
Machine Learning

CSE 6363 (Fall 2019)

Lecture 9 Logistic Regression

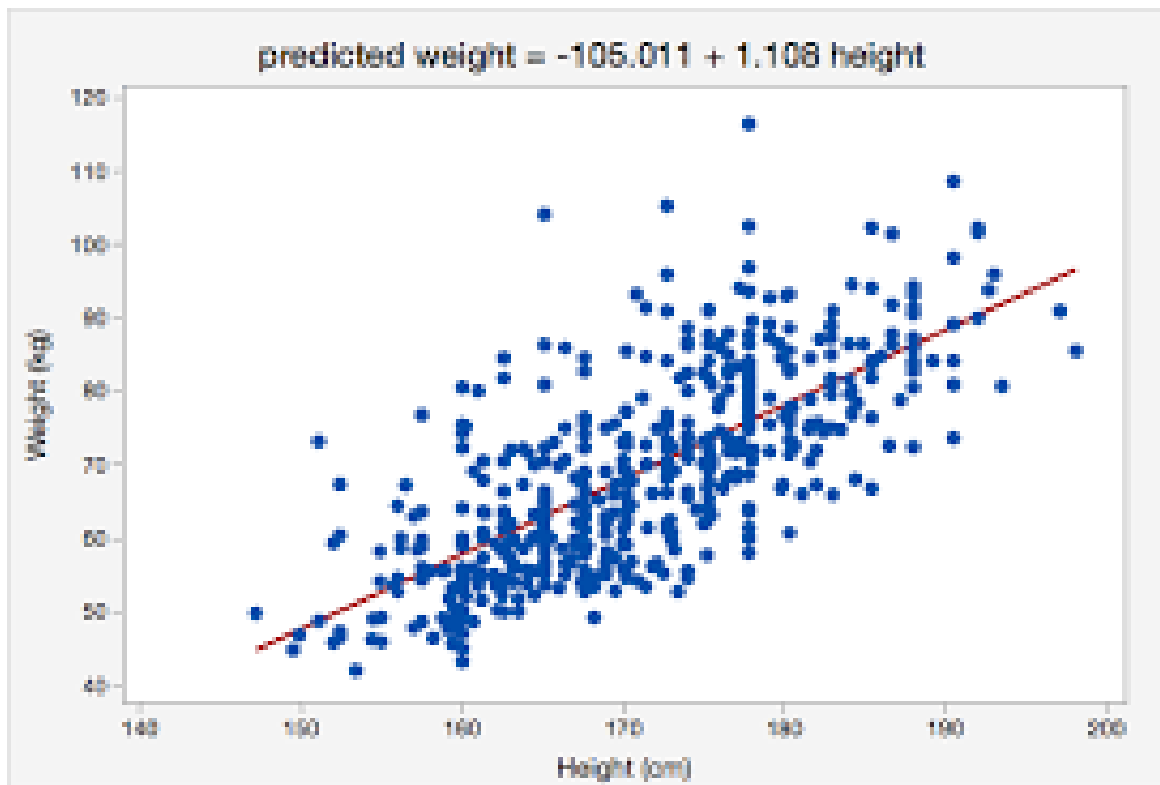
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*Slides of this course (CSE6363) courtesy: Dr. Heng Huang,
Dr. Aarti Singh*

