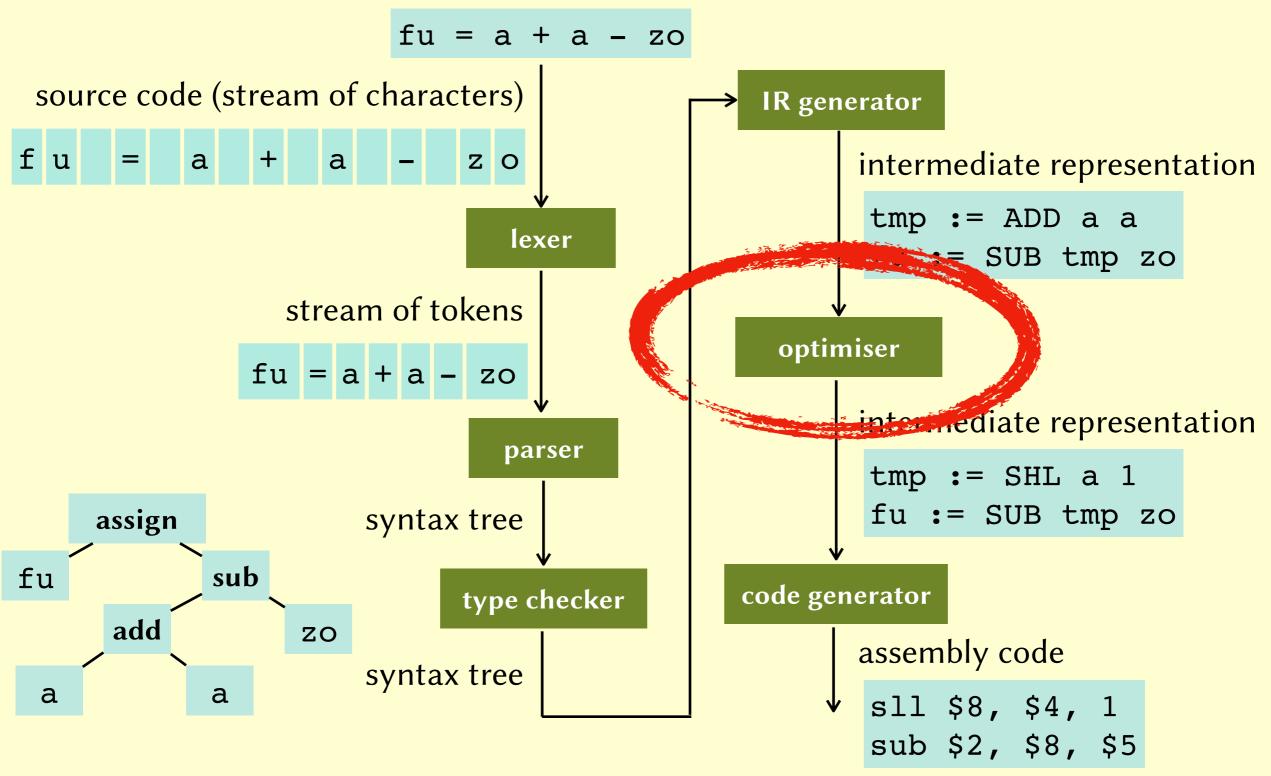
Lecture 12: Data flow analysis

John Wickerson

Anatomy of a compiler



```
int main (int a, int b, int c) {
  int d, e, f, g, h;
 d = a + b;
 e = d + b;
  f = d + a;
 g = a + c;
 h = e + g;
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
 //\{a, b, c\}
 d = a + b;
 e = d + b;
  f = d + a;
  g = a + c;
 h = e + g;
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
 //\{a, b, c\}
  d = a + b;
 //\{a, b, c, d\}
  e = d + b;
  f = d + a;
  g = a + c;
  h = e + g;
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  //\{a, b, c\}
  d = a + b;
  //\{a, b, c, d\}
  e = d + b;
  //\{a, c, d, e\}
  f = d + a;
  g = a + c;
  h = e + g;
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  //\{a, b, c\}
  d = a + b;
  //\{a, b, c, d\}
  e = d + b;
  //\{a, c, d, e\}
  f = d + a;
  //{ a, c, e, f }
  g = a + c;
  h = e + g;
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  //\{a, b, c\}
  d = a + b;
  //\{a, b, c, d\}
  e = d + b;
  //\{a, c, d, e\}
  f = d + a;
  //{ a, c, e, f }
  g = a + c;
  //\{e, f, g\}
  h = e + g;
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  //\{a, b, c\}
  d = a + b;
  //\{a, b, c, d\}
  e = d + b;
  //\{a, c, d, e\}
  f = d + a;
  //{ a, c, e, f }
  g = a + c;
  //\{e, f, g\}
  h = e + g;
  //{ f, h }
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  //\{a, b, c\}
  d = a + b;
  //\{a, b, c, d\}
  e = d + b;
  //\{a, c, d, e\}
  f = d + a;
  //{ a, c, e, f }
  g = a + c;
  //\{e, f, g\}
  h = e + g;
  //{ f, h }
  return f + h;
  //\emptyset
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
 d = a + b;
 e = d + b;
  f = d + a;
 g = a + c;
 h = e + g;
  return f + h;
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  d = a + b;
  e = d + b;
  f = d + a;
  g = a + c;
  h = e + g;
  return f + h;
 //\emptyset
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  d = a + b;
  e = d + b;
  f = d + a;
  g = a + c;
  h = e + g;
  //{ f, h }
  return f + h;
  //\emptyset
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  d = a + b;
  e = d + b;
  f = d + a;
  g = a + c;
  //\{e, f, g\}
  h = e + g;
  //{ f, h }
  return f + h;
  //\emptyset
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  d = a + b;
  e = d + b;
  f = d + a;
  //{ a, c, e, f }
  g = a + c;
  //\{e, f, g\}
  h = e + g;
  //{ f, h }
  return f + h;
  //\emptyset
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  d = a + b;
  e = d + b;
  //\{a, c, d, e\}
  f = d + a;
  //{ a, c, e, f }
  g = a + c;
  //\{e, f, g\}
  h = e + g;
  //{ f, h }
  return f + h;
  //\emptyset
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  d = a + b;
