

System Response

System is represented as TF

Example

$$\frac{Y(s)}{U(s)} = \frac{1}{\tau s + 1}$$

$$u(t) = t u(t) \Rightarrow U(s) = \frac{1}{s^2}$$

$$y_{ss} = \lim_{t \rightarrow \infty} y(t)$$

$$= (t - \tau)$$

$$Y(s) = \frac{1}{s^2 (\tau s + 1)} = \frac{1}{s^2} - \frac{\tau}{s} + \frac{\tau^2}{\tau s + 1}$$

$$y(t) = t u(t) - \tau u(t) + \tau e^{-\frac{1}{\tau} t}$$





State space model

$$\dot{x} = Ax + Bu, \quad x(t_0) = x_0$$
$$x \in \mathbb{R}^n, \quad A \in \mathbb{R}^{n \times n}, \quad B \in \mathbb{R}^n$$

$\dot{x} = Ax$ Find $x(t)$ given $x(t_0) = x_0$

LHS = Ke^{at} Let $x(t)$ is a solution which is

RHS = aKe^{at}

$x(t) = Ke^{at}$

$x(t) = x_0 e^{a(t-t_0)}$ $x(t_0) = x_0 = Ke^{at_0}$

$K = x_0 e^{-at_0}$



$$\dot{x} = ax, \quad x(t_0) = x_0$$

$$x(t) = x_0 e^{a(t-t_0)} \rightarrow \text{solution}$$

$$\dot{x} = Ax, \quad x \in \mathbb{R}^n, \quad x(t_0) = x_0$$

$$e^{At} = I + At + \frac{1}{2!} A^2 t^2 + \frac{1}{3!} A^3 t^3 + \dots$$

$$\frac{d}{dt} e^{At} = A + A^2 t + \frac{1}{2!} A^3 t^2 + \dots$$

$$= A \left[I + At + \frac{1}{2!} A^2 t^2 + \dots \right]$$

$$= A e^{At}$$

$$\Leftrightarrow$$

$$\frac{d}{dt} e^{at} = a e^{at}$$



$$\frac{d}{dt} e^{At} = A e^{At}$$

$$\dot{x} = Ax, \quad x(t_0) = x_0$$

$$\begin{matrix} x(t) & = & e^{At} \cdot k \\ n \times 1 & & \begin{matrix} n \times n & n \times 1 \end{matrix} \end{matrix}$$

$$A e^{At} k = A e^{At} k$$

$$\begin{aligned} \rightarrow x(t) &= e^{At} e^{-At_0} x_0 \\ &= e^{A(t-t_0)} x_0 \end{aligned}$$

$$\begin{aligned} x(t_0) &= e^{At_0} k = x_0 \\ k &= e^{-At_0} x_0 \end{aligned}$$



$$\dot{x} = ax$$

$$\downarrow a(t-t_0)$$
$$x(t) = x_0 e^{a(t-t_0)}$$

$$\dot{x} = Ax$$

$$\downarrow A(t-t_0)$$
$$x(t) = e^{A(t-t_0)} x_0$$

$n \times 1 \quad \quad n \times n \quad \quad n \times 1$

$$\dot{x} = Ax + Bu, \quad x(t_0) = x_0$$

$$\frac{d}{dt} e^{At} = A e^{At} = e^{At} A \quad \& \text{ verify}$$

$$e^{-At} \dot{x} = e^{-At} A x + e^{-At} B u$$

$$\frac{d}{dt} \left[e^{-At} x(t) \right] = \underbrace{e^{-At} \dot{x} - A e^{-At} x}_{=0} = e^{-At} B u$$



$$\frac{d}{dt} \left(e^{-At} x(t) \right) = e^{-At} B u(t)$$

$$\int_0^t d \left(e^{-A\tau} x(\tau) \right) = \int_0^t e^{-A\tau} B u(\tau) d\tau$$

