

Scribbling notes 3~4 people in a group

Ch 1. Introduction

Time domain approach
Frequency domain approach

1.1. The nature of time series data

Trends: ① trend ② seasonality ③ sporadic pattern

Return: $\text{Return}_t = \log P_t - \log P_{t-1} = \log \left(\frac{P_t}{P_{t-1}} - 1 + 1 \right) = \frac{P_t}{P_{t-1}} - 1$.

Price at time t

Symbols: WN: Gaussian, normal

Lesson 2 Fundamental Concept

- Stochastic process: a sequence of random variables
 $\{X_t: t = 0, \pm 1, \pm 2, \dots\}$
 - Specified by joint distribution of $\{X_t\}$
 $\Pr\{X_1 \in \mathcal{X}_1, X_2 \in \mathcal{X}_2, \dots, X_t \in \mathcal{X}_t\}$ for all t and $\mathcal{X}_1 \dots \mathcal{X}_n$
 - In practice, we can only approximate the model
 - Interests: $\tilde{\pi}_t[X_t]$, $\tilde{\pi}_t[X_s]$, $\tilde{\pi}_t[X_t X_s]$
- Time series: realizations of $\{X_t\}$: X_{t_1}, \dots, X_{t_n}

$$\text{mean: } \mu_x = \overline{\mathbb{E}[X_t]}$$

$$\begin{aligned} \text{Covariance } \gamma_{x(t,s)} &= \text{Cov}(X_t, X_s) = \overline{\mathbb{E}[(X_t - \mu_x)(X_s - \mu_x)]} \\ &= \overline{\mathbb{E}[X_t X_s]} - \overline{\mathbb{E}[X_t]} \overline{\mathbb{E}[X_s]} \end{aligned}$$

$$\text{Variance } \gamma_{x(t,t)} = \text{Var}(X_t) = \overline{\mathbb{E}[(X_t - \mu_x)^2]}$$

Definition (Stationary) $\{X_t\}$ is stationary if

$$P(X_{t+1} \in \chi_1, X_{t+2} \in \chi_2, \dots, X_{t+n} \in \chi_n) = P(X_1 \in \chi_1, X_2 \in \chi_2, \dots, X_n \in \chi_n)$$

(Joint distribution is independent of t)

Def. Weak Stationary

- 1. μ_x is independent of t
- 2. $\gamma_{x(t+h,t)} = \gamma_{x(h,0)} := \gamma_x(h)$ $\text{Cov}(X_{t+h}, X_t) = \text{Cov}(X_t, X_0)$

$$\text{Var}(X_t) = \text{Var}(X_0)$$

¶

Def. Auto Correlation Function (Assume weak stationary)

$$p_x(h) = \frac{\gamma_{x(h)}}{\gamma_{x(0)}} = \frac{\text{Cov}(X_h, X_0)}{\text{Cov}(X_0, X_0)} = ? \text{Corr}(X_h, X_0) \quad \text{ACF}$$

Prop 1. X_1, \dots, X_n independently distributed and $X_1 + \dots + X_n = C$,

we have $\text{Cov}(X_i, X_j)$ when $\text{Corr}(X_1, X_2) = \frac{-1}{n-1}$

Proof:

$$\begin{aligned} 0 &= \text{Var}(X_1 + \dots + X_n) = \sum_{i=1}^n \text{Var}(X_i) + \sum_{i \neq j} \text{Cov}(X_i, X_j) \\ &= n \text{Var}(X_1) + n(n-1) \text{Cov}(X_1, X_2) \end{aligned}$$

$$\Rightarrow \text{Cov}(X_1, X_2) = \frac{\text{Cov}(X_1, X_2)}{\text{Var}(X_1)} = \frac{-1}{n-1}$$

Examples:

① X_t iid distn, mean 0, variance σ^2

$E[X_t X_{t+h}] = 0$, $\gamma_X(t+h, t) = \text{Cov}(X_{t+h}, X_t) = \begin{cases} \sigma^2 & \text{if } h=0 \\ 0 & \text{if } h \neq 0 \end{cases}$
independent of t

$\Rightarrow \{X_t\}$ mark stationary. $\text{Rank } \sum_{i+j} X_i X_j = \sum_{i+j} X_i X_j$

② Random walk: X_t iid $WN(0, \sigma^2)$. $S_t = \sum_{i=1}^t X_i$

$E[S_t] = 0$ independent of t

$\text{Var}(S_t) = E[S_t^2] = E[\sum_i X_i^2] = 4t\sigma^2$ depends on t

$\Rightarrow S_t$ is not stationary

③ Moving average (1). MA(1)

$X_t = W_t + \theta W_{t-1}$. W_t iid $WN(0, \sigma^2)$

(i) $E[X_t] = 0$

(ii) $\gamma_X(t+h, t) = \text{Cov}(X_{t+h}, X_t)$
 $= \text{Cov}(W_{t+h} + \theta W_{t+h-1}, W_t + \theta W_{t-1}) = \begin{cases} \sigma^2(1+\theta^2) & h=0 \\ \theta\sigma^2 & h=\pm 1 \\ 0 & \text{otherwise} \end{cases}$
independent of t

\Rightarrow mark stationary

$$\text{Mg. } p_X(h) = \frac{\gamma_X(h)}{\gamma_X(0)} = \frac{\theta}{1+\theta^2} \text{ if } h=\pm 1$$

④ Autoregressive (1)

$X_t \perp\!\!\!\perp W_t$ for all t

$$X_t = \varphi X_{t-1} + W_t \quad (W_t \text{ iid } WN(0, \sigma^2)) \quad |\varphi| < 1$$

Assume $\{X_t\}$ is weak stationary

$$(i) \quad \overline{\text{E}}[X_t] = \overline{\text{E}}[\varphi X_{t+1}] = \varphi \overline{\text{E}}[X_{t+1}] \Rightarrow \overline{\text{E}}[X_t] = 0$$

$$(ii) \quad \gamma_x(h) = \gamma_x(t+h, t) = \text{Cov}(X_{t+h}, X_t)$$

$$= \text{Cov}(\varphi X_{t+h-1} + W_{t+h}, X_t) \quad \text{if } h > 0:$$

$$= \text{Cov}(\varphi X_{t+h-1}, X_t) = \varphi \text{Cov}(X_{t+h-1}, X_t)$$

$$= \varphi \gamma_x(t+h-1, t) = \varphi \gamma_x(h-1) = \varphi^h \gamma_x(0)$$

Rank: if $h < 0$, we still have $\gamma_x(t+h, t) = \varphi^{|h|} \gamma_x(0)$

$$\gamma_x(0) = \overline{\text{E}}[X_t^2] = \overline{\text{E}}[\varphi X_{t+1} + W_t]^2 = \varphi^2 \overline{\text{E}}[X_{t+1}^2] + \sigma^2$$

$$\text{By stationarity } \overline{\text{E}}[X_t^2] = \overline{\text{E}}[X_{t+1}^2] \Rightarrow \gamma_x(0) = \frac{\sigma^2}{1-\varphi^2}$$

$$\gamma_x(h) = \gamma_x(t+h, t) = \frac{\varphi^{|h|} \sigma^2}{1-\varphi^2}$$

⑤ Linear Process

$$X_t = \mu + \sum_{j=-\infty}^{\infty} \gamma_j W_{t-j} \quad W_j \stackrel{iid}{\sim} \text{WN}(0, \sigma^2)$$

$$\overline{\text{E}}[X_t] = \mu$$

$$\gamma_x(t+h, t) = \text{Cov}(X_{t+h}, X_t)$$

Lecture 3.

① $\sigma^2 = \gamma(0)$ known, $\frac{1}{n-1} \rightarrow$ unbiased

$\hat{\gamma}$ -estimators.

② σ^2 unknown, $\frac{1}{n}$ usually gives smaller bias

$$\mu = \overline{\text{E}}[X_t] \quad \hat{\mu} = \bar{x} = \frac{1}{n} \sum_{t=1}^n X_t \quad Q: \text{What is the unbiased estimator}$$

$$\gamma(h) = \text{Cov}(X_{t+h}, X_t), \quad \hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-h} (X_t - \bar{x})(X_{t+h} - \bar{x})$$

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)} \quad \hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}$$

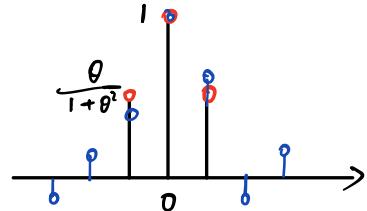
Example:

① White Gaussian Noise

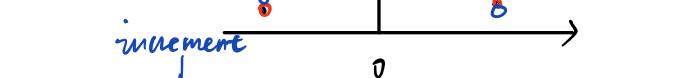
$$X_t = W_t \stackrel{iid}{\sim} WN(0, \sigma^2)$$



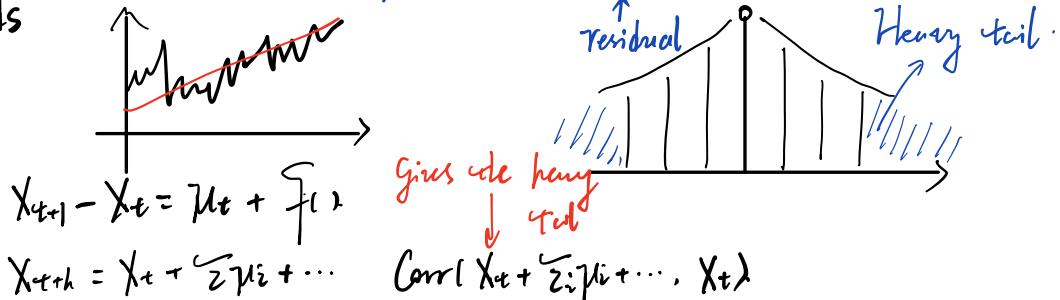
② Moving average $X_t = W_t + \theta W_{t-1}$



③ Auto regressive $X_t = \phi X_{t-1} + W_t$



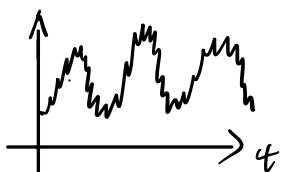
④ Trends



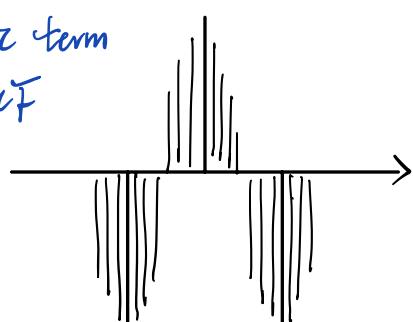
A more specific model: $X_t = \mu_t + \epsilon_t$
trend noise

$$\textcircled{1} \quad \mu_t = \beta_0 + \beta_1 t \quad \textcircled{2} \quad \mu_t = \beta_0 + \beta_1 t + \beta_2 t^2$$

⑤ Periodic.



Periodic term
of ACF



Summary.

WN. Concentrate on 0-

MA. only several non-zero values

AR. decays exponentially
 Trend. Henry curv.
 Periodical Periodic

\hat{s}_f^2 and least square

$$\min_c \sum_k (Y_i - c)^2$$

$$\sum_k (Y_i - c)^2 = \text{Var}(Y_i) + \sum_k (Y_i - \bar{Y})^2 = \text{Var}(Y_i) + \sum_k (Y_i - c)^2 \geq \text{Var}(Y_i)$$

The equality holds when $\bar{Y} = c$

$$\min_c \sum_k (X_{i+h} - \hat{f}(X_i)) | X_i)^2: \quad \hat{f}(X_i) = \sum_k \hat{\beta}_k X_{i+h} | X_i]. \quad \hat{\beta} = P(\cdot | X_i)$$

$$\sum_k (X_{i+h} - \hat{f}(X_i)) | X_i)^2 = \text{Var}(X_{i+h}) + \sum_k (\hat{f}(X_i) - \hat{E}[X_{i+h} | X_i])^2$$

$$\text{wks: } \sum_k \hat{\beta} X_{i+h} - \sum_k \hat{\beta} X_{i+h} | X_i] | X_i] = 0$$

$$= \sum_k \hat{\beta} X_{i+h} | X_i] - \sum_k \sum_k \hat{\beta} X_{i+h} | X_i] | X_i]$$

$$= \sum_k \hat{\beta} X_{i+h} | X_i] - \sum_k \hat{\beta} X_{i+h} | X_i] = 0$$

For Gaussian process $\{X_t\}$: $\hat{f}(h) \xrightarrow{\text{Stationary}} P(h, t)$

$$\hat{\beta} X_{i+h} | X_i] = \mu + P(h)(X_i - \mu)$$

$$\text{MS}_{\hat{\beta}} = \sum_k \sum_k (X_{i+h} - \sum_k \hat{\beta} X_{i+h} | X_i])^2 | X_i] = \text{Var}(X_{i+h} | X_i) = \sigma^2(1 - P^2(h))$$

$$X_1, X_2 \sim N(\mu, \sigma^2) \quad X_1 | X_2 = x_2 \sim N(\mu + P \frac{\partial f}{\partial x}(x_2 - \mu), \sigma^2(1 - P^2))$$

Remove sole Gaussian assumption:

$$\hat{f}(x) = a(x - \mu) + b \quad \text{for } \{X_t\} \text{ with } \mu, \sigma^2, P(h).$$

$$\text{Prove } \min_{a,b} \sum_k \sum_k (X_{i+h} - \hat{f}(X_i))^2 | X_i], \quad a = P(h), \quad b = \mu$$

Lecture 4.

