

### HW7.1 (20 points)

Calculate the **close-loop input and output resistance** ( $R_{in,CL}$  and  $R_{out,CL}$ ) using small-signal parameters and assuming that  $\gamma = 0$ .

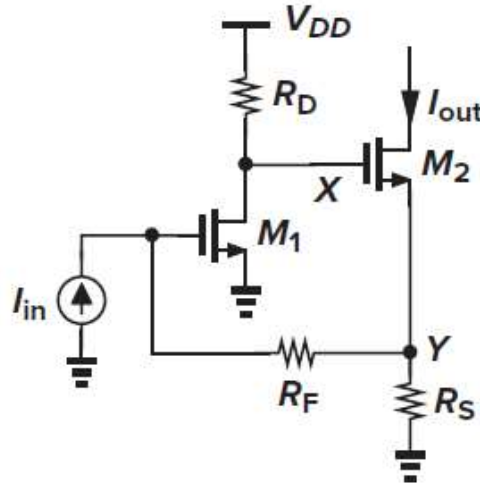


Fig. 7.1

### HW7.2 (20 points)

As shown in Fig. 7.2(a), please prove that the loop gain,  $I_F/I_t$  (shown in Fig. 7.2(c)), is the same as that using  $V_F/V_t$  (shown in Fig. 7.2(b)).

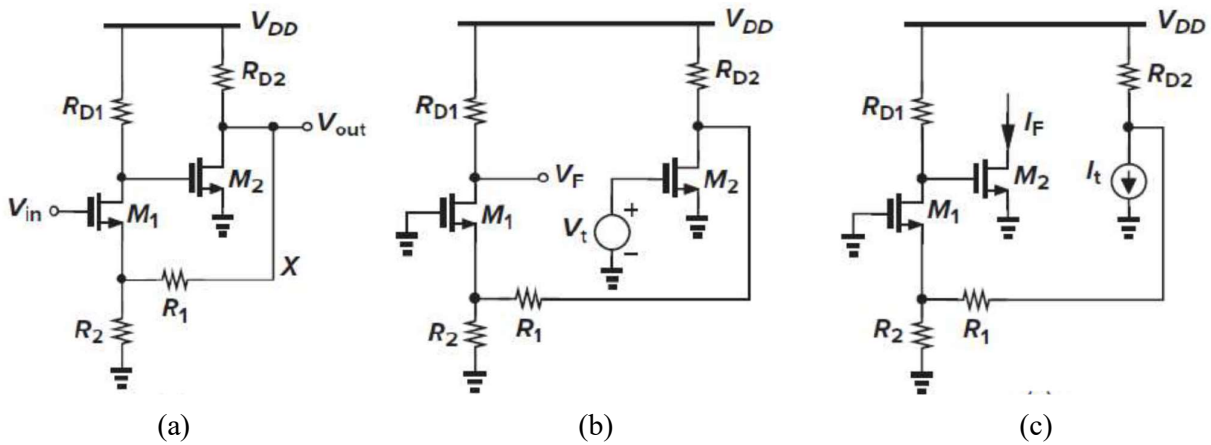


Fig. 7.2

### HW7.3 (40 points)

Using feedback techniques, calculate the input and output impedance and voltage gain of each circuit in Fig. 7.3. Using small-signal parameters to represent your solutions.

