

```
In [1]: import numpy as np  
        from PIL import Image
```

Load the image

```
In [2]: hm_img = Image.open('hidden_message.png')  
hm_img
```

Out[2]:




```
In [3]: hm_img_mat = np.array(list(hm_img.getdata()), float)
hm_img_mat.shape
```

```
Out[3]: (691200, 3)
```

Extract each of the RGB channels

```
In [4]: hm_imgR = hm_img.getchannel(0)    # Red channel in L-mode (Luminance)
hm_imgR
```

```
Out[4]:
```



```
In [5]: hm_imgG = hm_img.getchannel(1)    # Green channel in L-mode (Luminance)
hm_imgB = hm_img.getchannel(2)    # Blue channel in L-mode (Luminance)
```

Convert the channels into numpy array to make it easy to manipulate

```
In [6]: hm_imgR_mat = np.array(hm_imgR)
print(hm_imgR_mat.shape)
print('\n', hm_imgR_mat)
```

(960, 720)

```
[[248 248 246 ... 159 160 164]
 [246 246 249 ... 166 167 162]
 [244 244 247 ... 166 170 170]
 ...
 [215 217 208 ... 236 235 236]
 [217 214 214 ... 234 233 234]
 [225 218 213 ... 235 233 231]]
```

```
In [7]: hm_imgG_mat = np.array(hm_imgG)
hm_imgG_mat.shape
```

Out[7]: (960, 720)

```
In [8]: hm_imgB_mat = np.array(hm_imgB)
hm_imgB_mat.shape
```

Out[8]: (960, 720)

Create numpy arrays to store pixel values of message image

```
In [9]: dimension_R1, dimension_R2 = hm_imgR_mat.shape
msg_R = np.empty(shape = (dimension_R1//4, dimension_R2//4))
msg_R.shape
```

Out[9]: (240, 180)

```
In [10]: dimension_G1, dimension_G2 = hm_imgG_mat.shape
msg_G = np.empty(shape = (dimension_R1//4, dimension_R2//4))
msg_G.shape
```

Out[10]: (240, 180)

```
In [11]: dimension_B1, dimension_B2 = hm_imgB_mat.shape
msg_B = np.empty(shape = (dimension_R1//4, dimension_R2//4))
msg_B.shape
```

Out[11]: (240, 180)

Normalize image channel arrays

```
In [12]: def normalize_imgmat(imgmat):
    ...
    Min-Max scaling
    Values between [0-1]
    ...

    min_value = imgmat.min()
    max_value = imgmat.max()
    normalized_imgmat = (imgmat - min_value) / (max_value - min_value)
    return normalized_imgmat
```

```
In [13]: hm_imgR_norm = normalize_imgmat(hm_imgR_mat)
hm_imgR_norm
```

```
Out[13]: array([[0.97254902, 0.97254902, 0.96470588, ..., 0.62352941, 0.62745098,
0.64313725],
[0.96470588, 0.96470588, 0.97647059, ..., 0.65098039, 0.65490196,
0.63529412],
[0.95686275, 0.95686275, 0.96862745, ..., 0.65098039, 0.66666667,
0.66666667],
...,
[0.84313725, 0.85098039, 0.81568627, ..., 0.9254902 , 0.92156863,
0.9254902 ],
[0.85098039, 0.83921569, 0.83921569, ..., 0.91764706, 0.91372549,
0.91764706],
[0.88235294, 0.85490196, 0.83529412, ..., 0.92156863, 0.91372549,
0.90588235]])
```

```
In [14]: hm_imgG_norm = normalize_imgmat(hm_imgG_mat)
hm_imgB_norm = normalize_imgmat(hm_imgB_mat)
```

Compute singular values for each non-overlapping 4 * 4 block in the image

```
In [15]: def find_block_sv(arr_ch, msg_ch, T):
    ...
    Find the singular values of each block as  $\sigma_1, \sigma_2, \sigma_3, \sigma_4$ , sorted in descending
    Encode 1 "bit" of information as the difference between  $\sigma_2$  and  $\sigma_3$  wrt a thresh
    Map the resulting bit value to the corresponding message pixel
    ...

    n_rows, n_cols = msg_ch.shape
    for i in range(n_rows):
        for j in range(n_cols):
            block = arr_ch[4 * i: 4 * (i + 1), 4 * j: 4 * (j + 1)]
            U, sigma, V = np.linalg.svd(block)
            sig_1, sig_2, sig_3, sig_4 = sigma
            msg_pix_val = 0
            if sig_2 - sig_3 > T:
                msg_pix_val = 1
            msg_ch[i][j] = msg_pix_val
    return msg_ch
```

```
In [16]: T = 0.004      # Constant
```

```
In [17]: msg_R = find_block_sv(hm_imgR_norm, msg_R, T)
msg_R
```

```
Out[17]: array([[1., 1., 1., ..., 1., 1., 1.],
 [1., 1., 1., ..., 1., 1., 1.],
 [1., 1., 1., ..., 1., 1., 1.],
 ...,
 [1., 1., 1., ..., 1., 1., 1.],
 [1., 1., 1., ..., 1., 1., 1.],
 [1., 1., 1., ..., 1., 1., 1.]])
```

```
In [18]: msg_G = find_block_sv(hm_imgG_norm, msg_G, T)
msg_B = find_block_sv(hm_imgB_norm, msg_B, T)
```

Superimpose the three message channels


```
In [19]: # To create an RGB image from the three message channels

msg_uint8 = (np.dstack((msg_R, msg_G, msg_B)) * 255.999).astype(np.uint8)
# The reason for using 255.999 instead of 255 is to ensure that rounding errors
# Multiplying by 255 would round down values less than 1 to 0, which might result in a black image
msg_uint8.shape
```

```
Out[19]: (240, 180, 3)
```

```
In [20]: msg_img = Image.fromarray(msg_uint8)
msg_img
```

```
Out[20]:
```



Bonus - A play-on-words response

Mathematicians enjoy hiking because they are "add-venturous" "math-letes" who embark on a "pi-cnic" to find the "X" that marks the "vertex" with the most "sin-fully" beautiful "derivative" of the scenery and "acute" "tan-gential" insights "calculated" on the minimum "cos-t" "path", all while avoiding "complex" wildlife, "irrational" obstacles and "undefined" trails!

```
In [20]:
```

```
In [20]:
```