§ Trends $X_t = \mu_t + e_t$ μ_t : trend e_t : noise - Stationary

$$\tilde{e}_t(e_t) = 0$$

① $\mu_t \equiv \mu$ constant.

$$\tilde{\mu} = \frac{1}{n} \sum_{t=1}^n X_t := \bar{X}$$

$$\begin{aligned} \text{Var}(\tilde{\mu}) &= \text{Var}(\bar{X}) = \text{Var}\left(\frac{1}{n} \sum_i X_i\right) = \frac{1}{n^2} \sum_{i,j} \text{Cov}(X_i, X_j) \\ &= \frac{1}{n^2} \left[\sum_i \text{Var}(X_i) + 2 \sum_{i=1}^{n-1} \sum_{h=1}^{n-i} \text{Cov}(X_i, X_{i+h}) \right] \\ &= \frac{1}{n^2} [n\gamma(0) + 2 \sum_{i=1}^{n-1} (n-i)\gamma(i)] \\ &= \frac{\gamma(0)}{n} \left(1 + 2 \sum_{i=1}^{n-1} \left(1 - \frac{i}{n}\right) \rho(i) \right) \end{aligned}$$

Comparison: For Y_1, \dots, Y_n iid (μ, σ^2)

$$\text{Var}(\tilde{Y}) = \frac{\sigma^2}{n} = \frac{\gamma(0)}{n} \leq \text{Var}(\bar{X})$$

② $\mu_t = \beta_0 + \beta_1 t$

In linear regression $Y = X\beta + \epsilon$

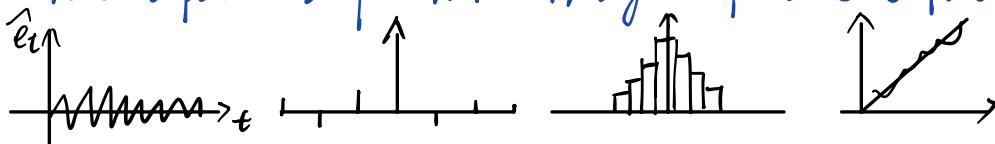
$$\min_{\beta} \|Y - X\beta\|_2^2 \Rightarrow \hat{\beta} = (X^T X)^{-1} X^T Y$$

$$\text{For } \mu_t = \beta_0 + \beta_1 t \quad \hat{\beta}_1 = \frac{\sum_t (y_t - \bar{y})(t - \bar{t})}{\sum_t (t - \bar{t})^2} \quad \hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{t}, \quad \bar{t} = \frac{n+1}{2}$$

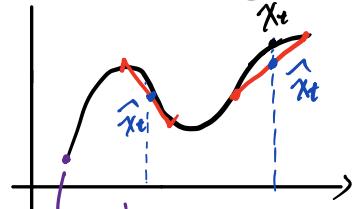
Interpretation: $R^2 = \frac{\text{Var}(\tilde{Y})}{\text{Var}(Y)} = \underline{\text{Corr}(\tilde{Y}, Y)}$ = Corr(θ)?

③ Residuals $\hat{e}_t = X_t - \tilde{\mu}_t$

residual plot, Sampled ACF, Histogram of \hat{e}_t , Q-Q plot



- Parametric Fitting $\Rightarrow \mu_t = \beta_0 + \beta_1 t$ No assumption \Rightarrow Smoothing
 - Smoothing: $\hat{\mu}_t = \frac{1}{2q+1} \sum_{h=-q}^q X_{t+h}$
 If μ_t is linear in $[t-q, t+q]$
 then $\hat{\mu}_t = \mu_t + \frac{1}{2q+1} \sum_{h=-q}^q \epsilon_t$
 Small $q \rightarrow$ high bias
 Large $q \rightarrow$ accurate estimation, but violates local linearity \rightarrow large bias.
 Smoothing: Special case of linear filtering. $\hat{\mu}_t = \frac{1}{2q+1} \sum_{h=-q}^q a_h X_{t+h}$
 - Issue: ① End point ② Tuning parameter q
 - Isotonic regression. $\min_{a_1, \dots, a_n} \sum_{t=1}^n (X_t - a_t)^+$ s.t. a_1, \dots, a_n monotonic
 merits: ① solved in $O(n \log n)$
 ② no tuning parameter
 ③ no end-point issue
 ④ non-parametric
 Drawback: Assuming monotonicity
- If n para & nonpara
 para: # para $\ll n$
 nonpara: # para $\sim n$



end point:
 estimation is biased

Lecture 5.

- Linear process & convergence in L_2
- (AR(1)) and causality
- (MA(1)) and invertibility

Def of WN:

mean square norm 0, finite var.

1. Linear process and convergence in L_2 uncorrelated

Linear process $X_t = \sum_{j=-\infty}^{\infty} \psi_j W_{t-j}$ $W_t \sim WN(0, \sigma^2)$, $\psi_j \in \mathbb{R}$

Def. Convergence in L_2 : $S_n \xrightarrow{L_2} Y$ iff $\lim_{n \rightarrow \infty} \mathbb{E}(S_n - Y)^2 = 0$

Cauchy criterion: $\Leftrightarrow \lim_{n, m \rightarrow \infty} \mathbb{E}(S_n - S_m)^2 = 0$

Proposition: Suppose $X_t = \sum_{j=-\infty}^{\infty} \psi_j W_{t-j}$ with $\sum_{j=-\infty}^{\infty} |\psi_j| < \infty$ $S_n = \sum_{j=-n}^n \psi_j W_{t-j}$

Then ① $|X_t| < \infty$ a.s. ② S_n converges to X_t in L_2

Def $|X_t| < \infty$ a.s. $\Leftrightarrow P(|X_t| > 2) \rightarrow 0$ as $2 \rightarrow \infty$

$$\begin{aligned} P(|X_t| > 2) &\leq \frac{1}{2} \mathbb{E}|X_t| = \frac{1}{2} \mathbb{E} \left| \sum_{j=-\infty}^{\infty} \psi_j W_{t-j} \right| \leq \frac{1}{2} \sum_{j=-\infty}^{\infty} |\psi_j| \mathbb{E}|W_{t-j}| \\ &\leq \frac{\sigma}{2} \sum_{j=-\infty}^{\infty} |\psi_j| \rightarrow 0 \text{ as } 2 \rightarrow \infty \end{aligned}$$

$$\mathbb{E}|W_{t-j}| = \sqrt{\mathbb{E}((W_{t-j})^2)} \leq \sqrt{\mathbb{E}|W_{t-j}| \mathbb{E}|W_{t-j}|} = \sigma$$

$$\begin{aligned} \mathbb{E}|W_{t-j}| &= \sqrt{\mathbb{E}((W_{t-j})^2)} \\ &= \sqrt{\mathbb{E}[W_{t-j}^2]} \\ &= \sqrt{\mathbb{E}[W_t^2]} \\ &= \sigma \end{aligned}$$

$$P \text{ of } ② \quad \mathbb{E}(S_m - S_n) = \mathbb{E} \left(\sum_{j=-m}^n \psi_j W_{t-j} \right)^2$$

$$\begin{aligned} \mathbb{E}(W_t W_j) &= 0 \quad = \sum_{n \neq j} \psi_n^2 \mathbb{E} W_t^2 \\ &= \sum_{n \neq j} \psi_n^2 \sigma^2 \end{aligned}$$

$$\begin{aligned} &= \sum_{n \neq j} \psi_n^2 \sigma^2 \\ &= \sigma^2 \left(\sum_{n \neq j} |\psi_n|^2 \right) \rightarrow 0 \text{ as } m, n \rightarrow \infty \end{aligned}$$

$$\sigma^2 \left(\sum_{n \neq j} |\psi_n|^2 \right) \rightarrow 0 \text{ as } m, n \rightarrow \infty$$

2. AR(1) and causality. (AR1: causal $\Leftrightarrow |\phi| < 1 \Leftrightarrow \phi(z) \neq 0$)

$$\text{AR}(1): X_t = \phi X_{t-1} + W_t, \quad W_t \sim WN(0, \sigma^2) \quad \text{if } |z| > 1$$

① If $|\phi| < 1$, then $\hat{X}_t = \sum_{j=0}^{\infty} \phi^j W_{t-j}$ is a solution
 $\sum_j |\phi|^j < \infty$

$$\text{② } E[X_t] = 0, \quad \text{Cov}(X_t, X_{t+n}) = \frac{\phi^n \sigma^2}{1 - \phi^2}$$

③ Uniqueness

Assume there is another weakly stationary solution \tilde{Y}_t :

$$\lim_{n \rightarrow \infty} \sqrt{n} \|Y_t - \sum_{j=0}^{n-1} \phi^j W_{t+j}\|^2 = \lim_{n \rightarrow \infty} \sqrt{n} (\phi^n Y_{t-n})^2 = \lim_{n \rightarrow \infty} \phi^n \sqrt{n} Y_{t-n}^2 \rightarrow 0 \text{ as } n \rightarrow \infty$$

$$Y_t = X_t \text{ in } L_2$$

Back-shift operator $\bar{T} X_t = X_{t-1}$

$$X_t = \phi X_{t-1} + W_t \quad X_t = \sum_{j=0}^{\infty} \phi^j W_{t+j} \quad \text{require: } |\phi| < 1$$

$$\Leftrightarrow X_t - \phi X_{t-1} = W_t \quad = \sum_{j=0}^{\infty} \phi^j B^j W_t$$

$$\Leftrightarrow (1 - \phi B) X_t = W_t \quad = \underbrace{\pi(B)}_{=} W_t$$

$$\phi(B) X_t = W_t \quad \phi(B) \pi(B) = 1$$

If $\{Y_t\}$ is causal for W_t if Y_t can be written as $Y_t = \psi(B) W_t$

$$\text{then } \psi(B) = \psi_0 + \psi_1 B + \psi_2 B^2 + \dots \quad \sum_{j=0}^{\infty} |\psi_j| < \infty$$

(AR1) is causal bcs $X_t = \pi(B) W_t, \quad \pi(B) = \sum_{j=0}^{\infty} \phi^j B^j$

If $|\phi| = 1 \Rightarrow X_t = \sum_{j=-\infty}^{\infty} W_{t-j} \sim WN(0, \infty)$ Depends on future w_j not

If $|\phi| > 1 \Rightarrow X_{t-1} = \frac{1}{\phi} X_t - \frac{1}{\phi} W_t \Rightarrow X_t = -\sum_{j=0}^{\infty} \phi^j W_{t+j}$ Causal.

AR is causal iff $|\phi(z)| < 1 \Leftrightarrow$
 $\Leftrightarrow \{\phi(z) \neq 0 \text{ if } |z| \leq 1\}$

$$= - \sum_{j=0}^p \phi_j B^{-j} w_t$$

Lecture 6. \hookrightarrow Places and the nerd \Rightarrow Edward Lee
 Paradigm ① Model ② estimation ③ evaluation ④ application.

I. AR(p)

Def. $\{x_t\}$ s.t. $x_t - \phi_1 x_{t-1} - \phi_2 x_{t-2} - \dots - \phi_p x_{t-p} = w_t$

$$w_t \sim WN(0, \sigma^2) \quad \phi(B) = 1 - [\phi_1 B + \phi_2 B^2 + \dots + \phi_p B^p]$$

$$\Leftrightarrow \phi(B)x_t = w_t \quad \phi(\cdot): \text{polynomial}$$

Thus Suppose $\{x_t\}$ w/ $x_t - \phi_1 x_{t-1} - \dots - \phi_p x_{t-p} = w_t$

$\{x_t\}$ is stationary $\Leftrightarrow |\phi(z)| \neq 0 \text{ for } |z| = 1$

Causal $\Leftrightarrow |\phi(z)| \neq 0 \text{ for } |z| \leq 1$

II. MA(1) and Invertibility:

Def $\{x_t\}$ is invertible of $\{w_t\}$ if $w_t = \psi(w_t)$

$$\text{where } \psi(w_t) = \sum_{j=0}^{\infty} \psi_j w_t^j \quad \sum_{j=0}^{\infty} |\psi_j| < \infty$$

Def MA(1) $\{x_t\}$ stationary w/ $x_t = \theta w_{t-1} + w_t = \underbrace{(1 + \theta B)}_{\theta(B)} w_t$

If $|\theta| < 1$, $\theta(B)^{-1} = 1 - \theta B + \theta^2 B^2 - \theta^3 B^3 \dots$ invertible

Prop. MA(1) is invertible $\Leftrightarrow |\theta| < 1 \Leftrightarrow \theta(z) \neq 0 \text{ for } |z| \leq 1$.

- $\sum |\theta_j| = 1$, diverges $\Rightarrow \text{Randomization experiment}$
 - $\sum |\theta_j| > 1$, $X_t = \theta W_{t-1} + W_t \Leftrightarrow \frac{1}{\theta} X_t = W_{t-1} + \frac{1}{\theta} W_t$
 $\Leftrightarrow \frac{1}{\theta} X_t = W_{t-1} + \frac{1}{\theta} W_t \Rightarrow W_t = \sum_{j=0}^{\infty} (-\theta)^j X_{t+j}$
- $\left\{ \begin{array}{l} \text{AR}(p): \phi(B)X_t = W_t \\ \text{MA}(p): X_t = \theta(B)W_t \end{array} \right.$
- 2nd ARMLD (p. 9)

Def - If ARMLD $\{X_t\}$ stationary w/ $\phi(B)X_t = \theta(B)W_t$

$$\text{i.e. } X_t - \phi_1 X_{t-1} - \cdots - \phi_p X_{t-p} = W_t + \theta_1 W_{t-1} + \cdots + \theta_q W_{t-q}$$

① ARMA(1,0): $\theta(B) = 1 \Rightarrow \text{AR}(1)$

ARMA(0,1): $\phi(B) = 1 \Rightarrow \text{MA}(1)$

② We need $\phi(B)$ $\theta(B)$ have no common factors.

which implies it is not a lower order model

$$\text{e.g. } X_t = W_t \Leftrightarrow X_t - X_{t-3} = W_t - W_{t-3} \Leftrightarrow (1-B^3)X_t = (1-B^3)W_t$$


Thm For a given stationary process w/ $\gamma(h)$

and any $k > 0$, $\exists \text{ARMLD } \{X_t\}$ s.t. $\gamma_X(h) = \gamma(h)$ for $h = 0, 1, \dots, k$.

