MAT301

Groups and Symmetries

Sinan Li

2024

CONTENTS

Part I

Notes

CHAPTER

1 INTRODUCTION

1.1 Course Information

- **Instructor**: Malors Emilio Espinosa Lara
- **Office**: BA 6256
- **Email**: srolam.espinosalara@mail.utoronto.ca
- **TA**: Shuofeng Xu, Mohammad Honari and Mohammadmahdi Rafiei
- **Office Hours**

LEC101, LEC2001	Tuesday 9 - 11 (PB B250)	Thursday 10 - 11 (MP 202)
Instructor Office Hours	Monday 12 - 1	BA6256 (My office)

- There are **no tutorials** for this course.

1.1.1 Communication

All communication will occur by U of T email. Feel free to contact the instructor via email to ask extra questions and doubts, corrections about homeworks, inquiries, etc. However, the following titles must be used in the subject of the email:

- **MAT301: Mark Correction**. Put this title whenever you feel a correction is needed in one of your homeworks or midterm.

- **MAT301: Math Doubt**. If you have a mathematical doubt.
- **MATH301: Administrative Issue**. If you have any other concern that doesnt fall into the previous categories.

1.1.2 Evaluation Criteria

We will follow the following grading scheme for this course.

10 Homeworks (drop the lowest scored one of the first five and of the last five)	25%
Midterm	25%
Final Examination	50%

Notice that **late homework submission are usually given mark zero**. Exceptions due to required accommodations or unexpected circumstances will be of course taken into account and discussed in a case by case basis. Please write to the instructor in these situations.
Any grade curve that might occur will only be done over the final course mark and not for particular homework, midterm or final test.

1.2 Important Dates

The following are some of the dates relevant, and with respect, to MAT301:

First day of classes of University	Monday, January 8
First Lecture	Tuesday, January 9
Family Day	February 19 (University Closed)
Winter Reading Week(No lectures, nor Office hours)	February 19 to 23
Our Course Midterm	February 26, 19:00 - 21:00 (Venues TBA)
Good Friday	March 29 (University Closed)
Last day of classes	April 5
Study Day	April 9
Final Exam Period	April 10 - 30

1.3 Course Description

This course covers Groups oriented to computations. In order to understand groups well, a solid background in *linear algebra* is required: matrices, determinants, eigenvalues, eigenvectors, etc. *Modular arithmetic* is also required, as well as some basic notions of *number theory*.

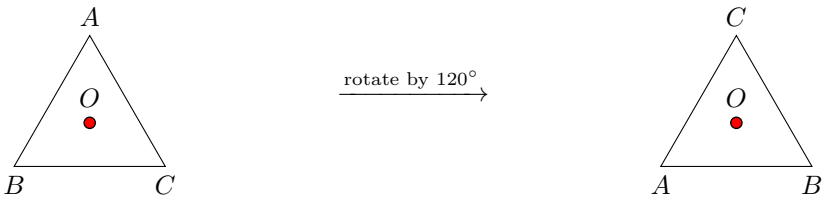
CHAPTER

INTRODUCTION TO SYMMETRY 2

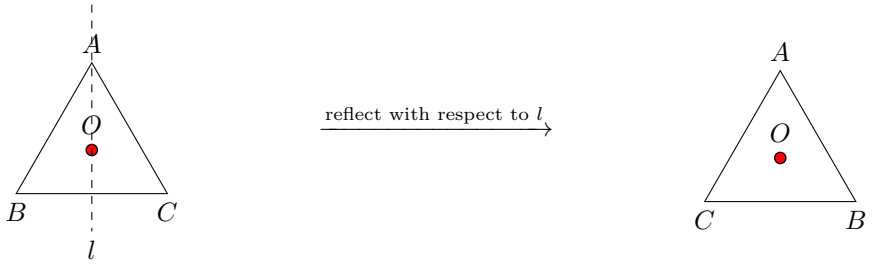
2.1 Intuition and Motivation

The idea of symmetry is the the object has a property that remains invariant under a transformation. For example, if we rotate a square by 90 degrees, the square remains the same. However, symmetry is more than a geometric concept. It is a fundamental concept in mathematics and physics.

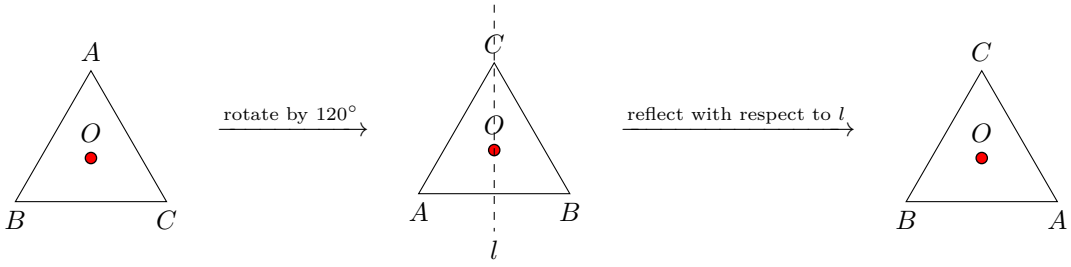
Example (Polygons)**.** We can rotate the following triangle with respect to O by 120°, and the triangle remains the same. This triangle has rotational symmetry.



Moreover, we can also reflect the triangle with respect to the line l passing through O, and the triangle remains the same. This triangle has reflection symmetry.

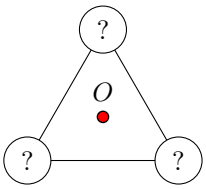


Is there any other symmetry? Yes, we can combine the two symmetries above. We first rotate the triangle by 120°, and then reflect it with respect to l. This triangle has both rotational and reflection symmetry.



♢

The above example is a very simple one. However, given an general object, it is not easy to find all its symmetries. We can label the vertices of the triangle with A, B, C, then permute the labels.



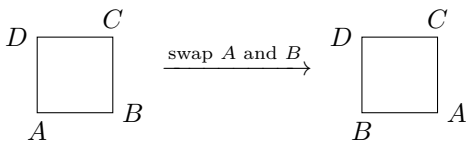
Since the transformations are linear, they preserve linearity. This, it suffices to consider the transformations of the vertices.

Example (Continued)**.** The following table shows all the permutations of the vertices of the triangle.

Identity	A	B	C
Rotation	C	A	B
Reflection	A	C	B
Rotation + Reflection	C	B	A
	B	A	C
	B	C	A

As we can see, there are six transformations of the vertices, each of which corresponds to a symmetry of the triangle. ♢

Naively, given an square, one would argue that there are 24 ways to permute the vertices, and thus 24 symmetries. However, this is not true. There are certain permutations that are not symmetries.



2.2 Symmetric Group

Definition 2.2.1 Symmetric Group

The **symmetric group**, denoted S_n, is the set of all permutations of n elements $1, 2, \ldots, n$.

Definition 2.2.2 Identity Permutation

The **identity permutation** is the permutation that does not change the order of the elements.

Example. The identity permutation of S_3 is the identity permutation of $1, 2, 3$. ♢

Definition 2.2.3 Transposition

A **transposition** is a permutation that swaps two elements and leaves the other elements unchanged.

Example. The following are some transpositions of S_3.

- $2, 1, 3$ swaps 1 and 2.
- $1, 3, 2$ swaps 2 and 3.
- $3, 2, 1$ swaps 1 and 3.

♢

Definition 2.2.4 Cycle

A **cycle** is a permutation that moves the first element to the second, the second to the third, and so on, and the last element to the first.

Example. The cycle $3, 2, 1$ moves 1 to 3, 3 to 2, and 2 to 1. ♢

Definition 2.2.5 Permutation

A permutation is a way to order n elements. We codify them in "cycles"

Example. Consider S_3.

1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3
1 2 3	1 3 2	3 2 1	2 1 3	3 1 2	2 3 1
(1)(2)(3)	(1)(23)	(13)(2)	(12)(3)	(132)	(123)

Here, (1)(23) means

- 1 goes to 1.

- 2 goes to 3, and 3 goes to 2.

♢

Example. Consider the following permutation.

1 2 3 4 5 6 7	1 2 3 4 5 6 7
3 4 2 1 7 5 6	2 3 1 4 6 5 7
(1324)(576)	(1 2 3)(5 6)

♢

Example. Suppose you have two permutations σ and τ:

- $\sigma = (12)(3456)$
- $\tau = (1654)(32)$

What happens if we perform one after the other?

- σ first, τ second[1]: $(1654)(32)(12)(3456) = (1654)(32)(12)(3456)$
  - We start with 1: $1 \to 2 \to 3$, so $1 \to 3$.
  - We then consider 3: $3 \to 4 \to 1$, so $3 \to 1$.
  - Now, we consider 2: $2 \to 1 \to 6$, so $2 \to 6$.
  - $6 \to 3 \to 2$, so $6 \to 2$.
  - $4 \to 5 \to 4$, so $4 \to 4$.
  - $5 \to 6 \to 5$, so $5 \to 5$.

  Thus, we get
  $$(13)(26)(4)(5).$$
- τ first, σ second: $(12)(3456)(1654)(32) = (12)(3456)(1654)(32)$
  - We start with 1: $1 \to 6 \to 4$, so $1 \to 3$.
  - We then consider 3: $4 \to 5 \to 1$, so $4 \to 1$.
  - ...

  Eventually, we get
  $$(13)(24)(5)(6).$$

It is important to note that the order of the permutations matters. ♢

The above example demonstrates an important property of permutations: closed under composition. That is, if we "merge" two permutations, we get another permutation.

[1] Note that we read from right to left.

$\circ$	$\mathbb{1}$	(12)	(13)	(23)	(123)	(132)
$\mathbb{1}$						
(12)						
(13)						
(23)	(23)	(132)	(123)	$\mathbb{1}$	(13)	(12)
(123)						
(132)						

This is a multiplication table of S_3. Symmetries of the same group have the same multiplication table, despite the fact that they are different permutations.

Remark

Note that in the above table of S_3, we have $(123) = (23)(13)$, and $(132) = (23)(12)$. **All the permutations can be written as a composition of transpositions.**
It is important to note that this is not unique. For example, we can write $\mathbb{1} = (12)(12)$.

Theorem 2.2.1

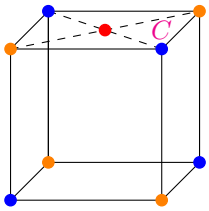
The amount of transpositions needed to create a permutation preservers its parity.

In other words, if a permutation α can be expressed as a product of transpositions

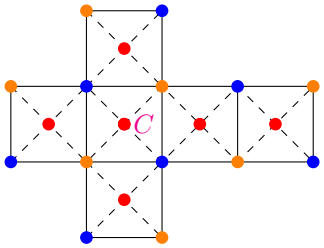
$$\alpha = \tau_1\tau_2\dots\tau_n \qquad \text{and} \qquad \alpha = \sigma_1\sigma_2\dots\sigma_m$$

where τ and σ are transpositions, then n and m have the same parity (both even or both odd). The smaller groups are called **alternating groups**.

Example. Consider the following figure of a cube.



which expands to the following graph.