Why Logistic Regression

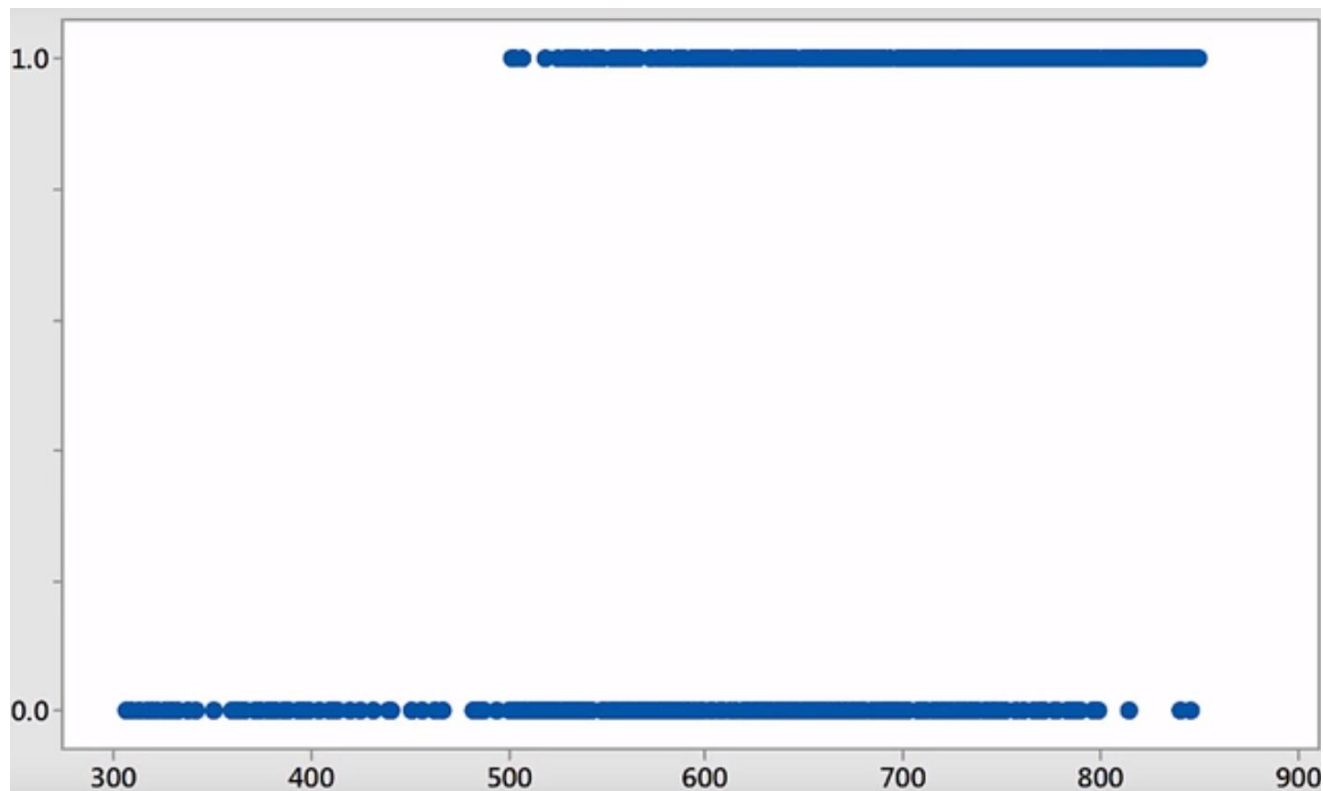
- Ordinary Regression



Why Logistic Regression

Get offer 😊

Go home 😞

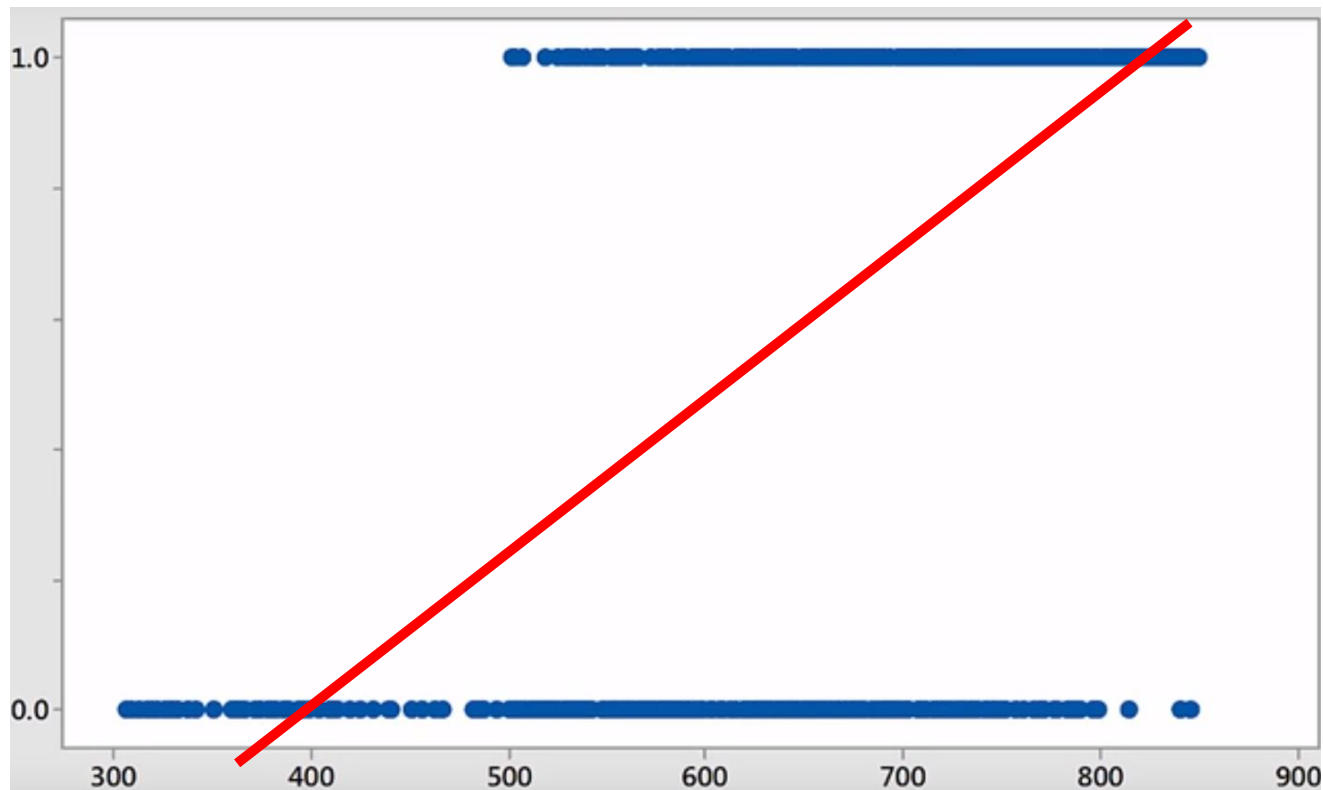


Review scores

Why Logistic Regression

Get offer 😊

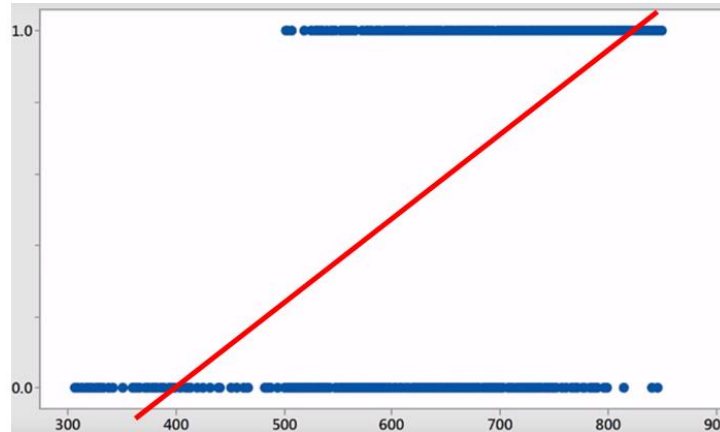
Go home 😞



Review scores

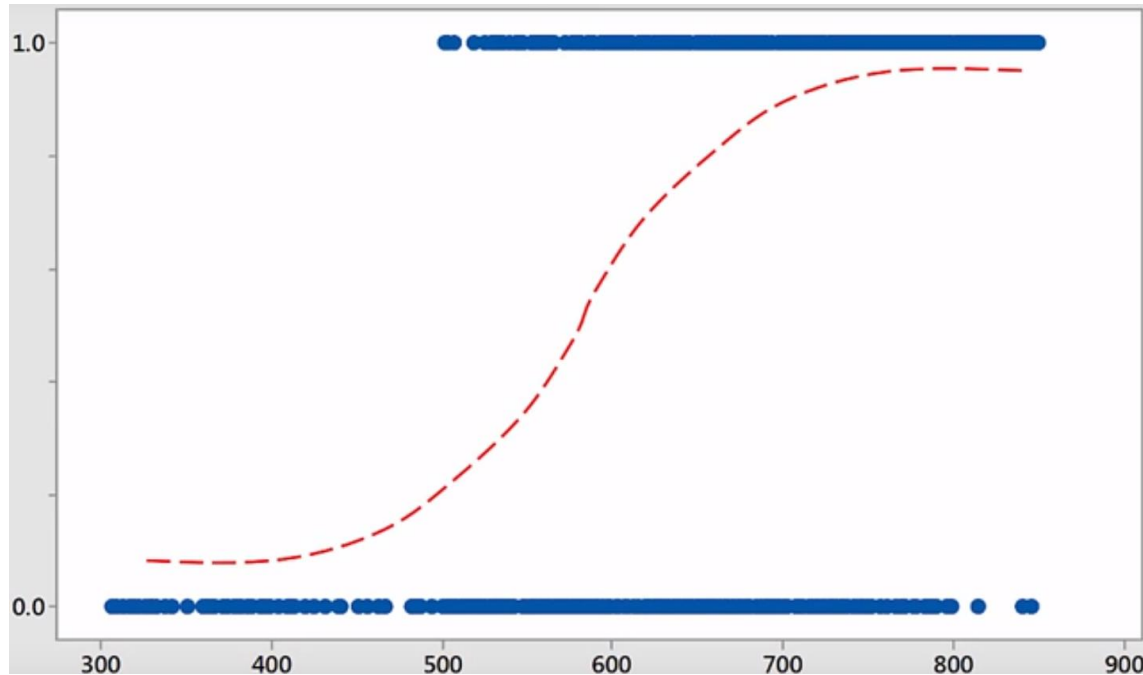
Sum squared error $\sum_i (X_i^\top w - y_i)^2$

Why Logistic Regression



- Error are NOT normally distributed (error has pattern!!!)
- Predicted Y should be 0 or 1. It should be better than Mean!

Why Logistic Regression



- Error are NOT normally distributed (error has pattern!!!) - **Solved**
- Predicted Y should be 0 or 1. It should be better than Mean! – **Solved**
- **Moreover, we are predicting Probability!**

Probability and Odds

$$P = \frac{\textit{Outcomes of Interest}}{\textit{All Possible Outcomes}}$$

