

EE 250
Tutorial sheet 4
Solution

Q1 Plot the root locus when

$$(a) L(s) = \frac{1}{s^2}$$

$$(b) L(s) = \frac{s+1}{s+2} \frac{1}{s^2}$$

$$(c) L(s) = \frac{s+1}{s+9} \frac{1}{s^2}$$

$$(d) L(s) = \frac{s+1}{s+4} \frac{1}{s^2}$$

Comment on the results

Solution 1(a)

$$L(s) = \frac{1}{s^2}$$

Characteristic polynomial

$$s^2 + K = 0$$

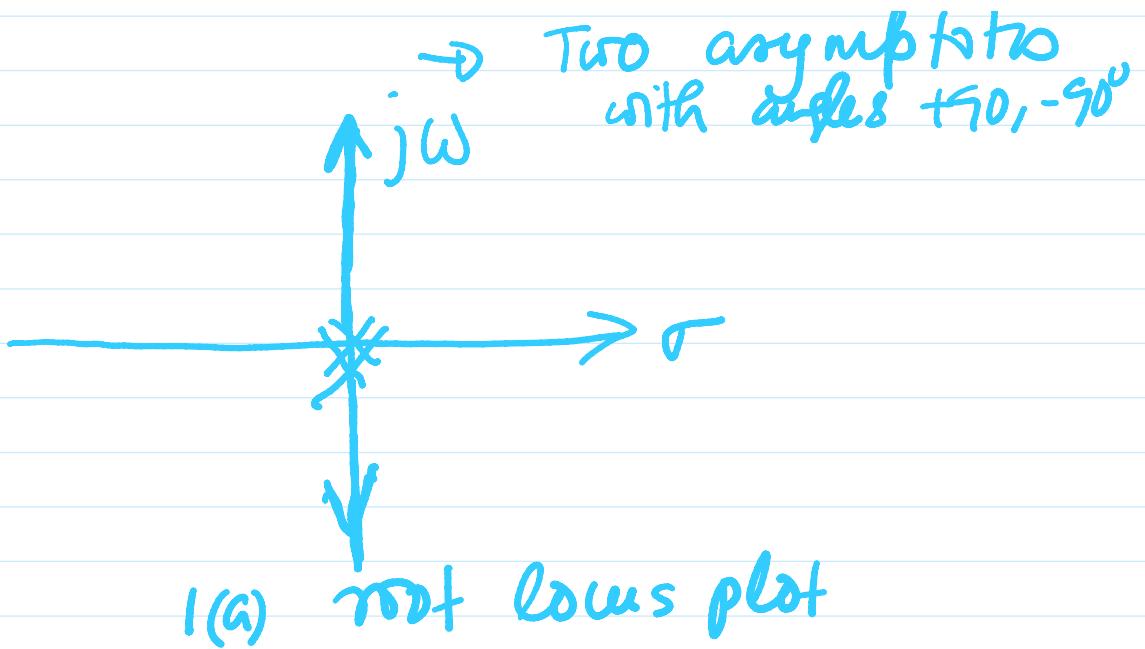
$$\lambda_{1,2} = \pm j\sqrt{K}$$

Break away pt $\frac{dk}{ds} = -2s = 0$

$$\Rightarrow s = 0$$

Two poles \rightarrow Two root locus branches

\rightarrow Two asymptotes



solution 1(b)

$$L(s) = \frac{s+1}{s+2} \frac{1}{s^2}$$

1. There are three poles and one zero. Two poles will converge at ∞ and the other pole will converge at zero

2. Two root locus branches converge at $\infty \Rightarrow$ two asymptotes with angles $+90^\circ, -90^\circ$

$$\begin{aligned}\phi_l &= \frac{180 + 360(l-1)}{n-m} \\ &= 180/2, \frac{180 + 360}{\underline{\quad}}\end{aligned}$$