$$\left[e^{-A\tau} x(\tau) \right]_0^t = \int_0^t e^{-A\tau} B u(\tau) d\tau$$

$$e^{At} x(t) - x_0 = \int_0^t e^{A(t-\tau)} B u(\tau) d\tau$$

$$x(t) - e^{At} x_0 = \int_0^t e^{A(t-\tau)} B u(\tau) d\tau$$



$$x(t) = e^{At} x_0 + \int_0^t e^{A(t-\tau)} B u(\tau) d\tau$$

Generic Response

$$\dot{x} = Ax + Bu, \quad x(t_0) = x_0$$

First challenge Compute e^{At}



$$\mathcal{L} \dot{x} = \mathcal{L} A x$$

$$x(0) = x_0$$

$$sX(s) - x(0) = AX(s)$$

$$(sI - A)X(s) = x_0$$

$$X(s) = (sI - A)^{-1} x_0$$

$$x(t) = e^{A(t-t_0)} x_0, \quad t_0 = 0$$

$$= e^{At} x_0$$

$$e^{At} = \mathcal{L}^{-1} (sI - A)^{-1}$$

Ex

$$A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$$

Compute

$$\begin{aligned} e^{At} &= (sI - A)^{-1} = \left\{ \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \right\}^{-1} \\ &= \begin{bmatrix} s & -1 \\ 2 & s+3 \end{bmatrix}^{-1} = \frac{1}{s(s+3)+2} \begin{bmatrix} s+3 & 1 \\ -2 & s \end{bmatrix} \\ &= \frac{1}{(s+1)(s+2)} \begin{bmatrix} s+3 & 1 \\ -2 & s \end{bmatrix} = \begin{bmatrix} \end{bmatrix} \end{aligned}$$





$$(sI - A)^{-1} = \begin{bmatrix} \frac{2}{s+1} - \frac{1}{s+2} & \frac{1}{s+1} - \frac{1}{s+2} \\ -\frac{2}{s+1} + \frac{2}{s+2} & \frac{2}{s+2} - \frac{1}{s+1} \end{bmatrix}$$

$$e^{At} = \mathcal{L}^{-1}(sI - A)^{-1} = \begin{bmatrix} 2e^{-t} - e^{-2t} & e^{-t} - e^{-2t} \\ -2e^{-t} + 2e^{-2t} & 2e^{-2t} - e^{-t} \end{bmatrix}$$



$$\dot{x} = Ax + Bu, \quad x(0) = x_0$$

$$x(t) = ?$$
$$= \underline{e^{At} x_0 + \int_0^t e^{A(t-\tau)} B u(\tau) d\tau}$$

$$sX(s) - x_0 = A X(s) + B U(s)$$

$$(sI - A) X(s) = x_0 + B U(s)$$

$$X(s) = (sI - A)^{-1} x_0 + (sI - A)^{-1} B U(s)$$

$$\underline{x(t) = e^{At} x_0 + \int_0^t e^{A(t-\tau)} B u(\tau) d\tau}$$

Another example

$$\dot{x} = \begin{bmatrix} -1 & 1 \\ -1 & 10 \end{bmatrix} x + \begin{bmatrix} 0 \\ 10 \end{bmatrix} u$$

Find $x(t)$ under zero initial condition

$$x(t) = \int_0^t e^{A(t-\tau)} B u(\tau) d\tau$$

$$e^{At} = \mathcal{L}^{-1} (sI - A)^{-1} = \mathcal{L}^{-1} \frac{1}{s^2 + 11s + 11} \begin{bmatrix} s+10 & 1 \\ -1 & s+1 \end{bmatrix}$$





$$\tilde{S} + 11S + 11 = (s + 1.1125)(s + 7.8875)$$

$$e^{At} = \begin{bmatrix} \underbrace{1.0128 e^{-1.1125t} - 0.0128 e^{-7.8875t}}_{1st} & 0.114 e^{-1.1125t} - 0.114 e^{-7.8875t} \\ -0.114 e^{-1.1125t} + 0.114 e^{-7.8875t} & -0.0128 e^{-1.1125t} + 1.0128 e^{-7.8875t} \end{bmatrix}$$

$$x(t) = \int e^{A(t-\tau)} B u(\tau) d\tau$$

Find out step response



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$$x(t) = \begin{bmatrix} 0.5054 - 1.0247e^{-1.1125t} - 5.88t \\ + 0.1153e^{-1.1125t} \\ - 0.0132 + 0.1153e^{-1.1125t} - 5.88t \\ - 0.1019e^{-1.1125t} \end{bmatrix}$$



Summary

1. Response given TF

$$TF = \frac{Y(s)}{U(s)}$$

$$Y(s) = TF \times U(s)$$

$$y(t) = \mathcal{L}^{-1} \underbrace{TF \times U(s)}$$



Response of a system in
state space representation

1. $\dot{x} = Ax + Bu, \quad x(t_0) = x_0$

$$x(t) = e^{At} x_0 + \int_0^t e^{A(t-\tau)} B \underline{u}(\tau) d\tau$$

$$\underline{e^{At}} = \mathcal{L}^{-1} (sI - A)^{-1}$$