

ENGINEERING MATHEMATICS (II) – MIDTERM Solutions

Winter 2023

PROBLEM 1

(a) If you type in the following MATLAB commands

$$A=[1\ 3\ 2; 4\ 6\ -7; 9\ 8\ 7];$$

$$B = A(:,3)$$

then what is shown on your screen?

Sol: The first command produces $\begin{bmatrix} 1 & 3 & 2 \\ 4 & 6 & -7 \\ 9 & 8 & 7 \end{bmatrix}$. After the second command, which shows the third column, we can get $\begin{bmatrix} 2 \\ -7 \\ 7 \end{bmatrix}$.

(b) a) continued. If you continue to type in the command $\mathbf{C} = A([2,3],[1,2])'$, then what is shown on your screen?

Sol: \mathbf{C} is the transpose of a submatrix of \mathbf{A} (2-3 rows and 1-2 columns), and thus we can see $\begin{bmatrix} 4 & 6 \\ 9 & 8 \end{bmatrix}' = \begin{bmatrix} 4 & 9 \\ 6 & 8 \end{bmatrix}$

(c) Suppose that $\mathbf{EA} = \mathbf{B}$, where \mathbf{E} is a 3×3 matrix,

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & -1 & 4 \\ 2 & 3 & 1 & 5 \end{bmatrix}, \quad \text{and} \quad \mathbf{B} = \begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & -1 & 4 \\ 4 & 6 & 2 & 10 \end{bmatrix}$$

then what is \mathbf{E}^{-1} ?

Sol: We can see that the difference between \mathbf{A} and \mathbf{B} is that the 3rd row of \mathbf{B} is two times that of \mathbf{A} , so \mathbf{E} is the 2nd type elementary matrix given by

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

Therefore,

$$\mathbf{E}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{2} \end{bmatrix}$$

(d) Suppose that $\mathbf{x}^T \mathbf{A} \mathbf{x} > 0 \ \forall \ \mathbf{x} \neq \mathbf{0}$, where \mathbf{A} is an $n \times n$ matrix and \mathbf{x} is an $n \times 1$ column vector, then is it true that all diagonal elements of \mathbf{A} are larger than zero? **Hint:** What is $\mathbf{x}^T \mathbf{A} \mathbf{x} > 0$ if $\mathbf{x} = \mathbf{e}_i$, where \mathbf{e}_i is an $n \times 1$ column vector whose i^{th} element is one and the remaining elements are zeros?

Sol: Note that $\mathbf{A}\mathbf{e}_i = \mathbf{a}_i$, i.e. the i^{th} column of \mathbf{A} . Thereby, $\mathbf{e}_i^T \mathbf{A}\mathbf{e}_i = [\mathbf{A}]_{i,i}$. Since $\mathbf{x}^T \mathbf{A}\mathbf{x} > 0$, for all \mathbf{x} , thus if we choose $\mathbf{x} = \mathbf{e}_i$, $i = 1, \dots, n$, we have $[\mathbf{A}]_{i,i} > 0$, $i = 1, \dots, n$, which implies that all diagonal elements of \mathbf{A} are larger than zero.

(e) Plot $\text{Span}\left(\begin{bmatrix} 0 \\ 0 \\ -0.5 \end{bmatrix}\right)$.

Sol: $\text{Span}\left(\begin{bmatrix} 0 \\ 0 \\ -0.5 \end{bmatrix}\right) = \alpha \begin{bmatrix} 0 \\ 0 \\ -0.5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -0.5\alpha \end{bmatrix} = \text{z-axis in } \mathcal{R}^3$.

(f) Suppose that $\mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is the only solution to $\mathbf{C}\mathbf{x} = \begin{bmatrix} 4 \\ 1 \\ -2 \\ 6 \\ 2 \end{bmatrix}$. Determine the number of linearly independent columns of \mathbf{C} .

Sol: We can first note that \mathbf{C} is a 5×3 matrix. Since $\mathbf{C}\mathbf{x}$, which is equal to the weighted summation of the columns of \mathbf{C} , has exactly one solution, all columns of \mathbf{C} are linearly independent, i.e. the number of linearly independents of \mathbf{C} is equal to 3. Or you can find that as now $\mathcal{N}(\mathbf{C}) = \mathbf{0}$, so $\dim(\mathcal{R}(\mathbf{C})) = n = 3$, which implies that all columns are linearly independent.

(g) (f) continued. Determine the reduced row echelon form of \mathbf{C} .