ARMLD can approximate any stationary process.

Thm

③ If $\phi(B), \theta(B)$ have no common factors, a unique, stationary solution $\{X_t\}$. $\phi(B)X_t = \theta(B)W_t$, $W_t \sim WN(0, \sigma^2)$ exists iff $|\phi(z)| \neq 0$ for $|z| = 1$

② ARMA(p,q) $\left\{ \begin{array}{l} \text{causal} \Leftrightarrow |\psi(z)| \neq 0 \text{ for } |z| \leq 1 \\ \text{invertible} \Leftrightarrow |\theta(z)| \neq 0 \text{ for } |z| \leq 1 \end{array} \right.$

③ ARMA(p,q) $\psi(B)X_t = \theta(B)W_t$ if $|\theta(z)| \neq 0$ for $|z|=1$

Then $\widehat{\psi}(B)$ polynomials $\widehat{\theta}$ and white noise $\{\tilde{W}_t\}$ st.

$\widehat{\psi}(B)X_t = \widehat{\theta}(B)\tilde{W}_t$ is a causal and invertible ARMA

Rmk. we can only stick to causal and invertible MA.

Thm (Representations of ARMA)

For $\{X_t\}$: $\psi(B)X_t = \theta(B)W_t$

① If $\{X_t\}$ is causal, $X_t = \psi(B)W_t$ (Linear combination of $\{W_t\}$)

② If $\{X_t\}$ is invertible, $\psi(B)X_t = W_t$

How to get $\psi(B)$: $\begin{cases} \psi(B)X_t = \theta(B)W_t \\ X_t = \psi(B)W_t \end{cases} \Rightarrow \psi(B)\psi(B)W_t = \theta(B)W_t$

$$(\phi_0 + \phi_1 B + \phi_2 B^2 + \dots)(\psi_0 + \psi_1 B + \psi_2 B^2 + \dots) = (\theta_0 + \theta_1 B + \theta_2 B^2 + \dots)$$

$$\begin{cases} \phi_0\psi_0 = \theta_0 \\ \phi_1\psi_0 + \phi_0\psi_1 = \theta_1 \\ \dots \end{cases} \Rightarrow \text{Solve the linear system}$$

Lesson 7.

1. Computation for ARMA.

1.1. How to get $\Psi(B)$ (causal)

Given ARMA(p, q) $\{X_t\}$ w.t. $\phi(B)X_t = \theta(B)W_t$

If $\{X_t\}$ is causal then $X_t = \Psi(B)W_t$

$$\phi(B)\Psi(B)W_t = \theta(B)W_t \Rightarrow$$

$$(1 - \phi_1B - \dots - \phi_pB^p)(\Psi_0 + \Psi_1B + \dots) = (1 + \theta_1B + \dots + \theta_qB^q)$$

$$\begin{cases} \Psi_0 = 1 \\ \Psi_1 - \Psi_0\phi_1 = \theta_1 \\ \dots \end{cases} \quad \begin{array}{l} \text{Solve the linear system,} \\ \text{then we obtain } \Psi_0, \Psi_1, \dots \end{array}$$

Example $(1 + \frac{1}{4}B^2)X_t = (1 + \frac{1}{2}B)W_t$

$|\phi(z)| = 0 \Rightarrow z = \pm 2i$ $|\theta(z)| = 0 \Rightarrow z = -2 \Rightarrow$ invertible

$$(1 + \frac{1}{4}B^2)(\Psi_0 + \Psi_1B + \Psi_2B^2 + \dots) = 1 + \frac{1}{2}B$$

$$\begin{cases} \Psi_0 = 1 \\ \Psi_1 = \frac{1}{2} \\ \Psi_2 + \frac{1}{4}\Psi_0 = 0 \Rightarrow \Psi_2 = -\frac{1}{4} \\ \Psi_3 + \frac{1}{4}\Psi_1 = 0 \Rightarrow \Psi_3 = -\frac{1}{8} \end{cases}$$

1.2. ITF of ARMA(p, q) $\{X_t\}$ (Don't memorize)

If $\{X_t\}$ causal then $X_t = \Psi(B)W_t$

$$\gamma(h) = \text{Cov}(X_{t+h}, X_t) = \text{Cov}(\Psi(B)W_{t+h}, \Psi(B)W_t)$$

$$= \text{Cov}(\Psi_0 W_{t+h} + \Psi_1 W_{t+h-1} + \dots + \Psi_h W_t, \Psi_0 W_t + \dots)$$

$$= \left(\sum_{j=0}^h \Psi_j \Psi_{j+h} \right) \sigma^2$$

Another approach: Causal: $X_t = \psi(B)W_t \Rightarrow \tilde{B}[\psi] = 0$

$$\psi(B)X_t = \theta(B)W_t$$

$$\tilde{B}[\psi(\phi(B))X_t]X_{t-h} = \tilde{B}[\theta(B)W_t]X_{t-h} = \tilde{B}[(\theta(B)W_t)(\psi(B)W_{t-h})]$$

$$\tilde{B}[\psi(X_t - \phi X_{t-1} - \dots - \phi_p X_{t-p})]X_{t-h}$$

$$= \tilde{B}[(W_t + \theta_1 W_{t-1} + \dots + \theta_q W_{t-q})(\psi_0 W_{t-h} + \psi_1 W_{t-h-1} + \dots)]$$

$$\Rightarrow \gamma(h) - \phi_1 \gamma(h-1) - \dots - \phi_p \gamma(h-p)$$

$$= (\theta_0 \psi_0 + \theta_1 \psi_1 + \dots + \theta_q \psi_{q-h}) \sigma^2 \Rightarrow \text{Linear equation system}$$

Example: ARMA(2,1) $(1 + \frac{1}{4}B^2)X_t = (1 + \frac{1}{2}B)W_t$

$$\psi = (1, \frac{1}{2}, -\frac{1}{4}, -\frac{1}{6}, \dots) \quad \phi = (1, 0, -\frac{1}{4}, 0, \dots) \quad \theta = (1, \frac{1}{2}, 0, \dots)$$

$$\gamma(h) + \frac{1}{4}\gamma(h-2) = \begin{cases} \sigma^2(\psi_0 \theta_0 + \psi_1 \theta_1) = \frac{5}{4}\sigma^2 \\ \sigma^2(\psi_0 \theta_1) = \frac{1}{2}\sigma^2 \\ 0 \end{cases}$$

2. Non-Stationary time series

2.1 Trends model:

$$X_t = \mu_t + W_t, \quad W_t \sim WN(0, \sigma^2)$$

$\left\{ \begin{array}{l} \text{mean changes} \\ \text{variance.} \\ \text{if } \mu_t \text{ usually not decay.} \end{array} \right.$

Deterministic: $\mu_t = C_0 + C_1 t + C_2 t^2$ mean changes over time.

can be converted to stationary by removing trends

Stochastic noise.

Stochastic: $\mu_t = \mu_{t-1} + \varepsilon_t$ $\text{Var}(x_t) \uparrow$. as $t \uparrow$

$\text{Cov}(x_t, x_{t+h})$ decays slowly.

Characteristics.

2.2 Differencing: $\nabla X_t = X_t - X_{t-1}$, $X_t = \mu_t + W_t$

$$(1) \mu_t = C_0 + C_1 t$$

$$Y_t = \nabla X_t = C_1 + W_t - \underline{W_{t-1}} \quad \text{Stationary}$$

$$\text{estimate } C_1 \text{ by } \hat{C}_1 = \frac{1}{n} \sum_{i=1}^{n-1} Y_i$$

How to forecast X_{n+1} ?

$$\nabla X_{n+1} = X_{n+1} - X_n \Rightarrow X_{n+1} = X_n + \nabla X_{n+1} = X_n + \frac{1}{n} \sum_{i=1}^{n-1} Y_i$$

$$(2) \mu_t = C_0 + C_1 t + C_2 t^2$$

$$\nabla^2 X_t = (X_t - X_{t-1}) - (X_{t-1} - X_{t-2}) = X_t - 2X_{t-1} + X_{t-2}$$

(3) Stochastic trend

$$\mu_t = \mu_{t-1} + \delta + \varepsilon_t \quad \text{measurement error}$$

$$Y_t = \mu_t + W_t \quad \text{observation error}$$

$$\nabla X_t = \delta + \varepsilon_t + W_t - W_{t-1} \quad \text{Stationary}$$

or Order data transformation.

① Percentage change $\underbrace{Y_t = (1 + Y_t)}_{\text{non-stationary}} \underbrace{Y_{t-1}}_{\text{stationary}}$ we expect after trans. Y_t is stationary

$$\log Y_t = \log Y_t - \log Y_{t-1} = \log(1 + Y_t) \approx Y_t$$

$$\textcircled{2} f(x) = \log(x) \text{ or } \tilde{f}(x) = \sqrt{x}$$

$$f(x) \approx f(t) + f'(t)(x-t) \quad \text{if } \text{Var}(X) \sim C \text{ then } \text{Var}(\sqrt{X}) \sim \frac{C}{4}$$

$$\text{Var}(\tilde{f}(x)) = (\tilde{f}'(x))^2 \text{Var}(X) \quad \text{if } \text{Var}(X) \sim C \text{ then } \text{Var}(\log(X)) \sim C$$

③ Box-Cox λ : tuning parameter.

$$X_t = \begin{cases} \frac{Y_t^\lambda - 1}{\lambda} & \lambda \neq 0 \\ \log(Y_t) & \lambda = 0 \end{cases}$$

3. ARIMA(p, d, q)

Differencing d times, here root 1

$$\text{Def: } \phi(B) Y^d X_t = \Theta(B) W_t \quad (\phi(B)(1-B)^d X_t = \Theta(B) W_t)$$

$$\text{Example: } X_t = X_{t-1} + W_t \quad \text{ARIMA}(0, 1, 0)$$

Lecture 8

I. Examples of ARIMA(p, d, q)

① ARIMA($p, 1, q$). X_t

$$Y_t = X_t - X_{t-1}$$

$$Y_t = \phi_1 Y_{t-1} - \cdots - \phi_p Y_{t-p} = W_t + \theta_1 W_{t-1} + \cdots + \theta_q W_{t-q}$$

$$\text{Characteristic polynomial: } \tilde{\phi}(z) = (1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p)(1 - z)$$

② If there are no AR in ARIMA i.e. ARIMA(0, d, q)

we call it integral MA (IMA(d, q))

$$\cdot \text{ IMA}(1, 1) \quad X_t - X_{t-1} = W_t - \theta W_{t-1}$$

Assume $X_j = 0$ if $j \leq -m-1$

$$\text{Then } X_t = \sum_{j=-m}^t (X_j - X_{j-1})$$

$$= (W_t + \theta W_{t-1}) + (W_{t-1} + \theta W_{t-2}) + \cdots + (W_{-m} + \theta W_{-m-1})$$

$$= W_t + (1+\theta)W_{t-1} + (1+\theta)W_{t-2} + \cdots + (1+\theta)W_{-m} + \theta W_{-m-1}$$

$$\text{Var}(X_t) = [1 + \theta^2 + (t+m)(1+\theta)^2] \sigma^2 \uparrow \text{Increasing variance.}$$

$$\text{Corr}(X_{t+k}, X_t) \approx \frac{k}{t+m} \rightarrow 1 \text{ For large } t \uparrow \text{ non-decay ACF.}$$

(Check!)

③ ARIMA($p, d, 0$) (no MA in ARIMA)

we call it Autoregressive Integral (ARI(p, d))

$$\cdot \text{ ARI}(1, 1)$$

$$\begin{aligned}
 & (\bar{x}_t - \bar{x}_{t-1}) - \phi(\bar{x}_{t-1} - \bar{x}_{t-2}) = w_t \\
 \Rightarrow & \bar{x}_t = (1 + \phi)\bar{x}_{t-1} - \phi\bar{x}_{t-2} + w_t \\
 & \bar{x}_t - (1 + \phi)\bar{x}_{t-1} + \phi\bar{x}_{t-2} = w_t \\
 \tilde{\psi} = & 1 - (1 + \phi)z + \phi z^2 = (1 - z)(1 - \phi z) \\
 \text{root} = 1: & \text{Implication.}
 \end{aligned}$$

II. Model Specification

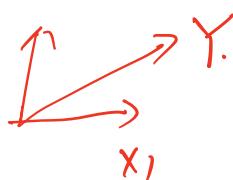
Q. Given real data, which model fits it?

Excuse:

$$Y \sim X_1 \Rightarrow R_1 = 0.1$$

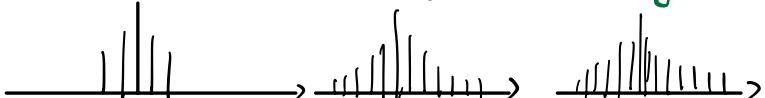
$$Y \sim X_2 \Rightarrow R_2 = 0.2$$

$$Y \sim X_1 + X_2 \Rightarrow R_3? \quad A: 0.2 \leq R_3 \leq 1.$$



A: ARF or Sample ARF.

