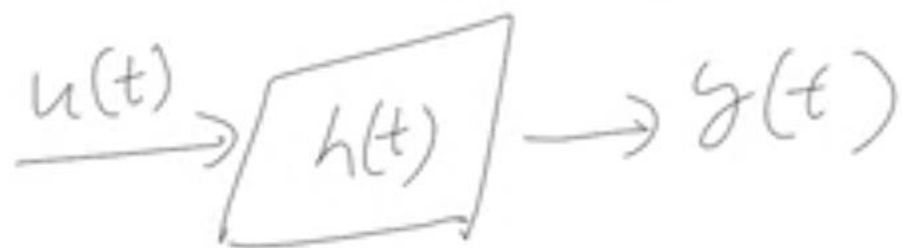




Transfer function



$$TF = \frac{Y(s)}{U(s)} = \mathcal{L} h(t)$$



All initial conditions
are zero



L Electrical Ckt



$$x_1 \triangleq v_C$$

$$x_2 = i_L$$

$$R = 10 \Omega$$

$$L = 0.0045 \text{ H}$$

$$C = 0.03 \text{ F}$$

$$\frac{dx_1}{dt} = -\frac{1}{RC} x_1 + \frac{1}{C} x_2$$

$$\frac{dx_2}{dt} = -\frac{1}{L} x_1 + \frac{1}{L} v_s$$



$$\frac{dx_1}{dt} = -3.33 x_1 + 33.3 x_2$$

$$\frac{dx_2}{dt} = -222.2 x_1 + 222.2 V_s$$

$$s X_1(s) = -3.33 X_1(s) + 33.3 X_2(s) \Rightarrow X_2(s) = \frac{s + 3.33}{33.3} X_1(s)$$

$$s X_2(s) = -222.2 X_1(s) + 222.2 V_s(s)$$

$$\frac{s(s + 3.33)}{33.3} X_1(s) = -222.2 X_1(s) + 222.2 V_s(s)$$

$$TF = \frac{Y(s)}{V_s(s)} = \frac{X_1(s)}{V_s(s)} = \frac{7400}{s^2 + 3.33s + 7400}$$



TF of a DC motor

$$\frac{dx_1}{dt} = -\frac{B}{J} x_1 + \frac{K_T}{J} x_2, \quad \begin{matrix} x_1 \triangleq \omega \\ x_2 \triangleq i_a \end{matrix}$$

$$\frac{dx_2}{dt} = -\frac{R_a}{L_a} x_2 - \frac{K_b}{L_a} x_1 + \frac{1}{L_a} V_a$$

$$B = 0.1, \quad J = 1.2, \quad K_T = \frac{0.8}{n \cdot n/A}, \quad K_b = 1.6 \frac{V \cdot rad}{sec}$$

$$L_a = 0.045 H, \quad R_a = 20 \Omega$$

$$y(t) = \omega = x_1$$
$$TF = \frac{Y(s)}{V_a(s)} = \frac{x_1(s)}{V_a(s)} = ?$$

$$T_m = K_T i_a$$
$$e_b = K_b \omega$$



$$\frac{dx_1}{dt} = -0.0833 x_1 + 0.667 x_2$$

$$\frac{dx_2}{dt} = -444.4 x_2 - 35.55 x_1 + 22.2 V_q$$

$$sX_1(s) = -0.0833 X_1(s) + 0.667 X_2(s)$$

$$X_2(s) = \frac{s + 0.0833}{0.667} X_1(s)$$

$$sX_2(s) = -444.4 X_2(s) - 35.55 X_1(s) + 22.2 V_q(s)$$

$$(s + 444.4) X_2(s) = -35.55 X_1(s) + 22.2 V_q(s)$$



$$\left[\frac{(s+0.0833)(s+444.4)}{0.667} + 35.55 \right] X_1(s) = 22.2 V_a(s)$$

$$TF = \frac{X_1(s)}{V_a(s)} = \frac{Y(s)}{V_a(s)} = \frac{14.8}{(s+0.0833)(s+444.4) + 23.7}$$

✓