# Chisel: Finite State Machines



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Lecture 7

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#### Finite State Machines

Finite state machines (FSM) are constructed using three building blocks

- Next state logic
- State register
- Output logic

State machines can be of two types

- Mealy state machines
- Moore state machines



Finite State Machines

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# Mealy State Machines

- Output of Mealy state machine depends on both state and input
- Can update the output faster?
- Is it synchronous or asynchronous?

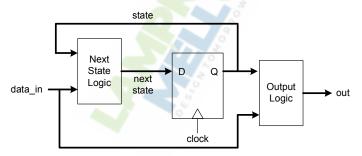


Figure: Mealy type state machine.



Finite State Machines

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### Moore State Machines

- Output of Moore state machine depends on state only
- Is it synchronous or asynchronous?

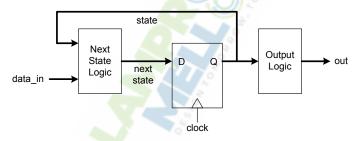


Figure: Moore type state machine.



#### State Machine Construct

State machines can be constructed using Enum and switch construct

```
// The set of states
val s0 :: s1 :: s2 :: s3 :: s4 :: Nil = Enum(5)
// The state register
val state = RegInit(s0)
// Next state logic
switch (state) {
     is (s0){
          // state transition logic for s0
          // corresponds to outgoing arrows from s0
     }
     is (s1) {
     is (s4) {
          // state transition logic for s4
```



## **Edge Detector**

```
import chisel3._
import chisel3.util._
class Edge_FSM extends Module {
   val io = IO(new Bundle{
        val sin = Input(Bool())
        val edge = Output(Bool())
   })
   // Detect the edge
   io.edge = !io.sin & RegNext(io.sin)
```



# Edge Detector Cont'd

```
import chisel3._
import chisel3.util._
class Edge_FSM extends Module {
     val io = IO(new Bundle {
          val sin = Input(Bool())
          val edge = Output(Bool())
     1)
     val zero :: one :: Nil = Enum(2) // The two states
     val state = RegInit(zero)
                                      // The state register
                                       // default value for output
     io.edge := false.B
     // Next state and output logic
     switch (state) {
          is(zero) {
                when (io.sin) {
                     state := one
          }
          is (one) {
                when (!io.sin) {
                     state := zero
                     io.edge := true.B
                }
```



### Up Down Counter

FSM Examples 00000000

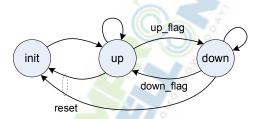


Figure: State transition diagram for up-down counter.

What type of state machine is this?



## Up Down Counter

```
// up-down counter implementation
package LM_Chisel
import chisel3.
import chisel3.util._
class CounterUpDown(n: Int) extends Module {
     val io = IO(new Bundle {
          val data_in = Input(UInt(n.W))
          val out = Output(Bool())
     })
     val counter = RegInit(0.U(n.W))
     val max_count = RegInit(6.U(n.W))
     val init :: up :: down :: Nil = Enum(3) // Enumeration type
     val state = RegInit(init)
                                                // state = init
     val up_flag = (counter === max_count)
     val down_flag = (counter === 0.U)
     switch (state) {
          is (init) {
                state := up
                                                     // on reset
          is (up) {
                when (up_flag) {
                     // start count down immediately on up_flag
                     counter := counter - 1.U
```



## Up Down Counter Cont'd

```
}.otherwise {
        counter := counter + 1.U
  is (down) {
      when (down_flag) {
        state := up
        counter := counter + 1.U
        max_count := io.data_in
                                  // load the counter
      }.otherwise {
        counter := counter - 1.U
  io.out := up_flag | down_flag
object CounterUpDown_generate extends App {
  chisel3.Driver.execute(args, () => new CounterUpDown(8))
```



### Up Down Counter Cont'd

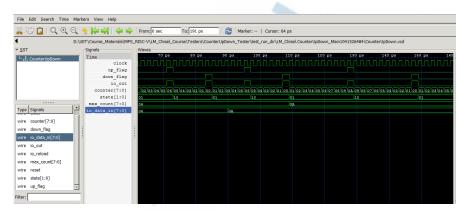


Figure: Up-down counter signal waveforms.