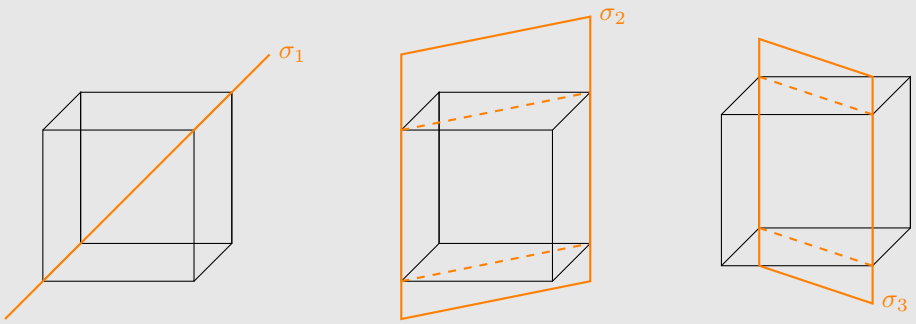
Question: What are the isometries that preserve the colouring of this object?

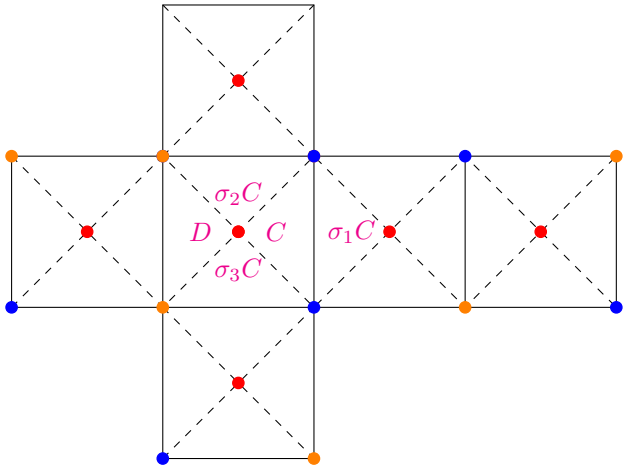
Definition 2.2.6 Isometry

An **isometry** is a transformation that preserves distance.

Remark

Consider reflection with respect to the planes σ_1, σ_2, and σ_3.





D can be obtained by either $\sigma_3\sigma_2 C$ or $\sigma_2\sigma_3 C$.

$$\begin{array}{ccccc} \mathbb{R}^3 & \xrightarrow{\sigma_3} & \mathbb{R}^3 & \xrightarrow{\sigma_2} & \mathbb{R}^3 \\ & \sigma_2 & & \sigma_3 & \end{array}$$

Matrices are not commute, and thus these transformations may be different. We ask the questions: since $\sigma_2\sigma_1$ and $\sigma_1\sigma_2$ move the triangle C in the same way, are they the same map?

Proposition 2.2.1

If $S, T : \mathbb{R}^3 \to \mathbb{R}^3$ preserve the coloured ube and send the triangle to the same place, then $S = T$ (as maps).

Proof. WTS $S = T$.

Remark

It is important that the triangle C is a field of vectors.

Consider $o = (0, 0, \frac{1}{2})$, $b = (\frac{1}{2}, \frac{1}{2}, \frac{1}{2})$, and $y = (-\frac{1}{2}, \frac{-1}{2}, \frac{1}{2})$.
$Sb = Tb, So = To, Sy = Ty \implies (S - T)b = 0, (S - T)o = 0, (S - T)y = 0$.
This implies b, o, and y are in the kernel of $S - T$.
Moreover, b, o, y are linearly independent since $\det \begin{bmatrix} \frac{1}{2} & 0 & -\frac{1}{2} \\ \frac{1}{2} & 0 & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \neq 0$.
Thus, $\dim \ker (() S - T) = 3$. Since $\dim \mathbb{R}^3 = 3$, $\ker (() S - T) = \mathbb{R}^3$. Thus, $S - T = 0$. ■

We can reach all 24 locations of the triangle C by applying σ_1, σ_2, and σ_3 to the triangle C. Thus, there are 24 isometries that preserve the coloured cube. Moreover, we know that 3 of them generates the set. It suffices to study these three isometries to understand the whole group. ♢

CHAPTER

3 INTRODUCTION TO GROUP

3.1 Introduction

Remark

What have we done so far: we have studied some **objects** with some properties, and we have asked how can we operate in this object and preserve its property.

Definition 3.1.1 Group

A **group** is a pair $(G, \cdot)$ where G is a set and $\cdot$ is a binary operation on G such that

$$\begin{array}{cccc} \cdot & G \times G & \to & G \\ & (a,b) & \mapsto & a \cdot b \end{array}$$

such that

- **Identity:** There exists an element $e \in G$ such that
$$e \cdot g = g \cdot e = a \quad \forall a \in G.$$
- **Inverse:** For every $g \in G$ there exists an element $h \in G$ such that
$$g \cdot h = h \cdot g = e.$$
- **Associativity:** For every $g, h, k \in G$ we have
$$g \cdot (h \cdot k) = (g \cdot h) \cdot k.$$

Definition 3.1.2 Abelian Group

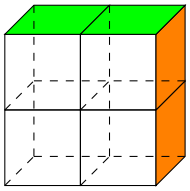
A group $(G, \cdot)$ is called **abelian** if

$$g \cdot h = h \cdot g \quad \forall g, h \in G.$$

This group is also called a **commutative group**.

The term *abelian* comes from the name of the Norwegian mathematician Niels Henrik Abel. He was the first to prove the impossibility of solving the general quintic equation in radicals. He also made important contributions to the study of elliptic functions, discovered Abelian functions, and many other important fields in mathematics.

Example. We will consider the following "toy"



The left side is red, the bottom is blue, and the back is yellow.

We have 7 operations

$$V_1, V_2, H_1, H_2, V, H, R$$

where

- V_1 is the vertical flip of the first column
- V_2 is the vertical flip of the second column
- H_1 is the horizontal flip of the first row
- H_2 is the horizontal flip of the second row
- V is the vertical flip of the whole cube
- H is the horizontal flip of the whole cube
- R is the rotation of the cube by $90°$ around the vertical axis

They satisfy

$$V_1{}^2 = 1, V_2{}^2 = 1, H_1{}^2 = 1, H_2{}^2 = 1, V^2 = 1, H^2 = 1, R^4 = 1,$$

However, we have redundancies:

- $V_1 V_2 = V_2 V_1 = V$
- $H_1 H_2 = H_2 H_1 = H$
- $V_1 H_1 = H_1 V_1 = R$

- $H_2H_1V_2V_1 = R^2$
- $R^3V_1R = R^{-1}V_1R = H_1$
- ...

We can flatten the cube into

$$\begin{array}{c|c} 1 & 2 \\ \hline 3 & 4 \end{array}$$

Then,

- $V_1 = (1, 4)$

$$\begin{array}{c|c} 1 & 2 \\ \hline 4 & 3 \end{array} \xrightarrow{V_1} \begin{array}{c|c} 4 & 2 \\ \hline 1 & 3 \end{array}$$

- $V_2 = (2, 3)$

$$\begin{array}{c|c} 1 & 2 \\ \hline 4 & 3 \end{array} \xrightarrow{V_2} \begin{array}{c|c} 1 & 3 \\ \hline 4 & 2 \end{array}$$

- $H_1 = (1, 2)$

$$\begin{array}{c|c} 1 & 2 \\ \hline 4 & 3 \end{array} \xrightarrow{H_1} \begin{array}{c|c} 4 & 3 \\ \hline 1 & 2 \end{array}$$

- $H_2 = (3, 4)$

$$\begin{array}{c|c} 1 & 2 \\ \hline 4 & 3 \end{array} \xrightarrow{H_2} \begin{array}{c|c} 1 & 2 \\ \hline 3 & 4 \end{array}$$

- $R = (1, 2, 3, 4)$

$$\begin{array}{c|c} 1 & 2 \\ \hline 4 & 3 \end{array} \xrightarrow{R} \begin{array}{c|c} 4 & 1 \\ \hline 3 & 2 \end{array}$$

We can verify that

$$(1, 2, 3, 4) = (3, 4)(1, 4)(1, 2),$$

which proposes that

$$R = H_2 \circ V_1 \circ H_1$$

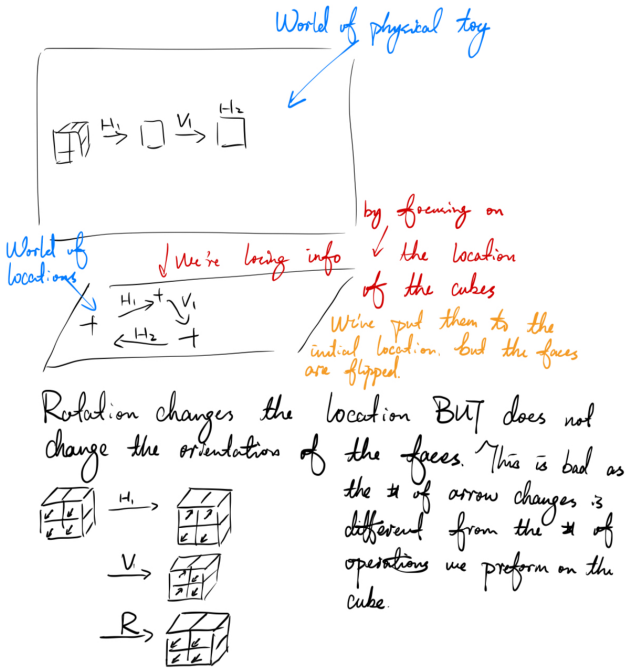
♢

We have a group that is the one generator by the operations of the ‘toy‘ above. We have two models to understand the group:

1. The complete toy

2 The location code

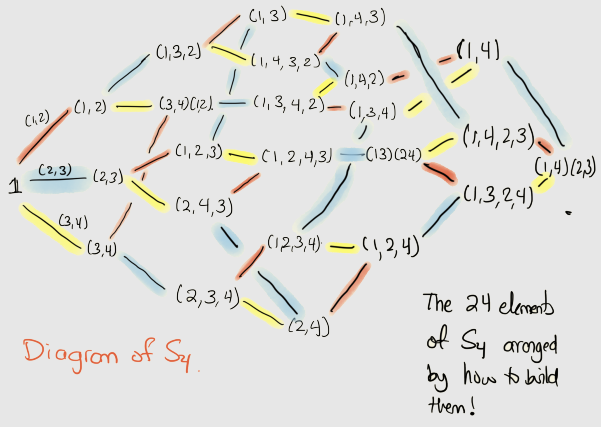
What we have seen is that these two models are codify information in different ways. We can generate a map of the potential positions.



If we only allow H_1, V_1, H_2, V_2, then the locations are believable. The group they generate is S_4.

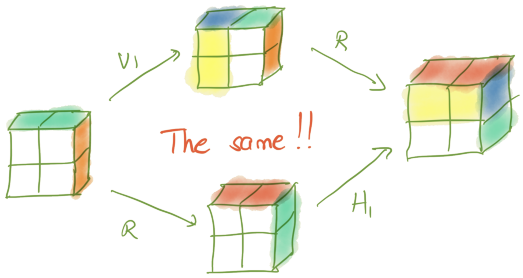
Remark

Think of S_4 independently.
We consider the permutations independently as a group.