  //\{a, b, c, d\}
  e = d + b;
  //\{a, c, d, e\}
  f = d + a;
  //{ a, c, e, f }
  g = a + c;
  //\{e, f, g\}
  h = e + g;
  //{ f, h }
  return f + h;
  //\emptyset
```

```
int main (int a, int b, int c) {
  int d, e, f, g, h;
  //\{a, b, c\}
  d = a + b;
                           live_{before}(s) = live_{after}(s) - def_{V}(s) \cup use_{V}(s)
  //\{a, b, c, d\}
  e = d + b;
  //\{a, c, d, e\}
                                    def_V(\mathbf{return} \ f + h) = \emptyset
  f = d + a;
                                    def_V(h = e + g) = \{h\}
  //{ a, c, e, f }
                                    use_V(return f + h) = \{ f, h \}
  g = a + c;
                                    use_V(h = e + q) = \{e, q\}
  //\{e, f, g\}
  h = e + g;
  //{ f, h }
  return f + h;
  //\emptyset
```

- Useful for register allocation.
- Also useful for **dead code elimination**.

```
int main (int a, int b, int c) {
  int d, e;

d = a + b;

e = b * c;

return a + e;
}
```

- Useful for register allocation.
- Also useful for dead code elimination.

```
int main (int a, int b, int c) {
  int d, e;

d = a + b;

e = b * c;

return a + e;
  //Ø
}
```

- Useful for register allocation.
- Also useful for dead code elimination.

```
int main (int a, int b, int c) {
  int d, e;

d = a + b;

e = b * c;
  //{a,e}
  return a + e;
  //Ø
}
```

- Useful for register allocation.
- Also useful for dead code elimination.

```
int main (int a, int b, int c) {
  int d, e;

d = a + b;
  //{a,b,c}
  e = b * c;
  //{a,e}
  return a + e;
  //Ø
}
```

- Useful for register allocation.
- Also useful for dead code elimination.

```
int main (int a, int b, int c) {
  int d, e;
  //{a,b,c}
  d = a + b;
  //{a,b,c}
  e = b * c;
  //{a,e}
  return a + e;
  //Ø
}
```

Analysis	Operates on	Transformation	
live variables	sets of variables	register allocation, dead code elimination	

```
int main (int a, int b, int c) {
  int d, e, f;
 d = a + b;
 e = c * b;
  f = a + b;
 a = f / 10;
 return a + b;
```

```
int main (int a, int b, int c) {
  int d, e, f;
  // \emptyset
  d = a + b;
  e = c * b;
  f = a + b;
  a = f / 10;
  return a + b;
```

```
int main (int a, int b, int c) {
  int d, e, f;
  //\emptyset
  d = a + b;
  //{ a+b }
  e = c * b;
  f = a + b;
  a = f / 10;
  return a + b;
```

```
int main (int a, int b, int c) {
  int d, e, f;
  //\emptyset
  d = a + b;
  //{ a+b }
  e = c * b;
  //\{a+b,c*b\}
  f = a + b;
  a = f / 10;
  return a + b;
```

```
int main (int a, int b, int c) {
  int d, e, f;
  // \emptyset
  d = a + b;
  //{ a+b }
  e = c * b;
  //\{a+b,c*b\}
  f = a + b;
  //\{ a+b, c*b \}
  a = f / 10;
  return a + b;
```

