# Machine Learning CSE 6363 (Fall 2019)

Lecture 2 Linear Algebra Review

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- Why?
  - Solve linear equations?
  - Everything is about "Matrix"

• Example:

$$5x_1 + 5x_2 = 15$$
$$-x_1 + 7x_2 = 13$$

With matrix notation, we can write the above system as:

$$A x = B$$

$$A = \begin{bmatrix} 5 & 5 \\ -1 & 7 \end{bmatrix}, B = \begin{bmatrix} 15 \\ 13 \end{bmatrix}$$

#### • Basic Notation

- $-A \in \mathbb{R}^{m \times n}$
- $-x \in \mathbb{R}^n$
- $-x^T$

### • Matrix Multiplication

$$A \in \mathbb{R}^{m \times n} \text{ and } B \in \mathbb{R}^{n \times p}$$

$$C = AB \in \mathbb{R}^{m \times p}$$

$$C_{ij} = \sum_{k=1}^{n} A_{ik} B_{kj}$$

- Vector-Vector Products
  - Inner product or dot product

$$x^T y \in \mathbb{R} = \begin{bmatrix} x_1 & x_2 & \cdots & x_n \end{bmatrix} \begin{bmatrix} y_1 \\ x_2 \\ \vdots \\ y_n \end{bmatrix} = \sum_{i=1}^n x_i y_i$$

Outer product

$$xy^{T} \in \mathbb{R}^{m \times n} = \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{m} \end{bmatrix} \begin{bmatrix} y_{1} & y_{2} & \cdots & y_{n} \end{bmatrix} = \begin{bmatrix} x_{1}y_{1} & x_{1}y_{2} & \cdots & x_{1}y_{n} \\ x_{2}y_{1} & x_{2}y_{2} & \cdots & x_{2}y_{n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m}y_{1} & x_{m}y_{2} & \cdots & x_{m}y_{n} \end{bmatrix}$$

• How to understand "Matrix-Matrix products"

$$C = AB = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ \vdots & \vdots & \vdots \\ - & a_m^T & - \end{bmatrix} \begin{bmatrix} | & | & & | \\ b_1 & b_2 & \cdots & b_p \\ | & | & & | \end{bmatrix} = \begin{bmatrix} a_1^T b_1 & a_1^T b_2 & \cdots & a_1^T b_p \\ a_2^T b_1 & a_2^T b_2 & \cdots & a_2^T b_p \\ \vdots & \vdots & \ddots & \vdots \\ a_m^T b_1 & a_m^T b_2 & \cdots & a_m^T b_p \end{bmatrix}$$

✓ "Columns-Rows"

$$C = AB = \begin{bmatrix} | & | & & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & & | \end{bmatrix} \begin{bmatrix} - & b_1^T & - \\ - & b_2^T & - \\ & \vdots & \\ - & b_n^T & - \end{bmatrix} = \sum_{i=1}^n a_i b_i^T$$

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- How to understand "Matrix-Matrix products"
  - ✓ "Matrix-Columns"

$$C = AB = A \begin{bmatrix} | & | & & | \\ b_1 & b_2 & \cdots & b_p \\ | & | & & | \end{bmatrix} = \begin{bmatrix} | & | & & | \\ Ab_1 & Ab_2 & \cdots & Ab_p \\ | & | & & | \end{bmatrix}$$

✓ "Rows-Matrix"

$$C = AB = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} B = \begin{bmatrix} - & a_1^T B & - \\ - & a_2^T B & - \\ & \vdots & \\ - & a_m^T B & - \end{bmatrix}$$

• Basic properties of matrix multiplication

- Associative: (AB)C = A(BC)
- Distributive: A(B+C) = AB + AC
- NOT Commutative:  $AB \neq BA$

Identity matrix

$$I_{ij} = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

Diagonal matrix

$$D_{ij} = \begin{cases} d_i & i = j \\ 0 & i \neq j \end{cases}$$

• Transpose  $(A^T)^T = A$   $(AB)^T = B^T A^T$   $(A+B)^T = A^T + B^T$ 

- Symmetric matrix  $A = A^T$
- Trace  $\operatorname{tr} A = \sum_{i=1}^{n} A_{ii}$

For  $A \in \mathbb{R}^{n \times n}$ ,  $\operatorname{tr} A = \operatorname{tr} A^T$ .

For  $A, B \in \mathbb{R}^{n \times n}$ ,  $\operatorname{tr}(A + B) = \operatorname{tr}A + \operatorname{tr}B$ .

For  $A \in \mathbb{R}^{n \times n}$ ,  $t \in \mathbb{R}$ , tr(tA) = t tr A.

For A, B such that AB is square, trAB = trBA.

For A, B, C such that ABC is square, trABC = trBCA = trCAB, and so on for the product of more matrices.