We want to merge R with the rest of the operations.
Consider

$$H_1R = RV_1 \qquad H_2R = RV_2$$



Example. "Simplify" the instructions

$$RV_1H_2RV_2H_1H_2RV_1H_2$$

Using the two equations above,

$$\begin{aligned} RV_1H_2RV_2H_1H_2RV_1H_2 &= RV_1H_2RV_2H_1RV_2V_1H_2 \\ &= RV_1H_2RV_2RV_1V_2V_1H_2 \\ &= RV_1H_2RRH_2V_1V_2V_1H_2 \\ &= RV_1H_2V_1V_2H_1H_2H_2V_1V_2V_1H_2 \qquad (RR = V_1V_2H_1H_2) \end{aligned}$$

This way, we have moved all the "noice", R, to the last steps. ♢

Fact: All elements of the group can be written as

$$X\sigma$$

where $X = 1$ or R and $\sigma \in S_4$.

Proposition 3.1.1

This writing is **unique**.

Proof. Suppose $X_1\sigma_1 = X_2\sigma_2$.

- If $X_1 = X_2 = 1$, then $\sigma_1 = \sigma_2$.
- If $X_1 = X_2 = R$, then $R\sigma_1 = R\sigma_2$.
  Multiplying by R^{-1}, we have

$$\begin{aligned} R^{-1}R\sigma_1 &= R^{-1}R\sigma_2 \\ \sigma_1 &= \sigma_2 \end{aligned}$$

- $X_1 = 1, X_2 = R$. Then,

$$\begin{aligned} \sigma_1 &= R\sigma_2 \\ \sigma_1{\sigma_2}^{-1} &= R\sigma_2{\sigma_2}^{-1} \\ \sigma_1{\sigma_2}^{-1} &= R \end{aligned}$$

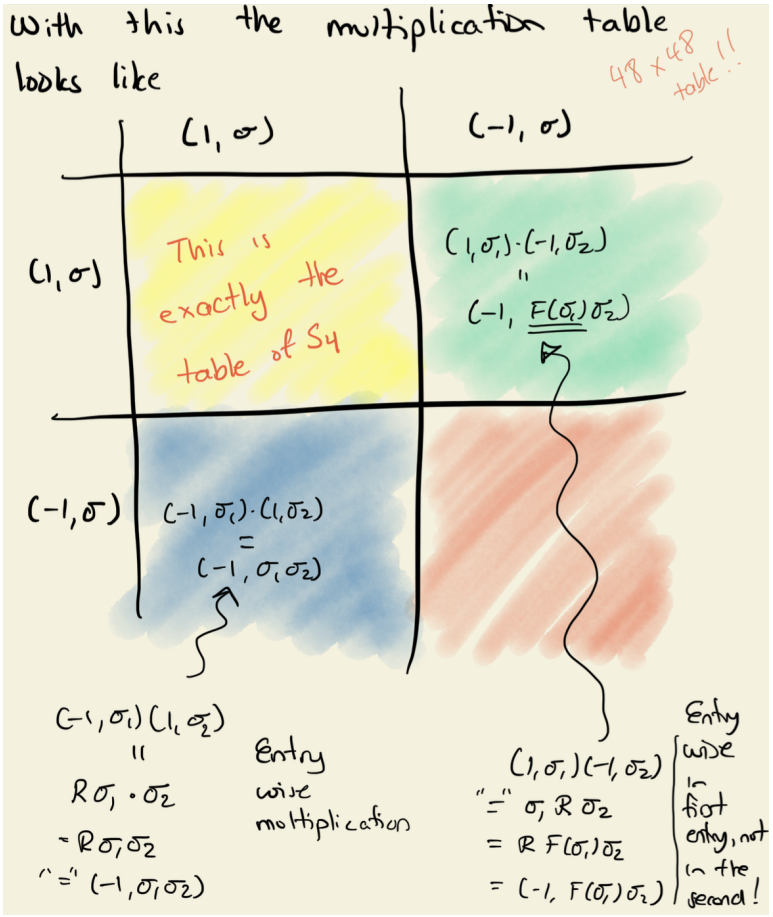
  which means $R \in S_4$, which is impossible.

■

These decomposition also has coordinates. X uses the R-coordinate and σ uses the S_4-coordinate. We can write this as

$$(1, \sigma) \in \pm 1 \times S_4$$

However, note that $(s_1, \sigma_1)(s_2, \sigma_2) = (s_1 s_2, \sigma_1 \sigma_2)$ is **not true**. The reason is because there is "noice" (procued by R) in the first coordinate.



3.2 Subgroups

Definition 3.2.1 Subgroup

Let $(G, \cdot)$ be a group. A non-empty[a] subset $H \subseteq G$ is called a **subgroup** of G if H with the same operation $\cdot$ is a group. We write $H \leq G$.

[a] H has to be non-empty, as the identity $e \in H$.

Example. In the Rubik's cube example, the elements generated by H_1, V_1, H_2, V_2 is a subgroup of S_4. ♢

Definition 3.2.2 Order (Element)

Given an element $g \in G$, the **order** of g is the smallest positive integer n such that

$$g^n = e.$$

in case it exists. If no such n exists, then g has infinite order.

Example. Consider the following examples.

- In the Dihedral group D_n, R has order n, and S has order 2.
- In S_4 (which has 24 elements), the orders can only be $1, 2, 3, 4$. This implies $g^{12} = e$ for all $g \in S_4$.
- Not everything has an order. $(\mathbb{Z}, +)$ is a group.

  Given $n \in \mathbb{Z}$, $n \neq 0$. If its order was k,

$$\underbrace{n + n + \cdots + n}_{k \text{ times}} = 0 \implies kn = 0 \implies k = 0$$

♢

Claim. A finite group always has an finite order.

Definition 3.2.3 Order (Group)

Let G be a group. The **order** of G is its cardinality, denoted by $|G|$.

All of these definitions are languages to be able to understand the main question:

What are all the groups?

In order to take account of repetition, we give the following definition.

Definition 3.2.4 Homomorphism

Let G, H be groups and $\varphi : G \to H$ a function. We say Φ is an **homomorphism** if

$$\varphi(g_1 \cdot g_2) = \varphi(g_1) \cdot \varphi(g_2) \quad \forall g_1, g_2 \in G.$$

This ia a "relabeling" of the multiplication table.

Example. Consider the following examples.

- The sign function

$$\begin{array}{rccc} \operatorname{sgn}: & S_n & \to & \{\pm 1\} \\ & \sigma & \mapsto & \operatorname{sgn}(\sigma) \end{array}$$

  We have $\operatorname{sgn}(\sigma_1\sigma_2) = \operatorname{sgn}(\sigma_1)\operatorname{sgn}(\sigma_2)$.

- For every isometry of the coloured cube φ, we assosiate a pemutation P_φ. $P_{\varphi_1 \cdot \varphi_2} = P_{\varphi_1} \cdot P_{\varphi_2}$.

♢

Definition 3.2.5 Mono-, Epi-, Iso-

An homomorphism is

- A **monomorphism** if it is injective.
- An **epimorphism** if it is surjective.
- An **isomorphism** if it is bijective.

Definition 3.2.6 Kernel

Let $\Phi : G \to H$ be an homomorphism. The **kernel** of Φ is

$$\ker(()\,\Phi) = \{g \in G \mid \Phi(g) = e_H\}.$$

Definition 3.2.7

Let $\Phi : G \to H$ be an homomorphism. The **image** of Φ is

$$\operatorname{Im}(\Phi) = \{\Phi(g) \mid g \in G\}.$$

Example. Consider S_n and the sign function $\operatorname{sgn} : S_n \to \{\pm 1\}$. We have

$$\ker(()\operatorname{sgn}) = \{\sigma \in S_n \mid \sigma \text{ needs an even number of transpositions to write}\} = A_n.$$

This is called the **alternating group** of degree n, denoted A_n[1]. ♢

[1] Note that this group is non-decomposible for $n \geq 5$. This is why there is no formula for the general quintic equation.

Example. Consider A_4.

- $\text{id} \in A_4$
- Transpositions have an odd number of transpositions, so they are not in A_4.
- Three cycles can be decomposied into two transpositions, so they are in A_4.
- Four cycles are decomposed into three transpositions, so they are not in A_4.

Thus,

$$A_4 = \{\mathbb{I}, (a,b)(c,d), (a,b,c)\}$$

which has 12 elements. ♢

Definition 3.2.8 Group Action

Let G be a group and X a set. A **group action** on X by G, denoted $G \curvearrowright X$, is a function

$$\begin{array}{rccc} \cdot : & G \times X & \to & X \\ & (g,x) & \mapsto & g \cdot x \end{array}$$

such that

1. $1 \cdot x = x \quad \forall x \in X.$
2. $h \cdot (g \cdot x) = (h \cdot g) \cdot x \quad \forall g, h \in G, x \in X.$

Given $x \in X$, all the elements reachible by x (i.e. $\{g \cdot x \mid g \in G\}$) are called the **orbit** of x.

CHAPTER

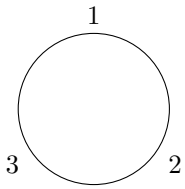
4 CYCLIC GROUPS

4.1 Introduction

For every positive integer n, we consider the integers modulo n.

Example. For $n = 3$, we have the multiplication table:

$+$	0	1	2
0	0	1	2
1	1	2	0
2	2	0	1



Similarly, for $n = 4$, we have the multiplication table:

$+$	0	1	2	3
0	0	1	2	3
1	1	2	3	0
2	2	3	0	1
3	3	0	1	2

♢

Definition 4.1.1 Cuclic Group

Let n be a positive integer. A **cyclic group** of order n is one that admits a generator of order n.

$$C_n = \{0, 1, \ldots, n-1\}$$

Definition 4.1.2 Generator

A **generator** of a group G is an element $g \in G$ such that every element of G can be written as a power of g.

The group of integers modulo n is called the **cyclic group of order** n and is denoted by C_n or $\mathbb{Z}/n\mathbb{Z}$.

Example. The integers $\mathbb{Z}$ form a cyclic group under addition.

$$\cdots \xrightarrow{+1} -2 \xrightarrow{+1} -1 \xrightarrow{+1} 0 \xrightarrow{+1} 1 \xrightarrow{+1} 2 \xrightarrow{+1} \cdots$$

♢

Given a group G and an element $g \in G$, we produce

$$\underbrace{\{\ldots, g^{-2}, g^{-1}, 1 = g^0, g, g^2, g^3, \ldots\}}_{\langle g \rangle} \subseteq G$$

Proposition 4.1.1

Let G be a group and $g \in G$.

1. The set of powers of g,
$$\{g^m \mid m \in \mathbb{Z}\}$$
is a subgroup of G (denoted by $\langle g \rangle$).
2. g has order m if and only if $\langle g \rangle$ is isomorphic to C_m.
3. g has no order if and only if $\langle g \rangle$ is isomorphic to $\mathbb{Z}$.

