

## Midterm Exam

Name: \_\_\_\_\_  
Student ID: \_\_\_\_\_

Solutions

There are **4 problems** that add up to 110 points.  
The total for this Midterm Exam is set to 100 points,  
i.e., there are 10 implicit bonus points.

Exam period: 11:30am to 12:50pm.

(Leave blank! To be filled in by grader.)

Problem	Points	Grader
1	/ 30	
2	/ 20	
3	/ 20	
4	/ 40	
Total:		

1. (30 pts) Consider the optimization problem

$$\begin{aligned} \text{minimize } & f(x_1, x_2) = (x_2 - x_1^2)^2 - x_1^2 \\ \text{subject to } & |x_1| \leq 10, \quad x_2 \in \mathbb{R}. \end{aligned}$$

- (a) (10 pts) Compute both the gradient and the Hessian matrix of  $f$ .
- (b) (10 pts) Determine the stationary points of  $f$  and check whether the stationary points could be (local) minimizers.
- (c) (10 pts) Observing the special structure of the cost functional  $f$ , it is possible to locate the global minimum of  $f$  for the given constrained optimization problem. Find  $x^*$  and also provide the associated optimal cost  $f(x^*)$ .

$$(a) \quad f(x_1, x_2) = x_2^2 - 2x_1^2 x_2 + x_1^4 - x_1^2$$

$$\rightarrow (\nabla f)(x) = \begin{pmatrix} -4x_1 x_2 + 4x_1^3 - 2x_1 \\ 2x_2 - 2x_1^2 \end{pmatrix}$$

$$\rightarrow (Hf)(x) = \begin{pmatrix} -4x_2 + 12x_1^2 - 2 & -4x_1 \\ -4x_1 & 2 \end{pmatrix}$$

(b)  $(\nabla f)(x) = 0 \rightarrow$  solving for  $x$  gives stationary pt

$$\text{from 2nd eqn: } 2x_2 - 2x_1^2 = 0 \Rightarrow x_2 = x_1^2$$

plugging  $x_2 = x_1^2$  into 1st eqn yields

$$-4x_1^3 + 4x_1^3 - 2x_1 = 0 \Rightarrow \underline{x_1 = 0} \Rightarrow \underline{x_2 = x_1^2 = 0}$$

$\rightarrow (0, 0)$  only stationary point

$$(Hf)(0, 0) = \begin{pmatrix} -2 & 0 \\ 0 & 2 \end{pmatrix} \Rightarrow \text{by 2nd order necessary condition, } x^* = (0, 0) \text{ NOT a minimizer!}$$

(c) Goal: keep  $(x_2 - x_1^2)^2$  as zero and  $-x_1^2$  as negative as possible.

2. (20 pts) Consider the function

$$f(x_1, x_2) = \frac{1}{2}(x_1 + x_2^2)^2$$

Let  $x^0 = (0, 1)^\top$  and  $v = (1, -1)^\top$  and consider the iteration  $x^1 = x^0 + \gamma v$ . This problem concerns an exact line search method for  $f$  in the given setting.

- (a) (10 pts) Compute  $(\nabla f)(x^0)$  and verify that  $v$  is a *descent direction* at  $x^0$ .
- (b) (10 pts) Examine  $f(x^0 + \gamma v)$  with  $x^0$  and  $v$  as specified above and show that

$$f(x^0 + \gamma v) = \frac{1}{2} \left( \left( \gamma - \frac{1}{2} \right)^2 + \frac{3}{4} \right)^2.$$

Is there an optimal  $\gamma$  for the exact line search? Provide its value if it does exist.

$$(a) \quad f(x_1, x_2) = \frac{1}{2}(x_1 + x_2^2)^2 = \frac{1}{2}(x_1^2 + 2x_1 x_2^2 + x_2^4)$$

$$(\nabla f)(x) = \begin{pmatrix} x_1 + x_2^2 \\ 2x_1 x_2 + 4x_2^3 \end{pmatrix} \text{ evaluated at } (0, 1) : \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$(\nabla f)(x^0) \cdot v = \begin{pmatrix} 1 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix} = 1 - 4 = -3 < 0$$

$\Rightarrow v$  is a descent direction ✓

$$(b) \quad f(x^0 + \gamma v) = f((0) + (1, -1)) = f\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right) = \frac{1}{2}(1 + (1-1)^2)^2$$

$$= \frac{1}{2}(1 + 1 - 2 + 1)^2 = \frac{1}{2}(\underline{\underline{\gamma^2 - \gamma + 1}})^2$$