Fair coin flip: P (heads)?

Fair die roll: P (1 or 2)?

Deck of playing cards: P (diamond card)?

Probability and Odds

$$\text{odds} = \frac{P(\text{occurring})}{P(\text{not occurring})}$$

Fair coin flip: odds (heads): 1

Fair die roll: P (1 or 2): 0.5

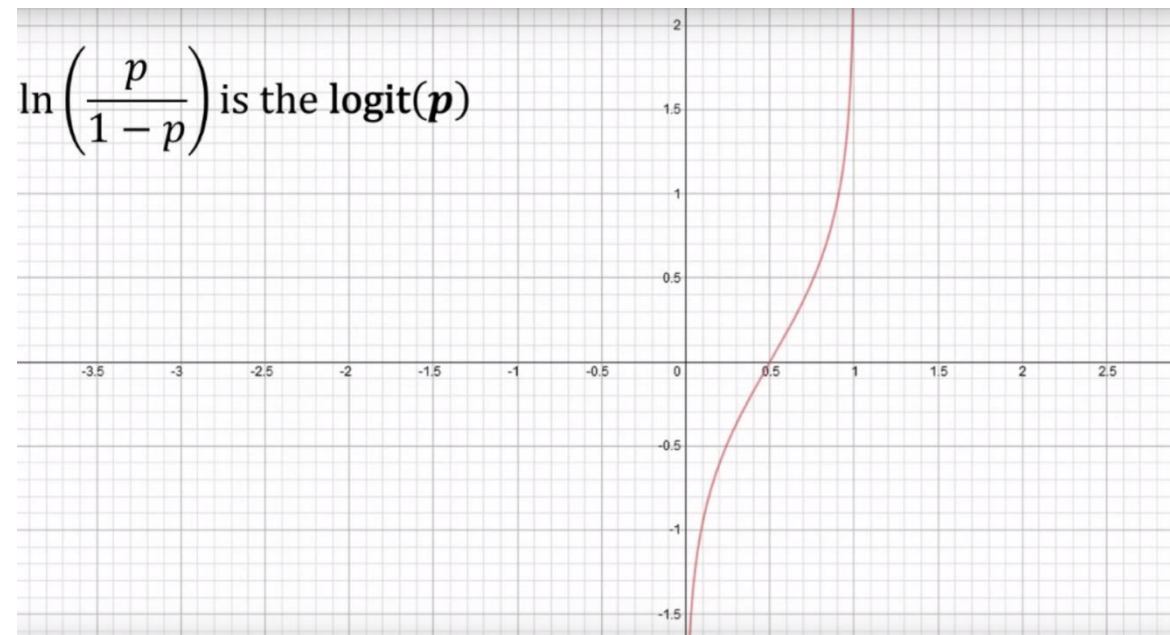
Deck of playing cards: P (diamond card): 1/3

What is the logit

- The goal of logistic regression is to estimate p for a linear combination of the independent variables.
- To tie together our linear combination of variables and in essence Binomial distribution, we need a function to link them together. That means we need a mapping function to map the linear combination of variables that could result in any value onto the Binomial probability distribution with a domain from 0 to 1.
- The natural log of the odds ratio – the logit- is the link function.