Proof. (Proposition 4.1.1) WTS $\langle g \rangle$ is a subgroup of G.

- **Associativity** follows from that of G.
- **Identity** is a power of g, namely, $g^0 = 1$.
- Each element has an **inverse**, indeed, the inverse of g^n is g^{-n} which is also a power.
- **Closed** under the operation
$$g^n \cdot g^m = g^{n+m}$$
which is also a power.

■

Proof. (Proposition 4.1.2) WTS g has order m if and only if $\langle g \rangle \cong C_m$.
If G has order m,
$$1, g, g^2, \ldots, g^{m-1}$$

are distinct.
Define $\Phi : C_m \to \langle g \rangle$ by $\Phi(k) = g^k$.
This is well defined if $a \equiv b \pmod{m}$, then $a = b + mt$ for some $t \in \mathbb{Z}$.

$$g^a = g^{b+mt} = g^b \cdot g^{mt} = g^b \cdot (g^m)^t = g^b \cdot 1^t = g^b$$

It is an homomorphism, indeed,

$$\Phi(a+b) = g^{a+b} = g^a \cdot g^b = \Phi(a) \cdot \Phi(b)$$

- **Injectivity**
  If $\Phi(a) = \Phi(b)$, then $g^a = g^b$, so $g^{a-b} = 1$.
  We can pick $a, b \in \{0, 1, \ldots, m-1\}$. We can also suppose $a \geq b$, thus

  $$0 \leq a - b \leq m - 1$$

  Then $g^{a-b} = 1$ implies $a - b = 0$, for owtherwise g has order smaller than m.
  Thus, $a = b$, so Φ is injective.
- **Surjectivity**
  By assumption

  $$\langle h \rangle = \{g^0, g^1, \ldots, g^{m-1}\}$$

  Since by definition

  $$\Phi(k) = g^k,$$

  by taking $k = 0, 1, \ldots, m-1$ we produce all elements of $\langle g \rangle$.
  Thus, Φ is surjective.

We conclude that Φ is an isomorphism. ■

Example. Consider $C_6 = \{0, 1, 2, 3, 4, 5\}$.
The cyclic groups the elements generate are

- 0 generates $\{0\} \equiv C_1$.
- 1 and 5 generate $\equiv C_6$, $C_6 = \langle 1 \rangle = \langle 5 \rangle$.
- $\langle 2 \rangle = \{0, 2, 4\} = \langle 4 \rangle \cong C_3$.
- $\langle 3 \rangle = \{0, 3\} \cong C_2$.

♢

Example. We have already seen in a previous example what happens. The cyclic subgroups are

- $\langle 1 \rangle = \{\mathrm{id}\} = C_1$.
- $\langle (1,2) \rangle = \{\mathrm{id}, \langle (1,2) \rangle\} = C_2$
- $\langle (1,3) \rangle = \{\mathrm{id}, \langle (1,3) \rangle\} = C_2$
- $\langle (2,3) \rangle = \{\mathrm{id}, \langle (2,3) \rangle\} = C_2$
- $\langle (1,2,3) \rangle = \{\mathrm{id}, (1,2,3), (1,3,2) \rangle\} = C_3$

♢

Proposition 4.1.2

Let p be a prime number, and G be a group of order p. Then G is cyclic,

$$G \cong C_p$$

Proof. Let G be a group of order p.
Since p is prime, G has at least two elements. Thus, there exists $g \in G$ with $g \neq e$.
Since G is finite, g must have a finite order m. Thus,

$$C_m = \{1, g, g^2, \dots, g^{m-1}\} \subseteq G$$

Let $x \in G$ and multiply by g successively by the left.

$$x \xrightarrow{g} gx \xrightarrow{g} g^2x \xrightarrow{g} \cdots \xrightarrow{g} g^{m-1}x \xrightarrow{g} g^m x = x$$

There is no repetition earlier than m, since otherwise $g^i x = g^j x$ for some $0 \leq i < j \leq m-1$, so $g^i = g^j$ (since g has order m), which is a contradiction.
Doing this, we see that G decomposes into cycles of size m. There must be a finite number of cycles, say k.
Thus, $|G| = km$, so $p = km$. Since p is prime, $k = 1$ or $m = 1$.
However, $m \neq 1$ since $g \neq e$. Thus, $k = 1$, so $m = p$ and $G = C_p$. ■

Let us rephrase a step. Let $x \in G$, and multiply x vy every element of C_m.
Doing that we have

- G a group
- H a subgroup of G of order m.
- $x \in G$ an element.

Multiply every element of H by x,

Example. Consider $S_3 = \{\mathrm{id}, (1,2), (1,3), (2,3), (1,2,3), (1,3,2)\}$.
Let $H = \{\mathrm{id}, (1,2)\}$.

- $H(2,3) = \{1(2,3), (1,2)(2,3)\} = \{(2,3), (1,2,3)\}$
- $H(1,3) = \{1(1,3), (1,2)(1,3)\} = \{(1,3), (1,3,2)\}$

These two sets are called the **right cosets** of H in G. ♢

Definition 4.1.3 Coset

Given a group G and a subgroup H, we define a **coset** of H in G as a set of the form

$$Hx = \{hx \mid h \in H\} \qquad \text{(right coset)}$$
$$xH = \{xh \mid h \in H\} \qquad \text{(left coset)}$$

We denote by

- $H\backslash G$ the set of right cosets of H in G, and
- G/H the set of left cosets of H in G.

Proposition 4.1.3

Let G be a group and h be a subgroup of G. Then

1. All cosets of H in G have the cardinality of H.
2. All left cosets are disjoint, and so are all right cosets.

Proof. We prove the two statements.

1. Multiplying by x is a bijection.
2. Suppose $xH \cap yH \neq \varnothing$.
   Then there exists $z \in xH \cap yH$, that is, $z = xh_1 = yh_2$ for some $h_1, h_2 \in H$.
   $$y^{-1}xh^1{h_1}^{-1} = y^{-1}yh_2{h_1}^{-1}$$
   $$y^{-1}x = h_2{h_1}^{-1} \in H$$
   Then, $y^{-1}x = h$ for some $h \in H$, so $x = yh \in yH$.
   But then for $x\tilde{h} \in xH$, $x\tilde{h} = (yh)\tilde{h}$
   $$= y(h\tilde{h}) \in yH$$
   That is, $xH \subseteq yH$. Similarly, $yH \subseteq xH$, so $xH = yH$.

■

Theorem 4.1.1 Langrange's Theorem

Let G be a finite group and H be a subgroup of G. Then

$$|G| = |H| \text{ divides } |G|$$

Proof. G is a disjoint union of cosets of H in G.
Say there are k cosets. Then

$$|G| = k|H| \implies H \mid G$$

■

Corollary 4.1.1 Corollary of Proposition

Let $H \leq G$ be a subgroup of a finite group G. Then

1. $xH = yH$ if and only if $y^{-1}x \in H$.
2. $Hx = Hy$ if and only if $xy^{-1} \in H$.

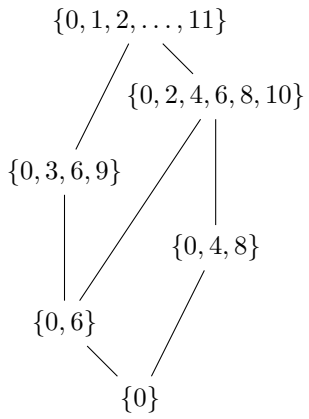
Example. C_n has order N. n has certain divisors, and C_n has a generator g:

$$C_n = \{1, g, g^2, \ldots, g^{n-1}\}$$

Consider when $n = 12$.
$C_n = \mathbb{Z}/12\mathbb{Z} = \{0, 1, 2, \ldots, 11\}$
$12 = 4 \times 3$, so the devisors are

1	$\{0\}$
2	$\{0, 6\}$
3	$\{0, 4, 8\}$
4	$\{0, 3, 6, 9\}$
6	$\{0, 2, 4, 6, 8, 10\}$
12	$\{0, 1, 2, \ldots, 11\}$

$C_n$has exactly one subgroup of each order dividing n.
We can construct a subgroup map.



This is called the **Hasse diagram** of the subgroup lattice of C_{12}. ♢

CHAPTER

5 ISOMORPHIC THEOREMS

5.1 Normal Subgroups

Definition 5.1.1 Normal Subgroup

Let G be a group and N be a subgroup. We say N is a **normal subgroup** of G, denoted $N \triangleleft G$, if

$$\forall g \in G, gN = Ng.$$

Equivalently, if $gNg^{-1} = N$.

Definition 5.1.2 Simple Group

A group G is **simple** if it has no nontrivial normal subgroups.

Example. Kernels of group homomorphisms are normal subgroups.

Proof. Let $x \in \ker(\varphi)$ for some homomorphism $\varphi : G \to H$.
Then, $\varphi(gxg^{-1}) = \varphi(g)\varphi(x)\varphi(g)^{-1} = \varphi(g)e\varphi(g)^{-1} = e$.
Therefore, $gxg^{-1} \in \ker(\varphi)$. ■

♢

It is important to note that some group are normal under one group but not under another.

Example. The alternating group, A_n, is normal in the symmetric group, S_n.
This is because A_n is the kernel of the sign homomorphism, which is a normal subgroup by the previous example.

For example, consider S_3 and A_3.

$$S_3 = \{e, (12), (13), (23), (123), (132)\}, \quad A_3 = \{e, (123), (132)\}.$$

We have $(13)A_3(13) = \{(13)e(13), (13)(123)(13), (13)(132)(13)\} = \{e, (132), (123)\} = A_3$. ♢

5.2 Isomorphism Theorem

Definition 5.2.1 Quotient Group

Let G be a group and N a normal subgroup. Then, we can define the **quotient group** G/N as the set of left cosets of N in G with the operation

$$(gN)(hN) := (gh)N.$$

Theorem 5.2.1

G/N is a group if and only if $N \triangleleft G$.

Example. A_n is normal in S_n, so S_n/A_n is a group.
A_n has 2 cosets: itself, and the set of all odd permutations. Therefore, $S_n/A_n \cong \mathbb{Z}_2$.