Observe:  $(\gamma - \frac{1}{2})^2 + \frac{3}{4} = \gamma^2 - \gamma + \frac{1}{4} + \frac{3}{4} = \underline{\underline{\gamma^2 - \gamma + 1}}$

$\Rightarrow f(x^0 + \gamma v) = \frac{1}{2} \left( \underbrace{(\gamma - \frac{1}{2})^2}_{\geq 0} + \frac{3}{4} \right)^2$

For  $f(x^0 + \gamma v)$  to be as small as possible, we need  $(\gamma - \frac{1}{2})^2 = 0$ , i.e.,  $\underline{\underline{\gamma = \frac{1}{2}}}$ .

3. (20 pts) Consider the convergent sequence given by

$$z_{k+1} = \frac{z_k^2 + 1}{2z_k}.$$

Initializing with  $z_0 > 0$ , results in convergence of the sequence to  $z^* = 1$ . This fact can be assumed as given and does not have to be verified.

Show that the convergence of  $(z_k)$  to  $z^* = 1$  is at a *quadratic* rate.

$$\begin{aligned} \text{Consider: } & \frac{|z_{k+1} - 1|}{(z_k - 1)^2} = \frac{\left| \frac{z_k^2 + 1}{2z_k} - 1 \right|}{(z_k - 1)^2} \\ &= \frac{\left| \frac{z_k^2 + 1 - 2z_k}{2z_k} \right|}{(z_k - 1)^2} \quad \text{recognize as } \frac{(z_k - 1)^2}{(z_k - 1)^2} \\ &= \frac{\frac{(z_k - 1)^2}{2z_k}}{(z_k - 1)^2} \\ &= \frac{1}{2z_k} \xrightarrow{k \rightarrow \infty} \frac{1}{2} \end{aligned}$$

$$\begin{aligned} \text{In summary: } & \limsup_{k \rightarrow \infty} \frac{|z_{k+1} - z^*|}{(z_k - z^*)^2} = \frac{1}{2} \\ \text{i.e. } & p=2 \quad \& \quad \beta = \frac{1}{2} < \infty \end{aligned}$$

→ Quadratic convergence

4. (40 pts: 5 pts each) Determine whether the following statements are TRUE or FALSE. Explanations are not strictly required but could lead to partial credit in cases where the answer is incorrect but the explanation includes relevant and correct lines of thought.

- (a) A local optimizer of a function  $f : \mathbb{R} \rightarrow \mathbb{R}$  is always a global minimizer of an appropriate restriction of  $f$  to a smaller domain  $A \subset R$ , i.e.,  $g : A \rightarrow \mathbb{R}$  defined by  $g(x) = f(x)$  for all  $x \in A \subset R$ , with restricted domain  $A$  suitably chosen.

True

False

- (b) If  $x^* \in \mathbb{R}^n$  is a critical point of a function  $f \in C^2(\mathbb{R}^n, \mathbb{R})$  and  $(Hf)(x^*) \succcurlyeq 0$ , then  $x^*$  is a minimizer of  $f$ .

True

False

- (c) If  $x^* \in \mathbb{R}^n$  is a local minimizer of  $f \in C^2(\mathbb{R}^n, \mathbb{R})$ , then  $(\nabla f)(x^*) = 0$  and  $(Hf)(x^*) \succcurlyeq 0$ .

True

False

- (d) If for all  $v \in \mathbb{R}^n$  it holds that  $(D_v f)(x^*) = 0$ , then  $x^*$  is a critical point.

True

False

- (e) If for all  $v \in \mathbb{R}^n$ , the function  $h_v(t) := f(x^* + tv)$  has a global minimum at  $t = 0$ , then  $x^*$  is a global minimizer of  $f$ .

True

False

- (f) For  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ , if  $\bar{x} = 0$  is a strict global minimizer of  $x \mapsto f(x, 0)$  and  $\bar{y} = 0$  is a strict global minimizer of  $y \mapsto f(0, y)$ , then  $(\bar{x}, \bar{y}) = (0, 0)$  is a minimizer of  $f$ .

True

False

- (g) For a quadratic cost  $f(x) = x^\top Qx$  with  $Q \succcurlyeq 0$ , the origin is a global minimum.

True

False

- (h) For a quadratic cost functional  $f(x) = x^\top Qx$  with  $Q \succcurlyeq 0$ , the fixed-step gradient method with the step-size chosen as in the theorem in the lecture will result in the algorithm to produce a sequence of iterates that converge to a local minimum.

True

False