AR(1)(q) (AR(p)) ARMA(p, q)
 cut off after q. decay decay-



Def of Sampled ARF

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-h} (\bar{x}_{t+h} - \bar{x})(\bar{x}_t - \bar{x})$$

$$\text{ARF: } \hat{P}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}$$

Then if $X_t = \sum_j \psi_j W_{t-j}$ stationary with $\sum_k |W_k|^4 < \infty$

Then $\begin{pmatrix} \hat{\rho}_{(1)} \\ \vdots \\ \hat{\rho}_{(K)} \end{pmatrix} \xrightarrow{\text{Asymptotic}} N\left(\begin{pmatrix} \rho_{(1)} \\ \vdots \\ \rho_{(K)} \end{pmatrix}, \frac{1}{n} V\right)$ as $n \rightarrow \infty$

where $V_{ij} = \sum_{h=1}^{\infty} (\rho_{(i+h)} + \rho_{(i-h)} - 2\rho_{(i)}) (\rho_{(j+h)} + \rho_{(j-h)} - 2\rho_{(j)})$.
(Bartlett's formula)

① White Noise Confidence Interval \Rightarrow Hypothesis testing.

$\begin{pmatrix} \hat{\rho}_{(1)} \\ \vdots \\ \hat{\rho}_{(K)} \end{pmatrix} \xrightarrow{\text{Asymptotic}} N\left(\begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}, \frac{1}{n} I\right)$ as $n \rightarrow \infty$

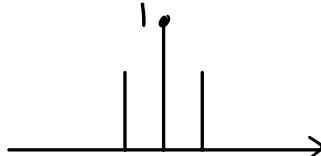
$H_0: X_t$ is white noise $\hat{\rho}_{(h)} \sim N(0, \frac{1}{n})$ (In most case)

Reject H_0 if $|\hat{\rho}_{(h)}| > \frac{Z_{0.025}}{\sqrt{n}} \approx \frac{1.96}{\sqrt{n}}$ (pay attention to $\hat{\rho}_{(1)}$)

② MA(1) $X_t = W_t + \theta W_{t-1}$ $\rho_{(1)} = \frac{|\theta|}{1+\theta^2}$, $|\rho_{(1)}| \leq \frac{1}{2}$

$$V_{11} = 1 - \rho_{(1)}^2 + 4\rho_{(1)}^4 \quad (\text{Check})$$

$$V_{22} = 1 + 2\rho_{(1)}^2$$



Rejection Region:

$$h=1: |\hat{\rho}_{(h)} - \rho_{(1)}| \geq \frac{\sqrt{V_{11}}}{\sqrt{n}} Z_{0.025} \quad (\text{pay attention to } \hat{\rho}_{(1)} \text{ in most case})$$

$$h>1: |\hat{\rho}_{(h)} - \rho_{(h)}| = |\hat{\rho}_{(h)}| > \frac{\sqrt{V_{hh}}}{\sqrt{n}} \times Z_{0.025}$$

③ AR(1): $X_t - \phi X_{t-1} = W_t$, $\rho_{(h)} = \phi^h$

$$V_{ii} \approx \frac{(1+\phi^2)(1-\phi^{2i})}{1-\phi^2} \approx \frac{1+\phi^2}{1-\phi^2} \text{ for large } i \quad (\text{Check})$$

$$V_{11} = 1 - \phi^2$$

Sequential check: estimate one parameter at a time

④ MA(q) $V_{kk} = 1 + 2 \sum_{i=1}^q \rho_{(i)}^2$



Lezione 9. 1. Partial ACF. II. Parameter estimation 2. ML

I. Partial ACF. Generally we assume $\{X_t\}$ is stationary

1.1 Motivation: $X_t \sim AR(1)$ $X_t - \phi X_{t-1} = W_t$

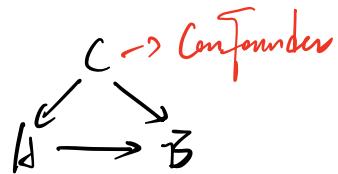
Want to see $\text{Cov}(X_t, X_{t-2})$

$$\begin{aligned}\text{Cov}(X_t, X_{t-2}) &= \text{Cov}(\phi X_{t-1} + W_t, X_{t-2}) \\ &= \text{Cov}(\phi^2 X_{t-2} + \phi W_{t-1} + W_t, X_{t-2}) \\ &= \phi^2 \gamma(0)\end{aligned}$$

Therefore X_t depends on X_{t-2} because X_{t-1} .

But sometimes we want to see correlation b/w X_t, X_{t-2}
without X_{t-1}

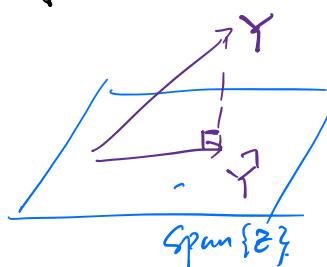
- Remove Confounder: $\begin{cases} \text{Blocking} \\ \text{Fitting - residual} \end{cases}$



1.2 Basic Linear Prediction

Given Y, Z_1, \dots, Z_n r.v. we want to find:

$$\begin{aligned}\hat{\beta}_1, \dots, \hat{\beta}_m \text{ s.t. } \sum_k [Y - \hat{\beta}_1 Z_1 - \hat{\beta}_2 Z_2 - \dots - \hat{\beta}_m Z_m]^2 \text{ minimized} \\ \frac{\partial \sum_k [Y - \hat{\beta}_1 Z_1 - \hat{\beta}_2 Z_2 - \dots - \hat{\beta}_m Z_m]^2}{\partial \hat{\beta}} = \sum_k k Z_i \hat{\beta} - \sum_k k Y Z_i = 0 \\ \Rightarrow \sum_k k Z_i \hat{\beta} = \sum_k k Y Z_i\end{aligned}$$



Example: $Y = X_{n+1}$, $Z_1 = X_n$, $Z_2 = 1$.

$$\hat{\beta}_1 = P = \text{Cov}(X_{n+1}, X_n) \quad \hat{\beta}_2 = (1 - P)\mu$$

$$① \text{Proj}(z_i | Z_1, \dots, Z_n) = z_i$$

$$② Y - \text{Proj}(Y | Z_1, \dots, Z_n) \perp \text{Span}(Z)$$

Def PARC: $\phi_{hh} := \text{Cov}(X_{t+h} - \tilde{X}_{t+h}^{h-1}, X_t - \tilde{X}_t^{h-1})$

where $\tilde{X}_n^h = \text{Proj}(X_n | X_{n-1}, \dots, X_{n-h+1}) = \tilde{\beta}_{h,1} X_{n-1} + \dots + \tilde{\beta}_{hh} X_{n-h+1}$

$\tilde{X}_t^{h-1} = \text{Proj}(X_t | X_{t+1}, X_{t+2}, \dots, X_{t+h-1})$ (Increasing)

$$\hat{X}_{t+h}^{h-1} = \text{Proj}(X_{t+h} | X_{t+h-1}, X_{t+h-2}, \dots, X_{t+1}) \quad (\text{Recessing})$$

Projection In expectation manner.

$$\text{If } \hat{X}_{t+h}^{h-1} = \hat{\beta}_{m,1} X_{t+h-1} + \hat{\beta}_{m,2} X_{t+h-2} + \dots + \hat{\beta}_{m,h-1} X_{t+1}$$

$$\text{Then } \hat{X}_{t+h}^{h-1} = \hat{\beta}_{m,1} X_{t+1} + \hat{\beta}_{m,2} X_{t+2} + \dots + \hat{\beta}_{m,h-1} X_{t+h-1}$$

The same
Coefficients
if mean=0 and
stationary.

Proof: True linear prediction for Y given $Z = (Z_1, \dots, Z_m)^T$

is obtained by $\hat{Y} = \hat{B}^T Y Z$

Crucial fact: ① No matter what $\pi, \hat{\beta}_{m,1}, \dots, \hat{\beta}_{m,h-1}$ are the same

② $\phi_{mh} = \hat{\beta}_{mh}$ $P(h) = \text{lm Coefficients}$

\uparrow
True coefficient of X_{t+h+1}^h

Example:

$$\textcircled{1} \text{ AR}(p) \quad X_t = \phi_1 X_{t-1} + \dots + \phi_p X_{t-p} + W_t$$

$$\begin{aligned} \hat{X}_t^h &= \text{Proj}(X_t | X_{t-1}, \dots, X_{t-h}) \\ &= \text{Proj}\left(\sum_{j=1}^p \phi_j X_{t-j} | X_{t-1}, \dots, X_{t-h}\right) \\ &= \sum_{j=1}^p \phi_j \text{Proj}(X_{t-j} | X_{t-1}, \dots, X_{t-h}) \\ &= \sum_{j=1}^p \phi_j X_{t-j} \quad \text{if } h > p \end{aligned}$$

$$\begin{aligned} \text{If } h \leq p: \quad \hat{X}_t^h &= \sum_{j=1}^p \phi_j \text{Proj}(X_{t-j} | X_{t-1}, \dots, X_{t-h}) \\ &= \sum_{j=1}^p \phi_j X_{t-j} + \sum_{j=h+1}^p \text{Proj}(X_{t-j} | X_{t-1}, \dots, X_{t-h}) \end{aligned}$$

$$\Rightarrow \phi_{mh} = \begin{cases} ? & \text{if } |h| < p \\ \hat{\beta}_{mh} = \phi_h & \text{if } h = p \\ 0 & \text{if } h > p \end{cases}$$

$$\textcircled{2} \text{ MA}(q) \quad X_t = \sum_{j=1}^q \theta_j W_{t-j} + W_t$$

- \tilde{Z}_t^T Unreversible:

$$X_t = \sum_{i=1}^{\infty} \tilde{u}_i X_{t-i} + W_t$$

$$\hat{X}_t^h = \text{Proj}(X_t | X_{t-1}, \dots, X_{t-h})$$

$$= \text{Proj}\left(\sum_{i=1}^{\infty} \tilde{u}_i X_{t-i} + W_t | X_{t-1}, \dots, X_{t-h}\right)$$

$$= \sum_{j=1}^{h-1} \tilde{u}_j X_{t-j} + \sum_{i=h+1}^{\infty} \tilde{u}_i \text{Proj}(X_{t-i} | X_{t-1}, \dots, X_{t-h})$$

usually
 $\tilde{u}_{hh} = \tilde{p}_{hh} \neq 0$

Summary: AR(p) MA(q) ARMA(p,q)

ARF decay cut off at q decay

PLRF cut off at p decay decay

TL How to Compute ARF.

Recall: Basic Linear Prediction for Y given $Z = (z_1 \dots z_m)^T$.

Tucker-Walker's equation:

$$(E ZZ^T) \beta = E Y Z \Leftrightarrow P_h \beta_h = \gamma_h$$

$$\text{In our case } Z = \begin{pmatrix} X_{t+h} \\ \vdots \\ X_t \end{pmatrix} \Rightarrow P_h = E(Z Z^T) = \begin{pmatrix} \gamma_{(0)}, \gamma_{(1)}, \dots, \gamma_{(h-1)} \\ \gamma_{(1)}, \gamma_{(0)}, \dots, \\ \vdots \\ \gamma_{(h-1)}, \gamma_{(0)} \end{pmatrix}$$

\tilde{Z}_t^T solve linear system

$$\gamma_h = E Y Z = (\gamma_{(1)}, \dots, \gamma_{(h)})^T$$

\Rightarrow Complexity $O(h^3)$

1.1. Durbin - Zenvision:

$$\tilde{\beta}_h = (\tilde{\beta}_{h1}, \dots, \tilde{\beta}_{hn})^T \quad \tilde{\beta}_h = (\tilde{\beta}_{hh}, \dots, \tilde{\beta}_{h1})^T$$

$$\gamma_h = (\gamma_{(1)}, \dots, \gamma_{(h)}) \quad \tilde{\gamma}_h = (\gamma_{(h)}, \dots, \gamma_{(1)})^T$$

$$\text{Given } \tilde{\beta}_{h-1}, \quad \tilde{\beta}_h = \begin{pmatrix} \tilde{\beta}_{h-1} - \tilde{\beta}_{hh} \tilde{\beta}_{h-1} \\ \tilde{\beta}_{hh} \end{pmatrix} \quad \tilde{\beta}_{hh} = \frac{\gamma_{(h)} - \tilde{\beta}_{h-1}^T \cdot \tilde{\beta}_{h-1}}{\gamma_{(0)} - \tilde{\beta}_{h-1}^T \cdot \tilde{\beta}_{h-1}}$$

Complexity: $O(n^2)$

Example: AR(2)

$$\hat{\beta}_1 = \hat{\beta}_{11} = \phi_{11} = p_{(1)} = \frac{\gamma_{(1)}}{\gamma_{(0)}}$$

$$\hat{\beta}_{22} = \frac{\gamma_{(2)} - p_{(1)}\gamma_{(1)}}{\gamma_{(0)} - p_{(1)}\gamma_{(1)}} = \frac{p_{(2)} - p_{(1)}^2}{1 - p_{(1)}^2}$$

$$\hat{\beta}_2 = \begin{pmatrix} p_{(1)} - \hat{\beta}_{22}p_{(1)} \\ \hat{\beta}_{22} \end{pmatrix}$$

Zeitreihenanalyse:

I: Parameter Schätzung

II: Methoden für Schätzung: MLE | LS | Moment.

Routinen:

① Platz: Trend, Seasonalität, outlier:

② Daten Transformation: \rightarrow Residual:

a) Differenzierung.

b) Nonlinear: log. Sqrt.

③ Forecasting, inverse Transformation.

Model Tuning:

① Platz ACF, PACF \rightarrow several possible (p, q)

② For each (p, q) fit ARMA(p, q)

③ Compare fitted models by metrics like MSE, AIC, BIC

Assumptions: ① Known (p, q) ② mean 0. (if not, demean)

TI. Method for parameter estimation.