	A_n	$(12)A_n$
A_n	A_n	$(12)A_n$
$(12)A_n$	$(12)A_n$	A_n

$\cong$

	0	1
0	0	1
1	1	0

We have $S_n/A_n \cong \mathbb{Z}/2\mathbb{Z} = \{0, 1\} = \{-1, 1\}$.
Moreover, since $\text{sgn} : S_n \to \{-1, 1\}$, we see $S_n/\ker(\text{sgn}) \cong \text{Im}(\text{sgn})$. ♢

Theorem 5.2.2 The First Isomorphism Theorem

Let G be a group, and $\varphi : G \to H$ be an homomorphism. Then,

$$G/\ker(\varphi) \cong \text{Im}(\varphi).$$

and the isomorphism is given by

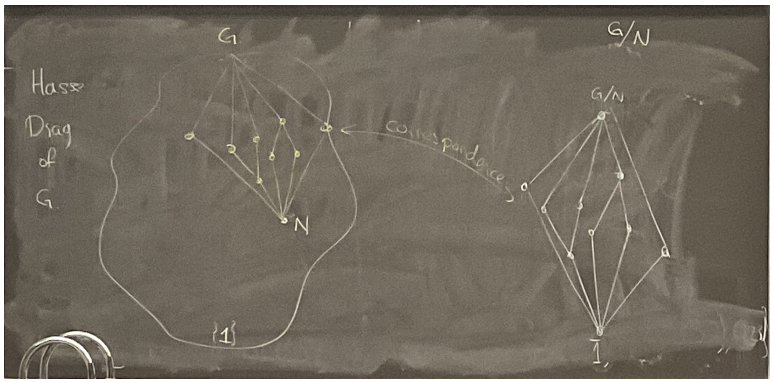
$$\begin{array}{ccc} G/\ker(\varphi) & \to & \text{Im}(\varphi) \\ g\ker(\varphi) & \mapsto & \varphi(g) \end{array}$$

Theorem 5.2.3 The Correspondence Theorem

Let G be a group, and $N \triangleleft G$. Then, there is a correspondence between the set of subgroups

of G containing N and the set of subgroups of G/N.

$$\begin{array}{ccc} \{H \leq G \mid N \subseteq H \subseteq G\} & \longleftrightarrow & \{K \leq G/N\} \\ H & \longleftrightarrow & H/N \end{array}$$



The first isomorphism theorem tells us how to reduce the complexity of the group, and the correspondence theorem tells us that we do not loose any information when we do so.

Proposition 5.2.1

Let G be a group, and H a subgroup. Then H is normal in G if any only if there exists some homomorphism $\varphi : G \to K$ to some group K such that $H = \ker(\varphi)$.

Remark

Sometimes, it is difficult to prove that a subgroup is normal directly. However, if we can find a homomorphism with the subgroup as its kernel, then we can conclude that the subgroup is normal.

Definition 5.2.2 Index

Let H be a subgroup of G. The cardinality of G/H is called the **index** of H in G, denoted $[G : H]$.

Informally, the index of a subgroup is the number of cosets of the subgroup in the group.

Theorem 5.2.4

Let G be a group and $H \leq G$ of index 2. Then, H is normal in G.

We will construct a homomorphism $\varphi : G \to \mathbb{Z}_2$ with $H = \ker(\varphi)$, and thus $H \triangleleft G$.

Remark

We often construct the homomorphism by manifesting some property of the subgroup.

Proof. Since $[G : H] = 2$, we have $G = H \sqcup g_0 H$ for some $g_0 \in G \setminus H$.
Define a function

$$phi : G \to \{1, -1\}$$

by

$$\varphi(g) = \begin{cases} 1 & g \in H \\ -1 & g \in g_0 H \end{cases}$$

We claim that φ is a homomorphism. That means to prove $\varphi(gh) = \varphi(g)\varphi(h)$ for all $g, h \in G$.
In words, this means

- $g, h \in H$ implies $gh \in H$

  This follows from the fact that H is a subgroup.

- $g, h \notin H$ implies $gh \in H$

- $g \in H$ and $h \notin H$ implies $gh \notin H$

  If $g \in H$ and $h \notin H$, then $g \in H$ and $h \in g_0 H$.

  This means $\exists t \in H$ s.t. $h = g_0 t$.

  Suppose for contradiction that $gh = g g_0 t \in H$.

  Then, $g_0 = g^{-1}(gh)t^{-1} \in H$, which is a contradiction.

We conclude that φ is indeed a homomorphism.
By definition,

$$\ker(\varphi) = \{g \in G \mid \varphi(g) = 1\} = \{g \in G \mid g \in H\} = H.$$

Therefore, H is normal in G. ■

Example. These are some examples of normal subgroups we have seen before.

1. Let D_n be the dihedral group generated by R and S.
   $|D_n| = 2n$.
   $\{1, R, \ldots, R^{n-1}\} \cong C_n$ is a subgroup of index 2, $[D_n : C_n] = 2$.
   Thus, $\{1, R, \ldots, R^{n-1}\} \triangleleft D_n$.

2. Let $\mathcal{R}$ be the group generated by Rubik's cube of $2 \times 2 \times 1$.
   $|\mathcal{R}| = 48$.
   V_1, V_2, H_1, H_2 is a subgroup that generates S_4, so $[\mathcal{R} : S_4] = 2$.
   Thus, $S_4 \triangleleft \mathcal{R}$.

♢

Theorem 5.2.5

Let p be a prime number, and G be a group of order p^2. Then, G is isomorphic to

$$C_{p^2} \quad \text{or} \quad C_p \times C_p.$$

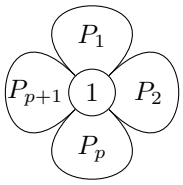
Proof. If G is cyclic, then $G \cong C_{p^2}$.
Suppose G is not cyclic.
Let $x \in G$. Since $|x|$ divides $|G| = p^2$ by Lagrange Theorem, we have $|x| \in \{1, p, p^2\}$.
$|x| = 1$ iff $x = e$, and $|x| \neq p^2$ since G is not cyclic.
Every non-identity element must have has order p.

We count the number of C_p's in G.
The only intersections two of these C_p's can have is the identity, $\{e\}$, since p is prime.
The count is as follows:

$$(\text{number of } C_p) \times (p-1) + 1 = p^2.$$

The number of C_p's is

$$\frac{p^2-1}{p-1} = p+1.$$



Each of these is a cyclic group of order p.
Take $g \in G$, P_i the cyclic group generated by g.

$$gP_ig^{-1} = P_j$$

for some cyclic group P_j.
Let us call $\Phi(g) \in S_{p+1}$ such that

$$gP_ig^{-1} = P_{\Phi(g)(i)}.$$

In this way we have created a map

$$\Phi : G \to S_{p+1}.$$

We claim that Φ is a homomorphism.
Pick $xy \in G$, $(xy)P_i(xy)^{-1} = x(yP_iy^{-1})x^{-1}$
$= xP_{\Phi(y)(i)}x^{-1}$
$= P_{\Phi(x)(\Phi(y)(i))}$.
Meanwhile, $(xy)P_i(xy)^{-1} = P_{\Phi(xy)(i)}$, so $\Phi(xy)(i) = \Phi(x)(\Phi(y)(i))$ for all i.
Therefore, $\Phi(xy) = \Phi(x) \circ \Phi(y)$.

Thus, $\Phi : G \to S_{p+1}$ must satisfy

$$p^2 = |\ker(\Phi)| \cdot |\mathrm{Im}(\Phi)|.$$

If $\ker(\Phi) = \{e\}$, then $|\mathrm{Im}(\Phi)| = p^2$.
This cannot happen, since p^2 is not a divisor of $(p+1)!$, the order of S_{p+1}.
This is a violation of Lagrange's Theorem.
Then, the kernel of Φ is not trivial.

There are elements $x \neq e$ such that

$$xP_ix^{-1} = P_i \quad \text{for all } i.$$

Suppose P_i does not contain x, and consider y a generator of P_i.
Then, $xyx^{-1} = y^n$ for some n.

$$y^{2n} = (xyx^{-1})(xyx^{-1}) = xy^2x^{-1}$$

Continuing like this,

$$xy^kx^{-1} = y^{kn}$$

The powers of x, $\{1, x, x^2, \ldots, x^{p-1}\}$, move the elements of P_i as follows:

$$\begin{aligned} x^2yx^{-2} &= x(xyx^{-1})x^{-1} \\ &= xy^nx^{-1} \\ &= (xyx^{-1})^n \\ &= (y^n)^n \\ &= y^{n^2}. \end{aligned}$$

Continuing like this,

$$x^kyx^{-k} = y^{n^k}.$$

Pick $k = p-1$, we know that $x^{p-1} = x^{-1}$, so

$$x^{-1}yx = y^{n^{p-1}} = y$$

by Fermat's Little Theorem.

Theorem 5.2.6 Fermat's Little Theorem

Let p be a prime number, and a be an integer not divisible by p. Then,

$$a^{p-1} \equiv 1 \mod p.$$

This allows us to conclude the following face:

$$\exists x, y \in G \text{ of order } p \text{ that commute.}$$

Define

$$\begin{array}{rccc} \Psi : & \mathbb{Z}/p\mathbb{Z} & \times & \mathbb{Z}/p\mathbb{Z} \to G \\ & (m, n) & \mapsto & x^my^n \end{array}$$

Claim. Φ is an isomorphism.

- **Injectivity**
  $x^m y^n = 1 \implies x^m = y^{-n} \in P_i n P_j = \{e\}$, where $x \in P_i$ and $y \in P_j$.
- **Surjectivity**
  Let $g \in G$. Then, $g = x^m y^n$ for some $m, n \in \mathbb{Z}/p\mathbb{Z}$.
- **Homomorphism**
$$\begin{aligned}\Psi(m_1 + m_2, n_1 + n_2) &= x^{m_1+m_2} y^{n_1+n_2} \\ &= x^{m_1} x^{m_2} y^{n_1} y^{n_2} \\ &= x^{m_1} y^{n_1} x^{m_2} y^{n_2} \\ &= \Psi(m_1, n_1)\Psi(m_2, n_2)\end{aligned}$$

This completes the proof. ■

5.2.1 Hasse Diagram of Groups

Consider the Hasse diagram of D_6. There are 2 elements that generate everything, R and S. They satisfy $\begin{cases} R^6 = e \\ S^2 = e \\ SRS = R^5 \end{cases}$
The elements are

- e, R, R^2, R^3, R^4, R^5
- $S, SR, SR^2, SR^3, SR^4, SR^5$

To build the Hasse diagram, we need the divisors of $|D_6| = 12$. Hence, we have

$$1, 2, 3, 4, 6, 12,$$

same as C_{12}. However, since D_6 is not cyclic, we do not know if the subgroups of D_6 are cyclic.

Cyclic Subgroups of D_6

WED FEB 7, 2024

Hasse Diagrams of Groups

We have discussed before what are the Hasse Diagrams of Groups but for concreteness let us describe them.

Definition: Let G be a group. A Hasse Diagram (for the subgroups of G) is a drawing that will contain the subgroups of G distributed as follows:

→ It is layered by rows labeled 1, 2, 3, ...

→ The row layered n contains exactly the subgroups of G of order n.

→ If H_1, H_2 are two subgroups of G, there is a line from H_1 to H_2 if and only if $H_1 \leq H_2$ but there is not another subgroup H of G with $H_1 \leq H \leq H_2$.

The Hasse Diagram is an organizational tool that serves to read many properties of a group. However, it is more useful for finite groups where we can actually see it.

Example: We saw in a previous lecture the Hasse Diagram for C_{12}. We reconstruct it here.

By Lagrange's Theorem: if $H \leq C_{12}$ then $|H| \mid |C_{12}|$, that is, $|H|$ divides 12.

The divisors of 12 are

$$1, 2, 3, 4, 6, 12.$$

Thus the Diagram has at most 6 layers. We say at most because potentially there are some of these divisors who are not the order of any subgroup.

