

• Ex:

$$\underline{\underline{A}} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} \textcircled{1} & 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & \textcircled{1} & 0 & 2 \\ 0 & 0 & 0 & 0 & \textcircled{1} & -1 \end{bmatrix} = \underline{\underline{R}}$$

• row-space ( $\underline{\underline{A}}$ )  $\triangleq$   $(( [1 \ 1 \ 1 \ 1 \ 2], [1 \ 1 \ 1 \ 2 \ 2 \ 3], [1 \ 1 \ 1 \ 2 \ 3 \ 2] )) \xrightarrow{\text{l.i.}} \text{l.i. (obvious)}$   
 $= (( [1 \ 1 \ 1 \ 0 \ 0 \ 1], [0 \ 0 \ 0 \ 1 \ 0 \ 2], [0 \ 0 \ 0 \ 0 \ 1 \ -1] ))$

$\uparrow$   
 $\underline{\underline{A}}$  and  $\underline{\underline{R}}$  are row-equivalent (i.e. can be converted into each other via row's)

• col-space ( $\underline{\underline{A}}$ )  $\triangleq$   $(( \underbrace{\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}_{\text{l.i.}}, \underbrace{\begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}}_{\text{l.i.}}, \underbrace{\begin{bmatrix} 2 \\ 3 \\ 2 \end{bmatrix}}_{\text{l.i.}} )) = (( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} )) \xrightarrow{\text{l.i.}} \text{l.i. (as seen/checked from } \underline{\underline{R}} \text{)}$

• A basis for row-space ( $\underline{\underline{A}}$ ):  $\{ [1 \ 1 \ 1 \ 0 \ 0 \ 1], [0 \ 0 \ 0 \ 1 \ 0 \ 2], [0 \ 0 \ 0 \ 0 \ 1 \ -1] \}$

$\xrightarrow{\Delta} \dim(\text{row-space}(\underline{\underline{A}})) = 3 \xrightarrow{\Delta} \text{row-rank}(\underline{\underline{A}}) = 3$

• A basis for col-space ( $\underline{\underline{A}}$ ):  $\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \}$

$\xrightarrow{\Delta} \dim(\text{col-space}(\underline{\underline{A}})) = 3 \xrightarrow{\Delta} \text{column-rank}(\underline{\underline{A}}) \triangleq \text{col-rank}(\underline{\underline{A}}) = 3$

$\rightarrow \text{rank}(\underline{\underline{A}}) = 3$

• Ex:  $\underline{A} = \begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & -1 & 1 & 2 \\ 4 & 3 & 3 & 4 \\ 3 & 1 & 2 & 3 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 3/5 & 1 \\ 0 & 1 & 1/5 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \underline{R}$

• a basis for row-space( $\underline{A}$ ) =  $\left\{ \begin{bmatrix} 1 & 0 & 3/5 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 1/5 & 0 \end{bmatrix} \right\}$

• a basis for col-space( $\underline{A}$ ) =  $\left\{ \begin{bmatrix} 1 \\ 2 \\ 4 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 3 \\ 1 \end{bmatrix} \right\}$

• rank( $\underline{A}$ ) = 2

• Ex:  $\underline{A} = \begin{bmatrix} 1 & 1 & 8 \\ 2 & 4 & 26 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 5 \end{bmatrix} = \underline{R}$

• a basis for row-space( $\underline{A}$ ):  $\left\{ \begin{bmatrix} 1 & 0 & 3 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 5 \end{bmatrix} \right\}$

• P.S.  $\left\{ \begin{bmatrix} 1 & 1 & 8 \end{bmatrix}, \begin{bmatrix} 2 & 4 & 26 \end{bmatrix} \right\}$  also serves as a basis.

In fact, you have many other choices for basis.