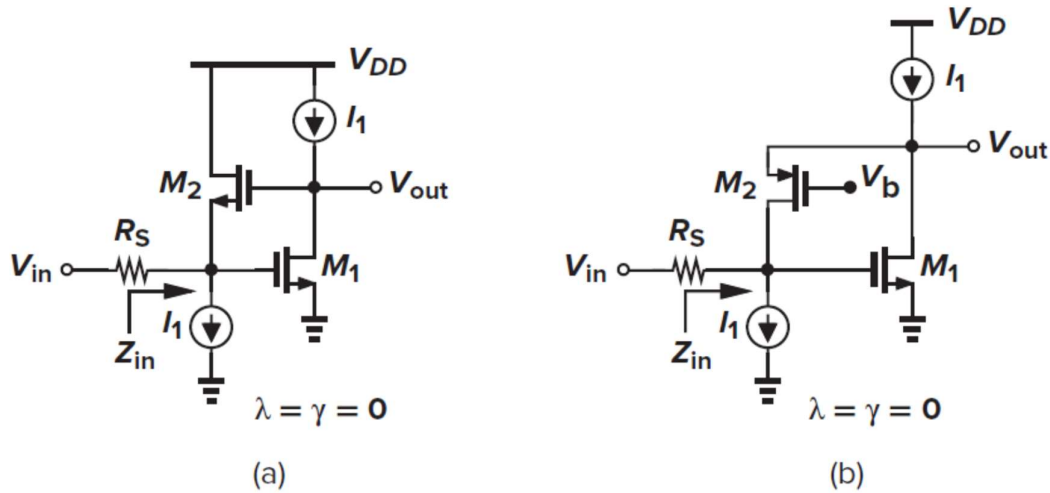


Fig. 7.3

### HW7.4 (20 points)

In the circuit of Fig. 7.4, assuming that  $\lambda = \gamma = 0$ , calculate the closed-loop gain and output impedance. Using small-signal parameters to represent your solutions.

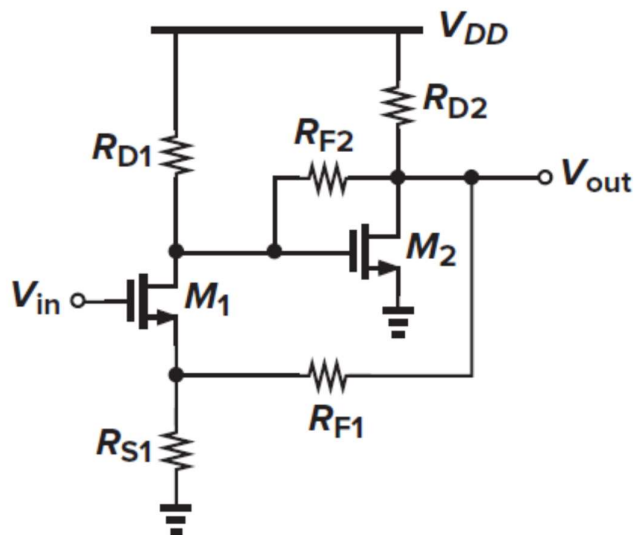


Fig. 7.4

# HW 7.1

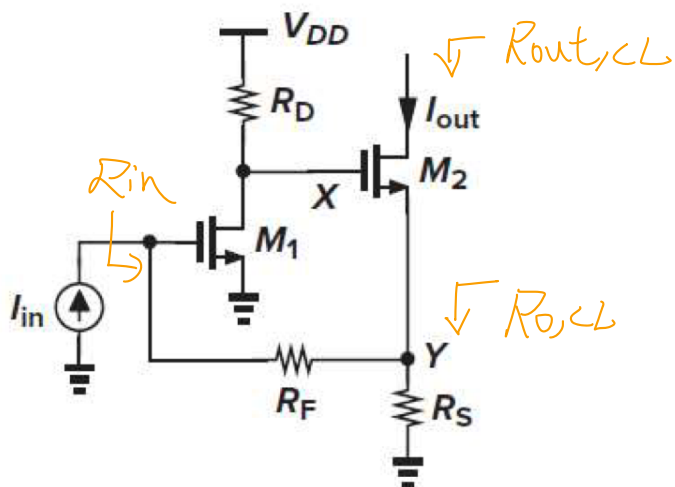
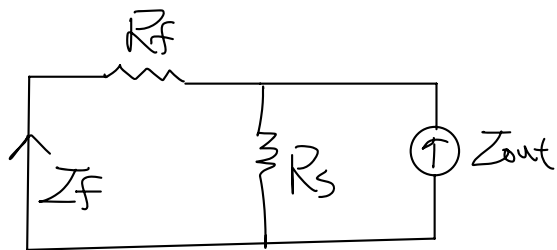


Fig. 7.1

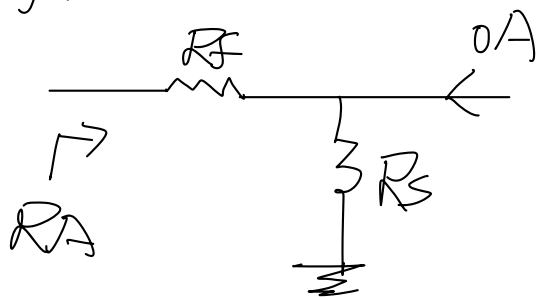
$Z-Z$  feedback

Find  $\beta_z$



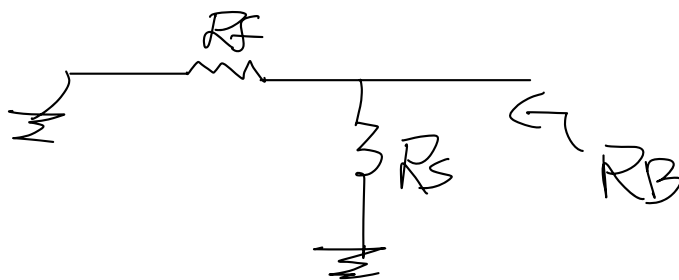
$$\beta_z = \frac{Z_F}{Z_{out}} = \frac{-R_S}{R_F + R_S}$$