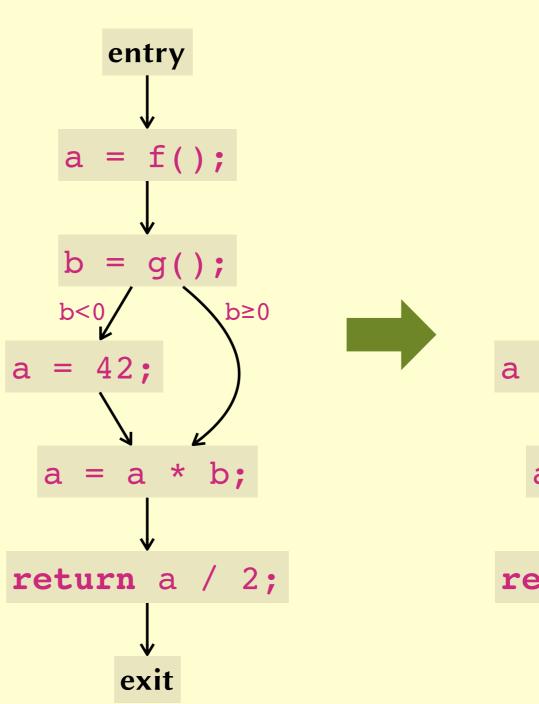
```
int main (int a, int b, int c) {
  int d, e, f;
  // \emptyset
                         avail_{after}(s) = avail_{before}(s) \cup gen_{AE}(s) - kill_{AE}(s)
  d = a + b;
  //{ a+b }
  e = c * b;
                               gen_{AE}(return a + b) = \{a+b\}
  //\{a+b,c*b\}
                               gen_{AE}(a = f / 10) = \{f/10\}
  f = a + b;
                               kill_{AE}(\mathbf{return} \ a + b) = \emptyset
  //{ a+b, c*b }
                               kill_{AE}(a = f / 10) = E_a
  a = f / 10;
  //{c*b, f/10}
  return a + b;
```

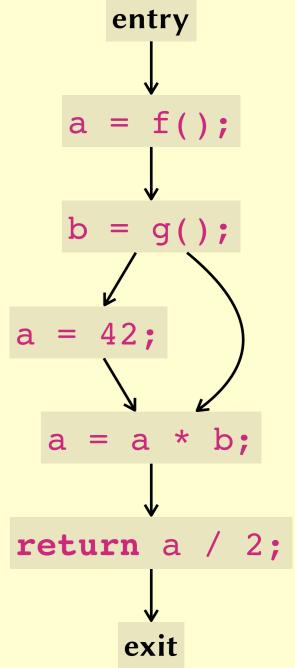
```
int main (int a, int b, int c) {
  int d, e, f;
  // \emptyset
                        avail_{after}(s) = avail_{before}(s) \cup gen_{AE}(s) - kill_{AE}(s)
  d = a + b;
  //{ a+b }
  e = c * b;
                              gen_{AE}(return a + b) = \{a+b\}
  //\{ a+b, c*b \}
                              gen_{AE}(a = f / 10) = \{f/10\}
  f = d;
                              kill_{AE}(\mathbf{return} \ a + b) = \emptyset
  //{ a+b, c*b }
                              kill_{AE}(a = f / 10) = E_a
  a = f / 10;
  //{c*b, f/10}
                                  "common
  return a + b;
                                 subexpression
                                  elimination"
```

Analysis	Operates on	Transformation	Direction	
live variables	sets of variables	register allocation, dead code elimination	Backward	
available expressions	sets of expressions	common subexpression elimination	Forward	

