

	Ile 1	Ile 2	Ile 3	Ile 4
Ile 1	0	0.3	0.3	0.4
Ile 2	0.3	0	0.4	0.3
Ile 3	0.3	0.4	0	0.3
Ile 4	0.4	0.3	0.3	0

```
In [1]: import random
import matplotlib.pyplot as plt
from collections import defaultdict
import os
import numpy as np
import pandas as pd

# Définition des constantes globales
TAILLE_VECTEUR = 1000
TAILLE_POPULATION = 20
MAX_ITER = 5000
N = 4 # Nombre d'îles
NB_RUNS = 10 # On répète l'expérience X fois

# -----
# Opérateurs de mutation
# -----
def mutation1flip(bits):
    """Mutation qui inverse un seul bit aléatoire."""
    child = bits[:]
    idx = random.randint(0, TAILLE_VECTEUR - 1)
    child[idx] = 1 - child[idx]
    return child

def mutation3flip(bits):
    """Mutation qui inverse trois bits aléatoires distincts."""
    child = bits[:]
    indices = random.sample(range(TAILLE_VECTEUR), 3)
    for idx in indices:
        child[idx] = 1 - child[idx]
    return child

def mutation5flip(bits):
    """Mutation qui inverse cinq bits aléatoires distincts."""
    child = bits[:]
    indices = random.sample(range(TAILLE_VECTEUR), 5)
    for idx in indices:
        child[idx] = 1 - child[idx]
    return child

def mutationBitFlip(bits):
    """Mutation qui inverse chaque bit avec une probabilité de 1/TAILLE_VECTEUR"""
    child = bits[:]
    for i in range(TAILLE_VECTEUR):
        if random.random() < 1 / TAILLE_VECTEUR:
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        child[i] = 1 - child[i]
    return child

# -----
# Classes de base
# -----
class Individu:
    def __init__(self):
        # Initialisation de bits à 0
        self.bits = [0 for _ in range(TAILLE_VECTEUR)]
        self.origin = None
        self.currentIsland = None
        self.upgrade = 0
        self.migrated = False

    def getFitness(self):
        return sum(self.bits)

class Island:
    def __init__(self, id_island, operator, name):
        self.id = id_island
        self.population = [Individu() for _ in range(TAILLE_POPULATION)]
        self.operator = operator # fonction de mutation
        self.name = name

    def getBestElement(self):
        if not self.population:
            return None
        return max(self.population, key=lambda x: x.getFitness())

    def getBestFitness(self):
        best = self.getBestElement()
        if best:
            return best.getFitness()
        return 0

    def local_search(self, archipel):
        """
        Local Search simple : on applique la mutation sur chaque individu.
        Si l'enfant est meilleur, on remplace le parent.
        On met à jour l'upgrade de chaque individu.

        IMPORTANT:
        - On incrémente archipel.nb_evals à chaque enfant évalué (child_fit
        """
        for ind in self.population:
            fitness_before = ind.getFitness()
            child_bits = self.operator(ind.bits)
            child_fitness = sum(child_bits)
            # On a évalué un nouvel individu => incrémenter nb_evals
            archipel.nb_evals += 1

            if child_fitness > fitness_before:
                ind.bits = child_bits
                ind.upgrade = ind.getFitness() - fitness_before