Find  $R_A$



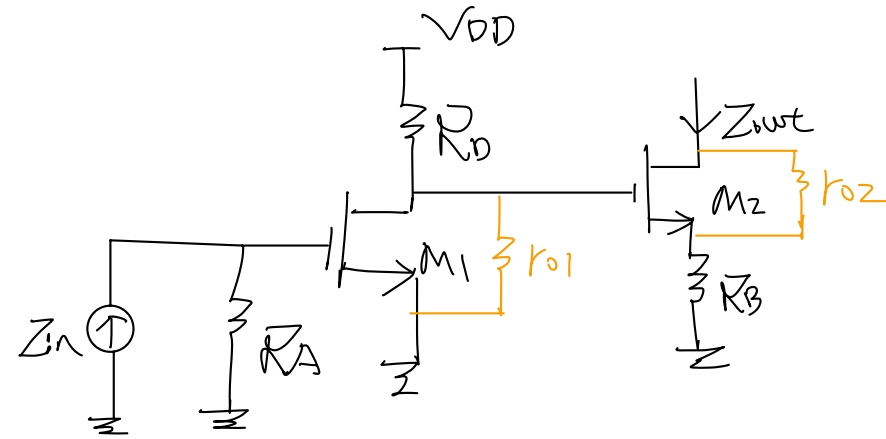
$$R_A = R_F + R_S$$

Find  $R_B$



$$R_B = R_S \parallel R_F$$

Find open loop gain  $A_{\bar{z}, OL}$



$$Z_{out} = Z_{in} R_A \times -g_{m1} (R_D \parallel r_{o1}) \times \frac{g_{m2} r_{o2}}{r_{o2} + (1 + g_{m2} r_{o2}) R_B}$$

$$A_{\bar{z}, OL} = -g_{m1} g_{m2} \frac{R_A (R_D \parallel r_{o1}) r_{o2}}{r_{o2} + (1 + g_{m2} r_{o2}) R_B}$$

$$R_{in, CL} = \frac{R_A}{1 + \beta_{\bar{z}} A_{\bar{z}, OL}} \#$$

$$R_{o, CL} = R_B (1 + \beta_{\bar{z}} A_{\bar{z}, OL})$$

$$R_{out, CL} = (1 + g_{m2} r_{o2}) R_{o, CL} + r_{o2} \#$$

# HW 7.2

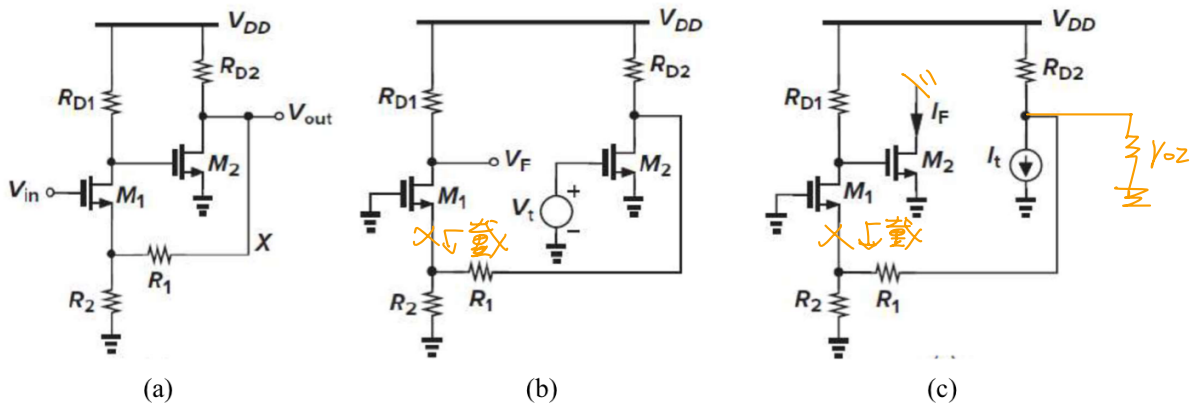


Fig. 7.2

(b)

利用戴維寧等效定理

$$V_{th} = -g_{m2} [R_{D2} \parallel r_{o2} \parallel (R_1 + R_2)] \times \frac{R_2}{R_1 + R_2}$$