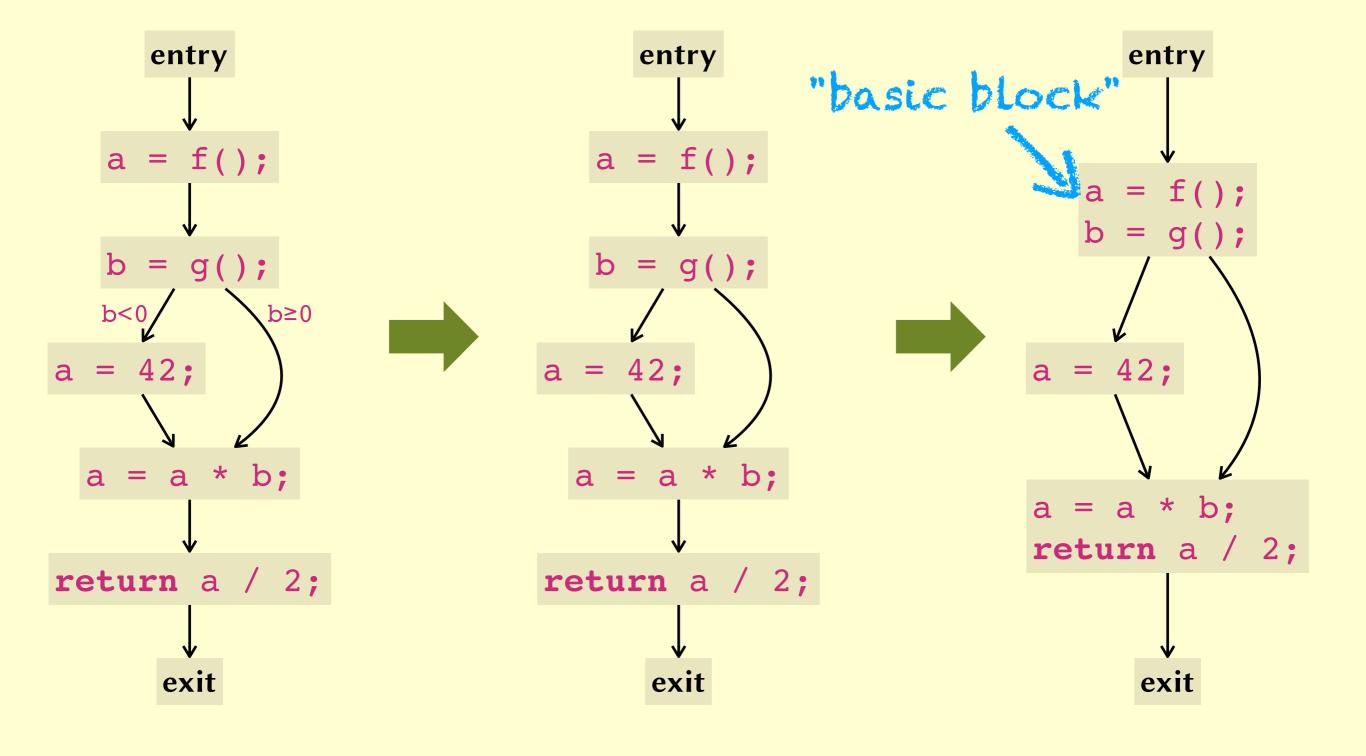
Control-flow graphs

```
a = f();
b = g();
if (b < 0) {
   a = 42;
}
a = a * b;
return a / 2;</pre>
```

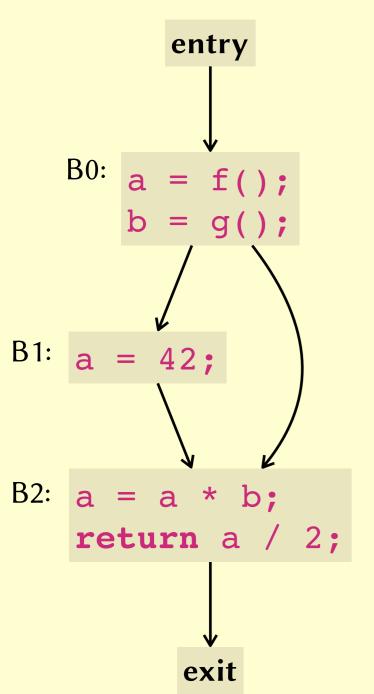




Control-flow graphs



Terminology



succ(B) = all blocks that B can jump to

pred(B) = all blocks that can jump to B

analyseBlock(B, X) = analyse block B, starting from X

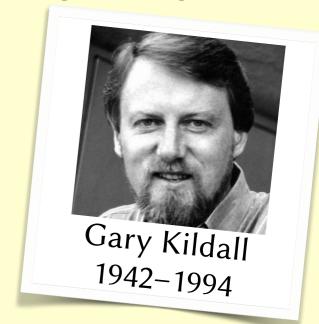
in: entry out: in: B0: a = f();b = g();out: a b in: b B1: a = 42; out: a b in: a b B2: a = a * b;return a / 2; out: in: exit out:

LV on a CFG

```
out[B] = in[B_1] \cup ... \cup in[B_n]
where succ(B) = \{B_1,...,B_n\}
```

 $in[B] = analyseBlock_{LV}(B, out[B])$

Start with $in[B] = out[B] = \emptyset$, for all B. Then keep applying these definitions until nothing changes.