Sol: From (f), $\text{rank}(\mathbf{C}) = 3 = \dim(\text{col}(\mathbf{C}))$ (three nonzero pivots in the (reduced) row echelon form), so the reduced row echelon form of \mathbf{C} is given by

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

(h) Assume that $\text{rank}(\mathbf{A}) = r$, then determine the rank of the following matrices:

$$2\mathbf{A}^T, \begin{bmatrix} \mathbf{A} & \mathbf{A} \end{bmatrix}, \begin{bmatrix} \mathbf{A} \\ \mathbf{A} \end{bmatrix}, \begin{bmatrix} \mathbf{A} & \mathbf{0} \\ \mathbf{0} & \mathbf{A} \end{bmatrix}$$

Sol: Note that $\text{rank}(\mathbf{A})$ is equal to the number of linearly independent columns (rows) of \mathbf{A} . Also, with extra zeros, the linearly independent rows/columns will double in the last matrix. Therefore,

$$\text{rank}(2\mathbf{A}^T) = r, \text{rank}\left(\begin{bmatrix} \mathbf{A} & \mathbf{A} \end{bmatrix}\right) = r, \text{rank}\left(\begin{bmatrix} \mathbf{A} \\ \mathbf{A} \end{bmatrix}\right) = r, \text{rank}\left(\begin{bmatrix} \mathbf{A} & \mathbf{0} \\ \mathbf{0} & \mathbf{A} \end{bmatrix}\right) = 2r$$

PROBLEM 2

Consider the following system of linear equations

$$\begin{aligned}x + 4y - z &= 1 \\2x + 6y + \gamma z &= \beta \\x + 6y - 5z &= 5\end{aligned}$$

Determine the values of γ and β such that the above system of linear equations has no solution, one solution, and infinitely many solutions. Also, **determine the corresponding solution set.**

Sol: To solve it, form the augmented matrix first and then reduce it to the row echelon form

$$\left[\begin{array}{ccc|c} 1 & 4 & -1 & 1 \\ 2 & 6 & \gamma & \beta \\ 1 & 6 & -5 & 5 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 4 & -1 & 1 \\ 0 & -2 & \gamma + 2 & \beta - 2 \\ 0 & 2 & -4 & 4 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 4 & -1 & 1 \\ 0 & 2 & -4 & 4 \\ 0 & -2 & \gamma + 2 & \beta - 2 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 4 & -1 & 1 \\ 0 & 2 & -4 & 4 \\ 0 & 0 & \gamma - 2 & \beta + 2 \end{array} \right].$$

Therefore, the solution sets can be divided into the following three cases:

- If $\gamma = 2$ and $\beta \neq -2$, then there is no solution.
- If $\gamma = 2$ and $\beta = -2$, then there is infinitely many solutions. Now the problem becomes

$$\begin{aligned}x + 4y - z &= 1 \\2y - 4z &= 4\end{aligned}$$

Setting the free variable $z = \alpha$, we can obtain the solution

$$\left\{ (-7 - 7\alpha, 2 + 2\alpha, \alpha) \mid \alpha \text{ is any arbitrary real numbers} \right\}$$

- If $\gamma \neq 2$, then there is exactly one solution. The problem now becomes

$$\begin{aligned}x + 4y - z &= 1 \\2y - 4z &= 4 \\(\gamma - 2)z &= \beta + 2\end{aligned}$$

Solving the above, we can obtain the solution

$$\left\{ \left(-7 - 7\frac{\beta + 2}{\gamma - 2}, 2 + 2\frac{\beta + 2}{\gamma - 2}, \frac{\beta + 2}{\gamma - 2} \right) \right\}$$

PROBLEM 3

Suppose that

$$\text{adj}(\mathbf{A}^{-1}) = \begin{bmatrix} -1 & -3 & -5 \\ 2 & 6 & 1 \\ 3 & 8 & 3 \end{bmatrix}$$

Also, $\det(\mathbf{A}) > 0$.

(a) Determine $\det(3\mathbf{A}^2\mathbf{A}^T)$. **Hint:** The fact $\mathbf{A}(\text{adj } \mathbf{A}) = \det(\mathbf{A})\mathbf{I}$ is of help.

Sol: Conducting the cofactor expansion along the first row of $\text{adj}(\mathbf{A}^{-1})$ yields

$$\det(\text{adj}(\mathbf{A})^{-1}) = (-1) \times (6 \times 3 - 1 \times 8) - (-3) \times (2 \times 3 - 1 \times 3) + (-5) \times (2 \times 3 - 1 \times 3) = 9$$

Also, taking the determinant on both sides of $\mathbf{A}(\text{adj } \mathbf{A}) = \det(\mathbf{A})\mathbf{I}$ yields $\det(\text{adj}(\mathbf{A})) = \det(\mathbf{A})^{n-1}$ (already shown this in HW 2). It follows that $\det(\text{adj}(\mathbf{A})^{-1}) = \frac{1}{\det(\mathbf{A})^{n-1}}$. Therefore, we have $\det(\mathbf{A}) = \frac{1}{3}$ as now $n = 2$. Consequently, we have

$$\det(3\mathbf{A}^2\mathbf{A}^T) = 3^3(\det(\mathbf{A}))^2\det(\mathbf{A}^T) = 27 \times \left(\frac{1}{3}\right)^3 \times \frac{1}{3} = 1$$

where we have used the fact that $\det(\mathbf{A}^T) = \det(\mathbf{A}) = \frac{1}{3}$.

