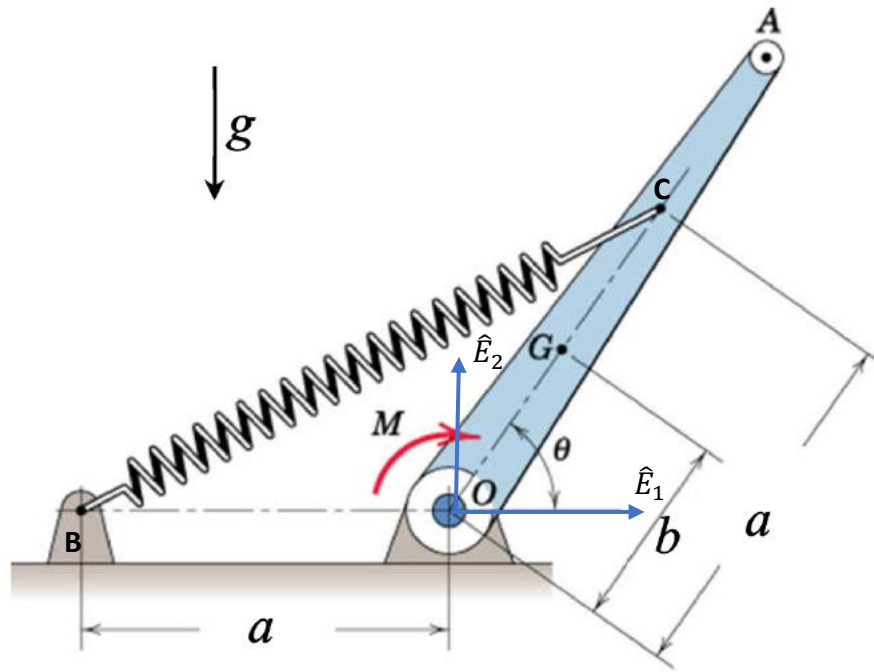


Solution:

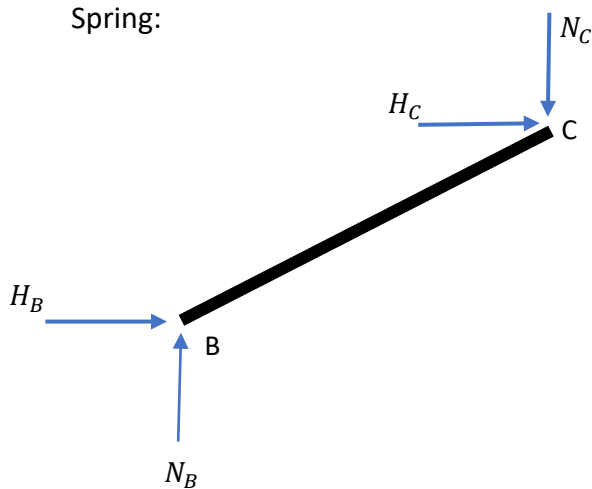
Data given: $m = 10 \text{ kg}$, $\omega = 1 \text{ rad/s}$ when $\theta = 0^\circ$, $k = 700 \text{ N/m}$, $b = 450 \text{ mm}$, $a = 800 \text{ mm}$, and radius of gyration, $r_k = 500 \text{ mm}$.



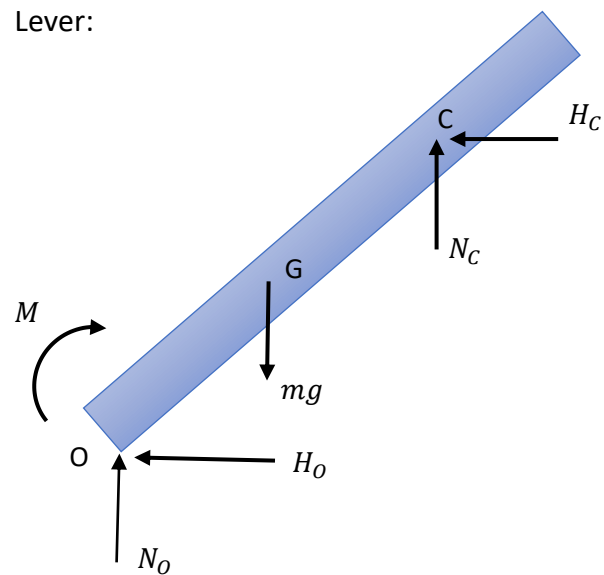
We have to find M when $\theta = 0^\circ$.