#### • Norm

- A realy value, e.g. 
$$||x||_2 = \sqrt{\sum_{i=1}^n x_i^2}$$

- 1. For all  $x \in \mathbb{R}^n$ ,  $f(x) \ge 0$  (non-negativity).
- 2. f(x) = 0 if and only if x = 0 (definiteness).
- 3. For all  $x \in \mathbb{R}^n$ ,  $t \in \mathbb{R}$ , f(tx) = |t|f(x) (homogeneity).
- 4. For all  $x, y \in \mathbb{R}^n$ ,  $f(x+y) \leq f(x) + f(y)$  (triangle inequality)

$$||x||_p = \left(\sum_{i=1}^n |x_i|^p\right)^{1/p}$$
  $||A||_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n A_{ij}^2} = \sqrt{\operatorname{tr}(A^T A)}$ 

• L-0 Norm  $||x||_0 = \sqrt[0]{\sum_i x_i^0} \implies ||x||_0 = \# \ of \ (i \mid x_i \neq 0)$ 

• L-1 Norm (Manhattan norm)

$$||x||_1 = \sum_{i=1}^n |x_i|$$

Sum of Absolute Difference (SAD)

$$SAD(x_1, x_2) = ||x_1 - x_2||_1 = \sum |x_1 - x_2|$$

Signal difference measurement - Mean-Absolute Error (MAE)

• L-2 Norm (Euclidean norm)

$$||x||_2 = \sqrt[2]{\sum_i x_i^2}$$

- Sum of Squared Difference (SSD) SSD  $(x_1, x_2) = ||x_1 - x_2||_2^2 = \sum_i (x_{1_i} - x_{2_i})^2$ 

- Mean-Squared Error (MSE)
- L-∞ Norm

$$||x||_{\infty} = \max_{i} |x_i|$$

- Linear dependent
  - If  $x_n = \sum_{i=1}^{n-1} a_i x_i$ , for some scalar values  $a_1$ ,  $a_2, ..., a_{n-1} \in \mathbb{R}$ , we say that  $x_1, ..., x_n$  are linearly dependent; otherwise, those vectors are linearly independent.
- Rank
  - Size of the largest subset of rows/columns that constitute a linearly independent set is row/column rank.

#### **♦** About Rank

- For  $A \in \mathbb{R}^{m \times n}$ , rank $(A) \leq \min(m, n)$ . If rank $(A) = \min(m, n)$ , then A is said to be **full rank**.
- For  $A \in \mathbb{R}^{m \times n}$ , rank $(A) = \text{rank}(A^T)$ .
- For  $A \in \mathbb{R}^{m \times n}$ ,  $B \in \mathbb{R}^{n \times p}$ ,  $\operatorname{rank}(AB) \leq \min(\operatorname{rank}(A), \operatorname{rank}(B))$ .
- For  $A, B \in \mathbb{R}^{m \times n}$ ,  $\operatorname{rank}(A + B) \leq \operatorname{rank}(A) + \operatorname{rank}(B)$ .

❖ Inverse: invertible or non-singular

$$A^{-1}A = I = AA^{-1}$$
  
 $(A^{-1})^{-1} = A$   
 $(AB)^{-1} = B^{-1}A^{-1}$   
 $(A^{-1})^T = (A^T)^{-1}$ .

### Orthogonal matrix

Two vectors  $x, y \in \mathbb{R}^n$  are **orthogonal** if  $x^T y = 0$ .

>U ∈  $\mathbb{R}^{n \times n}$  is orthogonal if all its columns are orthogonal to each other and normalized.

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & \sqrt{2} & -\sqrt{2} \\ -1 & 1 & 1 \end{bmatrix}$$

$$> U^T U = I = U U^T$$

$$||ux||_2 = ||x||_2$$

#### **♦** Determinant

$$A = \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix} \quad |A| = ?$$

#### > Properties of Determinants

- The determinant is a real number and can be negative
- The determinant only exists for square
- The inverse of a matrix will exist only if the determinant is not zero

#### The determinant of a matrix will be zero if

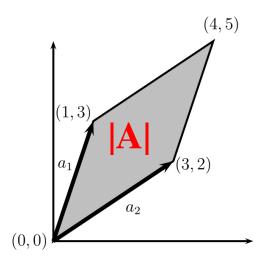
- An entire row is zero.
- Two rows or columns are equal.
- A row or column is a constant multiple of another row or column