• A basis for col-space( $\underline{A}$ ):  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \end{bmatrix} \right\}$

$\text{rank}(\underline{A}) = 2$

(It happens that  $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$  is also a basis for col-space( $\underline{A}$ ))

Recall  $\underline{A} \underline{x} = \begin{bmatrix} \underline{c}_1 & \underline{c}_2 & \dots & \underline{c}_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \underbrace{x_1 \cdot \underline{c}_1 + x_2 \cdot \underline{c}_2 + \dots + x_n \cdot \underline{c}_n}_{\downarrow}$

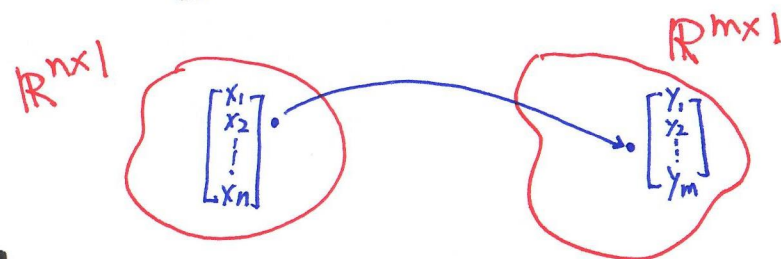
l.c. of columns of  $\underline{A}$ , with  $x_1, x_2, \dots, x_n$  as the coeffs. in the l.c.

Thm  $\underline{A} \underline{x} = \underline{b}$  is consistent iff  $\underline{b} \in \langle \underline{c}_1, \underline{c}_2, \dots, \underline{c}_n \rangle$

$\underline{b}$  can be expressed as a l.c. of  $\underline{c}_1, \underline{c}_2, \dots, \underline{c}_n$

Consider  $\underline{A} : m \times n$ . Let us define  $T_{\underline{A}} : \mathbb{R}^{n \times 1} \mapsto \mathbb{R}^{m \times 1}$  as

$T_{\underline{A}}(\underline{x}) \triangleq \underline{A} \underline{x}$   
 $\downarrow \in \mathbb{R}^{n \times 1} \quad \downarrow \in \mathbb{R}^{m \times 1}$



Def  $\text{range}(T_{\underline{A}}) \triangleq \{ \underline{A} \underline{x} \mid \underline{x} \in \mathbb{R}^{n \times 1} \} = \{ \text{all l.c.'s of columns of } \underline{A} \}$

Thm  $\text{range}(T_{\underline{A}}) = \text{col-space}(\underline{A})$



- Ex (null space of a matrix)

Consider  $A = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \stackrel{a}{=} \underline{\underline{R}}$

$$\text{null-space}(\underline{A}) \triangleq \{ \underline{x} \mid \underline{A} \underline{x} = \underline{0} \} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} \mid \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 2 & 2 & 3 \\ 1 & 1 & 1 & 2 & 3 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

$$= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} \mid \begin{bmatrix} 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

$R$  is obtained from  $A$  via  $\text{er0's}$

$$\begin{cases} x_1 = -x_2 - x_3 - x_6 \\ x_4 = -2x_6 \\ x_5 = x_6 \end{cases} \quad (\star)$$

- $x_2, x_3$ , and  $x_6$  (variables corresponding to columns that do not contain leading 1's) are free variables
- $x_1, x_4$ , and  $x_5$  (variables that correspond to columns that do contain leading 1's) are rapport/matching (耦合性的) variables.
- $\#(\text{free variables}) = \dim(\text{null-space}(\underline{A})) \triangleq \text{nullity}(\underline{A})$
- $\#(\text{free variables}) + \underbrace{\#(\text{rapport variables})}_{\substack{|| \\ \text{rank}(\underline{A})}} = \#(\text{columns of } \underline{A})$

• Finding a basis for null-space (A):

From (\*) we know

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} -x_2 - x_3 - x_6 \\ x_2 \\ x_3 \\ -2x_6 \\ x_6 \\ x_6 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_6 \begin{bmatrix} -1 \\ 0 \\ 0 \\ -2 \\ 1 \\ 1 \end{bmatrix}$$

• A basis for null-space (A) is  $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ -2 \\ 1 \\ 1 \end{bmatrix} \right\}$

• Ex  $\underline{A} = \begin{bmatrix} 1 & 1 & 8 \\ 2 & 4 & 26 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 5 \end{bmatrix} \equiv \underline{R}$

•  $\underline{A} \underline{x} = \underline{0} \equiv \underline{R} \underline{x} = \underline{0} \Rightarrow \begin{cases} x_1 = -3x_3 \\ x_2 = -5x_3 \end{cases}$

$\begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

•  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -3x_3 \\ -5x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} -3 \\ -5 \\ 1 \end{bmatrix} \Rightarrow$

• basis for null-space (A):  $\left\{ \begin{bmatrix} -3 \\ -5 \\ 1 \end{bmatrix} \right\}$

$\Downarrow$   
nullity (A) = 1