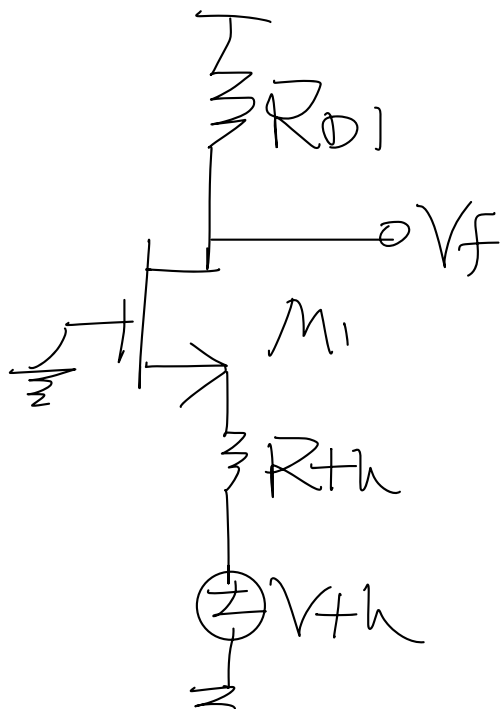
$$R_{th} = R_2 \parallel [R_1 + (R_D \parallel r_{o2})]$$

CG 放大器增益 A

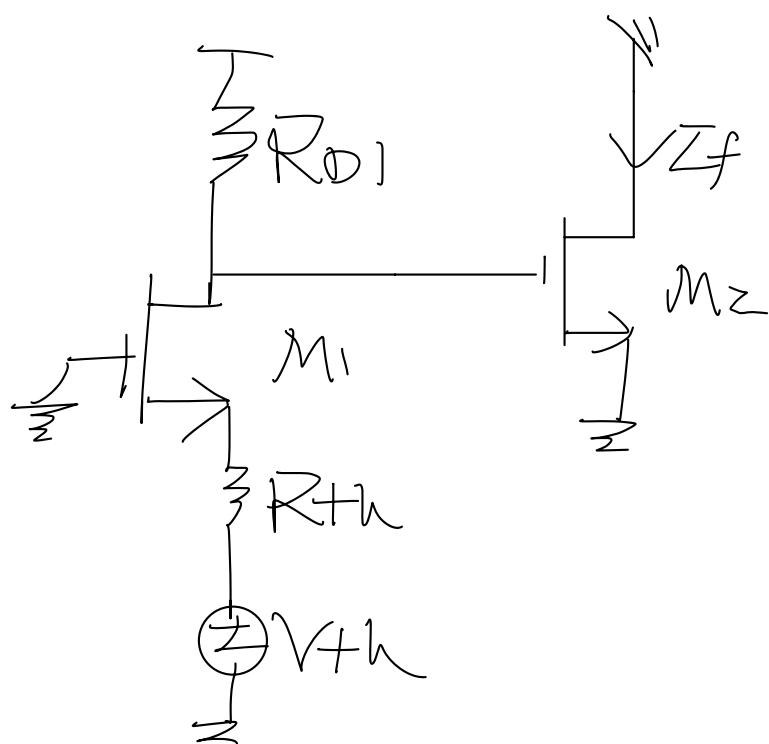
$$V_f = A \times V_{th}$$

$$= -A \times g_{m2} [R_{D2} \parallel r_{o2} \parallel (R_1 + R_2)]$$

$$\times \frac{R_2}{R_1 + R_2} \times V_t$$



(C)



$$V_{th} = I_t \times [R_{D2} \parallel r_{o2} \parallel (R_1 + R_2)] \frac{R_2}{R_1 + R_2}$$

$$R_{th} = R_2 \parallel [R_1 + (R_D \parallel r_{o2})]$$

$$I_f = A \times V_{th} \times g_{m2}$$

$$= A \times g_{m2} [R_{D2} \parallel r_{o2} \parallel (R_1 + R_2)] \frac{R_2}{R_1 + R_2} \times I_t$$

