# PROJECT PROPOSAL

#### **COMPANY NAME**

ABB AUTOMATION and ELECTRIFICATION (Vietnam) Company Limited

#### **CONTACT DETAILS**

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Support URL:

- FlexLoader SC 3000 Extended with deburring and air cleaning YouTube
- FlexLoader Vision for Machine Tending YouTube
- ABB Project Diagram: Lucidchart

#### PROJECT TITLE

Flexible loading station with vision guide

## PROJECT DESCRIPTION

- What is the problem domain?
- Web, android/IOS: HMI Human Machine Interface on Web or App
- Machine Learning: Teaching object recognition
- Cloud, networking: Database after teaching ML
- Embedded systems: Embedded C Language Robot Studio Simulation before real testing on ABB robot system (70-80% of the total process)
- IC design: No need for now
- Robotics: Robotics knowledge e.g., image processing, mechanics, robot movement
- Autonomous Systems, and Automation: Robot Vision and G Code (But we will skip that since we have Robot Studio, just coding embedded C)

#### • Describe the project:

- Objectives
- Context
- External interfaces (Connection)
- GUI (Graphical User Interface) UI

This is applied to load materials into processing machines, materials are lied on the infeed **Conveyor**. This system can be used for many kinds of materials with very quick changeover time **or mixed loading**.

#### **TECHNOLOGY**

What technologies will be used in the project: Languages, Algorithms, DB – Database, IDE – Integrated Development Environment, Design tools/products, Development methodologies, etc.

+ Vision (PC base – Camera + Station is already set up)

- + HMI on Window (WPF Window Presentation Foundation (.NET framework. Before proceeding with this tutorial, you should have a basic understanding of XML, Web Technologies, and HTML.), VB Visual Basic, VS Visual Studio, ... Python Code)
- + ABB robot
- + CNV = Conveyor, sensor, gripper, ... (just know how to the sensor and robots communicate with the others)

#### PROJECT DELIVERABLES

- What are the expected outcomes/deliverables of this project?
- Web application, or mobile application
- Working prototype
- Recommendation engine Part of ML (<u>Lecture 16.2 Recommender Systems</u> | Content Based Recommendations [ Andrew Ng ] YouTube) Not focus now
- etc.
- What we need for now:
- Image processing application on PC
- HMI for easy operation
- Robot-Vision integrated to teach/ change products.

#### **SUCCESS CRITERIA**

Provide a clear, well-defined, quantitative metric that will be used to measure success – e.g., actions/per second, %accuracy, time to complete task, %improvement, etc.

- + Vision can recognize product on CNV conveyer to guide the robot to pick
- + Robot pick and place with a customized program
- + Can change products and re-define pick point on HMI easily
- + System can run mixed products

#### TECHNICAL/PROFESSIONAL SKILLS REQUIRED

Please indicate any specific skills you believe are required for the project

- + Engineering background
- + Mechanical hardware design capable
- + Programming with C/C++ (Embedded Sys)
- + Image processing application-related (OpenCV Python)

### AVAILABLE RESOURCES

Hardware/software/other resources that will be made available for the team Robot, Conveyor.

#### **INTELLECTUAL PROPERTY: So Huu Tri Tue**

IP belongs to the sponsor. A WIL (Work Integrated Learning) agreement will be signed at the start of the project.

Agreed

## OTHER CONSIDERATIONS or INCENTIVES

E.g., Scholarship available/future work available, etc The internship is available.