal{E}_0} \times (\boldsymbol{\omega}_{\mathcal{E}/\mathcal{E}_0} \times \mathbf{r}^{B_1/0}) + \boldsymbol{\alpha}_{\mathcal{E}/\mathcal{E}_0} \times \mathbf{r}^{B_1/0} \\ \text{here, } \mathbf{r}^{B_1/0} &= R(-\hat{\mathbf{E}}_2) \\ \mathbf{a}_{\mathcal{E}_0}^{B_1} &= -6\hat{\mathbf{E}}_1 + \frac{3}{R}\hat{\mathbf{E}}_3 \times [\frac{3}{R}\hat{\mathbf{E}}_3 \times R(-\hat{\mathbf{E}}_2)] + \boldsymbol{\alpha}_{\mathcal{E}/\mathcal{E}_0} \times R(-\hat{\mathbf{E}}_2) \\ \text{let, } \boldsymbol{\alpha}_{\mathcal{E}/\mathcal{E}_0} &= \alpha\hat{\mathbf{E}}_3 \\ \mathbf{a}_{\mathcal{E}_0}^{B_1} &= -6\hat{\mathbf{E}}_1 + \frac{3}{R}\hat{\mathbf{E}}_3 \times (3\hat{\mathbf{E}}_1) + \alpha\hat{\mathbf{E}}_3 \times R(-\hat{\mathbf{E}}_2) \\ &= \frac{9}{R}\hat{\mathbf{E}}_2 + (\alpha R - 6)\hat{\mathbf{E}}_1 \\ \mathbf{a}_{\mathcal{E}_0}^{B_1} \cdot \hat{\mathbf{E}}_1 &= \frac{9}{R}\hat{\mathbf{E}}_2 \cdot \hat{\mathbf{E}}_1 + (\alpha R - 6)\hat{\mathbf{E}}_1 \cdot \hat{\mathbf{E}}_1 \end{aligned}$$

taking dot product with $\hat{\mathbf{E}}_1$ both sides

$$\mathbf{a}_{\mathcal{E}_0}^{B_1} \cdot \hat{\mathbf{E}}_1 = \frac{9}{R}\hat{\mathbf{E}}_2 \cdot \hat{\mathbf{E}}_1 + (\alpha R - 6)\hat{\mathbf{E}}_1 \cdot \hat{\mathbf{E}}_1$$

since $\mathbf{a}_0^{B_1} \cdot \hat{\mathbf{E}}_1 = 0$ and $\hat{\mathbf{E}}_2 \cdot \hat{\mathbf{E}}_1 = 0$

$$\implies \alpha = \frac{6}{R} \text{rad/s}^2 \quad (6)$$

Now, from Equation 5,

$$\begin{aligned} \mathbf{a}_{\mathcal{E}_0}^P &= -10\hat{\mathbf{E}}_1 + \frac{3}{R}\hat{\mathbf{E}}_3 \times (\frac{3}{R}\hat{\mathbf{E}}_3 \times r\hat{\mathbf{E}}_2) + (\frac{6}{R}\hat{\mathbf{E}}_3 \times r\hat{\mathbf{E}}_2) + 2(\frac{3}{R})\hat{\mathbf{E}}_3 \times 2\hat{\mathbf{E}}_1 + (-6\hat{\mathbf{E}}_1) \\ \mathbf{a}_{\mathcal{E}_0}^P &= -10\hat{\mathbf{E}}_1 + \frac{3}{R}\hat{\mathbf{E}}_3 \times (-\frac{3r}{R}\hat{\mathbf{E}}_1) + \frac{6}{R}r(-\hat{\mathbf{E}}_1) + \frac{12}{R}\hat{\mathbf{E}}_2 - 6\hat{\mathbf{E}}_1 \\ &= -10\hat{\mathbf{E}}_1 - \frac{9r}{R^2}\hat{\mathbf{E}}_2 - \frac{6}{R}r\hat{\mathbf{E}}_1 + \frac{12}{R}\hat{\mathbf{E}}_2 - 6\hat{\mathbf{E}}_1 \\ \mathbf{a}_{\mathcal{E}_0}^P &= -20\hat{\mathbf{E}}_1 + \left(\frac{12}{R} - \frac{9r}{R^2}\right)\hat{\mathbf{E}}_2 \\ \mathbf{a}_{\mathcal{E}_0}^P &= -20\hat{\mathbf{E}}_1 + 20\hat{\mathbf{E}}_2 \quad m/s^2 \end{aligned} \quad (7)$$