```

```
class Archipel:  
    def __init__(self):  
        self.islands = [  
            Island(0, mutation1flip, "Ile 1flip"),  
            Island(1, mutation3flip, "Ile 3flip"),  
            Island(2, mutation5flip, "Ile 5flip"),  
            Island(3, mutationBitFlip, "Ile BitFlip")  
        ]  
        # Matrice de migration : initialisée uniformément  
        self.migrationMatrix = [[1.0/N for _ in range(N)] for _ in range(N)]  
        # Matrice de récompense : mise à jour après chaque génération  
        self.rewardMatrix = [[0.0 for _ in range(N)] for _ in range(N)]  
  
        self.bestFitness = 0  
        self.bestIndividual = None  
  
        # Paramètres d'apprentissage / bruit  
        self.alpha = 0.9  
        self.beta = 0.1  
        self.noise = 0.01  
  
        # NOUVEAU: compteur global d'évaluations  
        self.nb_evals = 0  
  
    def getBestElement(self):  
        best_elements = []  
        for island in self.islands:  
            best = island.getBestElement()  
            if best is not None:  
                best_elements.append(best)  
        if not best_elements:  
            return None  
        return max(best_elements, key=lambda x: x.getFitness())  
  
    def getBestFitness(self):  
        best_element = self.getBestElement()  
        if best_element:  
            return best_element.getFitness()  
        return 0  
  
    def run_one_generation(self):  
        """  
        1) Migration  
        2) Local search  
        3) MàJ bestFitness  
        4) Calcul Reward  
        5) MàJ matrice de migration  
        """  
        # 1) MIGRATION  
        for source_island in self.islands:  
            probabilities = self.migrationMatrix[source_island.id]  
            for ind in source_island.population[:]: # copie pour itération  
                if not ind.migrated:  
                    rand = random.random()  
                    destination = None  
                    cumulative_prob = 0.0
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        for i, proba in enumerate(probabilities):
            cumulative_prob += proba
            if rand < cumulative_prob:
                destination = i
                break
        if destination is None:
            destination = random.randrange(N)

        ind.origin = source_island.id
        ind.currentIsland = destination
        ind.migrated = True

        source_island.population.remove(ind)
        self.islands[destination].population.append(ind)

# On réinitialise le flag migrated
    for island in self.islands:
        for ind in island.population:
            ind.migrated = False

# 2) LOCAL SEARCH
    for island in self.islands:
        island.local_search(self)

# 3) MàJ bestFitness
    current_best = self.getBestFitness()
    if current_best > self.bestFitness:
        self.bestFitness = current_best
        self.bestIndividual = self.getBestElement()

# 4) Calcul Reward
    num_islands = len(self.islands)
    self.rewardMatrix = [[0.0 for _ in range(num_islands)] for _ in range(num_islands)]

    migrants_by_origin_dest = defaultdict(list)
    for island in self.islands:
        for ind in island.population:
            if ind.origin is not None:
                migrants_by_origin_dest[(ind.origin, ind.currentIsland)]

    for i_source in range(num_islands):
        dest_improvements = {}
        for i_dest in range(num_islands):
            key = (i_source, i_dest)
            if key in migrants_by_origin_dest:
                inds = migrants_by_origin_dest[key]
                if inds:
                    mean_up = sum(i.upgrade for i in inds) / len(inds)
                    dest_improvements[i_dest] = mean_up
                else:
                    dest_improvements[i_dest] = 0.0
            else:
                dest_improvements[i_dest] = 0.0

    best_value = max(dest_improvements.values())
    best_destinations = [d for d, v in dest_improvements.items() if v == best_value]
```

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        if best_value > 0:
            reward_per_best = 1.0 / len(best_destinations)
            for bd in best_destinations:
                self.rewardMatrix[i_source][bd] = reward_per_best

    # 5) MàJ matrice de migration
    for i in range(num_islands):
        for j in range(num_islands):
            old_ij = self.migrationMatrix[i][j]
            r_ij = self.rewardMatrix[i][j]

            new_ij = (1 - self.beta) * (self.alpha * old_ij + (1 - self.alpha) * self.noise)
            self.migrationMatrix[i][j] = new_ij

    # Normalisation
    for i in range(num_islands):
        row_sum = sum(self.migrationMatrix[i])
        if row_sum > 0:
            for j in range(num_islands):
                self.migrationMatrix[i][j] /= row_sum
        else:
            # Ligne anormale, on répartit uniformément
            for j in range(num_islands):
                self.migrationMatrix[i][j] = 1.0 / num_islands

def run_experiment():
    """
    Lance UNE exécution complète (jusqu'à MAX_ITER ou jusqu'à la solution).
    Retourne :
    - best_fitness_history : liste des meilleures fitness par génération (
    - population_history   : {nom_ile: [taille_pop_à_chaque_génération]}
    - nb_evals_history     : liste du nb_evals après chaque génération
    - archipel             : l'objet final
    """
    archipel = Archipel()

    # Initialisation manuelle : origin et currentIsland
    for island in archipel.islands:
        for ind in island.population:
            ind.currentIsland = island.id
            ind.origin = island.id

    # Pour le suivi
    population_history = {island.name: [] for island in archipel.islands}
    best_fitness_history = []
    nb_evals_history = []

    for generation in range(MAX_ITER):
        if archipel.bestFitness == TAILLE_VECTEUR:
            break

        archipel.run_one_generation()

    # Sauvegarder la best_fitness
    best_fitness_history.append(archipel.bestFitness)
```

```

# Sauvegarder le nb_evals ACTUEL
nb_evals_history.append(archipel.nb_evals)

# Sauvegarder la taille des populations
for island in archipel.islands:
    population_history[island.name].append(len(island.population))

# Arrêt si OneMax optimum atteint
if archipel.bestFitness == TAILLE_VECTEUR:
    # on complète le reste des itérations (jusqu'à MAX_ITER-1)
    # par la même valeur, pour garder la même longueur
    for _ in range(generation+1, MAX_ITER):
        best_fitness_history.append(archipel.bestFitness)
        nb_evals_history.append(archipel.nb_evals)
        for island in archipel.islands:
            population_history[island.name].append(len(island.population))
    break

return best_fitness_history, population_history, nb_evals_history, archipel

def save_data_to_csv(fitness_histories, evals_histories, filename="modele en
"""
Sauvegarde dans un CSV trois colonnes: generation, fitness, nb_evals,
en prenant la MOYENNE sur tous les runs pour chaque génération.