$$\Rightarrow \frac{V_f}{V_t} = \frac{I_f}{I_t} \neq$$

# HW 7.3

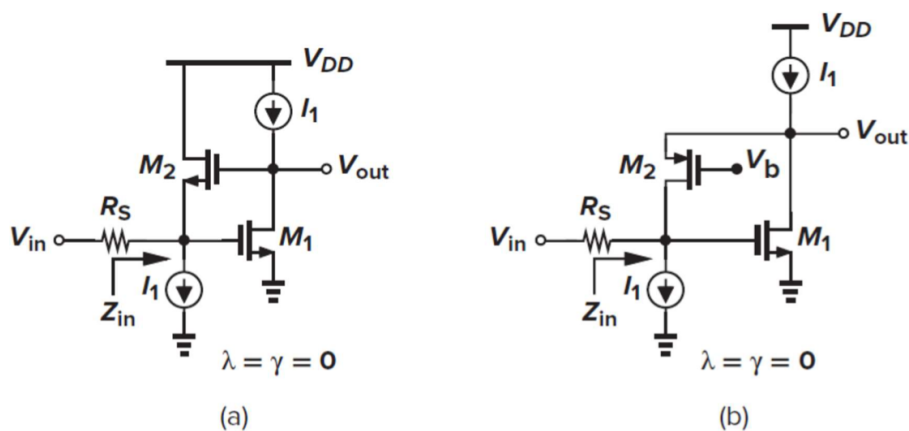
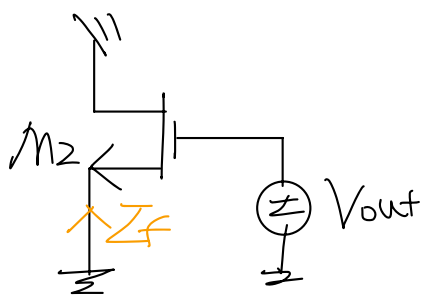


Fig. 7.3

(a)

V-Z feedback

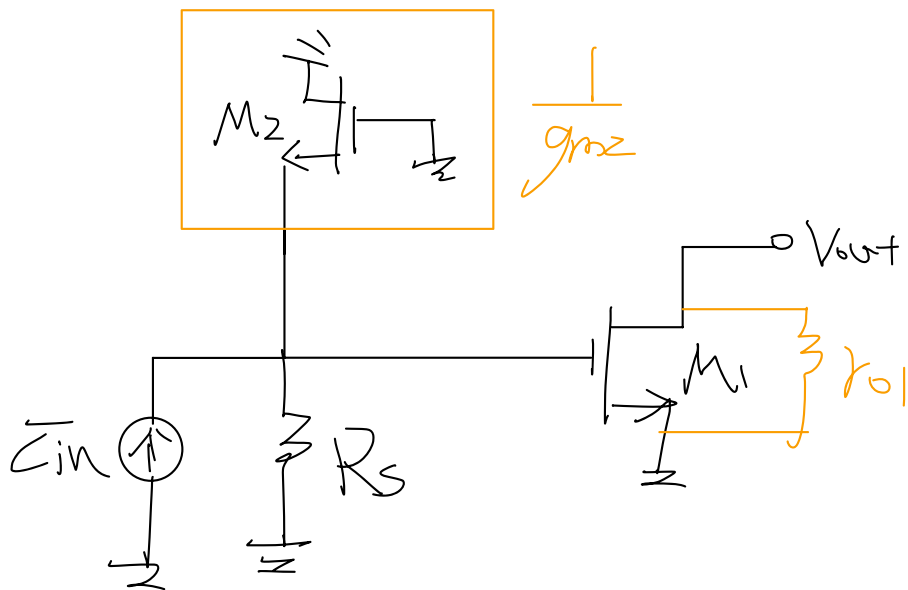
Find  $\beta_g$



$$Z_F = -g_{m2} V_{out}$$

$$\beta_g = \frac{Z_F}{V_{out}} = -g_{m2}$$

Find  $A_{Z,OL}$



$$V_{out,OL} = Z_{in}(R_S \parallel \frac{1}{g_{m2}}) \times (-g_{m1} r_{o1})$$

$$A_{Z,OL} = -g_{m1} r_{o1} (R_S \parallel \frac{1}{g_{m2}})$$

$$R_{in, OL} = R_S \parallel \frac{1}{g_{m2}}$$

$$R_{o, OL} = r_{o1}$$

$$A_{z, CL} = \frac{A_{z, OL}}{1 + \beta_g A_{z, OL}} = \frac{-g_{m1} r_{o1} (R_S \parallel \frac{1}{g_{m2}})}{1 + g_{m1} g_{m2} r_{o1} (R_S \parallel \frac{1}{g_{m2}})}$$