$$= 180/2, \frac{180+560}{2}$$

$$= 90^\circ, 270^\circ (-90^\circ)$$

3. Centroid of the asymptotes

$$C = \frac{\sum p_i - \sum z_i}{n-m}$$

$$= \frac{-12 - (-1)}{2} = -5.5$$

$$4. d(s) = \delta^v(s+12) + k(s+1) = 0$$

$$k = -\frac{\delta^v(s+12)}{s+1}$$

$$\frac{dk}{ds} = -\frac{[(s+1)(3s^v + 24s) - \delta^v(s+12)]}{(s+1)^2} = 0$$

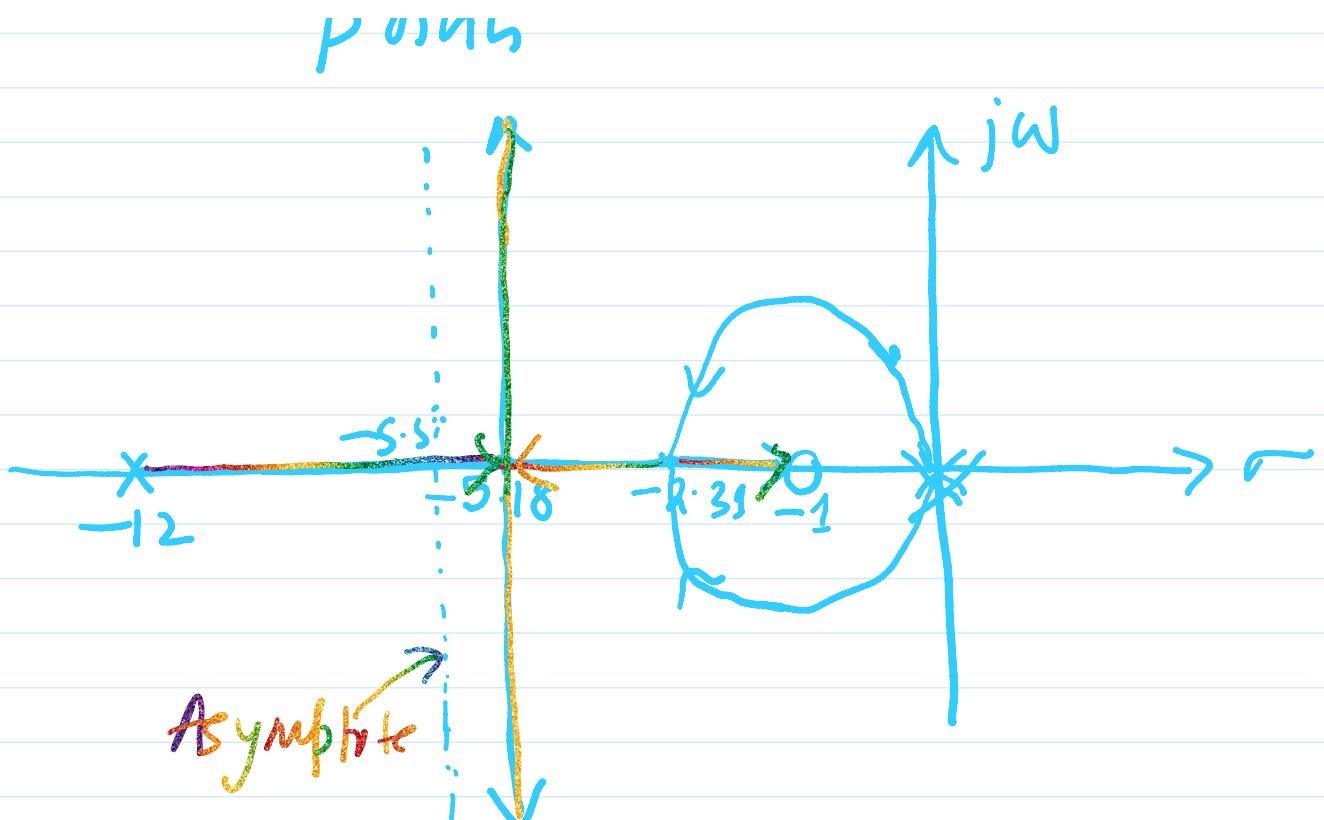
$$\Rightarrow 3s^3 + 3s^v + 24s^v + 24s - s^3 - 12s^2 = 0$$

$$\Rightarrow 2s^3 + 15s^v + 24s = 0$$

$$\Rightarrow s(2s^v + 15s + 24) = 0$$

roots are $s_1 = 0, s_2 = -2.31, s_3 = -5.18$

There are three breakaway points



1(b) root locus

Two poles break away at $s=0$ and break in on the real axis at $s = -2.31$. One branch converges at zero ($s=-1$) and other branch moves towards the other branch that is coming from $s=-12$. These two branches break away at $s=-5.18$ and follow the asymptotes at $\pm 90^\circ$.