We have proven in Homework that in a cyclic group there is exactly one subgroup of each possible order and that they are all cyclic.

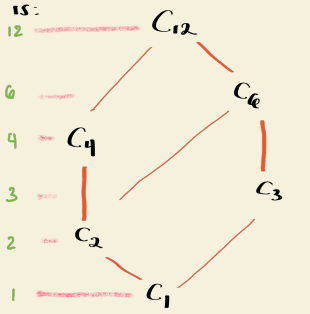
∴ We have $C_1, C_2, C_3, C_4, C_6, C_{12}$ as the subgroups of C_{12}.

Notice that

$$C_m \leq C_n \iff m \mid n$$

Again by Lagrange & the result from Homework. Make sure you agree!!

Thus our Hasse Diagram of C_{12} is:



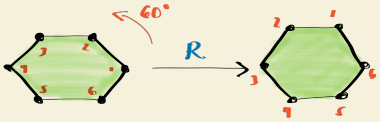
Notice we can say who is each subgroup:

$C_{12} = \{0, 1, 2, \ldots, 11\}$
$C_6 = \{0, 2, 4, 6, 8, 10\}$
$C_4 = \{0, 3, 6, 9\}$
$C_3 = \{0, 4, 8\}$
$C_2 = \{0, 6\}$
$C_1 = \{0\}$

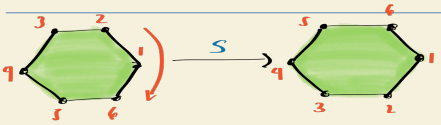
The shaded element is a generator.

Our task in these notes is to build the Hasse Diagram of D_6, i.e. the dyhedral group associated to the hexagon.

You studied this group on homework 1. Let us just fix the two generators:



Rotation counterclockwise by 60° is called R.



Reflection on the x-axis is called S.

You have proven in homework that all elements of D_{12} are:

$$1, R, R^2, R^3, R^4, R^5, S, SR, SR^2, SR^3, SR^4, SR^5$$

and that $R^6 = 1$, $S^2 = 1$, $SRS = R^5$.

To build the Hasse Diagram we need the divisors of $|D_6| = 12$. Hence, we have they are

$$1, 2, 3, 4, 6, 12$$

The same as for C_{12} but now this is not cyclic so we don't know immediately what the subgroups are!

First task: What cyclic subgroups are there in D_6?

The easiest subgroups to find are the cyclic groups because they correspond to the order of elements. Hence, we can simply see the elements.

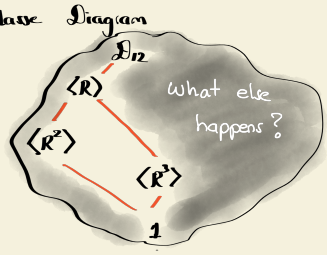
There are two types of elements: those with an S and those without an S.

Those without are $1, R, R^2, R^3, R^4, R^5$ which are the powers of R and form a C_6 generated by R.

Thus we know everything of these elements:

element	1	R	R^2	R^3	R^4	R^5
order	1	6	3	2	3	6

This subgroup alone contributes like this to the Hasse Diagram



We now check what happens with the elements with an S:

$$S, SR, SR^2, SR^3, SR^4, SR^5$$

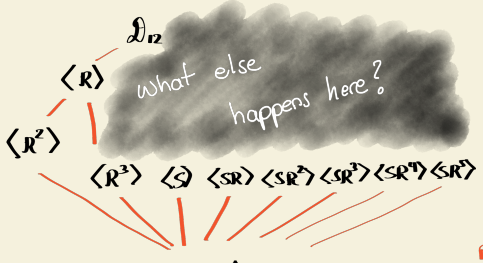
We claim all of them have order 2:

- $S^2 = 1$ we already knew.
- $SR \cdot SR = R^5 R = R^6 = 1$
- $SR^2 \cdot SR^2 = R^{10} R^2 = R^{12} = 1$
- $SR^3 \cdot SR^3 = R^{15} R^3 = R^{18} = 1$
- $SR^4 \cdot SR^4 = R^{20} R^4 = R^{24} = 1$
- $SR^5 \cdot SR^5 = R^{25} R^5 = R^{30} = 1$

we used $SR^k S = (SRS)^k = (R^5)^k = R^{5k}$

↑ conjugation by S!!

Thus each of them produces different cyclic groups of order 2. So we have



We have now found all cyclic subgroups. Also for prime orders, since the only groups of prime order are cyclic, we have found all possible subgroups of that order.

Order of Subgroup	Status
12	Only D_6; ALL FOUND
6	$\langle R \rangle$; Maybe non-cyclic missing
4	NONE FOUND YET
3	ALL FOUND, ONLY 1: $\langle R^2 \rangle$
2	ALL FOUND; 7 in total
1	ALL FOUND; only $\{1\}$

Perfect!

Second task: Are there normal subgroups?

① → Those of order 6 are normal because their index is 2.

② → The one of order 3 is normal because it is unique. Indeed,

$$g \langle R^2 \rangle g^{-1}$$

must be another subgroup of order 3... but there is no other! Thus $g \langle R^2 \rangle g^{-1} = \langle R^2 \rangle$ ↑ For all g, so normal!!

WED FEB 7, 2024

How do I use this? Well, it changes group by group but let us see some ideas.

→ Let $H \leq D_6$ be of order 6.

∴ H is normal in D_6 and thus there must exist an homomorphism

$$\phi: D_6 \longrightarrow \{1,-1\}$$

(This is the image because the index is 2)

with $\ker \phi = H$.

We don't know ϕ explicitly but we know it exists because of normality.

WED FEB 7, 2024

Now let $x \in D_6$ with order m. Then

$$x^m = 1.$$

Take ϕ:

$$\phi(x)^m = 1$$

If m is odd then $\phi(x) = 1$!!

We conclude: all elements of odd order are in the kernel of ϕ!!

That is, all elements of odd order are in H.

WED FEB 7, 2024

But the elements of odd order are exactly

$$\{1, R^2, R^4\} = \langle R^2 \rangle$$

which was the only subgroup of order 3 and thus normal.

Thus we have proven: let $H \leq D_6$ be of order 6. Then

$$\langle R^2 \rangle \leq H \leq D_6$$

(normal in D_6!!)

WED FEB 7, 2024

So now we TAKE THE QUOTIENT

(without fear!! Only by losing fear of quotients can we move on!!)

Quotienting by $\langle R^2 \rangle$ means making "R^2" trivial.

So our new words are

1	R	R^2	R^3	R^4	R^5	S	SR	SR^2	SR^3	SR^4	SR^5
$\bar{1}$	$\bar{R}$	$\bar{1}$	$\bar{R}$	$\bar{1}$	$\bar{R}$	$\bar{S}$	$\bar{SR}$	$\bar{S}$	$\bar{SR}$	$\bar{S}$	$\bar{SR}$

And the new elements are $1, \bar{R}, \bar{S}, \bar{SR}$.

The bar means "coset"

WED FEB 7, 2024

In the table we are seeing the cosets of $\{1, R^2, R^4\}$:

1	R	R^2	R^3	R^4	R^5	S	SR	SR^2	SR^3	SR^4	SR^5
$\bar{1}$	$\bar{R}$	$\bar{1}$	$\bar{R}$	$\bar{1}$	$\bar{R}$	$\bar{S}$	$\bar{SR}$	$\bar{S}$	$\bar{SR}$	$\bar{S}$	$\bar{SR}$

The bar means "the coset that it represents" and the same shaded elements form a coset.

$\bar{1} = \{1, R^2, R^4\}$

$\bar{R} = R\{1, R^2, R^4\}$

$\bar{S} = S\{1, R^2, R^4\}$

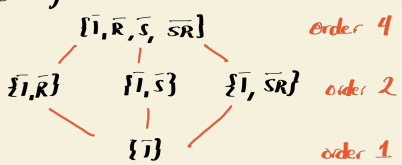
$\bar{SR} = SR\{1, R^2, R^4\}$

×	$\bar{1}$	$\bar{R}$	$\bar{S}$	$\bar{SR}$
$\bar{1}$	$\bar{1}$	$\bar{R}$	$\bar{S}$	$\bar{SR}$
$\bar{R}$	$\bar{R}$	$\bar{1}$	$\bar{SR}$	$\bar{S}$
$\bar{S}$	$\bar{S}$	$\bar{SR}$	$\bar{1}$	$\bar{R}$
$\bar{SR}$	$\bar{SR}$	$\bar{S}$	$\bar{R}$	$\bar{1}$

Multiplication table of $C_2 \times C_2$!!

WED FEB 7, 2024

Its Hasse Diagram is



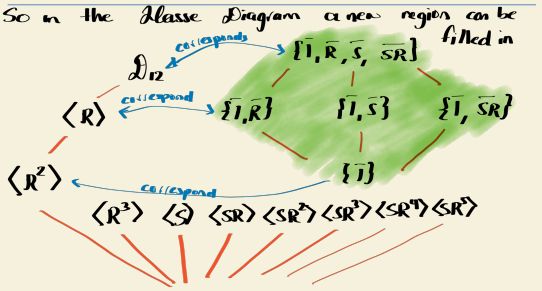
We now invoke the correspondence theorem which states that the subgroups

$$\langle R^2 \rangle \leq H \leq D_6$$

organize themselves as a copy of the Hasse Diagram of $D_6/\langle R^2 \rangle$.

WED FEB 7, 2024

So in the Hasse Diagram a new region can be filled in

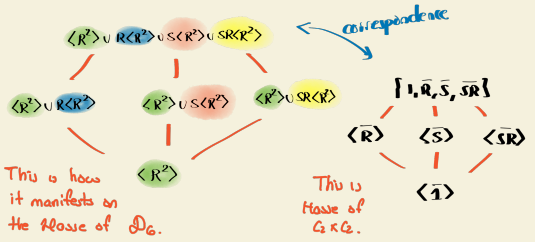


The question is how to describe the new groups we have found by correspondence.

WED FEB 7, 2024

It is by taking preimages:

1	R	R^2	R^3	R^4	R^5	S	SR	SR^2	SR^3	SR^4	SR^5
$\bar{1}$	$\bar{R}$	$\bar{1}$	$\bar{R}$	$\bar{1}$	$\bar{R}$	$\bar{S}$	$\bar{SR}$	$\bar{S}$	$\bar{SR}$	$\bar{S}$	$\bar{SR}$

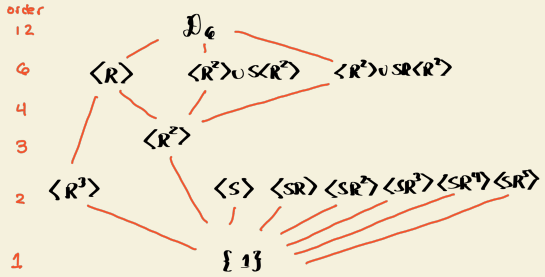


This is how it manifests on the Hasse of D_6.

This is Hasse of $C_2 \times C_2$.