$$A_{v, CL} = A_{z, CL} \times \frac{1}{R_S} \quad \#$$

$$R_{in, CL} = \frac{R_{in, OL}}{1 + \beta_g A_{z, OL}} \quad \#$$

$$R_{o, CL} = \frac{R_{o, OL}}{1 + \beta_g A_{z, OL}} \quad \#$$

因為  $\lambda = 0 \Rightarrow r_o \rightarrow \infty$

$$\Rightarrow A_{v, CL} \simeq -\frac{1}{g_{m2} R_S} \quad \#$$

$$R_{in, CL} \simeq 0 \quad \#$$

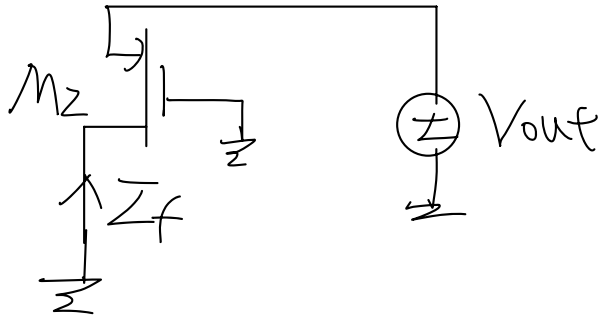
$$R_{o, CL} \simeq \frac{1}{g_{m1} g_{m2} (R_S \parallel \frac{1}{g_{m2}})} = \frac{\frac{1}{g_{m2}} + R_S}{g_{m1} R_S} \quad \#$$



(b)

V-Z feedback

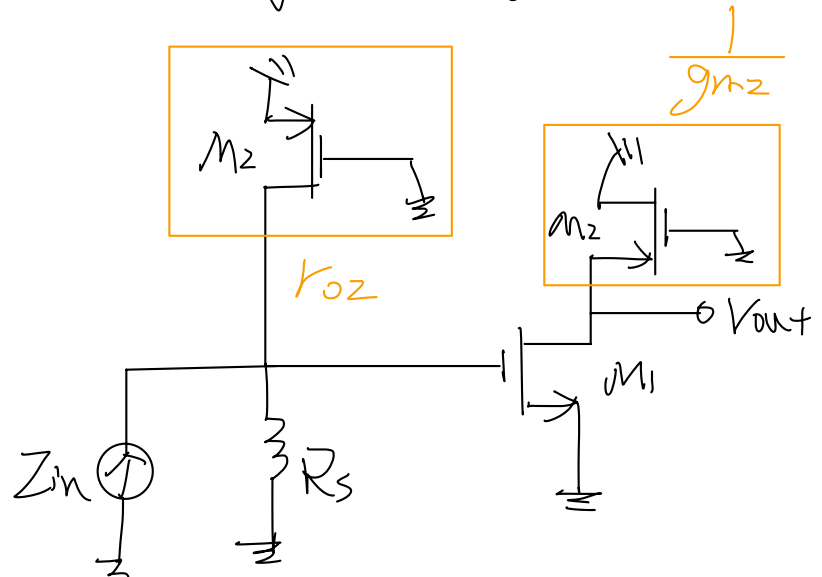
find  $\beta g$



$$Z_f = -g_{m2} V_{out}$$

$$\beta g = \frac{Z_f}{V_{out}} = -g_{m2}$$

find  $A_{Z, OL}$



$$V_{out} = Z_{in} (R_s \parallel r_{o2}) \times -g_{m1} (r_{o1} \parallel \frac{1}{g_{m2}})$$

$$A_{Z, OL} = \frac{V_{out}}{Z_{in}} = -g_{m1} (r_{o1} \parallel \frac{1}{g_{m2}}) (R_s \parallel r_{o2})$$