Paramètres
-----
fitness_histories : numpy array (NB_RUNS, MAX_ITER)
    best_fitness_history pour chaque run, aligné sur les générations.
evals_histories : numpy array (NB_RUNS, MAX_ITER)
    nb_evals_history pour chaque run, aligné sur les générations.
filename : str
    Nom du fichier CSV (par défaut "Archipel.csvArchipel.csv")
folder : str
    Nom du dossier où sauvegarder.
"""
# 1) Moyennes
mean_fitness = np.mean(fitness_histories, axis=0) # shape (MAX_ITER,)
mean_evals = np.mean(evals_histories, axis=0) # shape (MAX_ITER,)

# 2) DataFrame
data = {
    "generation": list(range(len(mean_fitness))),
    "fitness": mean_fitness,
    "nb_evals": mean_evals
}
df = pd.DataFrame(data)

# 3) Créer le dossier s'il n'existe pas
if not os.path.exists(folder):
    os.makedirs(folder)

# 4) Sauvegarde CSV
filepath = os.path.join(folder, filename)
df.to_csv(filepath, index=False)

```

```
print(f"Fichier CSV sauvegardé avec colonnes [generation, fitness, nb_ev

def main():
    all_fitness_runs = []
    all_population_runs = []
    all_evals_runs = []

    for run_index in range(NB_RUNS):
        bf_history, pop_history, nb_evals_history, archipel = run_experimen
        all_fitness_runs.append(bf_history)
        all_population_runs.append(pop_history)
        all_evals_runs.append(nb_evals_history)

    # Convertir en numpy array => shape (NB_RUNS, MAX_ITER)
    all_fitness_runs_array = np.array(all_fitness_runs)
    all_evals_runs_array = np.array(all_evals_runs)

    # Sauvegarder en CSV (moyenne sur NB_RUNS)
    save_data_to_csv(
        fitness_histories=all_fitness_runs_array,
        evals_histories=all_evals_runs_array,
        filename="modele en île.csv",
        folder="csv"
    )

    #
    # -- En plus, on peut tracer l'évolution moyenne comme avant --
    #
    # 1) Moyenne Best Fitness
    avg_best_fitness = np.mean(all_fitness_runs_array, axis=0) # shape (MAX
    # 2) Moyenne nb_evals
    avg_nb_evals = np.mean(all_evals_runs_array, axis=0) # shape (MAX

    # 3) Population moyenne
    # (On peut procéder comme auparavant pour calculer population moyenne
    island_names = list(all_population_runs[0].keys())
    avg_populations = {name: [0.0]*MAX_ITER for name in island_names}
    for name in island_names:
        for gen in range(MAX_ITER):
            s = 0.0
            for r in range(NB_RUNS):
                s += all_population_runs[r][name][gen]
            avg_populations[name][gen] = s / NB_RUNS

    # => Plot 1: Best Fitness vs. Generation
    plt.figure(figsize=(12, 6))
    plt.plot(avg_best_fitness, label=f"Best Fitness (moy. sur {NB_RUNS} runs
    plt.xlabel("Génération")
    plt.ylabel("Fitness")
    plt.title(f"Évolution moyenne de la Meilleure Fitness sur {NB_RUNS} runs
    plt.legend()
    plt.grid(True)
    plt.show()

    # => Plot 2: Best Fitness vs. nb_evals
    # (Optionnel: un scatter ou line, reliant points (avg_nb_evals, avg_b
```

```

# plt.figure(figsize=(12, 6))
# plt.plot(avg_nb_evals, avg_best_fitness, 'o-', label="Best Fitness vs
# plt.xlabel("Nombre moyen d'évaluations")
# plt.ylabel("Fitness")
# plt.title(f"Évolution de la Fitness par rapport au nb_evals (moy. sur
# plt.grid(True)
# plt.legend()
# plt.show()

# => Plot 3: Population size per Island
plt.figure(figsize=(12, 6))
for name in island_names:
    plt.plot(avg_populations[name], label=f"{name} (moy.)")
plt.xlabel('Génération')
plt.ylabel('Taille de population moyenne')
plt.title('Taille de population par Île (moy.) sur ' + str(NB_RUNS) + '
          + f" -  $\alpha$ ={archipelo.alpha},  $\beta$ ={archipelo.beta}, noise={archipe
plt.legend()
plt.grid(True)
plt.show()

if __name__ == "__main__":
    main()

```

Fichier CSV sauvegardé avec colonnes [generation, fitness, nb_evals] : csv/modele en île.csv



