# Σήματα και Συστήματα 2019 – Εργαστήριο Εφαρμογή 3

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## Ερώτημα 1ο

%1 syms t w; x=exp(-t^2); fourier(x) pretty(ans)

#### Ερώτημα 2ο

%2 syms t w; X=1/(1+j\*w); ifourier(X,t) pretty(ans)

#### Ερώτημα 3ο

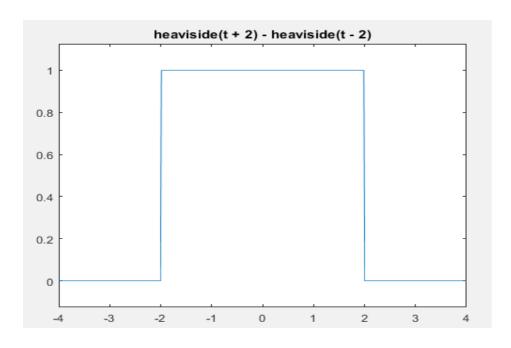
```
%3
syms w t;
x=1;
fourier(x,w)
pretty(ans)
```

```
>> %3
syms w t;
x=1;
fourier(x,w)
pretty(ans)
ans =

2*pi*dirac(w)
2 pi dirac(w)
```

#### Ερώτημα 4ο

```
%4 sinc
syms t w T;
x=heaviside(t+T/2)-heaviside(t-T/2);
xx=subs(x,T,4);
ezplot(xx,[-4,4])
```



#### X1=fourier(x,w) pretty(X1) simplify(X1)

```
>> Xl=fourier(x,w)
pretty(Xl)
simplify(Xl)

X1 =

(cos((T*w)/2)*li + sin((T*w)/2))/w - (cos((T*w)/2)*li - sin((T*w)/2))/w

/ T w \ / T w \ / T w \ / T w \
cos| --- | li + sin| --- | cos| --- | li - sin| --- |
\ 2 / \ 2 / \ 2 / \ 2 /

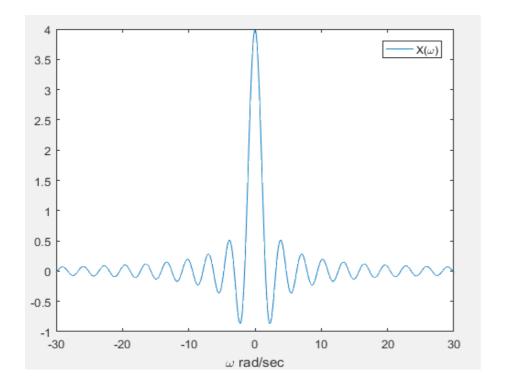
w

ans =

(2*sin((T*w)/2))/w

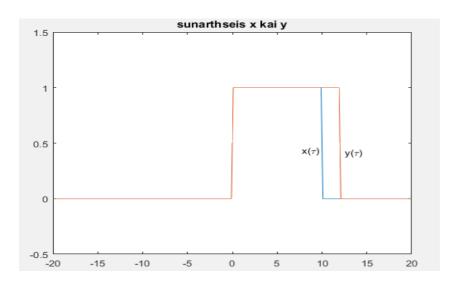
fx >> |
```

```
ww=[-30:0.1:-0.1 0.1:0.1:30];
X=subs(X1,w,ww);
X=subs(X,T,4);
plot(ww,X);
xlabel('\omega rad/sec');
legend('X(\omega)');
```



#### Ερώτημα 5ο

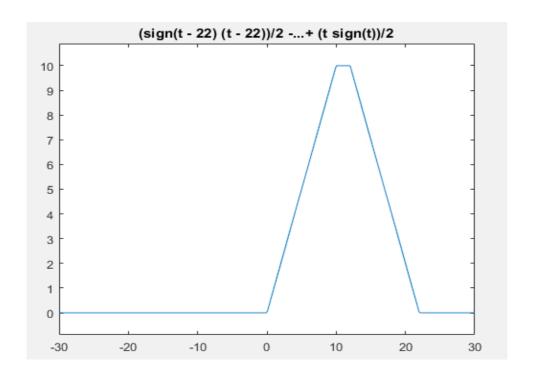
```
%5
t=-20:0.1:20;
x=heaviside(t)-heaviside(t-8-2);
y=heaviside(t)-heaviside(t-8-4);
plot(t,x,t,y)
axis([-20\ 20\ -0.5\ 1.5]);
title('sunarthseis x kai y');
gtext('x(\tau)');
gtext('y(\tau)');
```



```
syms t w T;
x=heaviside(t)-heaviside(t-8-2);
y=heaviside(t)-heaviside(t-8-4);
X=fourier(x,w)
pretty(X)
Y=fourier(y,w)
pretty(Y)
```

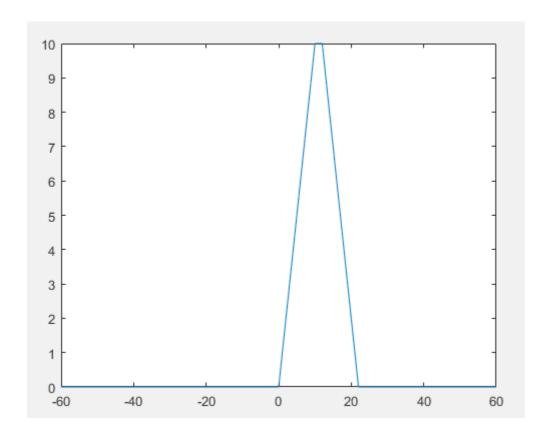
```
B=X*Y;
Z=ifourier(B,t);
pretty(Z)
```

# simplify(Z,'steps',20) ezplot(ans,[-30 30])



## Ερώτημα 6ο

```
%6
t=-30:0.01:30;
x=heaviside(t)-heaviside(t-8-2);
y=heaviside(t)-heaviside(t-8-4);
plot([-60:0.01:60],conv(x,y)*0.01)
```



Επομένως λαμβάνουμε ίδιο αποτέλεσμα με το ερώτημα 5.