### \*The determinant is the "size" of the output transformation

$$A = \begin{pmatrix} 1 & 3 \\ 3 & 2 \end{pmatrix} \frac{\mathbf{v1}}{\mathbf{v2}}$$

$$|A| = ?$$

$$S = \alpha v_1 + \beta v_2, \alpha \in [0,1], \beta \in [0,1]$$



• Quadratic form:  $A \in \mathbb{R}^{n \times n}$ ,  $x \in \mathbb{R}^n$ 

$$x^{T}Ax = \sum_{i=1}^{n} x_{i}(Ax)_{i} = \sum_{i=1}^{n} x_{i} \left(\sum_{j=1}^{n} A_{ij}x_{j}\right) = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij}x_{i}x_{j}$$

- Positive definite:  $A \in \mathbb{S}^n$ , for all non-zero vectors  $x \in \mathbb{R}^n$ ,  $x^T A x > 0$ .
- Positive semidefinite:  $A \in \mathbb{S}^n$ , for all non-zero vectors  $x \in \mathbb{R}^n$ ,  $x^T A x \ge 0$ .
- Negative definite:  $A \in \mathbb{S}^n$ , for all non-zero vectors  $x \in \mathbb{R}^n$ ,  $x^T A x < 0$ .
- Negative semidefinite:  $A \in \mathbb{S}^n$ , for all non-zero vectors  $x \in \mathbb{R}^n$ ,  $x^T A x \leq 0$ .
- One important property of positive definite and negative definite matrices is that they are always full rank, and hence, invertible.

- Gram matrix
  - Positive semidefinite  $G = A^T A$
- Eigenvectors and eigenvalues  $Ax = \lambda x$ ,  $x \neq 0$
- The trace of a A is equal to the sum of its eigenvalues,

$$tr A = \sum_{i=1}^{n} \lambda_i.$$

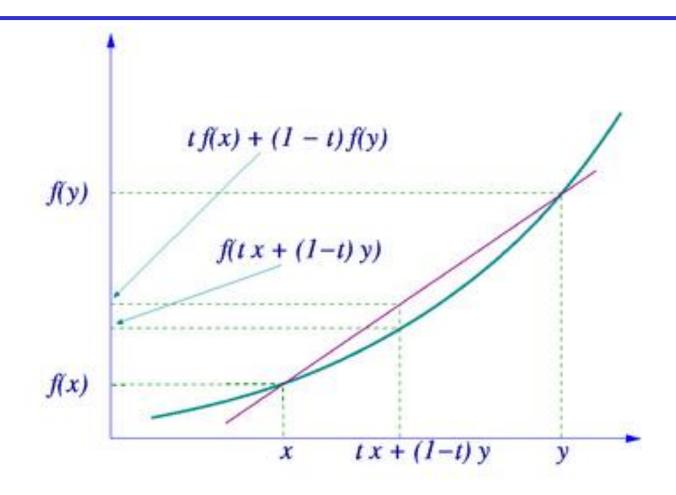
• The determinant of A is equal to the product of its eigenvalues,

$$|A| = \prod_{i=1}^{n} \lambda_i.$$

- The rank of A is equal to the number of non-zero eigenvalues of A.
- If A is non-singular then  $1/\lambda_i$  is an eigenvalue of  $A^{-1}$  with associated eigenvector  $x_i$ , i.e.,  $A^{-1}x_i = (1/\lambda_i)x_i$ .
- The eigenvalues of a diagonal matrix  $D = diag(d_1, \dots d_n)$  are just the diagonal entries  $d_1, \dots d_n$ . Fall 2019

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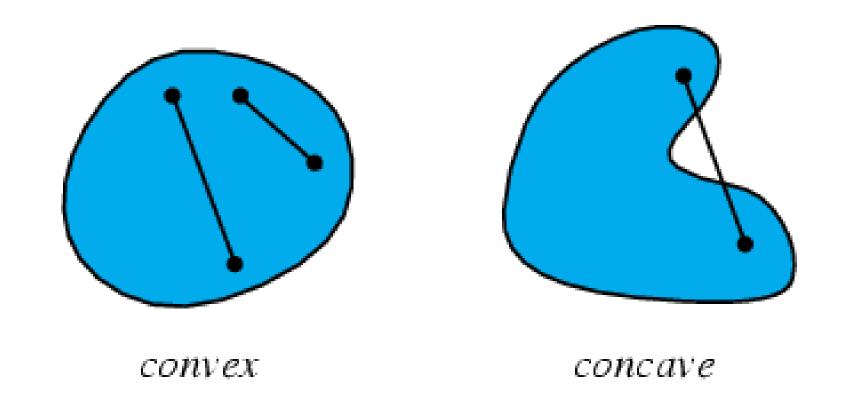
### Convex Function



$$f(t x + (1-t) y) \le t f(x) + (1-t) f(y)$$

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#### Convex Set



Region above a convex function is a convex set.

## Convex Programming

- Convex optimization function
- Convex feasible region
- Why is it so important???
  - Global optimum can be found in polynomial time.
  - Many practical problems are convex
    - Non-convex problems can be relaxed to convex ones.