Analysis precision

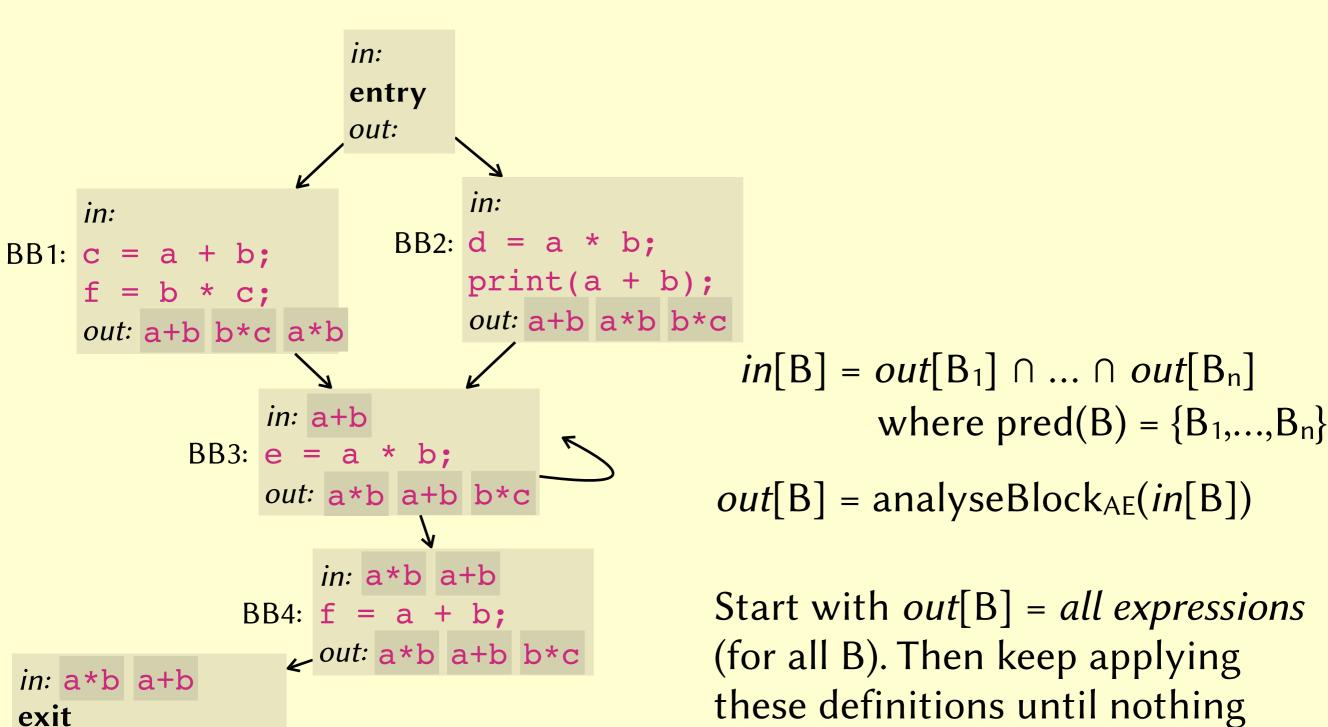
```
int main(int a,
         int b) {
  int foo[2];
  foo[a] = 42;
  return foo[b];
```

```
int main() {
 int a = 42;
 if (1) return 0; while(1);
 else return a;
```

```
int main() {
  int a = 42;
return a;
```

- What happens if the analysis wrongly says a variable is not live?
- What happens if the analysis wrongly says that a variable is live?
- Live-variable analysis **overapproximates** the set of live variables.