THU FEB 8, 2024

So the Hasse looks like



THU FEB 8, 2024

And our task table looks like:

Order of Subgroup	Status	Total
12	ALL FOUND	1
6	ALL FOUND	3
4	NONE FOUND YET	?
3	ALL FOUND	1
2	ALL FOUND	7
1	ALL	1

Third Task: Find the order 4 subgroups.

They cannot be cyclic because no element of D_6 has order 4.

THU FEB 8, 2024

Hence if we have such subgroups they must be isomorphic to $C_2 \times C_2$, but who are they?

Observation: $C_2 \times C_2$ contains three elements of order 2.

In our case only one element of order 2 does not have an S. Thus if some $H \leq D_6$ has $|H| = 4$ then at least two have an S. Say

$$SR^i,\ SR^j,\quad i \neq j$$

$$\therefore\ H \ni SR^i \cdot SR^j = (SR^i S) R^j = R^{5i+j}$$

(This must be the third element of order 2. But it has no S!! It is R^3.)

THU FEB 8, 2024

We have proven: If $H \leq D_6$ has order 4 then

$$\langle R^3 \rangle \leq H \leq D_6.$$

Thus we might be able to invoke correspondence if $\langle R^3 \rangle$ is normal in D_6.

There are two approaches here:

1. Prove $\langle R^3 \rangle \lhd D_6$ by finding an homomorphism it is a kernel of.
2. Verify the generators of D_6 conjugate $\langle R^3 \rangle$ to itself.

THU FEB 8, 2024

We do the second one: since $\langle R^3 \rangle$ is cyclic it is enough to check the generator. (Make sure you agree!!)

We have

$$R \cdot R^3 \cdot R^{-1} = R^3,$$

$$S R^3 S = R^3.$$

It works, so $\langle R^3 \rangle \lhd D_6$!!

Challenge: Find a nice homomorphism whose kernel is $\langle R^3 \rangle$.

THU FEB 8, 2024

Thus we can do correspondence. So now...

TAKE THE QUOTIENT

1	R	R^2	R^3	R^4	S	SR	SR^2	SR^3	SR^4	SR^5	R^5
1	$\bar{R}$	R^2	1	$\bar{R}$	$\bar{S}$	$\bar{SR}$	SR^2	$\bar{S}$	$\bar{SR}$	SR^3	R^2

We now have 6 cosets and thus the quotient group has 6 elements.

Challenge: who is this group?

THU FEB 8, 2024

This is not cyclic (not even abelian) so it is S_3.

We are looking for subgroups of order 4:

$$\langle R^2 \rangle \leq H \leq D_6$$

and thus

$$\{\bar{1}\} \leq H/\langle R^3 \rangle \leq D_6/\langle R^3 \rangle$$

and

$$\left| H/\langle R^3 \rangle \right| = |H|/\langle R^3 \rangle = 4/2 = 2$$

And viceversa. So subgroups of order 4 correspond to subgroups of the quotient of order 2!!

Let us look for them:

$\bar{1}$ has order 1

$\bar{R}\cdot\bar{R} = \overline{R^2} \neq \bar{1}$

$\overline{R^2}\cdot\overline{R^2} = \overline{R^4} = \bar{R} \neq \bar{1}$

} These actually have order 3!

$\bar{S}\cdot\bar{S} = \overline{S^2} = \bar{1}$

$\overline{SR}\cdot\overline{SR} = \overline{SRSR} = \bar{1}$

$\overline{SR^2}\cdot\overline{SR^2} = \overline{SR^2SR^2} = \bar{1}$

There are three elements of order 2 and the preimages of what they generate are the subgroups of order 4.

Thus the subgroups are

1	R	R^2	R^3	R^4	S	SR	SR^2	SR^3	SR^4	SR^5	R^6
$\bar{1}$	$\bar{R}$	$\bar{R^2}$	$\bar{1}$	$\bar{R}$	$\bar{S}$	$\bar{SR}$	$\overline{SR^2}$	$\bar{S}$	$\bar{SR}$	$\overline{SR^2}$	$\bar{R^2}$

so they are

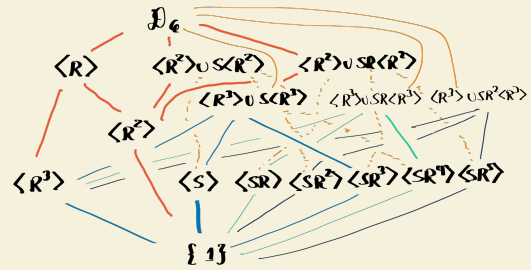
$\bar{S} \longleftrightarrow \{1, R^3, S, SR^3\}$

$\bar{SR} \longleftrightarrow \{1, R^3, SR, SR^4\}$

$\overline{SR^2} \longleftrightarrow \{1, R^3, SR^2, SR^5\}$

Thus we have 3 subgroups of order 4!

The Hasse Diagram looks like:



Slightly convoluted because there are many intersections, but everything is there.

Our final table of subgroups is:

Order of Subgroup	Status	Total
12	ALL FOUND	1
6	ALL FOUND	3
4	ALL FOUND	3
3	ALL FOUND	1
2	ALL FOUND	7
1	ALL FOUND	1

CHAPTER

6 ACTIONS OF GROUPS

6.1 Group Actions

Definition 6.1.1 Action

Let G be a group and X a set. We say G **acts on** X if there is a map

$$\begin{array}{rccc} \cdot : & G \times X & \to & X \\ & (g, x) & \mapsto & g \cdot x \end{array}$$

such that

1. $e \cdot x = x$ for all $x \in X$.
2. $g \cdot (h \cdot x) = (g \cdot h) \cdot x$ for all $g, h \in G$ and $x \in X$.

Associated with an action, there are three important constructions.

Definition 6.1.2 Orbit

Let G act on X. The **orbit** of $x \in X$ is the set

$$\mathcal{O}_x = \{g \cdot x \mid g \in G\}.$$

Definition 6.1.3 Stabilizer

Let G act on X. The **stabilizer** of $x \in X$ is the set

$$Stab_x(G) = \{g \in G \mid g \cdot x = x\}.$$

We can think of a group action as a homomorphism from G to group of bijections of X,

$$G \xrightarrow{\varphi} \sum(X) = \{f : X \to X \mid f \text{ is a bijection}\}.$$

Example. Given a group G we say G acts on itself by conjugation by defining

$$h^g = C_g(h) = ghg^{-1}.$$

This is an action.

- $1 \cdot x = 1 \cdot x \cdot 1^{-1} = x$
- $C_(C_h(k)) = C_g(hkh^{-1}) = ghkh^{-1}g^{-1} = ghk(gh)^{-1} = (gh) \cdot k = C_{gh}(k)$

♢

Definition 6.1.4 Conjugacy Class

The orbit under conjugation is called the **conjugacy class** of G.

Remark

Conjugacy classes is **not a subgroup** of G.

Example. Consider $S_3 = \{e, (12), (13), (23), (123), (132)\}$.

- $(12)1(12)^{-1} = 1$
- $(12)(12)(12)^{-1} = (12)$
- $(12)(13)(12)^{-1} = (23)$
- $(12)(23)(12)^{-1} = (13)$
- $(12)(123)(12)^{-1} = (132)$
- $(12)(132)(12)^{-1} = (123)$
- $(123)1(123)^{-1} = 1$
- $(123)(12)(123)^{-1} = (23)$
- $(123)(13)(123)^{-1} = (12)$
- $(123)(23)(123)^{-1} = (13)$
- $(123)(123)(123)^{-1} = (123)$
- $(123)(132)(123)^{-1} = (132)$

♢

Example. Now consider S_4.

- $(12)1(12)^{-1} = 1$
- $(12)(12)(12)^{-1} = (12)$
- $(12)(13)(12)^{-1} = (23)$
- $(12)(14)(12)^{-1} = (24)$
- $(12)(23)(12)^{-1} = (13)$
- $(12)(24)(12)^{-1} = (14)$
- $(12)(34)(12)^{-1} = (34)$
- $(12)(12)(34)(12)^{-1} = (12)(34)$
- $(12)(13)(24)(12)^{-1} = (14)(23)$
- $(12)(14)(23)(12)^{-1} = (13)(24)$
- $\cdots$

We can see that in both examples, the cycle structure is preserved under conjugation. This brings to a very important theorem. ♢

Theorem 6.1.1

The conjugacy classes of S_n are classified by the cycle structure of the elements.

Example. Consider S_4, it has the following cycle structures:

$$(a)(b)(c)(d), \quad (ab), \quad (ab)(cd), \quad (abc), \quad (abcd);$$

which has

$$1, \quad 6, \quad 3, \quad 8, \quad 6$$

elements, respectively. ♢

Example. Let G be the set of $n \times n$ matrices over $\mathbb{C}$.
If $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is such a 2×2 matrix that is diagonalizable, then that means there is a basis of eigenvectors $\{v_1, v_2\}$.
Then,

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = Q \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} Q^{-1}.$$

where Q is the change of basis matrix from the standard basis to the basis of eigenvectors.
That is,

$$Q = (v_1, v_2) = \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix}.$$

We see in generalized eigenvectors that we can either conjugate the matrix to Jordan form $\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$, or we can conjugate the matrix to a block diagonal matrix $\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$.

Consider if we want to answer if $\begin{pmatrix} 1 & 7 \\ 2 & 3 \end{pmatrix}$ and $\begin{pmatrix} 7 & 5 \\ 1 & i \end{pmatrix}$ conjugate, that is, if there exists a matrix Q such that

$$\begin{pmatrix} 1 & 7 \\ 2 & 3 \end{pmatrix} = Q \begin{pmatrix} 7 & 5 \\ 1 & i \end{pmatrix} Q^{-1}.$$

A naïve approach would be to solve for the eigenvalues of the two matrices, and then solve for the eigenvectors; however, this is not the most efficient way, as calculating the eigenvalues of a matrix is a difficult problem.
We see that the determinant is preserved under conjugation, so the two matrices are not conjugate.
Now consider $\begin{pmatrix} 1 & 7 \\ 3 & 2 \end{pmatrix}$ and $\begin{pmatrix} 1 & 2 \\ 0 & -19 \end{pmatrix}$. They have the same determinant, but are they conjugate?
The answer is no. We need the trace to be preserved as well.
This is because the determinant and the trace are all operations on the eigenvalues of the matrix (the determinant is the product of the eigenvalues, and the trace is the sum), and the eigenvalues are preserved under conjugation.

Remark Characteristic Polynomial

Consider an $n \times n$ matrix A. The characteristic polynomial of A, denoted by $p_A(t)$, is the polynomial defined by

$$p_A(t) = \det(tI - A).$$

where I denotes the $n \times n$ identity matrix.

Thus, we need to check the characteristic polynomial of the two matrices to see if they are conjugate. The coefficients of the characteristic polynomial are precisely the invariants of the matrix under conjugation.
The conjugacy classes is a replacement of eigenvalues. ♢

6.2 Orbit-Stabilizer Theorem

Theorem 6.2.1 Cauchy's Theorem

Let G be a finite group and p be a prime number. If p divides the order of G, then there exists an element $x \in G$ of order p.