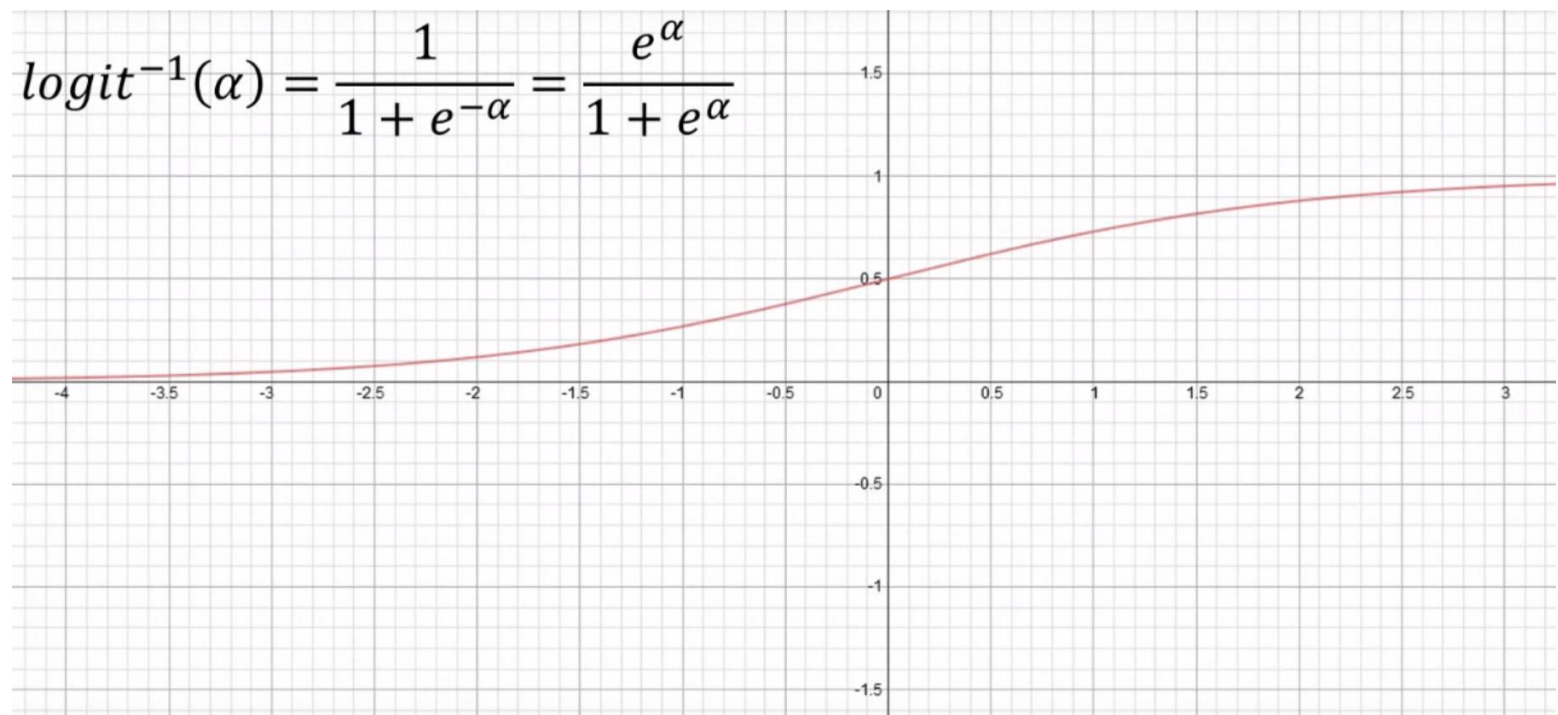
What is the logit

$$\text{logit}(p) = \ln\left(\frac{p}{1-p}\right)$$



Why Logistic Regression

$$\text{logit}(p) = \ln\left(\frac{p}{1-p}\right) = \beta x$$



Logistic Regression

Basic idea:

Regression \rightarrow Calculate p

Generative vs. Discriminative Classifiers

Generative classifiers (e.g. Naïve Bayes)

- Assume some functional form for $P(X, Y)$ (or $P(X|Y)$ and $P(Y)$)
- Estimate parameters of $P(X|Y)$, $P(Y)$ directly from training data
- Use Bayesrule to calculate $P(Y|X)$

Why not learn $P(Y|X)$ directly? Or better yet, why not learn the decision boundary directly?

Discriminative classifiers (e.g. Logistic Regression)

- Assume some functional form for $P(Y|X)$ or for the decision boundary
- Estimate parameters of $P(Y|X)$ directly from training data

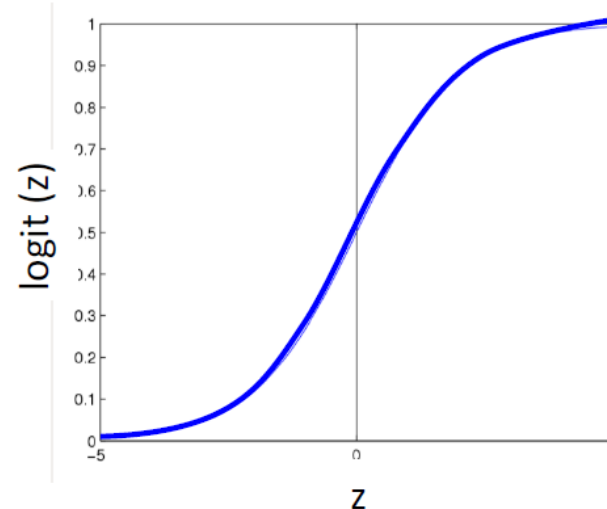
Logistic Regression

Assumes the following functional form for $P(Y|X)$:

$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Logistic function applied to a linear function of the data

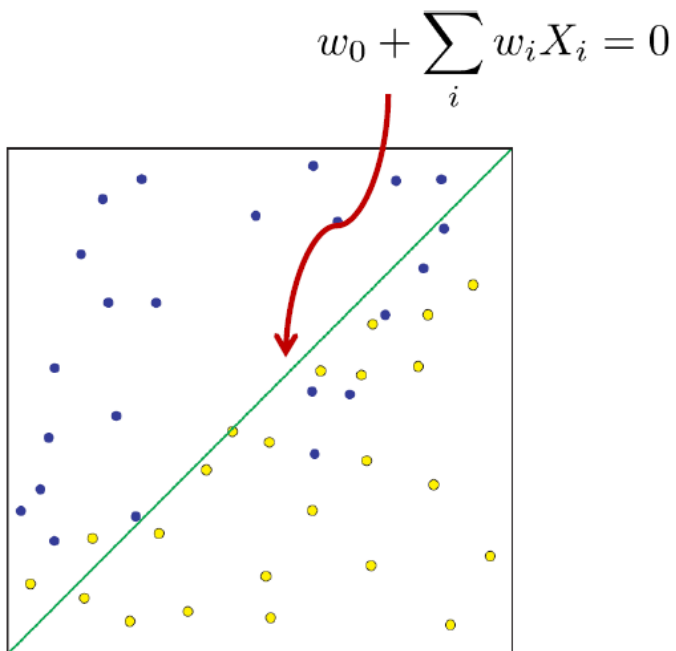
Logistic
function
(or Sigmoid): $\frac{1}{1 + \exp(-z)}$



Logistic Regression is a Linear Classifier

Assumes the following functional form for $P(Y|X)$:

$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$



$$w_0 + \sum_i w_i X_i \underset{1}{\overset{0}{\geq}} 0$$



$$P(Y = 0|X) \underset{1}{\overset{0}{\geq}} P(Y = 1|X)$$

Logistic Regression

Assumes the following functional form for $P(Y|X)$:

$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\Rightarrow P(Y = 0|X) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\Rightarrow \frac{P(Y = 0|X)}{P(Y = 1|X)} = \exp(w_0 + \sum_i w_i X_i) \quad \begin{matrix} 0 \\ \geq \\ 1 \end{matrix} \quad \mathbf{1}$$

$$\Rightarrow w_0 + \sum_i w_i X_i \quad \begin{matrix} 0 \\ \geq \\ 1 \end{matrix} \quad 0$$

Logistic Regression

We'll focus on binary classification
– 0 or 1 for Y

$$P(Y = 0|\mathbf{X}, \mathbf{w}) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$P(Y = 1|\mathbf{X}, \mathbf{w}) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Goal: Learn the parameters w_0, w_1, \dots, w_d **directly!**
-----But how?

Two Strategies

- Maximum Likelihood Estimation (MLE)
 - Maximizes the probability of observed data
- Maximum A Posteriori Estimation (MAP)
 - Maximizes a posterior probability

Maximum Likelihood Estimation

- **Data:** Observed set D of α_H Heads and α_T Tails
- **Hypothesis:** Binomial distribution
- Learning θ is an optimization problem
 - What's the objective function?
- MLE: Choose θ that maximizes the probability of observed data:

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} P(\mathcal{D} \mid \theta) \\ &= \arg \max_{\theta} \ln P(\mathcal{D} \mid \theta)\end{aligned}$$

Logistic Regression

Training Data $\{(X^{(j)}, Y^{(j)})\}_{j=1}^n$ $X^{(j)} = (X_1^{(j)}, \dots, X_d^{(j)})$

Maximum (**Conditional**) Likelihood Estimates

$$\hat{\mathbf{w}}_{MCLE} = \arg \max_{\mathbf{w}} \prod_{j=1}^n P(Y^{(j)} | X^{(j)}, \mathbf{w})$$

Discriminative method – Don't waste effort learning $P(X)$, focus on $P(Y|X)$ –that's all that matters for classification!

Logistic Regression

$$P(Y = 0|\mathbf{X}, \mathbf{w}) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$P(Y = 1|\mathbf{X}, \mathbf{w}) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\begin{aligned} l(\mathbf{w}) &\equiv \ln \prod_j P(y^j | \mathbf{x}^j, \mathbf{w}) \\ &= \sum_j \left[y^j (w_0 + \sum_i^d w_i x_i^j) - \ln(1 + \exp(w_0 + \sum_i^d w_i x_i^j)) \right] \end{aligned}$$