$$R_{in, OL} = r_{o2}$$

$$R_{o, OL} = \frac{1}{g_{m2}} \parallel r_{o1}$$

$$A_{v,CL} = \frac{A_{z,OL}}{1 + \beta g A_{z,OL}} \times \frac{1}{R_s}$$

$$R_{in,CL} = \frac{R_{in,OL}}{1 + \beta g A_{z,OL}}$$

$$R_{o,CL} = \frac{R_{o,OL}}{1 + \beta g A_{z,OL}}$$

$$\text{因為 } \lambda = 0 \Rightarrow r_o \rightarrow \infty$$

$$\Rightarrow R_{in,CL} \simeq \infty$$

$$R_{o,CL} \simeq \frac{1}{g_{m2}(1 + g_{m1}R_s)} \quad \#$$

$$A_{v,CL} \simeq \frac{-g_{m1}}{g_{m2}(1 + g_{m1}R_s)} \quad \#$$

# HW 7.4

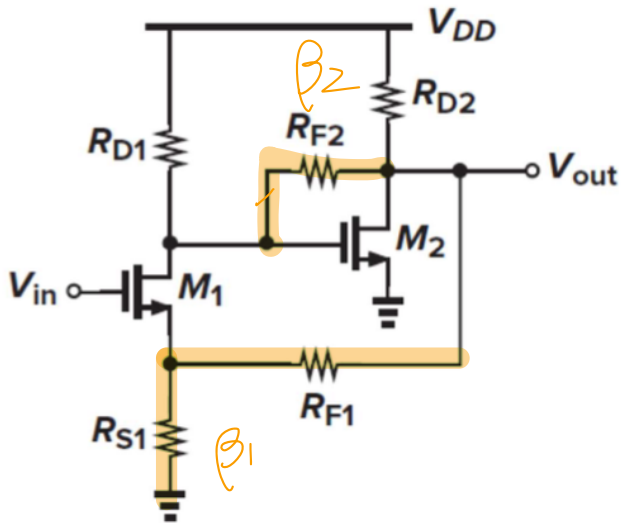
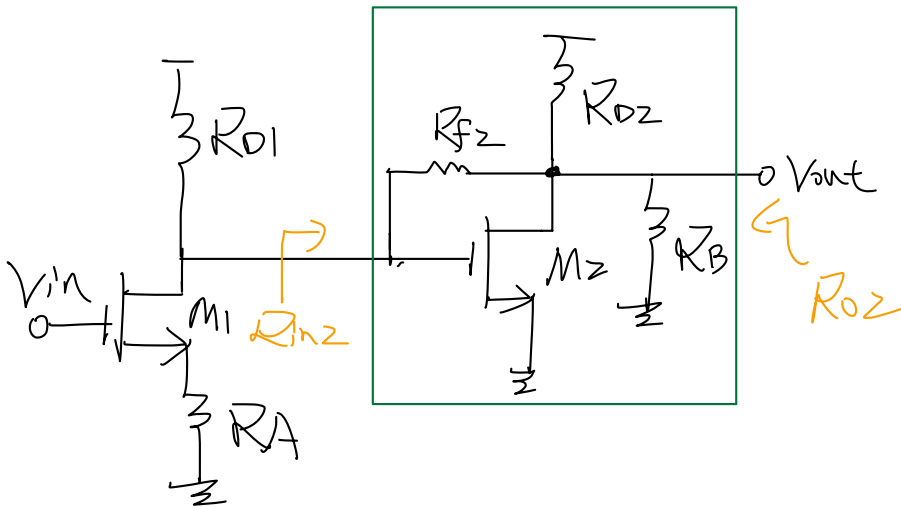