(b) What is \mathbf{A} ?

Sol: Replacing \mathbf{A} with \mathbf{A}^{-1} in $\mathbf{A}(\text{adj } \mathbf{A}) = \det(\mathbf{A})\mathbf{I}$ yields $\mathbf{A}^{-1}(\text{adj } \mathbf{A}^{-1}) = \det(\mathbf{A}^{-1})\mathbf{I}$. It follows that

$$\mathbf{A} = \frac{1}{\det(\mathbf{A}^{-1})}(\text{adj } \mathbf{A}^{-1}) = \det(\mathbf{A})(\text{adj } \mathbf{A}^{-1}) = \frac{1}{3} \begin{bmatrix} -1 & -3 & -5 \\ 2 & 6 & 1 \\ 3 & 8 & 3 \end{bmatrix}$$

PROBLEM 4

$$\mathbf{V} = \left\{ \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \end{bmatrix}, a_{i+2} = a_i + a_{i+1}, i = 1, 2, 3 \right\} \quad \text{and} \quad \mathbf{W} = \left\{ \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \end{bmatrix}, a_1 + a_2 = 0, a_3 + a_4 = 0 \right\}$$

(a) Find $\dim(\mathbf{V})$.

Sol: Based on the rule $a_{i+2} = a_i + a_{i+1}$, we have $a_3 = a_1 + a_2$, $a_4 = a_2 + a_3 = a_2 + a_1 + a_2 = a_1 + 2a_2$, and $a_5 = a_3 + a_4 = (a_1 + a_2) + (a_1 + 2a_2) = 2a_1 + 3a_2$. Thereby, a typical element of \mathbf{V} is given by

$$\begin{bmatrix} a_1 \\ a_2 \\ a_1 + a_2 \\ a_1 + 2a_2 \\ 2a_1 + 3a_2 \end{bmatrix} = a_1 \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \\ 2 \end{bmatrix} + a_2 \begin{bmatrix} 0 \\ 1 \\ 1 \\ 2 \\ 3 \end{bmatrix}.$$

It is easy to verify that these two spanning vectors $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 2 \\ 3 \end{bmatrix} \right\}$ are linearly independent

and thus is a basis, so $\dim(\mathbf{V}) = 2$.

(b) Find $\dim(V \cap W)$.

Sol: Note that based on its definition, $a_1 + a_2 = 0$, $(a_1 + 2a_2) + (2a_1 + 3a_2) = 3a_1 + 5a_2 = 0$.

It follows that $a_1 = 0$ and $a_2 = 0$. Therefore, a typical element of W is given by $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$. So

$$\dim(V \cap W) = 0.$$

PROBLEM 5 (10 pts)

Assume that $\mathbf{v} = \begin{bmatrix} -1 \\ 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$ and \mathbf{I} is a 5×5 identity matrix, then determine $(\mathbf{I} + \mathbf{v}\mathbf{v}^T)^{-1}\mathbf{v}$.

Hint: You can assume that $(\mathbf{I} + \mathbf{v}\mathbf{v}^T)^{-1} = \mathbf{I} + k\mathbf{v}\mathbf{v}^T$ and find k first.

Sol: It can be readily shown that $\mathbf{v}^T\mathbf{v} = 5$. Assume that $(\mathbf{I} + \mathbf{v}\mathbf{v}^T)^{-1} = \mathbf{I} + k\mathbf{v}\mathbf{v}^T$, then it follows that

$$\mathbf{I} = (\mathbf{I} + \mathbf{v}\mathbf{v}^T)(\mathbf{I} + k\mathbf{v}\mathbf{v}^T) = \mathbf{I} + \mathbf{v}\mathbf{v}^T + k\mathbf{v}\mathbf{v}^T + k\mathbf{v}\overbrace{\mathbf{v}^T\mathbf{v}}^{=5}\mathbf{v}^T = \mathbf{I} + (1 + k + 5k)\mathbf{v}\mathbf{v}^T$$

which leads to $k = -\frac{1}{6}$. Consequently,

$$(\mathbf{I} + \mathbf{v}\mathbf{v}^T)^{-1}\mathbf{v} = (\mathbf{I} - \frac{1}{6}\mathbf{v}\mathbf{v}^T)\mathbf{v} = \mathbf{v} - \frac{1}{6}\mathbf{v}\overbrace{\mathbf{v}^T\mathbf{v}}^{=5} = \frac{1}{6}\mathbf{v} = \frac{1}{6} \begin{bmatrix} -1 \\ 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$