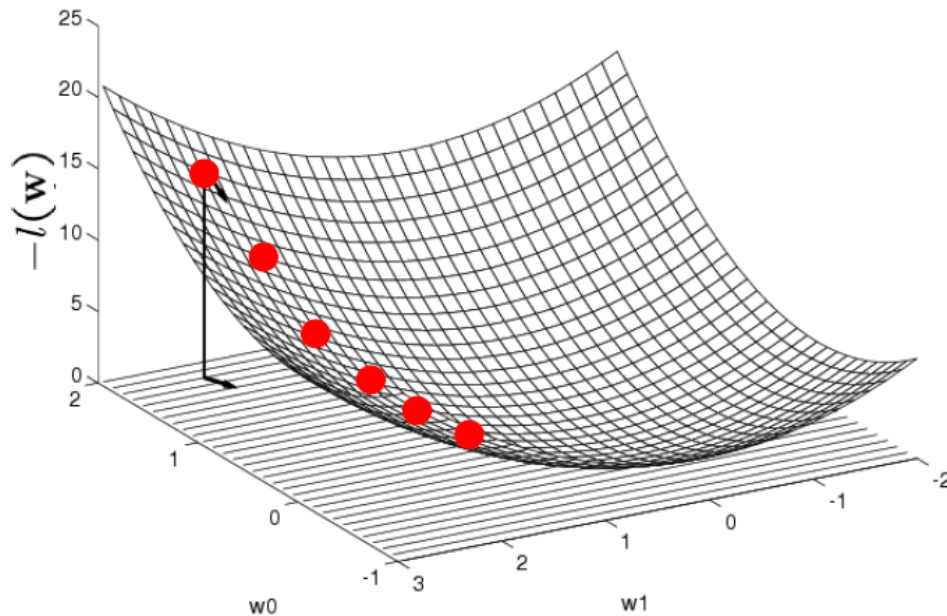
No closed-form solution to maximize $l(\mathbf{w})$

Logistic Regression

- Conditional likelihood for Logistic Regression is concave
- Maximum of a concave function = minimum of a convex function

Gradient Ascent (concave)/ Gradient Descent (convex)

Logistic Regression



Gradient:

$$\nabla_{\mathbf{w}} l(\mathbf{w}) = \left[\frac{\partial l(\mathbf{w})}{\partial w_0}, \dots, \frac{\partial l(\mathbf{w})}{\partial w_n} \right]'$$

Update rule:

Learning rate, $\eta > 0$

$$\Delta \mathbf{w} = \eta \nabla_{\mathbf{w}} l(\mathbf{w})$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left. \frac{\partial l(\mathbf{w})}{\partial w_i} \right|_t$$

Gradient Ascent for Logistic Regression

Gradient ascent algorithm:

iterate until change $< \epsilon$

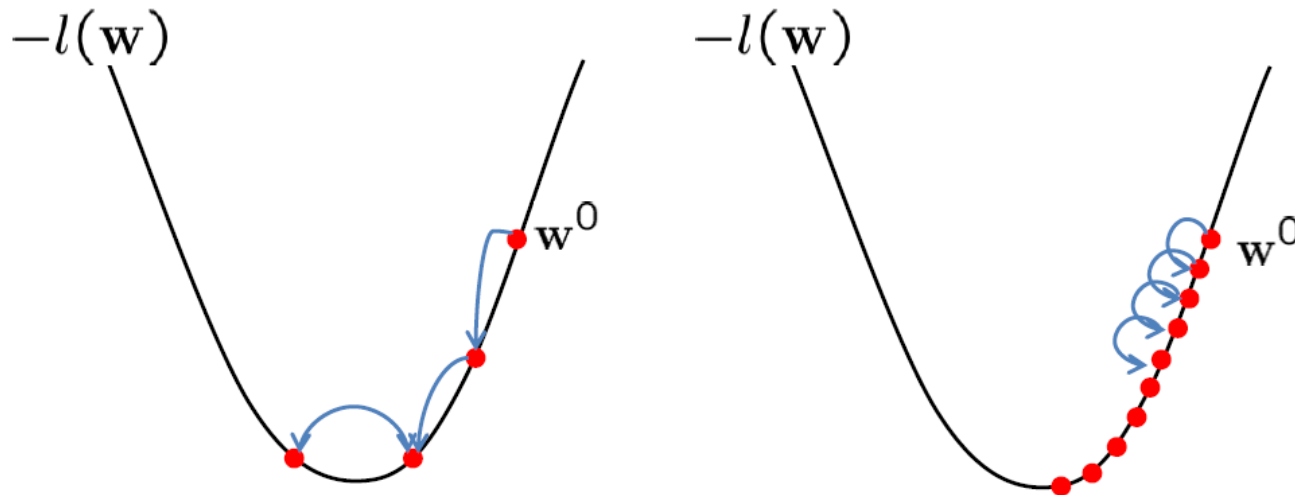
$$w_0^{(t+1)} \leftarrow w_0^{(t)} + \eta \sum_j [y^j - \hat{P}(Y^j = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})]$$

For $i=1, \dots, d$,

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})]$$

**Predict what current weight
thinks label Y should be**

Effect of step-size



Large $\eta \Rightarrow$ Fast convergence but larger residual error
Also possible oscillations

Small $\eta \Rightarrow$ Slow convergence but small residual error

Maximum A Posteriori (MAP) Estimation

- MAP estimation picks the mode of the posterior

$$\hat{\theta}_{MAP} = \arg \max_{\theta} p(D|\theta)p(\theta)$$

- If $\theta \sim Be(a, b)$, this is just

$$\hat{\theta}_{MAP} = (a - 1)/(a + b - 2)$$

- MAP is equivalent to maximizing the penalized maximum log-likelihood

$$\hat{\theta}_{MAP} = \arg \max_{\theta} \log p(D|\theta) - \lambda c(\theta)$$

where $c(\theta) = -\log p(\theta)$ is called a *regularization term*. λ is related to the strength of the prior.