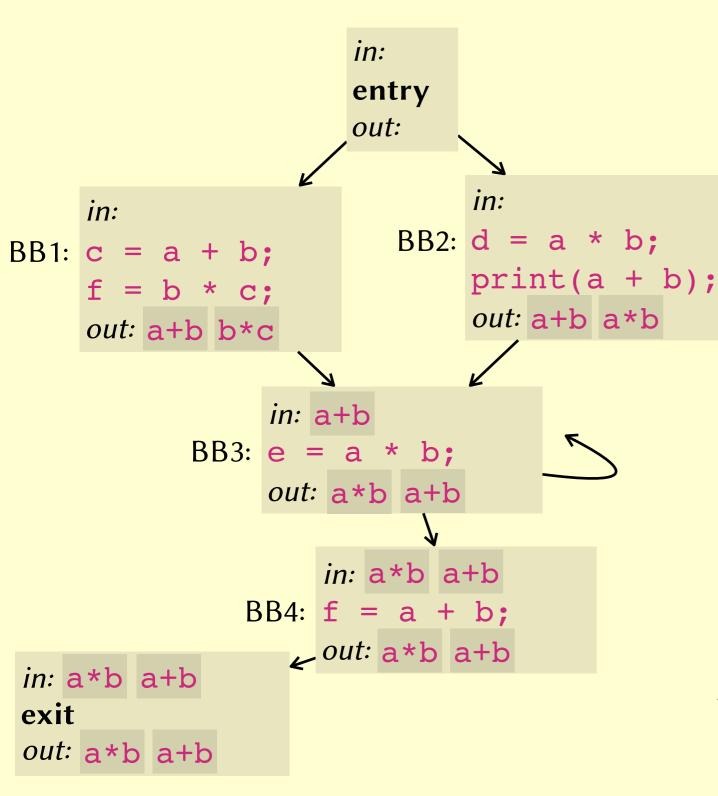
AE on a CFG



out: a*b a+b b*c

changes.

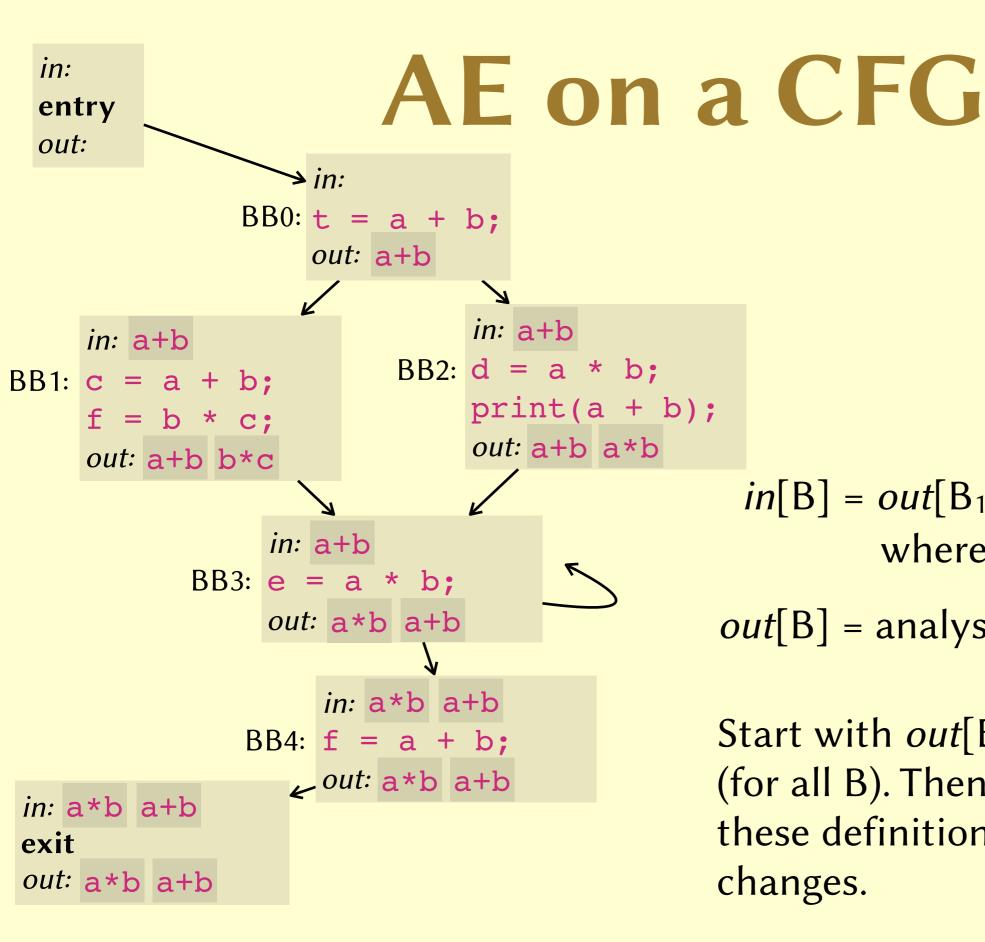
AE on a CFG



```
in[B] = out[B_1] \cap ... \cap out[B_n]
where pred(B) = {B<sub>1</sub>,...,B<sub>n</sub>}
```

out[B] = analyseBlockAE(in[B])