#### **UART Transmit**

```
import chisel3._
import chisel3 . stage . ChiselStage
import chisel3.util._
case class UART_Params(
    dataBits:
                 Int = 8,
    stopBits: Int = 2,
    divisorBits: Int = 5,
    oversample: Int = 2,
   nSamples: Int = 3,
   nTxEntries: Int = 4,
   nRxEntries: Int = 4) {
  def oversampleFactor = 1 << oversample</pre>
  require(divisorBits > oversample)
  require(oversampleFactor > nSamples)
```



#### UART Transmit Cont'd

```
class UART Tx(c: UART Params) extends Module {
  val io = IO(new Bundle {
             = Input(Bool())
   val en
   val in = Flipped(Decoupled(UInt((c.dataBits).W)))
   val out = Output(Bool())
   val div = Input(UInt((c.divisorBits).W))
   val nstop = Input(UInt((c.stopBits).W))
  })
  // pulses generated at baud rate using prescaler
  val prescaler = RegInit(0.U((c.divisorBits).W))
  val pulse = (prescaler === 0.U)
  private val n = c.dataBits + 1
  val counter = RegInit(0.U((log2Floor(n + c.stopBits)+1).W))
  val shifter = Reg(UInt(n.W))
             = RegInit(true.B)
  val out
```



```
val busy
             = (counter =/= 0.U)
 val state1 = io.en && !busy
 val state2 = busv
 io.in.ready := state1
 when(state1) {
    shifter := Cat(io.in.bits. false.B)
   counter := Mux1H(
      (0 until c.stopBits).map(i \Rightarrow (io.nstop === i.U) \rightarrow (n+i+2).U)
  }
  when(state2) {
    prescaler := Mux(pulse, (io.div - 1.U), prescaler - 1.U)
   when (pulse) {
      counter := counter - (1.U)
      shifter := Cat(true.B, shifter >> 1)
      out := shifter(0)
// Instantiation of the UART_Tx module for Verilog generator
object UART_Tx_generate extends App {
val param = UART Params()
  chisel3.Driver.execute(args. () => new UART Tx(param))
```



#### **Arbiter**

- A hardware module following data producer/consumer model
- Sequences n producers to 1 consumer
- Connects one of the producers, at a given time, to the consumer
- Connectivity follows a certain priority mechanism



### Chisel: Arbiter

```
val arb_priority = Module(new Arbiter(UInt(), 3))
// connect the inputs to different producers
arb_priority.io.in(0) <> producer0.io.out
arb_priority.io.in(1) <> producer1.io.out
arb_priority.io.in(2) <> producer2.io.out
// connect the output to consumer
consumer.io.in <> arb_priority.io.out
```

- An arbiter module with priority
- Lower indexed producer is given higher priority
- Uses DecoupledIO interface for input and output connectivity



```
val arb_noPriority = Module(new RRArbiter(UInt(), 3))
// connect the inputs to different producers
arb_noPriority.io.in(0) <> producer0.io.out
arb_noPriority.io.in(1) <> producer1.io.out
arb_noPriority.io.in(2) <> producer2.io.out
// connect the output to consumer
consumer.io.in <> arb_noPriority.io.out
```

- An arbiter module with no or equal priority
- Each producer gets its turn in a round robin fashion



### Reading List I

- Consult [chisel3, 2020] for further details
- Read Chapter 8 of [Schoeberl, 2019]



The Arbiter 0000

### References



chisel3 (2020).

Chisel3 library reference.

https://www.chisel-lang.org/api/latest/chisel3/util.



Schoeberl, M. (2019).

Digital Design with Chisel.

Kindle Direct Publishing.