How about MAP?

$$p(\mathbf{w} \mid Y, \mathbf{X}) \propto P(Y \mid \mathbf{X}, \mathbf{w})p(\mathbf{w})$$

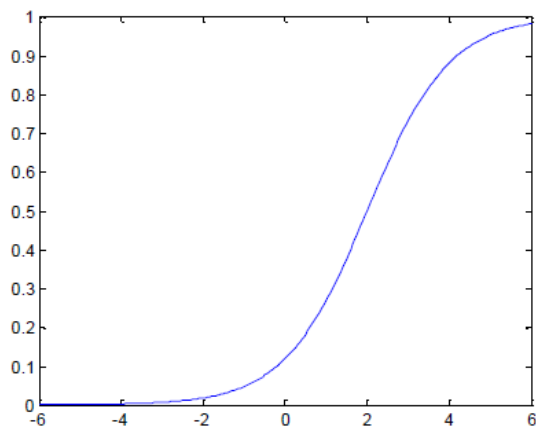
- One common approach is to define priors on \mathbf{w}
 - ✓ Normal distribution, zero mean, identity covariance
 - ✓ “Pushes” parameters towards zero
- Corresponds to *Regularization*
 - ✓ **Helps avoid very large weights and overfitting**
- M(C)AP estimate:

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[p(\mathbf{w}) \prod_{j=1}^n P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right]$$

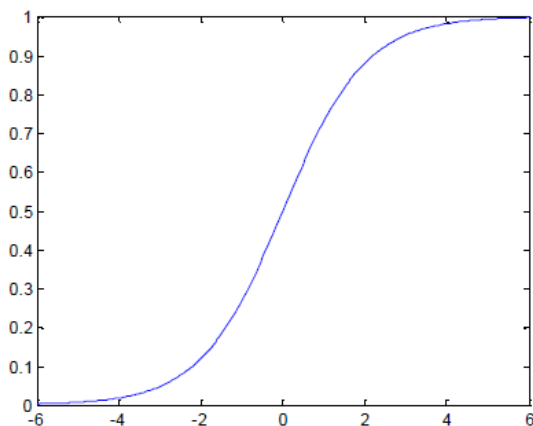
Understanding the sigmoid

$$g(w_0 + \sum_i w_i x_i) = \frac{1}{1 + e^{w_0 + \sum_i w_i x_i}}$$

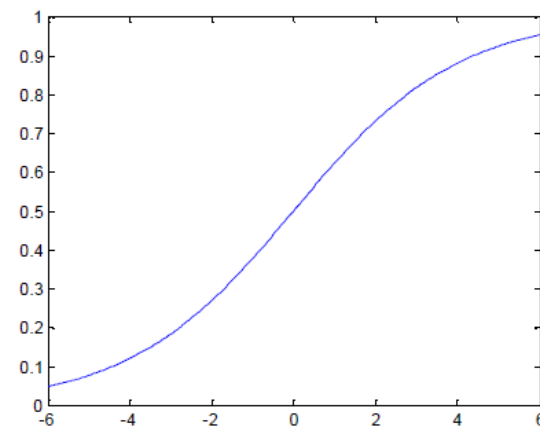
$$w_0 = -2, w_1 = -1$$



$$w_0 = 0, w_1 = -1$$



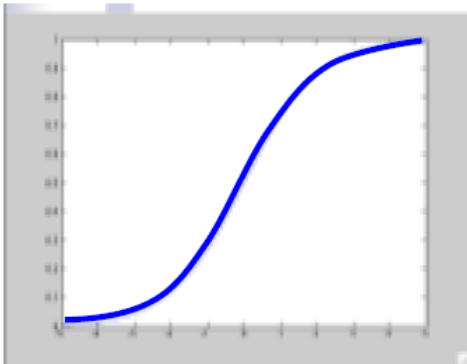
$$w_0 = 0, w_1 = -0.5$$



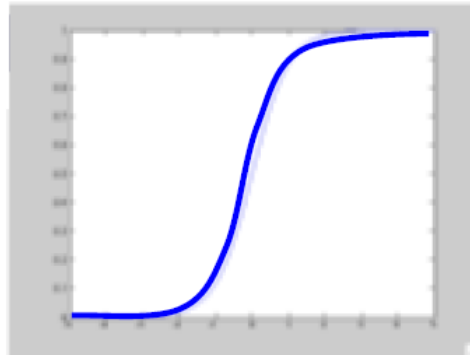
$$z = w_0 + \sum_i w_i x_i$$

Understanding the sigmoid

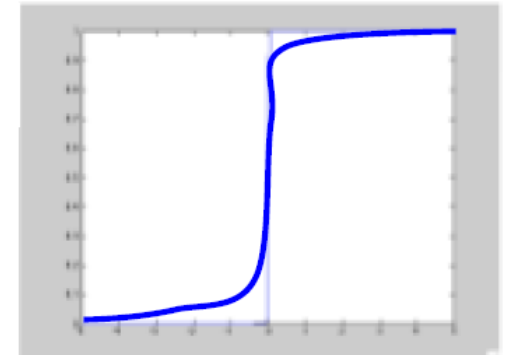
Large weights \rightarrow Overfitting



$$\frac{1}{1 + e^{-x}}$$



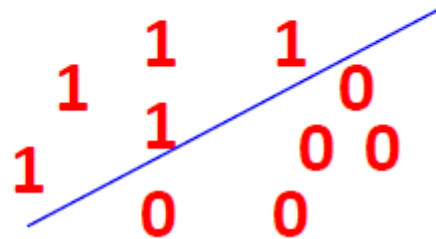
$$\frac{1}{1 + e^{-2x}}$$



$$\frac{1}{1 + e^{-100x}}$$

Understanding the sigmoid

- Large weights lead to overfitting:



- Penalizing high weights can prevent overfitting

M(C)AP –Regularization

$$\arg \max_{\mathbf{w}} \ln \left[p(\mathbf{w}) \prod_{j=1}^n P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right]$$

$$p(\mathbf{w}) = \prod_i \frac{1}{\kappa \sqrt{2\pi}} e^{\frac{-w_i^2}{2\kappa^2}}$$

Zero-mean Gaussian prior

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \sum_{j=1}^n \ln P(y^j \mid \mathbf{x}^j, \mathbf{w}) - \boxed{\sum_{i=1}^d \frac{w_i^2}{2\kappa^2}}$$