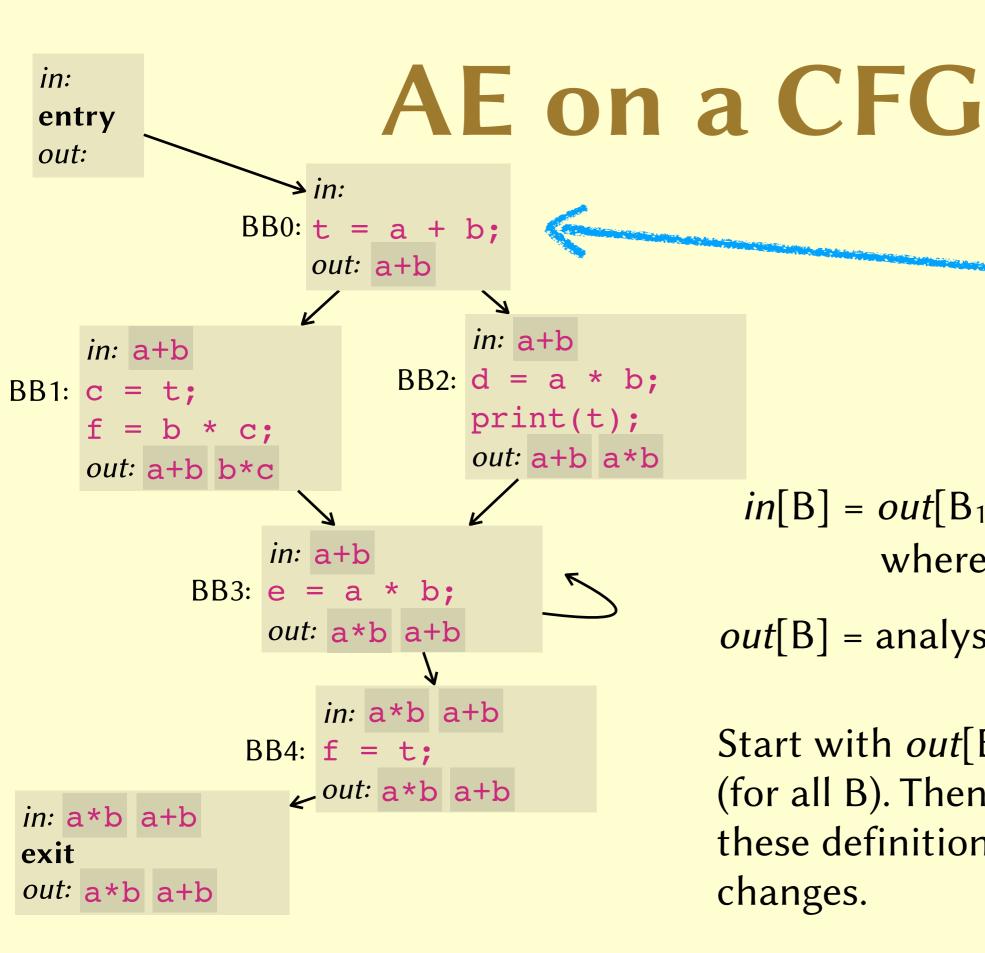
Start with *out*[B] = *all expressions* (for all B). Then keep applying these definitions until nothing changes.



```
in[B] = out[B_1] \cap ... \cap out[B_n]
where pred(B) = {B<sub>1</sub>,...,B<sub>n</sub>}
```

 $out[B] = analyseBlock_{AE}(in[B])$

Start with *out*[B] = *all expressions* (for all B). Then keep applying these definitions until nothing changes.



but was it worth it?

```
in[B] = out[B_1] \cap ... \cap out[B_n]
where pred(B) = {B<sub>1</sub>,...,B<sub>n</sub>}
```

out[B] = analyseBlockAE(in[B])

Start with *out*[B] = *all expressions* (for all B). Then keep applying these definitions until nothing changes.

Analysis precision

- What happens if the analysis wrongly says an expression is not available?
- What happens if the analysis wrongly says that an expression is available?
- Available-expression analysis underapproximates the set of available expressions.