1. MLE. $\{X_t\}$. Stationary, Gaussian

where B , $\phi(B)X_t = \theta(B)W_t$ w/ W_t iid $N(0, \sigma^2)$

$$f(\phi, \theta, \sigma^2) = \frac{1}{(2\pi\sigma^2)^n} \prod_{t=1}^n \exp(-\frac{1}{2} X_t^T T_n^{-1} X_t)$$

$$X = (X_1 \dots X_n)^T, \quad T_n = \begin{pmatrix} X(0) & \dots & X(n-1) \\ \vdots & \ddots & \vdots \\ X(n-1) & \dots & X(0) \end{pmatrix}$$

Advantages:

- ① Consistency. $\hat{\mu}_k \xrightarrow{k \rightarrow \infty}$ true value
- ② Efficiency. Reaches CR lower bound
- ③ Even non-Gaussian. Asymptotically Gaussian.

Disadvantage

- ① Hard to optimize
- ② Need a good initial point.

Examples of MLE: AR(1) (B is a Markov Chain)

$\tilde{B} X_t = \mu \dots, X_t - \mu = \phi(X_{t-1} - \mu) + W_t$. W_t iid $N(0, \sigma^2)$

Observe X_1, \dots, X_n estimate ϕ, μ, σ^2

① Given X_1 :

$$\begin{aligned} f(X_2 \dots X_n | X_1) &= f(X_n | X_{n-1}, \dots, X_1) f(X_{n-1} | X_{n-2}, \dots, X_1) \dots f(X_2 | X_1) \\ &= f(X_n | X_{n-1}) f(X_{n-1} | X_{n-2}) \dots f(X_2 | X_1) \end{aligned}$$

$$X_n | X_{n-1} \sim N(\mu + \phi(X_{n-1} - \mu), \sigma^2)$$

$$f_1(x_2, \dots, x_n | x_1) = (\frac{1}{2\pi\sigma^2})^{n-1} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{i=2}^n (x_i - \mu - \phi(x_{i-1} - \mu))^2 \right\}$$

$$\textcircled{2} \text{Var}(x_i) = \frac{\sigma^2}{1-\phi^2} \quad x_i \sim N(\mu, \frac{\sigma^2}{1-\phi^2})$$

$$\textcircled{3} \text{ } \textcircled{1} + \textcircled{2}: f_1(x_1, \dots, x_n) = f_1(x_1) \cdot f_1(x_2, \dots, x_n | x_1)$$

$$= \frac{\sqrt{1-\phi^2}}{(\frac{1}{2\pi\sigma^2})^n} \exp \left(-\frac{1}{2\sigma^2} \sum_{i=2}^n (x_i - \mu - \phi(x_{i-1} - \mu))^2 + (1-\phi^2)(x_i - \mu)^2 \right)$$

$$\ell(\mu, \phi, \sigma^2) = \log f_1(x_1, \dots, x_n)$$

$$\frac{\partial \ell}{\partial \sigma^2} = 0 \Rightarrow \hat{\sigma}^2 = \frac{\sum \hat{\phi} \hat{x}_i}{n} \quad \text{q. } \hat{\mu} \text{ satisfies } \begin{cases} \frac{\partial \ell}{\partial \mu} = 0 \\ \frac{\partial \ell}{\partial \phi} = 0 \end{cases}$$

$$S(\phi, \mu) = \sum_{i=1}^n (x_i - \mu - \phi(x_{i-1} - \mu))^2 + (1-\phi^2)(x_i - \mu)^2$$

2. Least Square: minimize $\sum_{i=1}^n w_i^2$

$$(LR(1)): \frac{\partial S_L}{\partial \mu} = 0 \Rightarrow \hat{\mu} = \bar{x}$$

$$\frac{\partial S_L}{\partial \phi} = 0 \Rightarrow \hat{\phi} = p_{(1)}$$

3. Moment Method: (matching)

The moment $\hat{\mu}$ ~~see~~ Sampled moment.

$$\mu = \bar{x}, \quad \sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$$

Example LR(1)

$$p_{(k)} = |\phi|^k$$

$$p_{(1)} = \hat{p}_{(1)} \Rightarrow \hat{\phi} = \hat{p}_{(1)} \text{ Sample Mtf.}$$

Example LR(p)

$$\text{Yule-Walker } P_h P_n = \gamma_h \Rightarrow h=p, \quad \vec{P}_p = (\phi_1, \dots, \phi_p)^T$$

$$\widehat{P}_p^T \vec{P}_p = \widehat{\gamma}_p \quad \downarrow \quad \text{Stands only when } h=p$$

in LR. equivalent to $h=\bar{p}$

Lecture 11. 4/7/2023

I. Roadmap

Given a dataset of time series.

Box-Jenkins (Exploratory Data Analysis)
John Tukey

① Plot the data $\left\{ \begin{array}{l} \text{trend} \\ \text{seasonality} \\ \text{outlier} \\ \text{stepchange} \end{array} \right\} \rightarrow \text{need transformation for stationarity.}$

② Data transformation. $\left\{ \begin{array}{l} \text{Differencing} \\ \text{nonlinear} \left\{ \begin{array}{l} \log \\ \sqrt{\cdot} \end{array} \right. \\ \text{smoothing} \end{array} \right\}$

③ Identify hyper-parameters p, q by acf or pacf .
 => Several candidate pairs

$\text{ARIMA}(p, q)$, $\phi(B)$, $\Theta(\bar{B})$, acf pacf etc.

$$\frac{P(h)}{P(h-1)} = 0.3, h=3, \frac{P(12)}{P(1)} \neq 0.3$$

$$P(h) = 0.3 P(h-1)$$

$$\gamma(h) = 0.3 \gamma(h-1)$$

$$\gamma(h) - \phi_1 \gamma(h-1) - \dots - \phi_p \gamma(h-p) = \begin{cases} \sigma^2 \sum_{j=0}^{q-h} \theta_{q-j} \psi_j & h \leq q \\ 0. & h > q \end{cases}$$

$$\phi_i = 0.3, \phi_j = 0, j \geq 2$$

相隔超过 p 的线性方程。
有解即唯一。

④ estimate γ 's for each (p, q)

Yule-Walker equation $\hat{\beta}_h \hat{\beta}_h = \hat{\gamma}_h$

how solve $\phi_i = \beta_i$ when $h=p$

⑤ diagnostic

⑥ Model Selection: choose p, q .

Distribution of \hat{MLE}

$AFM A(p, q) \quad \phi(\beta) Y_t = \theta(\beta) W_t, \quad M \sim N(0, \sigma^2)$ cannot uniquely specify model.

$$\downarrow \text{MLE}$$

$$\begin{aligned} \hat{\phi}_{MLE} &= \hat{\theta}_{MLE} \\ \phi(\beta) Z_t &= W_t \rightarrow T_{\phi\phi} = \begin{pmatrix} \gamma_{\phi(0)} & \cdots & \gamma_{\phi(p-1)} \\ \vdots & \ddots & \gamma_{\phi(p-1)} \\ \gamma_{\phi(p-1)} & \cdots & \gamma_{\phi(0)} \end{pmatrix} \end{aligned}$$

$$\theta(\beta) Y_t = W_t \rightarrow T_{\theta\theta}$$

$$\text{Then } \begin{pmatrix} \hat{\phi}_{MLE} \\ \hat{\theta}_{MLE} \end{pmatrix} \sim IAN \left(\begin{pmatrix} \phi \\ \theta \end{pmatrix}, \frac{\sigma^2}{n} \begin{pmatrix} T_{\phi\phi} & T_{\phi\theta} \\ T_{\theta\phi} & T_{\theta\theta} \end{pmatrix}^{-1} \right)$$

II. Forecast. Given $\hat{\phi}, \hat{\theta}$ for an $AFM A(p, q)$

$$\text{Compute } \hat{T}_n, \hat{\gamma}_n, T_n = \begin{pmatrix} \gamma_{(0)} & \cdots & \gamma_{(n-1)} \\ \vdots & \ddots & \gamma_{(n-1)} \\ \gamma_{(n-1)} & \cdots & \gamma_{(0)} \end{pmatrix}$$

$$\text{Yule-Walker} \Rightarrow \hat{\beta}_n = \hat{T}_n^{-1} \hat{\gamma}_n$$

$$\text{Forecast. } X_t^h = \hat{\beta}_{h1} X_{t+1} + \cdots + \hat{\beta}_{hn} X_{t+h}$$

$$\text{Exercise. Check } P_t^h = \sum (X_t - X_t^h)^2 = \gamma_{(0)} - \gamma_{(h)}^T P_n^{-1} \gamma_{(h)}$$

7.1 Diagnose: goodness of fit.

Time Series = Trend + Seasonality + Stationarity + WN.

Good Fit: WN has iid. mean 0, WN.

① Plot residuals: Any pattern?

② Check aut. corr.: if decay slowly \Rightarrow may not stationary

③ Stationarity check: Dickey - Fuller: unit-root test:

ARMA stationary if $\phi(z)$ has no root $= 1$

④ Mean 0 check: ANOVA

⑤ equal variance check: F-test

⑥ If residuals are uncorrelated:

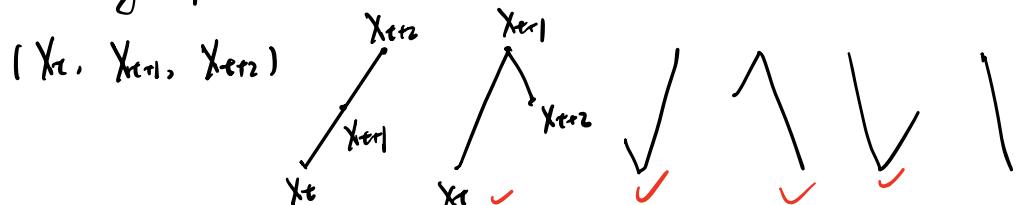
- Zung - Box Pierce test use uncorrected

$$V^2(h) = \sum_{t=h+1}^n (x_t - \bar{x}_h)^2 \quad h=1, \dots, H \quad \text{usually } H=20$$

$$Q = n(n+2) \sum_{h=1}^H \frac{V^2(h)}{n-h} \quad H: p_{(1)} = p_{(2)} = \dots = p_{(H)} = 0$$

$Q \sim \chi^2(H-p-q)$ Before: check mean 0 and equal variance.

- Turning-point test: Test $\{x_t\}$ uncorrelation



$T = \# \text{ turning points}$

$$\mathbb{E}(T) = \frac{2}{3}(n-2) \quad \text{if } n \geq 3$$

- Difference - signed test: uncorrelation
 $N = \#\{t: X_{t+1} > X_t\}$ $\bar{z}[N] = \frac{n-1}{2}$ $N \sim AN(\frac{n}{2}, \frac{n}{12})$
- Rank test: $Z = \#\{(i,j): X_i > X_j\}$
 $\bar{Z}_n = ?$ $Z \sim AN(\frac{n^2}{4}, \frac{n^3}{36})$

① Normal: Q-Q plot

Lecture 12 & 13 ① Model selection ② Forecasting.

1. Model selection:

1. AIC, BIC (Information Criteria)

$$\text{Def } AIC = -2\log ML + 2k$$

$BIC = -2\log ML + k\log n$. Hierer panely.

ML: maximum likelihood.

n: sample size, k = p + q (number of parameters).

2. Overfitting as a selection tool.

Given a data. Suppose AR(1) can fit it well.

If we use AR(2) to fit it. we will observe:

$$① \hat{\phi}_2 \approx 0$$

② $\hat{\phi}_1$ does not change much.

Stepwise selection: Sequentially fit AR(1), AR(2), ..., AR(k)

until we observe the above property.

Remark: When using overfitting as a selection tool.
we need to be as simple as possible.

For example: AR(1) $\not\rightarrow$ ARMA(2,1)

Reason: If $\{x_t\} \sim AR(1)$ $x_t - \phi x_{t-1} = w_t$

Then for any ϕ_2 : $(1 - \phi_2 B)(x_t - \phi_1 x_{t-1}) = (1 - \phi_2)w_t$

Exercise: AR(1) \rightarrow AR(2). Why not ARMA(1,1)?

$$x_t - \phi_1 x_{t-1} = w_t + \theta_1 w_{t-1}$$

Remark: when we use overfitting as a tool,
we always have find a satisfying (P, q)

3. Cross-validation: Data \rightarrow training | validation | testing

• k-Fold CV: For limited data

① CV for hyper parameters \rightarrow fit on all data
 \rightarrow overfitting risk

② residuals are conducted between folds

• In time series:

only care about future observations. For test

1	0	1	1	2	1	3	1	4	1
---	---	---	---	---	---	---	---	---	---

① 0. train. 1. val

② 0. 1. training, 2. val

③ 0. 1. 2. training, 3. val.