Will penalizes large weights

M(C)AP –Regularization

Calculate gradient

$$\frac{\partial}{\partial w_i} \ln \left[p(\mathbf{w}) \prod_{j=1}^n P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right]$$

$$\underbrace{\frac{\partial}{\partial w_i} \ln p(\mathbf{w})}_{\text{ }} + \underbrace{\frac{\partial}{\partial w_i} \ln \left[\prod_{j=1}^n P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right]}_{\text{Same as MCLE}}$$

$$\rightarrow \propto \frac{-w_i}{\kappa^2}$$

Extra term penalizes large weights

M(C)LE vs. M(C)AP

- Maximum conditional likelihood estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[\prod_{j=1}^n P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right]$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - P(Y = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})]$$

- Maximum conditional a posteriori estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[p(\mathbf{w}) \prod_{j=1}^n P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right]$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\frac{1}{\kappa^2} w_i^{(t)} + \sum_j x_i^j [y^j - P(Y = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})] \right\}$$

Generative vs Discriminative

Given **infinite data** (asymptotically),

- If conditional independence assumption holds, Discriminative and generative NB perform similar

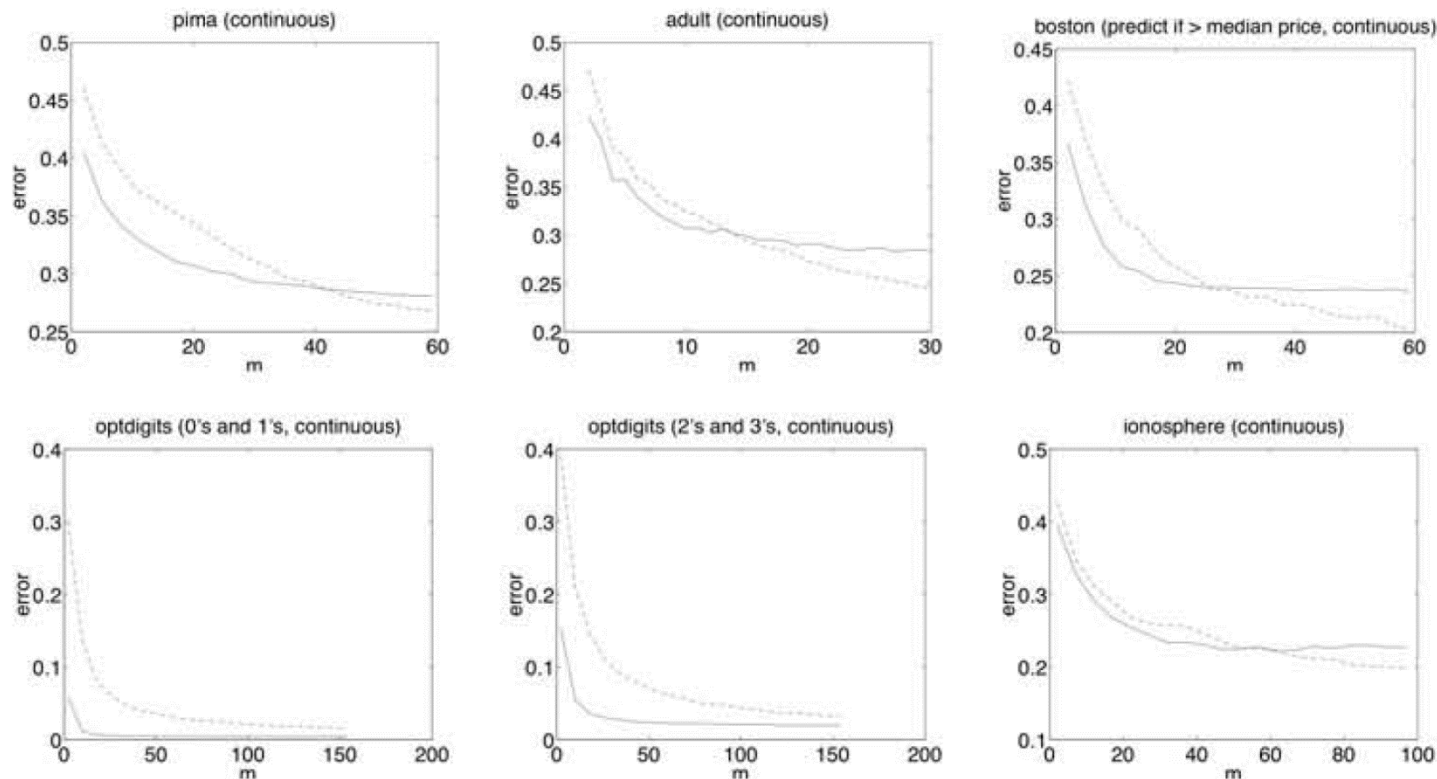
$$\epsilon_{\text{Dis},\infty} \sim \epsilon_{\text{Gen},\infty}$$

- If conditional independence assumption does NOT hold, Discriminative outperforms generative NB

$$\epsilon_{\text{Dis},\infty} < \epsilon_{\text{Gen},\infty}$$

[Ng & Jordan, NIPS 2001]

Naïve Bayes vs Logistic Regression



— Naïve Bayes

----- Logistic Regression

[Ng & Jordan, NIPS 2001]

Summary

- LR is a linear classifier
 - decision rule is a hyperplane
- LR optimized by conditional likelihood
 - no closed-form solution
 - concave !global optimum with gradient ascent
 - Maximum conditional a posteriori corresponds to regularization
- In general, NB and LR make different assumptions
 - NB: Features independent
 - LR: Functional form of $P(Y|X)$, no assumption on $P(X|Y)$
- Convergence rates
 - GNB (usually) needs less data
 - LR (usually) gets to better solutions in the limit