

Lecture 14

2.4. Coordinate Vectors

Proposition (Bases give coordinates)

Let $B = \{\vec{e}_1, \dots, \vec{e}_n\}$ be a list of vectors in a vector space V .

The following statements are equivalent:

1. B is a basis for V .
2. For every $\vec{v} \in V$, there exist unique scalars a_1, \dots, a_n such that

$$\vec{v} = a_1 \vec{e}_1 + \dots + a_n \vec{e}_n$$

Example Find the coordinate vector of

$$p = 2x^2 - 2x + 3$$

w.r.t. the basis

$$B = \left\{ \underbrace{1+x}_{p_1}, \underbrace{x^2+x-1}_{p_2}, \underbrace{x^2+x+1}_{p_3} \right\}$$

of Poly_2 .

Solution We compute

$$\begin{aligned} p = 2x^2 - 2x + 3 &= \boxed{-4}(1+x) \\ &+ \boxed{-5/2}(x^2+x-1) + \boxed{9/2}(x^2+x+1) \end{aligned}$$

$$\therefore [p]_B = \begin{bmatrix} -4 \\ -5/2 \\ 9/2 \end{bmatrix}$$

Proof (1) \Rightarrow (2)

Let $B = \{ \vec{e}_1, \dots, \vec{e}_n \}$ be a basis for V . Let $\vec{v} \in V$.

Since B spans V , there exist scalars a_1, \dots, a_n s.t.

$$\vec{v} = a_1 \vec{e}_1 + \dots + a_n \vec{e}_n \quad \dots (1)$$

To prove uniqueness, suppose that we also have

$$\vec{v} = b_1 \vec{e}_1 + \dots + b_n \vec{e}_n \quad \dots (2)$$

Subtracting (1) from (2):

$$\vec{0} = (b_1 - a_1) \vec{e}_1 + \dots + (b_n - a_n) \vec{e}_n$$

Since \mathcal{B} is lin. ind., we must have

$$(b_1 - a_1) = 0, \dots, (b_n - a_n) = 0$$

$$\therefore b_1 = a_1, \dots, b_n = a_n$$

So the scalars are unique.

(2) \Rightarrow (1) Suppose (2) is true.

We need to show that $\mathcal{B} = \{\vec{e}_1, \dots, \vec{e}_n\}$ is a basis for V .

Clearly \mathcal{B} spans V .

\mathcal{B} is linearly independent Suppose

$$k_1 \vec{e}_1 + \dots + k_n \vec{e}_n = \vec{0} \quad (*)$$

We know one soln to $(*)$,
namely

$$k_1 \vec{e}_1 + k_2 \vec{e}_2 + \dots + k_n \vec{e}_n = \vec{0}$$

By our assumption (2), this must
be the unique soln. In other words,
we must have

$$k_1 = 0, \dots, k_n = 0$$

$\therefore \mathcal{B} = \{\vec{e}_1, \dots, \vec{e}_n\}$ is lin. ind.

$\therefore \mathcal{B}$ a basis.



Definition We call a_1, \dots, a_n
the coordinates of \vec{v} w.r.t. the
basis B . The column vector

$$[\vec{v}]_B := \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$$

is called the coordinate vector of
 \vec{v} w.r.t. the basis B .

Example Find the coordinate vector of $\vec{v}, \vec{w} \in \mathbb{R}^2$ w.r.t. the basis \mathcal{B} (Example 2.4.4.)

$$\vec{v} = \boxed{2} \vec{b}_1 + \boxed{-1} \vec{b}_2$$

~~then~~

$$\therefore [\vec{v}]_{\mathcal{B}} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$\vec{w} = \boxed{-3} \vec{b}_1 + \boxed{+2} \vec{b}_2$$

$$\therefore [\vec{w}]_{\mathcal{B}} = \begin{bmatrix} -3 \\ 2 \end{bmatrix}$$

Example Find the coordinate vector of

$$f = \sin^2 x - \cos^3 x \in \text{Trig}_3$$

with respect to the standard basis

$$S = \{ 1, \cos x, \sin x, \cos^2 x, \sin^2 x, \cos^3 x, \sin^3 x \}$$

of Trig_3 .

Solution We have

$$\begin{aligned} f = & \boxed{\frac{1}{2}} 1 + \boxed{-\frac{3}{4}} \cos x + \boxed{0} \sin x \\ & + \boxed{-\frac{1}{2}} \cos^2 x + \boxed{0} \sin^2 x \\ & + \boxed{-\frac{1}{4}} \cos^3 x + \boxed{0} \sin^3 x \end{aligned}$$

Use:

$$\star \cos(A \pm B) = \cos A \cos B \pm \sin A \sin B$$

$$\sin(A \pm B) = \sin A \cos B \mp \cos A \sin B$$

$$\therefore [f]_S = \begin{bmatrix} \frac{1}{2} \\ -\frac{3}{4} \\ 0 \\ -\frac{1}{2} \\ 0 \\ -\frac{1}{4} \\ 0 \end{bmatrix}$$