II. Forecasting $\left\{ \begin{array}{l} \text{Forecast future } X \\ \text{evaluation} \end{array} \right.$

① Base linear prediction: $h \in \mathcal{L}$

$$\underbrace{\mathbb{E}((X_t - h(X_{t-1}, \dots, X_{t-h}))^2}_{\text{minimized}}$$

$$X_t^h = \beta_{h1} X_{t-1} + \beta_{h2} X_{t-2} + \dots + \beta_{hh} X_{t-h}$$

$$\text{Yule-Walker } P_h \vec{\gamma}_h = \vec{\gamma}_h$$

$$\hat{P}_h^h = \underbrace{\mathbb{E}((X_t - X_t^h)^2)}_{\gamma(0)} = \vec{\gamma}_h^\top P_h^{-1} \vec{\gamma}_h$$

$$X_t^h \pm Z_{1-\alpha/2} \sqrt{\hat{P}_h^h}$$

② Base prediction: f is any function.

$$\underbrace{\mathbb{E}((X_t - f(X_{t-1}, \dots, X_{t-h}))^2}_{\text{minimized}}$$

$$\Rightarrow f(X_{t-1}, \dots, X_{t-h}) = \underbrace{\mathbb{E}(X_t | X_{t-1}, \dots, X_{t-h})}_{\text{Fitterung}}$$

In general, we consider:

$$\underbrace{\mathbb{E}(X_t | X_{t-1}, \dots, X_1)}_{\text{Base predictor}} = \underbrace{\mathbb{E}(X_t | \mathcal{F}_{t-1})}_{\text{Fitterung}}$$

Base predictor for X_{t+h} is still:

$$\underbrace{\mathbb{E}(X_{t+h} | X_1, \dots, X_t)}$$

Example

① Deterministic model $X_t = \mu_t + W_t \sim WN(0, \sigma^2)$

$$\hat{X}_t(1) = \underbrace{\mathbb{E}(X_{t+1} | \mathcal{F}_t)}_{\text{unbiased}} = \mu_{t+1}$$

$$\text{err}_t(1) = W_{t+1} \quad \underbrace{\mathbb{E}(\text{err}_t(1))}_{\text{unbiased}} = 0. \quad \text{Var}(\text{err}_t(1)) = \sigma^2.$$

Unbiased:

$$\mathcal{F}_t = \sigma(X_t, W_t)$$

② In (1): $X_t = W_t + \theta W_{t-1}, \quad W_t \sim WN(0, \sigma^2)$ We may assume $W_0 = 0$.

$$\hat{X}_t(1) = \underbrace{\mathbb{E}(X_{t+1} | \mathcal{F}_t)}_{\text{unbiased}} = \underbrace{\mathbb{E}(W_{t+1} + \theta W_t | \mathcal{F}_t)}_{\text{unbiased}} = \theta W_t$$

$$\text{err}_t(1) = X_{t+1} - \hat{X}_t(1) = W_{t+1} \quad \underbrace{\mathbb{E}(\text{err}_t(1))}_{\text{unbiased}} = 0$$

$$X_t = W_t + \theta W_{t-1}$$

$$X_{t-1} = W_{t-1} + \theta W_{t-2} \dots X_1 = W_1 + \theta W_0 = W_1$$

$$\text{Var}(e_{W_t}(1)) = \sigma^2 \quad \text{Var}(e_{W_t}(2)) = (1+\theta^2) \sigma^2$$

$$\tilde{X}_t(\ell) = \dots$$

③ AR(1) $X_t = \mu + \phi_1 X_{t-1} + W_t \quad W_t \sim \text{WN}(0, \sigma^2)$

$$\tilde{X}_t(1) = \tilde{\mathbb{E}}[X_{t+1} | \mathcal{F}_t] = \mu + \phi_1 X_{t-1}$$

$$\tilde{X}_t(2) = \tilde{\mathbb{E}}[X_{t+2} | \mathcal{F}_t] = \mu + \phi_1 \tilde{\mathbb{E}}[X_{t+1} | \mathcal{F}_t] = \mu + \phi_1 \mu + \phi_1^2 X_{t-1}$$

$$\tilde{X}_t(\ell) = \tilde{\mathbb{E}}[X_{t+1} | \mathcal{F}_t] = \mu + \phi_1 \tilde{X}_t(\ell-1) = \frac{\mu(1-\phi_1^\ell)}{1-\phi_1} + \phi_1^\ell X_t \rightarrow \frac{\mu}{1-\phi_1}$$

Remark: $\tilde{\mathbb{E}}(X_t) = \frac{\mu}{1-\phi_1} = \lim_{\ell \rightarrow \infty} \tilde{X}_t(\ell)$ Best prediction leads to mean.

④ ARMA(1, 1)

$$(1). \text{ARMA}(1, 1) \quad X_t = \mu + \phi_1 X_{t-1} + W_t + \theta_1 W_{t-1}, \quad |\phi_1| < 1, \quad \tilde{\mathbb{E}}(X_t) = \frac{\mu}{1-\phi_1}$$

$$\tilde{X}_t(1) = \tilde{\mathbb{E}}[\mu + \phi_1 X_{t-1} + W_{t+1} + \theta_1 W_t | \mathcal{F}_t]$$

$= \mu + \phi_1 X_t + \theta_1 W_t$ (W_t can be written as $g(\mathcal{F}_t)$?).

$$\tilde{X}_t(2) = \tilde{\mathbb{E}}[X_{t+2} | \mathcal{F}_t] = \mu + \phi_1 \tilde{X}_t(1)$$

$$\tilde{X}_t(\ell) = \mu + \frac{\mu(1-\phi_1^\ell)}{1-\phi_1} + \phi_1^\ell X_t + \theta_1 \phi_1^{\ell-1} W_t \rightarrow \frac{\mu}{1-\phi_1} = \tilde{\mathbb{E}}(X_t).$$

$$e_t(1) = X_{t+1} - \tilde{X}_t(1) = W_{t+1} \quad \text{Var}(e_t(1)) = \sigma^2.$$

\Rightarrow Prediction Interval $\tilde{X}_t(1) \pm 2\sigma$.

$$(2) ARMA(p, q) \quad X_t = \mu + \phi_1 X_{t-1} + \cdots + \phi_p X_{t-p} + \theta_1 W_{t-1} + \cdots + \theta_q W_{t-q}$$

$$\hat{X}_t(1) = \mu + \phi_1 X_t + \cdots + \phi_p \hat{X}_{t+1-p} + \theta_1 W_t + \cdots + \theta_q W_{t+1-q}.$$

$$\hat{X}_t(\ell) = \mu + \sum_{i=1}^p \phi_i \hat{X}_t(\ell-i) + \sum_{j=1}^q \theta_j W_t(\ell-j)$$

We define $\hat{X}_t(\ell-i) = X_{t+\ell-i}$ if $\ell-i \geq 0$

$$W_t(\ell-i) = \begin{cases} 0 & \text{if } \ell-i > 0 \\ W_{t+\ell-i} & \text{if } \ell-i \leq 0 \end{cases}$$

$$e_t(\ell) = X_{t+\ell} - \hat{X}_t(\ell) = \sum_{i=1}^{\min(p, \ell-1)} \phi_i e_{t+i} + \sum_{j=0}^{\min(q, \ell-1)} W_{t+\ell-j} \uparrow \text{as } \ell \uparrow$$

$\text{Var}(e_t(\ell)) < \infty$ for $\ell \rightarrow \infty$. Suppose $\{X_t\}$ is causal

$$X_t = \mu + \sum_{j=0}^{\infty} \psi_j W_{t-j} \quad (\psi_j = 1)$$

$$e_t(\ell) = W_{t+\ell} + \psi_1 W_{t+\ell-1} + \cdots + \psi_{\ell-1} W_{t+1}$$

$$\text{Var}(e_t(\ell)) = \sum_{j=0}^{\ell-1} \psi_j^2 < \infty$$

Prediction interval: $\hat{X}_t(\ell) \pm Z_{\alpha/2} \sqrt{\text{Var}(e_t(\ell))}$ (Assume Gaussian)

or Transformed time series.

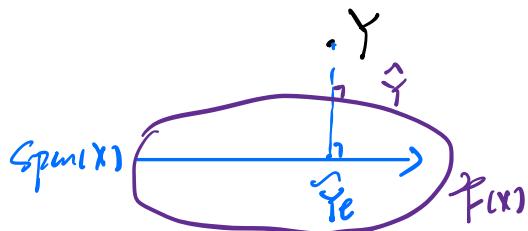
Transform: \varnothing ARIM(0, 1, 1) $\Rightarrow X_t = W_t + \theta_1 W_{t-1}$

$$X_t = W_t + \theta_1 W_{t-1} + Y_{t-1}$$

$$\hat{X}_t(1) = \mathbb{E}[X_{t+1} | \mathcal{F}_t] = X_t + \theta_1 W_t$$

$$\hat{X}_t(2) = \mathbb{E}[X_{t+2} | \mathcal{F}_t] = \mathbb{E}[\hat{X}_{t+1} | \mathcal{F}_t] = X_t + \theta_1 W_t$$

$$\hat{X}_t(\ell) = \mathbb{E}[\hat{X}_{t+1} | \mathcal{F}_t] = X_t + \theta_1 W_t \quad \text{for all } \ell$$



Zyklus 2. Log transformation. $\mathbb{E}(e^{\exp(W_t)}) = \exp(\frac{\sigma^2}{\Sigma})$

$$Z_t = \phi_1 Z_{t-1} + \dots + \phi_p Z_{t-p} + W_t, \quad W_t \sim N(0, \sigma^2)$$

$$Z_t = \log(X_t) \quad X_t = \exp(Z_t) \quad C_t(l) = \phi_1 Z_{t+l-1} + \dots + \phi_p Z_{t+l-p}$$

$$\hat{X}_t(1) = \mathbb{E}[X_{t+1} | \mathcal{F}_t] = \exp\{\phi_1 Z_{t+1} + \dots + \phi_p Z_{t+p}\}$$

$$\begin{aligned} \hat{X}_t(l) &= \mathbb{E}[X_{t+l} | \mathcal{F}_t] = \mathbb{E}[\exp\{Z_{t+l}\} | \mathcal{F}_t] \\ &= \mathbb{E}[\exp(C_t(l)) | \mathcal{F}_t] = \mathbb{E}[\exp(W_{t+l})] \\ &= \mathbb{E}[\exp(C_t(l)) | \mathcal{F}_t] \exp(\frac{\sigma^2}{\Sigma}) \quad \begin{cases} l > p \\ l \leq p \end{cases} \end{aligned}$$

Zyklus 3. $Z_t = \phi_0 + Z_{t-1} + \phi_1 Z_{t-2} + \phi_2 Z_{t-3} + W_t \quad W_t \sim N(0, \sigma^2)$

$$Z_t = \log(X_t)$$

$$\begin{aligned} \hat{X}_t(2) &= \mathbb{E}[X_{t+2} | \mathcal{F}_t] = \mathbb{E}[\exp(Z_{t+2}) | \mathcal{F}_t] \\ &\approx \mathbb{E}[\exp(\phi_0 + Z_{t+1} + \phi_1 Z_t + \phi_2 Z_{t-1} + W_{t+2}) | \mathcal{F}_t] \\ &= \exp(\phi_0 + \frac{\sigma^2}{\Sigma}) \exp(\phi_1 Z_t + \phi_2 Z_{t-1}) \underbrace{\mathbb{E}[\exp(Z_{t+1}) | \mathcal{F}_t]}_{\hat{X}_t(1)} \end{aligned}$$

$$\hat{X}_t(1) = \mathbb{E}[\exp(Z_{t+1}) | \mathcal{F}_t] = \exp(\phi_0 + \frac{\sigma^2}{\Sigma}) \exp\{Z_t + \phi_1 Z_{t-1} + \phi_2 Z_{t-2}\}.$$

Lecture 14. ⑦ Multiplicative seasonal ARIMA model

① Pure seasonal ARIMA model.

Def. For $P, Q \in \mathbb{N}, S \in \mathbb{N}^+$, we say $\{X_t\}$ is an ARIMA $(P, Q)_S$ process if $\Phi(B^S)X_t = \Theta(B^S)W_t$.

$$W_t \sim WN(0, \sigma^2), \quad \Phi(B^S) = 1 - \sum_{j=1}^P \Phi_j B^{Sj}, \quad \Theta(B^S) = 1 + \sum_{j=1}^Q \Theta_j B^{Sj}$$

- ① ARIMA $(P, Q)_S$ stationary iff roots of $\Phi(z^S)$ are not on the unit circle
- ② Causal iff roots of $\Phi(z^S)$ are outside the unit circle.
- ③ Invertible iff ... $\Theta(z^S)$... outside ... — —

Example: MA(1)₁₂

$$P=0, Q=1, S=12$$

$$X_t = W_t + \Theta_1 W_{t-12}$$

$$\gamma(0) = (1 + \Theta_1^2) \sigma^2$$

$$\gamma(12) = \Theta_1 \sigma^2$$

$$\gamma(h) = 0, h \neq 0, 12$$

Example (AR(1)₁₂)

$$P=1, Q=0, S=12$$

$$X_t = \Phi_1 X_{t-12} + W_t$$

$$\gamma(0) = \frac{\sigma^2}{1 - \Phi_1^2}$$

$$\gamma(12i) = \frac{\sigma^2 \Phi_1^i}{1 - \Phi_1^2}$$

$$\gamma(h) = 0 \text{ otherwise}$$

Summary.

