

$$G(s) = \begin{bmatrix} \frac{4}{(s+1)(s+2)} & \frac{-1}{(s+1)} \\ \frac{2}{(s+1)} & \frac{-1}{2(s+1)(s+2)} \end{bmatrix}$$

1

$$r = \text{rank}[G(s)] = 2$$

$$G(s) = \frac{1}{d(s)} \cdot P(s) = \frac{1}{(s+1)(s+2)} \begin{bmatrix} 4 & -(s+2) \\ 2(s+2) & -0.5 \end{bmatrix}$$

$$P(s) = \begin{bmatrix} 4 & -(s+2) \\ 2(s+2) & -0.5 \end{bmatrix} \sim S(s) = \begin{bmatrix} \varepsilon_1'(s) & 0 \\ 0 & \varepsilon_2'(s) \end{bmatrix}$$

ALGORITMO

$$D_0(s) = 1$$

$$D_1(s) = \text{MCD} \{ 4, -(s+2), 2(s+2), -0.5 \} = 1$$

$$D_2(s) = \text{MCD} \left\{ \underbrace{\begin{vmatrix} 4 & -(s+2) \\ 2(s+2) & -0.5 \end{vmatrix}}_{\text{determinante}} \right\} = -2 + 2(s+2)^2$$

$$= 2(s^2 + 4s + 4) - 2 = 2s^2 + 8s + 6 = 2(s^2 + 4s + 3)$$

$$= 2(s+1)(s+3)$$

si trascura

$$\varepsilon_1^1(s) = \frac{D_1(s)}{D_0(s)} = 1$$

$$\varepsilon_2^1(s) = \frac{D_2(s)}{D_1(s)} = (s+1)(s+3)$$

$$G(s) \sim M(s) = \frac{1}{(s+1)(s+2)} \begin{bmatrix} 1 & 0 \\ 0 & (s+1)(s+3) \end{bmatrix} = \begin{bmatrix} \frac{1}{(s+1)(s+2)} & 0 \\ 0 & \frac{s+3}{(s+2)} \end{bmatrix}$$

$$p(s) = (s+1)(s+2)^2 \quad \text{polinomio dei poli}$$

$$z(s) = (s+3) \quad \text{polinomio degli zeri}$$

grado di Smith-McMillan pari a 3 (grado di  $p(s)$ )

3 poli  $s=-1$   $s=-2$   $s=-2$

1 zero  $s=-3$

Gli zeri non sono individuabili dalla  $G(s)$

I poli sono individuabili dalla  $G(s)$

ma non <sup>ne</sup> conosciamo la molteplicità

# COROLLARIO

$G(s)$  quadrato (a meno di cancellazioni)

3

$$\det[G(s)] = c \frac{z(s)}{p(s)} \quad c = \text{costante}$$

$$\det[G(s)] = \frac{2(s+3)}{(s+1)(s+2)^2}$$

$$z(s) = (s+3)$$

$$p(s) = (s+1)(s+2)^2$$

>> syms

$$>> g_{11} = 4 / ((s+1)*(s+2))$$

$$>> g_{12} = -1 / (s+1)$$

$$>> g_{21} = 2 / (s+1)$$

$$>> g_{22} = -0.5 / ((s+1)*(s+2))$$

$$>> G = [g_{11} \ g_{12}; g_{21} \ g_{22}]$$

$$>> \det(G)$$

Matlab

$$G_{ss} = ss(G)$$

$$z = \text{tzero}(\text{minreal}(G_{ss}))$$

$$p = \text{pole}(\text{minreal}(G_{ss}))$$

$$G(s) = \begin{bmatrix} \frac{1}{(s+1)} & \frac{1}{(s+1)(s+2)} \\ \frac{s}{(s+1)(s+2)} & \frac{2s+1}{(s+1)(s+2)} \end{bmatrix}$$

$$= \frac{1}{(s+1)(s+2)} \begin{bmatrix} s+2 & 1 \\ s & 2s+1 \end{bmatrix}$$

$$P(s) = \begin{bmatrix} s+2 & 1 \\ s & 2s+1 \end{bmatrix} \quad N \quad S(s) = \begin{bmatrix} \varepsilon_1'(s) & 0 \\ 0 & \varepsilon_2'(s) \end{bmatrix}$$

$$D_0(s) = 1$$

$$D_1(s) = \text{MCD} \{ s+2, 1, s, 2s+1 \} = 1$$

$$D_2(s) = \text{MCD} \left\{ \begin{vmatrix} s+2 & 1 \\ s & 2s+1 \end{vmatrix} \right\} = (s+2)(2s+1) - s = 2s^2 + 4s + 2$$

$$= 2(s^2 + 2s + 1) = 2(s+1)^2$$

si trascura

$$\varepsilon_1'(s) = \frac{D_1(s)}{D_0(s)} = 1$$

$$\varepsilon_2'(s) = \frac{D_2(s)}{D_1(s)} = (s+1)^2$$

$$S(s) = \begin{bmatrix} 1 & 0 \\ 0 & (s+1)^2 \end{bmatrix}$$

$$G(s) \sim M(s) = \frac{1}{(s+1)(s+2)} \begin{bmatrix} 1 & 0 \\ 0 & (s+1)^2 \end{bmatrix} = \begin{bmatrix} \frac{1}{(s+1)(s+2)} & 0 \\ 0 & \frac{s+1}{s+2} \end{bmatrix}$$

$$Z(s) = (s+1) \quad Z = -1$$

$$p(s) = (s+1)(s+2)^2 \quad p_1 = -1 \quad p_2 = -2 \quad p_3 = -2$$

grado di Smith McMillan è 3

No B<sub>0</sub> polo e zero cancellate in  $s = -1$

$$G(s) = \begin{bmatrix} \frac{1}{s+1} & \frac{1}{(s+1)(s+2)} \\ \frac{s}{(s+1)(s+2)} & \frac{2s+1}{(s+1)(s+2)} \end{bmatrix}$$

$$(A, B, C, D)$$

$$x \in \mathbb{R}^m \quad m=5$$

$$\det(G(s)) = \frac{2}{(s+2)^2}$$

cancellazione  
polo e zero in  $s=-1$

$G$  costruita con il comando `tf`

$$Z = \text{tzero}(\text{minreal}(ss(G)))$$

$$P = \text{pole}(\text{minreal}(ss(G)))$$

$s_0 = -1$  zero di trasmissione

$$\text{rank} \begin{bmatrix} s_0 I - A & -B \\ C & D \end{bmatrix} = 6 < n + \min(p, m) = 7$$