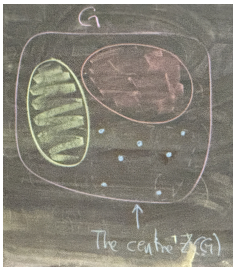
Example. Let $n = 15$, and $|D_{15}| = 30 = 2 \cdot 3 \cdot 5$.
Then, by Cauchy's Theorem, there exists an element of order 2, 3, and 5 in D_{15}. ♢

Example. Consider S_7. We have $|S_7| = 7! = 2^4 \cdot 3^2 \cdot 5 \cdot 7$.
Then, by Cauchy's Theorem, there exists an element of order 2, 3, 5, and 7 in S_7. ♢

Example. Consider $\mathcal{R}$. We have $|\mathcal{R}| = 48 = 2^4 \cdot 3$.
Then, by Cauchy's Theorem, there exists an element of order 2 and 3 in $\mathcal{R}$. ♢

There are two observations to make about conjugation,

- If $x \in G$ is fixed by the conjugation, that is, $gxg^{-1} = x$ for all $g \in G$, then x is in the center of G.
- All conjugacy classes are disjoint.



From this we get

$$|G| = |Z(G)| + \sum_{\substack{x \notin Z(G) \\ \text{without repeating conjugacy classes}}} |Conj(x)|.$$

This equation is called the **class equation**.

Theorem 6.2.2 Orbit-Stabilizer Theorem

Let G be a finite group acting on a set X. Then, for any $x \in X$,

$$|G| = |\mathcal{O}_x| \cdot |Stab_x(G)|.$$

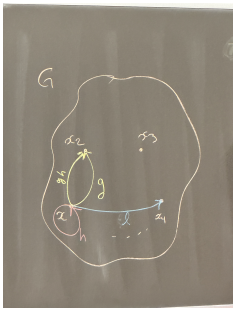
It can also be written as

$$G/Stab_x(G) \cong \mathcal{O}_x.$$

- $\mathcal{O}_x$ are all elements of X I can reach from x.
- $Stab_x(G)$ are all elements of G that fix x (i.e. $g \cdot x = x$).

Proof. Let $x \in X$ and $\mathcal{O}_x = \{h \cdot x \mid g \in G\} = \{x_1, x_2, \ldots, x_k\}$.
We make a table

	Elements g s.t. $g \cdot x = x_i$
$x = x_1$	$g \cdot x = x$ I have written the elements of $Stab_x(G)$
x_2	$g \cdot x = x_2$
$\vdots$	$\vdots$
x_k	$g \cdot x = x_k$



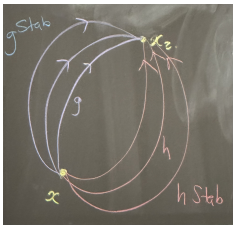
We can write

$$gh$$

with $h \in Stab_x(G)$ and $g \cdot x = x_2$ and get

$$gx \cdot x = g \cdot (h \cdot x) = g \cdot x = x_2$$

With this we see that $gStab_x(G)$ satisfies to only one element of $\mathcal{O}_x$. This is a coset of $Stab_x(G)$. However, there may be an x_i who produces more than one cosets, so we cannot make the claim yet.



If a row contains g and h, then they must be in the same coset of $Stab_x(G)$.
Indeed, $g^{-1} \cdot (h \cdot x) = g^{-1} \cdot x_2 = x$, thus $g^{-1}h \in Stab_x(G)$.
This is the criteria for two elements to be in the same coset. Thus g and h are in the same coset.
Then $|G| = \underset{Numberofrows}{|\mathcal{O}_x|} \cdot \underset{Numberofelementsineachrow}{|Stab_x(G)|}$. ■

Example. Consider the proof for Cauchy's Theorem.

Proof. Suppose we know the result for two cases:

1. If H is abelian
2. If $|H| < |G|$

Let us use the class equation

$$|G| = |Z(G)| + \sum_{\substack{x \notin Z(G) \\ \text{without repeating conjugacy classes}}} |Conj(x)|.$$

We know $p \mid |G|$. We have two possibilities:

1. $p \mid |Z(G)|$

   In this case, we are done.

2. $p \not| |Z(G)|$

   We consider the conjugacy classes.

   Known that $|G| = |Conj(x)| \cdot |Stab_x(G)|$ by the Orbit-Stabilizer Theorem, and $|Stab_x(G)| < |G|$, so we fall under the second case ($|H| < |G|$).

   The only case remaining is if $p \mid |Conj(G)|$ and $p \not| |Z(G)|$.

   However, this is not possible, as $|Conj(G)| = |G| - |Z(G)|$, and $p \not| |Z(G)|$.

■

♢

6.3 Sylow Theorems

6.3.1 First Sylow Theorem

Definition 6.3.1 p-Group

If G is a group and $p \mid |G|$ for some prime p, then we say $H \leq G$ is a **p-group** if $|H| = p^k$ for some $k \geq 0$.

Example. If $|G| = 20$ and H is a 2-group of G, then $k \leq 2$.
When $k = 0$, $|H| = 1$, and when $k = 1$, $|H| = 2$. ♢

Definition 6.3.2 p-Sylow Subgroup

Let G be a group and p be a prime number. A **p-Sylow subgroup** of G is a subgroup $H \leq G$ such that

1. $|H| = p^k$ for some $k \geq 0$ (i.e. H is a p-group).
2. For all p-groups N of G, we cannot have $H \lneq N$ ($H \leq N$ and $H \neq N$) [a].

   In other words, a p-Sylow subgroup is a maximal p-group.

[a] A p-Sylow group cannot be strictly inside another p-group.

Example. Consider $G = \mathbb{Z}/n\mathbb{Z}$. We have $|G| = n$.
Notice that the group generated by $n/p^a \in G$ has size p^a.
This is a p-Sylow subgroup of G. ♢

Example. In S_3 the we have

- 2-groups $\{1, (12)\}$, $\{1, (13)\}$, and $\{1, (23)\}$
- 2-Sylow subgroup $\{1, (123), (132)\}$

♢

Theorem 6.3.1 The First Sylow Theorem

If $|G| = p^a \cdot m$ where $p \not| m$, then any p-Sylo group has size p^a.

Proof. Consider the collection $X = \{A \subset G \mid |A| = p^a\}$.
Consider the action

$$\begin{array}{ccc} G \times X & \to & X \\ (g, A) & \mapsto & \{g \cdot a, a \in A\} \end{array}$$

We want to find an element $A \in X$ such that $|Stab_G(A)| = p^a$.
We want to use the orbit stabilizer theorem to show that necessarily there is such collection A.

$$|G| = |G \cdot A| \cdot |Stab_G(A)|.$$

We have to show that there is an A such that $|G \cdot A| = m$.
Because $G \times X \to X$ is an action and orbits from a partition of X, we have

$$|X| = \sum_{\text{orbits}} |\mathcal{O}_x| = \sum_{\text{orbits}} |G \cdot A|.$$

By the definition of X, we have

$$\begin{aligned}|X| &= \frac{(mp^a)!}{(p^a)!(mp^a-p^a)!} \\ &= \frac{mp^a(mp^a-1)(mp^a-2)\cdots(mp^a-p^a+1)}{p^a(p^a-1)(p^a-2)\cdots 1} \\ &= m\cdot\left[\frac{(mp^a-1)(mp^a-2)\cdots(mp^a-p^a+1)}{(p^a-1)(p^a-2)\cdots 1}\right] \\ &= m\cdot\binom{mp^a-1}{p^a-1}\end{aligned}$$

which is not a power of p^a, but indeed a power of m.
Thus, there is an element A such that $|G\cdot A|$ has size m.
We have

$$\begin{array}{ccc} m_g\cdot G & \to & G \\ h & \mapsto & gh \end{array} \quad \text{and} \quad \begin{array}{ccc} m_g\cdot X & \to & X \\ A & \mapsto & gA \end{array}$$

This is a bijection.
Thus, all orbits of elements of X have the same size.

Claim (Claim 1)**.** If $A\in X$ than $|G\cdot A| \mid |G|$.

If we can prove claim 1, we have $m \mid |G\cdot A|$.
Thus, $|G\cdot A|\cdot|Stab_G(A)| = |G| = p^a\cdot m$.
Since $|G\cdot A|$ is not divisible by p^a, we have $|Stab_G(A)| = p^a$.
That is, $Stab_G(A)$ is a p-Sylow subgroup of G of the desired size. ■

> **Remark**
> Creating / defining the right actions on the right sets gives us powerful ways of proving statements.

6.3.2 Second and Third Sylow Theorems

Theorem 6.3.2 The Second Sylow Theorem

- If H is a p-subgroup of G, then there is a p-Sylow subgroup $P\le G$ such that $H\le P$.
-
- If P_1, P_2 are two p-Sylow subgroups of G, then there exists $g\in G$ such that $P_1 = gP_2g^{-1}$.

Theorem 6.3.3 The Third Sylow Theorem

Let G be a group and $|G| = p^am$ with $p\not| m$.
Let n_p denote the number of p-Sylow subgroups of G. Then,

- $n_p \mid m$.
- $n_p \equiv 1 \mod p$.

Remark

Consider S_3. We can ask how many 2-Sylow subgroups there are.
By the third Sylow theorem, we must have

- $n_2 \mid 3$
- $n_2 \equiv 1 \mod 2$

Proposition 6.3.1

If $n_p = 1$ for some prime p with $p \mid |G|$, then that p-Sylow group is normal in G.

What happen if P is a p-Sylow subgroup of G, and we conjugate gPg^{-1}?

- It goes to another p-Sylow subgroup.

Thus, if there is only one p-Sylow subgroup, then it is invariant under conjugation, and thus normal.

Example. Consider a group G of size 20.
Let us find the possibilities for n_2 and n_5.

- $n_2 \mid 5 \wedge n_2 \equiv 1 \mod 2 \implies n_2 \in \{1, 5\}$
- $n_2 \mid 4 \wedge n_2 \equiv 1 \mod 5 \implies n_5 \in \{1\}$

We ask if it is possible to rule out $n_2 = 5$. ♢

Example. If $|G| = 2p^a$, then

- $n_2 \mid p^a$ and $n_2 \equiv 1 \mod 2$
- $n_p \mid 2$ and $n_p \equiv 1 \mod p$
  Thus, the only possibility is $n_p = 1$.

Thus, G has a normal subgroup of order p^a. ♢

Remark

Claim. If $|G| = p^a q^b$ with p, q odd primes and $a < q - 1$, then all Sylow subgroups of G are normal.

Proof. Fix p a prime divisor of G.
WTS the number of p-Sylow groups is exactly 1 ($n_p = 1$).
Thus, $n_p \div q^b$ and $n_p \equiv 1 \mod p$.
Is it possible for $q^k \equiv 1 \mod p$?

By Fermat's Little Theorem, $k \equiv 0 \mod q-1$.
Since $a < q-1$, we must only have $k = 0$.
Thus, $n_p = 1$. ■

Part II

Appendices

BIBLIOGRAPHY