$$1.C \quad L(s) = \frac{s+1}{s+9} \quad \frac{1}{s^2}$$

1. 3 poles & one zero \Rightarrow two branches converges to infinity along the asymptotes at $\pm 90^\circ$.

2. Centroid of the asymptotes

$$C = \frac{\sum p_i - \sum z_i}{n-m} = \frac{-9 - (-1)}{2} = -4$$

3. Break away points

$$\frac{dk}{ds} = 0,$$

$$\text{char. ptly } d(s) = s^2(s+9) + k(s+1) = 0$$

$$k = -\frac{s^2(s+9)}{s+1}$$

$$\frac{dk}{ds} = -\frac{(s+1)(3s^2+18s) - s^2(s+9)}{(s+1)^2} = 0$$

$$\Rightarrow 3s^3 + 3s^2 + 18s^2 + 18s - s^3 - 9s^2 = 0$$

$$2s^3 + 12s^2 + 18s = 0$$

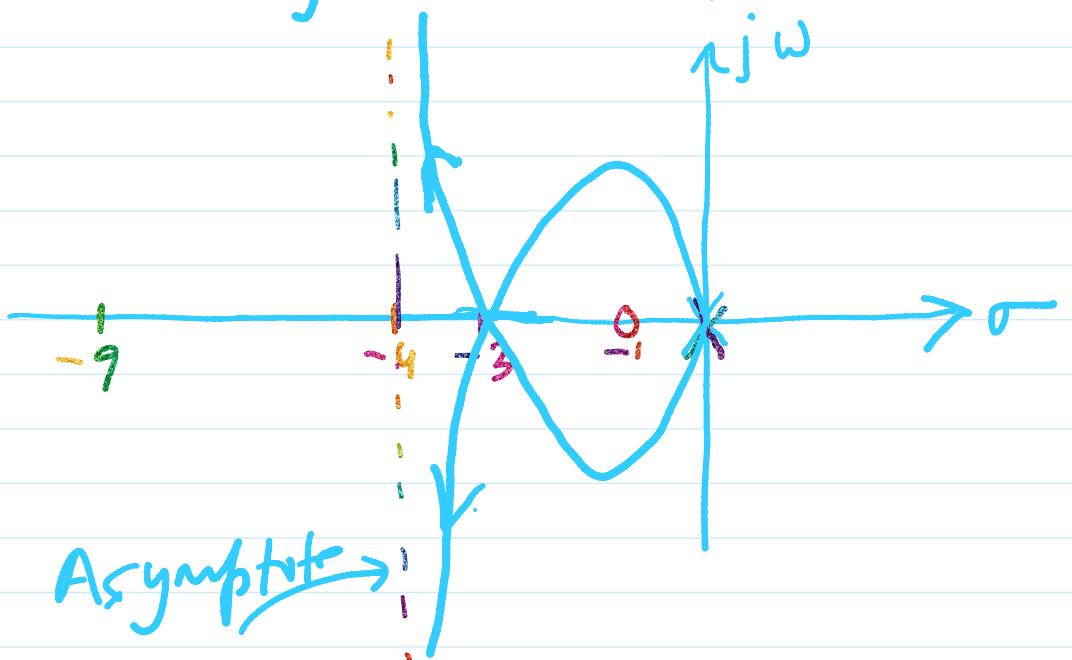
$$s(2s^2 + 12s + 18) = 0$$

$$s(s^2 + 6s + 9) = 0$$

$$s(s+3)^2 = 0$$

break away points $s = 0, s_1 = -3, s_2 = -3$

$s(s+ts) = 0$
 break away pts are $s_1=0, s_2=-3, s_3=-3$