Model	$A_i F(h)$	$P_i A_i F(h)$	$h = iS$
AR(P) _S	decay	0 for $i > P$	
MA(Q) _S	0 for $i > Q$	decay	
ARIMA $(P, Q)_S$	decay	decay	

Seasonal + nonseasonal

$$(1) Y_t = W_t + \theta_1 W_{t-1} + \theta_2 W_{t-2}$$

$$(2) Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + W_t$$

Exercise:

$$(3) Y_t = W_t - \theta_1 W_{t-1} - \theta_2 W_{t-2} + \theta_3 W_{t-3} + \theta_4 W_{t-4}$$

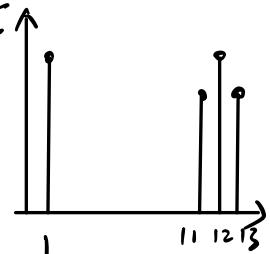
$$\gamma(0) = (1 + \theta_1^2 + \theta_2^2 + \theta_3^2 + \theta_4^2) \sigma^2 = (1 + \theta^2)(1 + \bar{\theta}^2) \sigma^2$$

$$\gamma(1) = -\theta_1 \sigma^2 - \theta_2 \theta_3 \sigma^2 \quad p_{(1)} = \frac{-\theta}{1 + \theta^2}$$

$$\gamma(11) = \theta_1 \theta_4 \sigma^2$$

$$\gamma(12) = -\theta_2 \theta_4 \sigma^2 \quad p_{(11)} = p_{(12)} = \frac{\theta_1 \theta_4}{(1 + \theta^2)(1 + \bar{\theta}^2)}$$

$$\gamma(13) = \theta_3 \theta_4 \sigma^2 \quad p_{(12)} = \frac{-\theta_2}{1 + \theta^2}$$



② Multiplicative Seasonal Models

Def: $P, Q, p, q \geq 0, s > 0$. we say $\{Y_t\}$ is a multiplicative seasonal ARIMA process if $(p, q) \times (P, Q)$,

$$\text{if } (\nabla_s B^s) \phi(B) Y_t = \Theta(B^s) \Theta(B) W_t$$

Additionally, $d > 0$. we say $\{Y_t\}$ is a multiplicative seasonal ARIMA process if $(p, d, q) \times (P, D, Q)$,

$$\text{if } (\nabla_s B^s) \phi(B) \nabla_s^D \nabla_d^d Y_t = \Theta(B^s) \Theta(B) W_t$$

$$\text{where } \nabla_s^D = (1 - B^s)^D$$

How to choose parsas:

① Differencing \rightarrow Stationary

② Aut. PACF to give potential candidates

Example $\bar{\gamma} = q = 1$, $\bar{\gamma} = \theta = 0$, $s = 12$.

$$Y_t = \bar{\gamma} X_{t-12} + W_t - \theta W_{t-1}$$

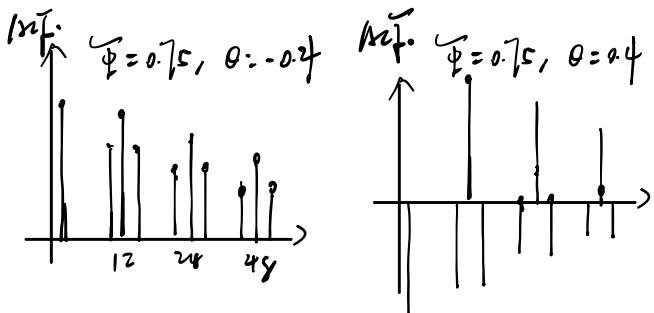
$$\gamma_{(0)} = \frac{(1+\theta^2)\sigma^2}{1-\bar{\gamma}^2} \quad \gamma_{(1)} = \bar{\gamma}^2 \gamma_{(0)} - \theta \theta^2 \Rightarrow \gamma_{(1)} = \frac{-\theta \sigma^2}{1-\bar{\gamma}^2}$$

$$\rho_{(1)} = -\frac{\theta}{1+\theta^2}$$

$$\gamma_{(12k)} = \bar{\gamma}^k \gamma_{(0)}$$

$$\gamma_{(12k-1)} = \bar{\gamma}^k \gamma_{(1)}$$

$$\gamma_{(12k+1)} = \bar{\gamma}^k \gamma_{(1)}$$



Exercise: AR characteristic function. $(1-1.6X+0.7X^2)(1-0.8X^{12})$

① Is it stationary?

② Identify the model as certain seasonal

Solution ① Stationary: Because the roots

$$\text{are } z_1 = \frac{\sqrt{6}}{7} \text{ i } z_2 = -\frac{\sqrt{6}}{7} \text{ i } z_3 = 1.02 \quad z_4 = -1.02$$

② $s = 12$ $\bar{\gamma}(B^s) \phi(B) X_t = W_t$

$$\bar{\gamma}(B^s) = 1 - 0.8B^{12} \quad \phi(B) = 1 - 1.6B + 0.7B^2$$

Exercise: $\{Y_t\}$ satisfies $Y_t = a + bt + S_t + Z_t$

S_t deterministic and periodic with period s

and $\{Z_t\}$ is a seasonal ARIMA $(p, 0, q) \times (P, 1, Q)_s$

What is $\bar{\gamma}_t = Y_t - Y_{t-s}$?

$$\begin{aligned} \bar{\gamma}_t &= a + bt + S_t + Z_t - a - b(t-s) - S_{t-s} - Z_{t-s} \\ &= bs + Z_t - Z_{t-s} \end{aligned}$$

$$\bar{\gamma}(B^s) \phi(B) (1 - B^s) Z_t = \Theta(B^s) \phi(B) W_t$$

$$\tilde{\Psi}(B) \phi(B) (Z_t - Z_{t-s}) = \Theta(B^s) \theta(B) W_t$$

$Z_t - Z_{t-s}$ is ARIMA $(p,q) \times (P,Q)_s$ stationary.

Exercise: Identify the following multiplicative seasonal ARIMA

$$(a) X_t = X_{t-1} + X_{t-12} - X_{t-13} + W_t - 0.5W_{t-1} - 0.5W_{t-2} + 0.25W_{t-3}$$

$$(b) X_t = 0.5X_{t-1} + X_{t-4} - 0.5X_{t-5} + W_t - 0.3W_{t-1}$$

$$\Rightarrow (X_t - X_{t-4}) - 0.5(X_{t-1} - X_{t-5}) = W_t - 0.3W_{t-1}$$

$$(c) X_t - X_{t-1} - X_{t-12} + X_{t-13} = W_t - 0.5W_{t-1} - 0.5W_{t-2} + 0.25W_{t-3}$$

ARIMA $(1, 3) \times (1, 0)_1$

$$(d) (1 - 0.5B)(1 - B^4)(X_t) = (1 - 0.3B)W_t$$

ARIMA $(1, 0, 1) \times (0, 1, 0)_4$

Lesson 15:

① Forecast Seasonal models. Base prediction.

① ARIM(0, 1, 1) \times (1, 0, 1)₁₂

$$X_t - X_{t-1} = \hat{\Phi}(X_{t+12} - X_{t-12}) + W_t - \theta W_{t-1} - \Theta W_{t-12} + \theta \Theta W_{t-13}$$

$$\Rightarrow X_t = X_{t-1} + \hat{\Phi} X_{t+12} - \hat{\Phi} X_{t-12} + W_t - \theta W_{t-1} - \Theta W_{t-12} + \theta \Theta W_{t-13}$$

$$\hat{X}_t(1) = \hat{E}(X_t | \mathcal{F}_t) = X_t + \hat{\Phi} X_{t-1} - \hat{\Phi} X_{t-12} - \theta W_t - \Theta W_{t-1} + \theta \Theta W_{t-12}$$

$$\hat{X}_t(\ell) = \hat{X}_t(\ell-1) + \hat{\Phi} \hat{X}_t(\ell-12) - \hat{\Phi} \hat{X}_t(\ell-13) \text{ if } \ell > 13.$$

② AR(1)₁₂.

$$X_t = \hat{\Phi} X_{t+12} + W_t \quad W_t \sim WN(0, \sigma^2)$$

$$\hat{X}_t(\ell) = \begin{cases} \hat{\Phi} \hat{X}_t(\ell-12), & \ell > 12 \\ \hat{\Phi} X_{t+\ell-12}, & 1 \leq \ell \leq 12 \end{cases} \quad \frac{1 - \hat{\Phi}^{2k+2}}{1 - \hat{\Phi}^2} \sigma^2 ?$$

$$\hat{X}_t(\ell) = \hat{\Phi}^{k+1} X_{t+r-11} \text{ where } \ell = 12k + r + 1, \quad 0 \leq r \leq 12$$

$$e_t(\ell) = X_{t+\ell} - \hat{X}_t(\ell)$$

Ex. Compute $\text{Var}(e_t(\ell))$. where $\ell = 12k + r + 1$

$$\gamma(\ell) = \hat{\Phi}^2 \gamma(0) + \sigma^2 \quad (1 - \hat{\Phi}^2) \gamma(0) = \sigma^2 \quad \gamma(0) = \frac{\sigma^2}{1 - \hat{\Phi}^2}$$

$$\gamma_{(12k+1)} = \text{Cov}(\hat{\Phi}^k X_t, X_t) = \hat{\Phi}^k \gamma(0)$$

$$\text{Var}(e_t(\ell)) = \gamma(0) + \hat{\Phi}^{2k+2} \gamma(0) - 2\text{Cov}(X_{t+r}, \hat{\Phi}^{k+1} X_{t+r-11})$$

$$= (1 + \hat{\Phi}^{2k+2}) \gamma(0) - 2\hat{\Phi}^{k+1} \gamma(\ell - r + 1)$$

$$= (1 + \hat{\Phi}^{2k+2}) \gamma(0) - \hat{\Phi}^{k+1} \gamma(12(k+1))$$

$$= (1 + \hat{\Phi}^{2k+2}) \gamma(0) - 2\hat{\Phi}^{k+1} \hat{\Phi}^{k+1} \gamma(0)$$

$$= \frac{1 - \hat{\Phi}^{2k+2}}{1 - \hat{\Phi}^2} \sigma^2$$

$$\textcircled{1} \quad \ln A(1)_{12} \quad Y_t = W_t + \Theta W_{t-12}$$

$$\tilde{Y}_t(1) = \Theta W_{t-1}$$

$$\tilde{Y}_t(\ell) = \begin{cases} 0 & \ell > 12 \\ \Theta W_{t+12-\ell} & 1 \leq \ell \leq 12 \end{cases}$$

$$e_{t+1} = Y_{t+1} - \tilde{Y}_{t+1} \quad \text{Var}(e_{t+1}) = \begin{cases} \sigma^2, & 1 \leq \ell \leq 12 \\ (1 + \Theta^2) \sigma^2, & \ell > 12 \end{cases}$$

Exercise: $\hat{Y}_t = \frac{1}{2} X_{t-4} + W_t - \theta_1 W_{t-1} - \theta_2 W_{t-2}$

① Find one step four 4-neighbors for the model.

② Suppose $\theta_1 = 0.5$, $\theta_2 = -0.25$, $\sigma^2 = 1$

Find one forecast for next four quarters:

Swiss 25 20 25 20

Austria 2 1 2 3

③ Give 95% prediction interval

Answer:

$$\textcircled{1} \quad (1 - \frac{1}{2} B^4) \hat{Y}_t = (1 - \theta_1 B - \theta_2 B^2) W_t$$

$$(1 - \frac{1}{2} B^4)(1 + \psi_0 + \psi_1 B + \psi_2 B^2 + \dots) W_t = (1 - \theta_1 B - \theta_2 B^2) W_t$$

$$\psi_0 = 1 \quad \psi_1 = -\theta_2 \quad \psi_2 = -\theta_1 \quad \psi_3 = 0 \quad \psi_4 = \frac{1}{2} \quad \psi_5 = \frac{1}{2}$$

Another approach:

$$\hat{Y}_t = \frac{1}{2} X_{t-4} + W_t - \theta_1 W_{t-1} - \theta_2 W_{t-2}$$

$$= \frac{1}{2} (\frac{1}{2} X_{t-8} + W_{t-4} - \theta_1 W_{t-5} - \theta_2 W_{t-6}) + W_t - \theta_1 W_{t-1} - \theta_2 W_{t-2}$$

$$= W_t - \theta_1 W_{t-1} - \theta_2 W_{t-2} + \frac{1}{2} W_{t-4} - \frac{1}{2} \theta_1 W_{t-5} - \frac{1}{2} \theta_2 W_{t-6} + \frac{1}{4} X_{t-8}$$

From role coefficients we can get:

$$\psi_0 = 1 \quad \psi_1 = -\theta_1 \quad \psi_2 = -\theta_2 \quad \psi_3 = 0 \quad \psi_4 = \frac{1}{2}$$

$$\textcircled{2} \quad \tilde{z}(x_5 | \mathcal{F}_4) = \frac{1}{2}x_1 - \theta_1 w_4 - \theta_2 w_3 = 11.5$$

$$\tilde{z}(x_6 | \mathcal{F}_4) = \frac{1}{2}x_2 - \theta_2 w_4 = 10.75$$

$$\tilde{z}(x_7 | \mathcal{F}_4) = \frac{1}{2}x_3 = 12.5$$

$$\tilde{z}(x_8 | \mathcal{F}_4) = \frac{1}{2}x_4 = 20$$

$$\textcircled{3} \quad \ell_{t(1)} = w_{t+1} \quad \text{Var}(\ell_{t(1)}) = \sigma^2 = 1$$

$$\ell_{t(2)} = w_{t+2} - \theta_1 w_{t+1} \Rightarrow \text{Var}(\ell_{t(2)}) = (1 + \theta_1^2) \sigma^2 = \frac{5}{4}$$

$$\ell_{t(3)} = x_{t+3} - \hat{x}_{t(3)} = w_{t+3} - \theta_1 w_{t+2} - \theta_2 w_{t+1}$$

$$\text{Var}(\ell_{t(3)}) = (1 + \theta_1^2 + \theta_2^2) \sigma^2 = \frac{21}{16}$$

$$\ell_{t(4)} = w_{t+4} - \theta_1 w_{t+3} - \theta_2 w_{t+2}$$

$$\Rightarrow \text{Var}(\ell_{t(4)}) = (1 + \theta_1^2 + \theta_2^2) \sigma^2 = \frac{21}{16}$$

The prediction interval for $\hat{x}_{t(i)}$ is $\hat{x}_{t(i)} \pm z_{\alpha/2} \sqrt{\text{Var}(\ell_{t(i)})}$

④ Models For Seasonality (Sine)

$$y_t = s_t + z_t \text{ stationary}$$

Sine seasonality ($s_{t+d} = s_d$) d is the period

⑤ Parameter Model:

$$s_d = a_0 + \sum_{f=1}^k [a_f \sin\left(\frac{2\pi f}{d} t\right) + b_f \cos\left(\frac{2\pi f}{d} t\right)]$$

(Fourier Expansion)

a_f, b_f : amplitude d/f : period for sin, cos

f/d : frequency for sin, cos

k : Hyperparameter

① Non parametric Seasonality Function.

$$\hat{s}_t = \text{mean}(s_i, s_{i+d}, \dots, s_{i+kd}, \dots)$$

Small sample size \Rightarrow overfitting.