Analysis	Operates on	Transformation	Direction	Meet
live variables	sets of variables	register allocation, dead code elimination	Backward	U
available expressions	sets of expressions	common subexpression elimination	Forward	\cap

```
23 int main () {
24 int a = f();
25 int b = g();
if (b > 0) a = 42;
a = a * b;
28 return a / 2;
```

```
23 int main () {
   //\emptyset
 int a = f();
25 int b = g();
if (b > 0) a = 42;
a = a * b;
28 return a / 2;
```

```
23 int main () {
   // \emptyset
 int a = f();
24
   //{ 24: a }
int b = g();
 if (b > 0) a = 42;
26
a = a * b;
28 return a / 2;
```

```
23 int main () {
    //\emptyset
  int a = f();
24
    //{ 24: a }
int b = g();
    //{ 24: a, 25: b }
 if (b > 0) a = 42;
26
a = a * b;
28 return a / 2;
```

```
23 int main () {
    //\emptyset
  int a = f();
24
    //{ 24: a }
25 int b = g();
    //{ 24: a, 25: b }
  if (b > 0) a = 42;
26
    //{ 24: a, 25: b, 26: a }
  a = a * b;
  return a / 2;
28
```

```
23 int main () {
    //\emptyset
  int a = f();
24
    //{ 24: a }
int b = g();
     //{ 24: a, 25: b}
  if (b > 0) a = 42;
26
    //{ 24: a, 25: b, 26: a }
  a = a * b;
27
     //{ 25: b, 27: a }
     return a / 2;
28
     The value of a
      on line 28 is
      provided on
        line 27
```

```
int main () {
  int a = 7;
  int b = f();
  return a - b;
}
```

```
23 int main () {
     //\emptyset
    int a = f();
24
     //{ 24: a }
int b = g();
     //{ 24: a, 25: b}
    if (b > 0) a = 42;
26
     //{ 24: a, 25: b, 26: a }
  a = a * b;
27
     //{ 25: b, 27: a }
     return a / 2;
28
     The value of a
      on line 28 is
```

```
int main () {
  int a = 7;
  int b = f();
  return 7 - b;
}
```

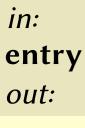
"constant propagation"

```
The value of a on line 28 is provided on line 27

Oops, you forgot to initialise d!
```

```
int main () {
  int a = f();
  return a - d;
}
```

```
23 int main () {
     //\emptyset
  int a = f();
24
    //{ 24: a }
                          reach_{after}(s) = reach_{before}(s) - kill_{D}(s) \cup gen_{D}(s)
int b = g();
     //{ 24: a, 25: b }
  if (b > 0) a = 42;
26
     //{ 24: a, 25: b, 26: a }
                                   kill_D(L: return a / 2) = \emptyset
  a = a * b;
                                   kill_D(L: a = 42) = D_a
    //{ 25: b, 27: a }
                                  gen_D(L: return a / 2) = \emptyset
  return a / 2;
                                   gen_D(L: a = 42) = \{ L: a \}
```



```
in:
BB0: 24 a = f();
     25 b = g();
     out: a:24 b:25
                           in: a:24 b:25
                      BB1: 26 a = 42;
                           out: a:26 b:25
                 in: a:24 a:26 b:25
            BB2: 27 a = a * b;
                 28 return a / 2;
                 out: a:27 b:25
                     in: a:27 b:25
                     exit
                     out: a:27 b:25
```

```
in[B] = out[B_1] \cup ... \cup out[B_n]
where pred(B) = \{B_1,...,B_n\}
out[B] = analyseBlock_{RD}(in[B])
```

Start with $out[B] = in[B] = \emptyset$, for all B. Then keep applying these definitions until nothing changes.

Dataflow analyses



Analysis	Operates on	Transformation	Direction	Meet
live variables	sets of variables	register allocation, dead code elimination	Backward	U
available expressions	sets of expressions	common subexpression elimination	Forward	\cap
reaching definitions	sets of definitions	constant propagation, spotting undefined variables	Forward	U

Dataflow analyses



Analysis	Operates on	Transformation	Direction	Meet
live variables	sets of variables	register allocation, dead code elimination	Backward	U
available expressions	sets of expressions	common subexpression elimination	Forward	Λ
reaching definitions	sets of definitions	constant propagation, spotting undefined variables	Forward	U
?	?	?	Backward	Λ

Very busy expressions

```
int main (int a, int b, int c) {
  if (b > 0) {
    print(b + c);
  } else if (b < 0) {</pre>
    f(b + c);
  } else {
    a = b + c;
  a = a * a;
  return a;
```

Very busy expressions

```
int main (int a, int b, int c) {
  int t = b + c;
  if (b > 0) {
                           "hoisting"
   print(t);
  } else if (b < 0) {</pre>
   f(t);
  } else {
    a = t;
  a = a * a;
  return a;
```

Summary

- Data flow analysis approximates a program by a flow graph made up of basic blocks.
- Analyses can go forwards or backwards.
- Analyses can consider all (∩) paths or any (∪) paths.
- Analyses may not be completely precise, so need to overapproximate or underapproximate as appropriate.
- Analyses enable transformations (but need to consider whether each transformation is actually worth doing).