I.C root locus plot

1d. $L(s) = \frac{s+1}{s+4} \frac{1}{s^2}$

Cent mid $c = \frac{-4 - (-1)}{2} = -1.5$

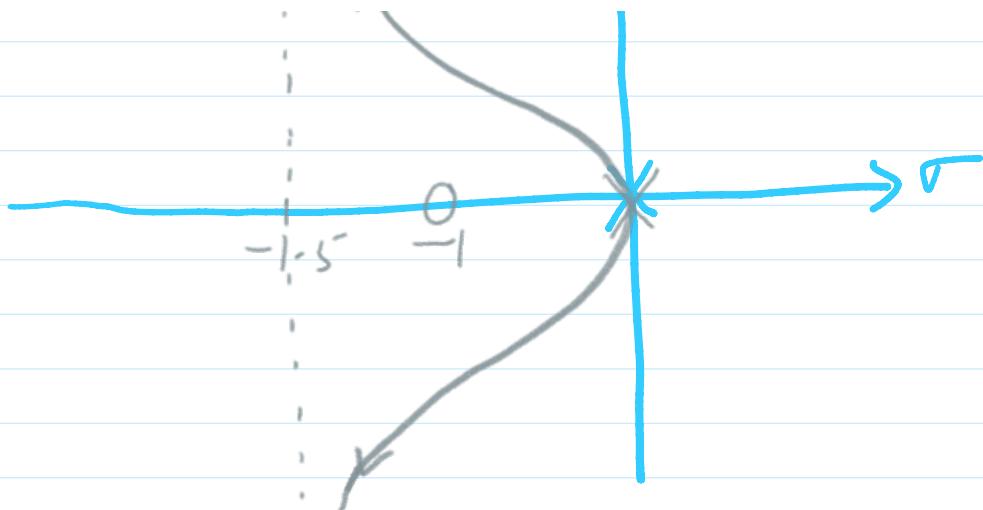
Break away pts $\frac{dk}{ds} = 0$

$$2s^3 + 7s^2 + 8s = 0$$

$$s_1=0, s_{1,2} = -1.75 \pm j0.9$$

$s_{1,2}$ do not lie on the mt locus.





Comments on results:

$\frac{s+1}{s+12}$, $\frac{s+1}{s+5}$, $\frac{s+1}{s+4}$ are all valid compensators. Desired specifications will determine which one is a better one.

Q2 Draw the root locus of the system with $L(s) = \frac{K}{s(s+1)(s+20)}$.

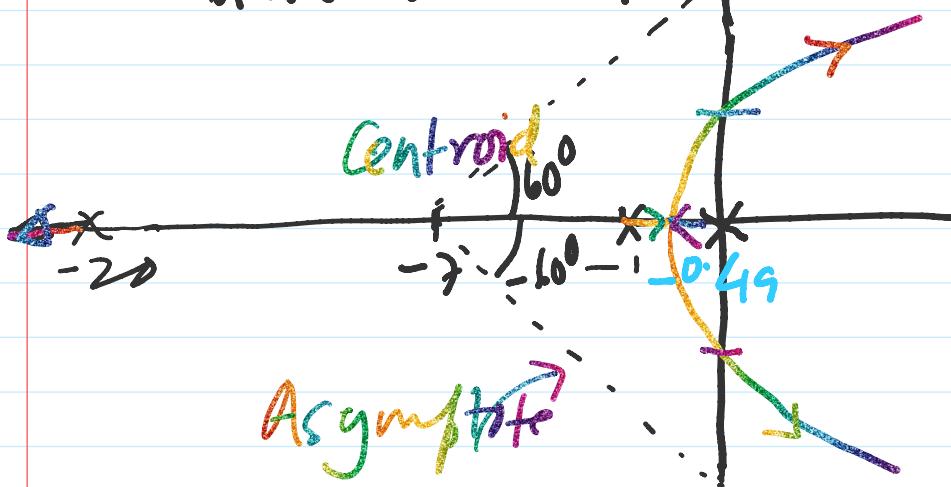
(i) Determine K such that dominant poles have $\zeta = 0.5$

(ii) Find the second order approximation of the closed loop system for part (i).

(iii) find range of K for which the system is stable.