Fig. 7.4

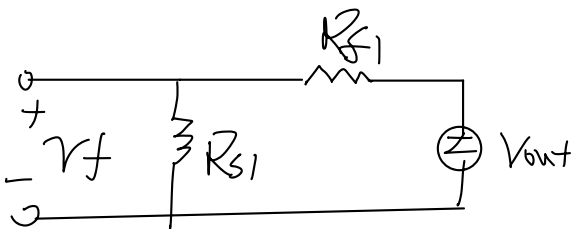
$A_2$



$$R_A = R_{F1} + R_{S1}$$

$$R_B = R_{F1} \parallel R_{S1}$$

find  $\beta_1$



$$\beta_1 = \frac{R_{S1}}{R_{F1} + R_{S1}}$$

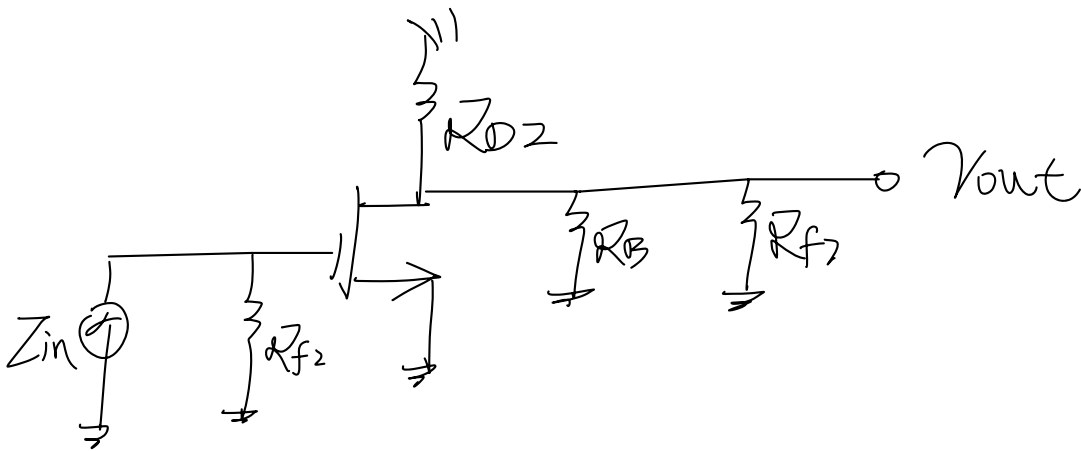
find  $\beta_2$



$$\bar{Z}_f = \frac{0 - V_{out}}{R_{f2}}$$

$$\beta_2 = \frac{Z_f}{V_{out}} = \frac{-1}{R_{f2}}$$

find  $A_{2,OL}$



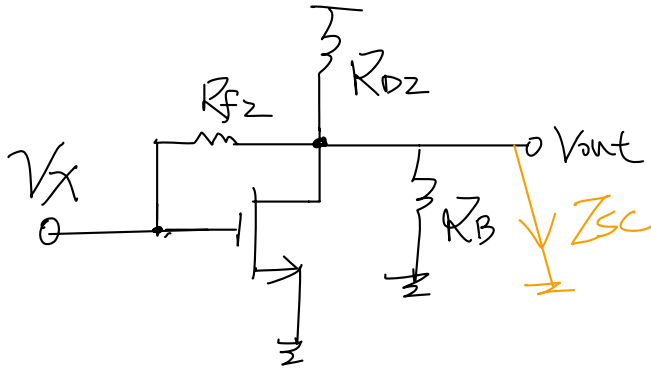
$$A_{2,OL} = \frac{V_{out}}{Z_{in}} = R_{f2} \times -g_{m2} (R_{D2} \parallel R_B \parallel R_{f2})$$

$$\beta_2 A_{2,OL} = g_{m2} (R_{D2} \parallel R_B \parallel R_{f2})$$

$$R_{in2} = \frac{R_{f2}}{1 + g_{m2}(R_{D2} \parallel R_B \parallel R_{f2})}$$

$$R_{D2} = \frac{R_{B2} \parallel R_{f2} \parallel R_{D2}}{1 + g_{m2}(R_{D2} \parallel R_B \parallel R_f)}$$

find  $A_z$

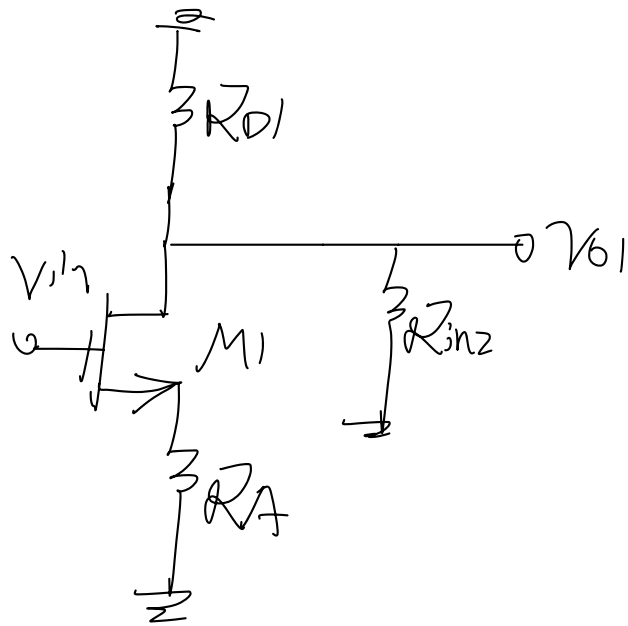


$$G_m = \frac{I_{sc}}{V_x} = \frac{1}{R_{f2}} - g_{m2}$$

$$R_o = R_B \parallel R_{D2} \parallel R_{f2}$$

$$A_z = \frac{V_{out}}{V_x} = G_m R_o$$

Find  $A_1$



$$A_1 = \frac{v_{O1}}{v_{in}} = \frac{-g_{m1}(R_{O1} \parallel R_{in2})}{1 + g_{m1}R_A}$$

$$A_{VT, OL} = A_1 \times A_2$$

$$R_{O, OL} = R_{O2}$$

$$A_{VT, CL} = \frac{A_{VT, OL}}{1 + \beta_1 A_{VT, OL}} \quad \#$$

$$R_{O, CL} = \frac{R_O}{1 + \beta_1 A_{VT, OL}} \quad \#$$

$$R_{in, CL} \rightarrow \infty \quad \text{直接看到 Gate} \quad \#$$