

The door as viewed from the direction of the blue arrow.

A planar problem with 2D notations $\mathcal{E}_{0} \odot \hat{\mathcal{E}}_{3}$ * Origin of the observer frame (c) corresponds to the point where A will be, when the door hits the floor. midpoint of AA'

* Oragin of the BFCS (G) corresponds to the CG of the down.

Coordinate systems,

(observer) (BFCS) [A spring frame which is fixed to the right top wall at the point
$$D$$
.

 $V^{G} = V_{1}\hat{E}_{1} + V_{2}\hat{E}_{2}$
A spring frame which is fixed to the right top wall at the point D .

Angular velocity about C_{G} .

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Given tiny end-rollers, mars of the end-rollers can be ignored. Also, the frictional force acting on the door at A and B will be zero.

Also, reglecting friction in the two pulleys.

Hence, conservative system.

Using power balance method.

FBD of the door,

Fs I I'm

Note,

 $sin o = \frac{b-a}{a}$ (at the stooting rest position)

No moments acting on the rigid body, M = 0Hence, no V_j .

The reaction force N will not do any work, Since motion of B is always perpendicular to the force direction.

Only two forces contribute towards energy change,

 $\frac{E}{E} = -mg \hat{E}_{2} = -V (mg \alpha_{2})$

 $E^2 = -F_s \hat{e}'_1 = -Ky \hat{e}'_1 = -P(\frac{1}{2}ky^2)$

y → extension of the two springs starting initial from the rest position of the door. That is, yo = 0 at the starting rest position.

Note that, $y = \frac{a - x_A}{2}$, where x_A is the position of A. $\left(x_A = x_A \hat{E}_2 \right)$

Initial, when $x_A = a$, $y_0 = 0$ Final, when $x_A = 0$, $y = \frac{a}{a}$ (just before hitting the floor)

If Ex is the kinetic energy of the door,

Ex + U, + QU = constant.

Initial, $E_K^i = 0$, $U_1 = mg(a + \frac{a}{2}sino)$, $U_2 = \frac{1}{2}ky_0^2 = 0$

Final, $E_K^f = \frac{1}{2} m V_2^2$, $U_1 = mg \frac{a}{2}$, $U_2 = \frac{1}{2} K \left(\frac{a}{2}\right)^2$

Note that, Wf = 0

and V^6 at final state of the door will be just $-V_2 \, \hat{E}_2$.

Thus, equating the total energy at initial and final states,

 $mg(a + \frac{a}{2}sino) = \frac{1}{2}mV_2^2 + mg\frac{a}{2} + 2 + \frac{1}{2}K\frac{a^2}{4}$

Using equation of and rearranging,

 $\frac{1}{2}mV_2^2 = mg\left(a + \frac{b-a}{2}\right) - mg\frac{a}{2} - \frac{\kappa a^2}{4}$

 $= mg \frac{b}{2} * - \frac{ka^2}{4}$

i.e. $V_2^2 = 9b - \frac{ka^2}{2m}$

 $V_2 = \sqrt{9b - \frac{\kappa a^2}{2m}} - \cdots 3$

given a = 3m, b = 3.5 m, K = 600 N/m,

Taking $g = 9.8 \text{ m/s}^2$ and m = 150 kg.

 $V_{s} = 4.037 \, \text{m/s}$

Since same rigid body without $V^A = V^A = V^G$ any angular velocity,