Soln We have solved the similar problem in the class. The root locus will

class. The rest locus will have the shape as:



Break away pt

$$\text{Char poly } s^3 + 21s^2 + 20s + K = 0$$

$$K = - (s^3 + 21s^2 + 20s)$$

$$\frac{dK}{ds} = 0 \Rightarrow 3s^2 + 42s + 20 = 0$$

$$s_1 = -13.5, s_2 = -0.49$$

Break away pt must lie between 0 & -1. Hence $s_2 = -0.49$ is the break away pt

Crossing of $j\omega$ axis

$$s^3 + 21s^2 + 20s + K = 0$$

$$s^3 \quad 1 \quad 20$$

$$s^2 \quad 21 \quad K$$

$$s^1 \quad \frac{21 \times 20 - K}{21} \quad 0$$

$$K = 420 \text{ when } j\omega \text{ lies}$$

$$\frac{1}{2s} \quad 0$$

*when jw line
is crossed*

At this point,

Aux eqn $2s^2 + 420 = 0$
 $s^2 + 210 = 0$
 $s = \pm j\sqrt{210}$
 $= \pm j4.47$

Range of K for which
the system is stable

(iii) $0 < K < 420$

(i) Draw the root locus on a graph sheet.

The asymptote will cross the
jw axis at ± 12.12

The root locus will be parallel
to the asymptote.

Then draw the line of θ

$$\theta = \cos^{-1} \frac{1}{2} = \cos^{-1} 0.5 = 60^\circ$$

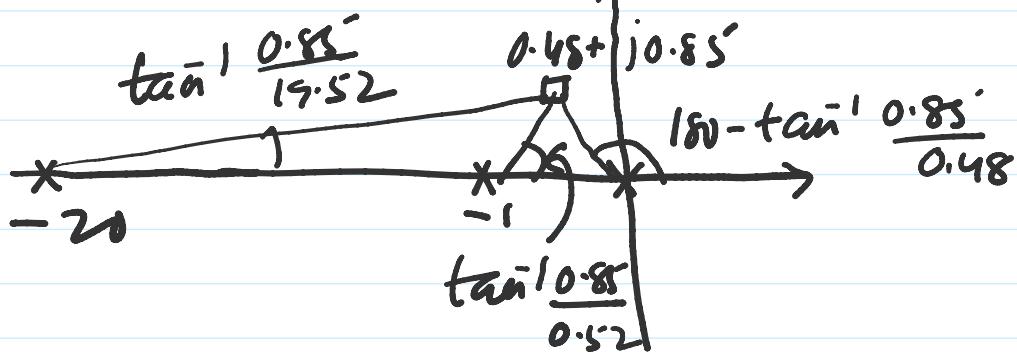
This will meet the root locus
at $s_1 = -0.475 \pm 0.85j$

(tutors can demonstrate
using MATLAB)

One can also verify if it is

One can also verify if it is correct by angle criteria

$$\boxed{G(s)} \Big|_{s=s_1} = -180^\circ$$



$$-(180 - 60.54) - 58^\circ - 2.5^\circ \approx 167^\circ$$

$$|K G(s)| = 1$$

$$\begin{aligned} K &= (s_1)(s_1+1)(s_1+20) \\ &= 0.97 \times 0.996 \times 19.5 \\ &\approx 18.95 \end{aligned}$$

(ii) Dominant pole pairs are

$$s_{1,2} = -0.48 \pm j0.85$$

9 deg 2nd order than poly

$$\begin{aligned} &(s - s_1)(s - s_2) \\ &= s^2 + 0.96s + 0.95 \end{aligned}$$

$$\begin{aligned} \text{Actual TF} &= \frac{K}{s^2 + 2s + 0.95 + K} \\ &= \frac{18.95}{s^2 + 2s + 0.95 + 18.95} \end{aligned}$$

$$\begin{aligned}
 &= \frac{18.95}{s^3 + 21s^2 + 20s + 18.95} \\
 &= \frac{18.95}{(s^2 + 0.96s + 0.95)(s + 20.05)} \\
 &\approx \frac{18.95 / 20.05}{s^2 + 0.96s + 0.95} \\
 &\approx \frac{0.95}{s^2 + 0.96s + 0.95}
 \end{aligned}$$

DC gain for both = 1