FBD:

Spring:



Lever:



Observations:

1. Spring is massless.
2. All joints are frictionless.
3. N_c, H_c are internal forces.
4. N_B, H_B, N_O, H_O are external forces but do no work as $\underline{v}^O = \underline{v}^B = 0$.
5. External forces/Moments are mg, M and spring forces.

For 2D conservative system

$$E_k + \sum_{n=1}^N \sum_i U_{in} + \sum_{n=1}^N \sum_j V_{jn} = \text{constant} \dots (1)$$

Clearly $N = 2$. Kinetic energy of the system is given as

$$E_k = \frac{1}{2} m |\underline{v}^G|^2 + \frac{1}{2} \underline{\omega}^B \cdot \underline{I}_G^B \cdot \underline{\omega}^B$$

For 2D system,

$$E_k = \frac{1}{2} m |\underline{v}^G|^2 + \frac{1}{2} I_3^G \omega_B^2$$

where, $\underline{\omega}^B = \dot{\theta} \hat{E}_3$ at any instant of time.

For \underline{v}^G , performing kinematics

Consider lever OA, since both points O and G are on same body therefore

$$\underline{v}^G = \underline{v}^O + \underline{\omega}^B \times \underline{r}_{G/O}$$

and

$$\underline{r}_{G/O} = b \cos \theta \hat{E}_1 + b \sin \theta \hat{E}_2$$

this gives:

$$\underline{v}^G = 0 + \dot{\theta} \hat{E}_3 \times (b \cos \theta \hat{E}_1 + b \sin \theta \hat{E}_2)$$

$$\Rightarrow \underline{v}^G = b \dot{\theta} \cos \theta \hat{E}_2 - b \dot{\theta} \sin \theta \hat{E}_1$$

$$\Rightarrow |\underline{v}^G|^2 = b^2 \dot{\theta}^2$$

Therefore,

$$E_k = \frac{1}{2} m b^2 \dot{\theta}^2 + \frac{1}{2} I_3^G \dot{\theta}^2 \dots (2)$$

where $I_3^G = m r_k^2$.

Scalar potentials due to external forces and moments,

$$\sum_{n=1}^2 \sum_i U_{in} = mgb \sin \theta + \frac{1}{2} kx^2 \dots \dots (3)$$

where x is displacement of spring at any instant.

$$\sum_{n=1}^2 \sum_j V_{jn} = -M\theta \dots \dots (4)$$

Now using Eqs. (2), (3) and (4) into Eq. (1), we get

$$\frac{1}{2} mb^2 \dot{\theta}^2 + \frac{1}{2} I_3^G \dot{\theta}^2 + mgb \sin \theta + \frac{1}{2} kx^2 - M\theta = \text{constant} \dots \dots (5)$$

For obtaining the value of 'constant', using initial condition.

At $\theta = 90^\circ$, $\dot{\theta} = 0$ rad/s and $x = 0$.

From Eq. (5), we get

$$\text{constant} = mgb - \frac{M\pi}{2}$$

then Eq. (5) becomes

$$\frac{1}{2} mb^2 \dot{\theta}^2 + \frac{1}{2} I_3^G \dot{\theta}^2 + mgb \sin \theta + \frac{1}{2} kx^2 - M\theta = mgb - \frac{M\pi}{2} \dots \dots (6)$$

We have to find M when $\theta = 0^\circ$.

At $\theta = 90^\circ$, spring is unstretched and its length is $\sqrt{2}a$, and when $\theta = 0^\circ$, spring stretched, and its length become $2a$. so $x = 2a - \sqrt{2}a$.

Use Eq. (6) when $\theta = 0^\circ$.

$$\begin{aligned} & \frac{1}{2} (10)(0.45)^2 (1)^2 + \frac{1}{2} (10)(0.5)^2 (1)^2 \\ & + (10)(9.81)(0.45) \sin 0^\circ + \frac{1}{2} (700) \left(2(0.8) - \sqrt{2}(0.8) \right)^2 - M(0) \\ & = (10)(9.81)(0.45) - \frac{M\pi}{2} \end{aligned}$$

$$M = 22.28 \text{ Nm}$$