② Differencing (Seasonal differencing)

$$x_t - x_{t-d} = z_t - z_{t-d} \text{ stationary.}$$

Models for trend + Seasonality:

$$x_t = \underbrace{m_t}_{\text{Trend}} + \underbrace{s_t}_{\text{Seasonality}} + \underbrace{z_t}_{\text{Stationary}}$$

③ Parametric:

Linear regression $\Rightarrow m_t$

$$\checkmark \text{Fourier series} \Rightarrow \hat{s}_t$$

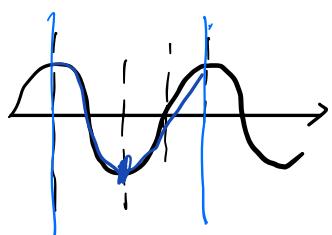
④ Smoothing.

2021.1 - 2021.6 \rightarrow Spring, Summer, Winter

2021.7 - 2021.12 \rightarrow Summer, Fall, Winter. *Heterogeneous*

$$\hat{m}_t = \frac{x_{t-d/2} + x_{t-d/2+1} + \dots + x_{t+d/2}}{d}$$

The time interval for smoothing should match the seasonal period.



$$\begin{aligned} \text{⑤ Differencing } x_t - x_{t-d} &= s_t - s_{t-d} + m_t - m_{t-d} + z_t - z_{t-d} \\ &= m_t - m_{t-d} + z_t - z_{t-d} \end{aligned}$$

Can be done by *lapply* (Seasonal.)

Coefficients will be simpler.

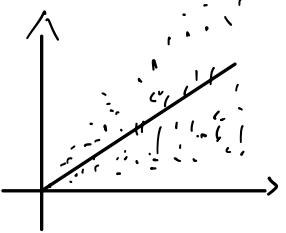
Lecture 16: Financial Time Series.

Price: P_t not comparable across different stocks

Return on the t -th day: $\gamma_t = \log(p_t) - \log(p_{t-1}) \approx \frac{p_t - p_{t-1}}{p_{t-1}}$

Advantage: scaleless.

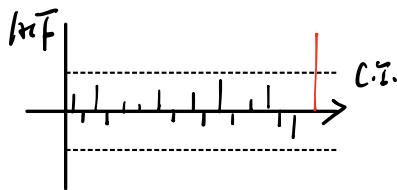
① Features of Returns.

① Heteroscedasticity 

Volatility clustering

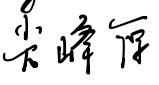


② Serially uncorrelated.

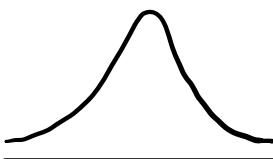


③ Sometimes significantly uncorrelated

④ Peak and heavy tail.

Leptokurtosis. ()

Kurtosis () = $E[(X - \bar{X})^4]$



Meaning: compare tail to standard normal ($= 3$)

> 3 : Heavy tail

Def. For a r.v. X , if there exists C_1, C_2 s.t.

① $P(|X| \geq t) \leq C_1 \exp(-\frac{t^2}{C_2}) \Rightarrow X$ is called sub-Gaussian.

② $P(|X| \geq t) \leq C_1 \exp(-\frac{t}{C_2}) \Rightarrow$ called sub-exponential

Fact: A sub-Gaussian X , $\mu = \mathbb{E}X$, $\sigma^2 = \text{Var}(X)$.

The medians of X when $|\mu - m| < C\sigma$ for some $C > 0$

$$H-D: Y = X\beta + \varepsilon \quad X \in \mathbb{R}^{n \times p} \quad p = h(n) \quad \hat{\beta} \xrightarrow{P} \beta$$

$$K(t) = \log(\mathbb{E}(e^{tX})) \stackrel{\text{Taylor}}{=} \sum_{n=1}^{\infty} K_n \frac{t^n}{n!}$$

$K(1) = \text{mean}$, $K(2) = \text{variance}$, $K(3) = 3\text{rd central moment}$

$$K(4) = \mathbb{E}[X - \mathbb{E}(X)]^4 - 3[\mathbb{E}(X - \mathbb{E}X)^2]^2$$

For normal distribution: $K(n) = 0$ for $n \geq 3$. and normal

is the only distribution with this property.

Summary:

① $\mathbb{E}X$: mean ② $\mathbb{E}(X - \mathbb{E}X)^2$: variance

③ $\mathbb{E}(X - \mathbb{E}X)^3$: skewness

④ $\mathbb{E}(X - \mathbb{E}X)^4$: kurtosis

⑦ Volatility Models. $Y = f(X_1, \dots, X_k) + \varepsilon$

To give ε heteroscedasticity and heavy tail.

We model $\varepsilon = \sigma(X_1, \dots, X_k)V$. $V \text{ iid WN}(0, 1)$ (process model).

ARCH: $\varepsilon_t = \sqrt{h_t} u_t$ $h_t = \alpha_0 + \alpha_1 \varepsilon_{t-1}^2 + \dots + \alpha_q \varepsilon_{t-q}^2$

$u_t \text{ iid WN}(0, 1)$ $u_t \perp \varepsilon_{t-j}, j \geq 1$

$$\mathbb{E}(\varepsilon_t^2) = \mathbb{E}(h_t^2 u_t^2)$$

Properties:

$$\text{Var}(\varepsilon_t | \mathcal{F}_{t-1}) = \mathbb{E}[\varepsilon_t^2 | \mathcal{F}_{t-1}] - \underbrace{\mathbb{E}[\varepsilon_t | \mathcal{F}_{t-1}]^2}_{0}$$

$$= \mathbb{E}[V_t^2] \mathbb{E}[h_t | \mathcal{F}_{t-1}] = \alpha_0 + \alpha_1 \varepsilon_{t-1}^2 + \dots + \alpha_q \varepsilon_{t-q}^2 = h_t$$

$\eta_t = \varepsilon_t^2 - h_t$ η_t : Serially uncorrelated with mean 0

Example AR(1) $\varepsilon_t = \sqrt{h_t} u_t$

① $\text{Var}(\varepsilon_t | \mathcal{F}_{t-1}) = h_t = \bar{\alpha}_0 + 2\bar{\alpha}_1 \varepsilon_{t-1}^2$ (depicts volatility)

The B scale of ε_t \Rightarrow scale of $\underline{\varepsilon_t}$ depends on ε_{t-1}^2

② $\text{Var}(\varepsilon_t) = \mathbb{E}(\varepsilon_t^2) - \mathbb{E}^2(\varepsilon_t) = \mathbb{E}\varepsilon_t^2 = \bar{\alpha}_0 + 2\bar{\alpha}_1 \mathbb{E}\varepsilon_{t-1}^2 + \dots + 2\bar{\alpha}_q \mathbb{E}\varepsilon_{t-q}^2$

Stationarity: $\text{Var}(\varepsilon_t) = \mathbb{E}(\varepsilon_t^2) = \frac{\bar{\alpha}_0}{1 - 2\bar{\alpha}_1 - \dots - 2\bar{\alpha}_q}$ Why?

weak stationarity does not preclude the nonconstant conditional variance.

③ AR(1) $\underline{\varepsilon_t} = 0 \quad \mathbb{E}\varepsilon_t \varepsilon_{t-1} = 0 \Rightarrow \varepsilon_t$ is white noise

④ $\varepsilon_t^2 \sim \text{AR}(1)$ for AR(1) $\varepsilon_t^2 = \bar{\alpha}_1 \varepsilon_{t-1}^2 + u_t + \bar{\alpha}_0$

$$j_t \in \varepsilon_t^2 - \mathbb{E}(\varepsilon_t^2) = \varepsilon_t^2 - h_t \quad \Rightarrow \varepsilon_t^2 = \bar{\alpha}_0 + 2\bar{\alpha}_1 \varepsilon_{t-1}^2 + j_t$$

$$\mathbb{E}j_t = 0 \quad \mathbb{E}j_t j_{t-1} = \mathbb{E}[(\varepsilon_t^2 - \mathbb{E}\varepsilon_t^2)(\varepsilon_{t-1}^2 - \mathbb{E}\varepsilon_{t-1}^2)] = 0$$

⑤ kurtosis AR(1) ε_t iid $N(0, 1)$

$$\begin{aligned} \mathbb{E}\varepsilon_t^4 &= \frac{\bar{\alpha}_0}{1 - 2\bar{\alpha}_1} \quad \mathbb{E}(\varepsilon_t - \mathbb{E}\varepsilon_t)^4 = \mathbb{E}\varepsilon_t^4 = \mathbb{E}(h_t^2 + u_t^2) = \mathbb{E}h_t^2 \\ &= 3\mathbb{E}(\bar{\alpha}_0^2 + 2\bar{\alpha}_1 \varepsilon_{t-1}^2 + 2\bar{\alpha}_0 \bar{\alpha}_1 \varepsilon_{t-1}^2) \end{aligned}$$

$$\xrightarrow{\text{Stationary}} (1 - 3\bar{\alpha}_0^2)\mathbb{E}\varepsilon_t^4 = 3\bar{\alpha}_0^2 + \frac{6\bar{\alpha}_0 \bar{\alpha}_1}{1 - 2\bar{\alpha}_1} = \frac{3\bar{\alpha}_0^2(1 + \bar{\alpha}_1)}{1 - 2\bar{\alpha}_1}$$

$$\Rightarrow \mathbb{E}\varepsilon_t^4 = \frac{3\bar{\alpha}_0^2(1 + \bar{\alpha}_1)}{(1 - \bar{\alpha}_1)(1 - 3\bar{\alpha}_0^2)} \quad \frac{\mathbb{E}\varepsilon_t^4}{(\mathbb{E}\varepsilon_t^2)^2} - 3 > 0$$

⑥ AR(1) (Lagrange Multiplier) testing

$$H_0: \bar{\alpha}_0 = \bar{\alpha}_1 = \dots = \bar{\alpha}_q$$

$$H_1: \bar{\alpha}_0, \bar{\alpha}_1, \dots, \bar{\alpha}_q \neq 0$$

Forcing:

$$h_t = \bar{\alpha}_0 + \bar{\alpha}_1 \varepsilon_{t-1}^2 + \dots + \bar{\alpha}_q \varepsilon_{t-q}^2$$

$$h_{t+1} = \mathbb{E}(h_{t+1} | \mathcal{F}_t) = \bar{\alpha}_0 + \bar{\alpha}_1 \varepsilon_t^2 + \dots + \bar{\alpha}_q \varepsilon_{t+1-q}^2$$

$$h_{t+l} = \mathbb{E}(h_{t+l} | \mathcal{F}_t) = \bar{\alpha}_0 + \bar{\alpha}_1 h_{t+(l-1)} + \dots + \bar{\alpha}_q h_{t+(l-q)} \quad l > q,$$

Lecture 18.

① Generalized ARCH: GARCH(p, q)

Motivation: If ε_t depends on large lag of noise. ε_{t-j}
 Then ARMA(q) has issues: $\begin{cases} \text{parameter estimation not acc} \\ \text{calculation of } h_t \text{ unacc} \end{cases}$

Solution: introduce lags of conditional variance (h_{t-j})

Def. $\varepsilon_t = \sqrt{h_t} v_t$. v_t uncorrelated, indep of ε_{t-j}

$$\mathbb{E} v_t = 0, \quad \text{Var } v_t = 1$$

$$h_t = \alpha_0 + \beta_1 h_{t-1} + \dots + \beta_p h_{t-p} + \underline{\alpha_1 \varepsilon_{t-1}^2 + \dots + \alpha_q \varepsilon_{t-q}^2}$$

Rank. ① Looks like ARMA(p, q)

② More suitable for higher-order ARCH process,
 with less computation (less paras)

③ GARCH(1, 1) \Leftrightarrow AR(∞) $\alpha_0 + \alpha_1 < 1 \Rightarrow$ stationary

Properties of GARCH(1, 1) v_t uncorrelated, indep of ε_{t-j}

$$\begin{cases} \varepsilon_t = \sqrt{h_t} v_t & \mathbb{E} \varepsilon_t = 0 \\ h_t = \alpha_0 + \beta_1 h_{t-1} + \alpha_1 \varepsilon_{t-1}^2 & \text{Var } \varepsilon_t = \frac{\alpha_0}{1 - \alpha_1 - \beta_1} \\ \mathbb{E} v_t = 0, \quad \text{Var}(v_t) = 1. & \beta_1 \neq 1 \end{cases}$$

$$\begin{aligned} ① \quad \mathbb{E}[h_t] &= \alpha_0 + \beta_1 \mathbb{E}[h_{t-1}] + \alpha_1 \mathbb{E}[\varepsilon_{t-1}^2] \\ &= \alpha_0 + (\beta_1 + \alpha_1) \mathbb{E}[h_t] \quad (\text{Stationary}) \\ \Rightarrow \mathbb{E}[h_t] &= \frac{\alpha_0}{1 - \alpha_1 - \beta_1} \quad \text{Var}(\varepsilon_t) = \frac{\alpha_0}{1 - \alpha_1 - \beta_1} \end{aligned}$$

② GARCH: equivalent to AR(∞)

$$h_t = \alpha_0 + \alpha_1 \varepsilon_{t-1}^2 + \beta_1 h_{t-1}.$$

\checkmark Ex. $\varepsilon_t \sim \text{AR}(1)$. we know $\varepsilon_t^2 \sim \text{AR}(1)$

③ $\varepsilon_t \sim \text{GARCH}(p, q) \Rightarrow \varepsilon_t^2 \sim \text{ARMA}(r, p)$, $r = \max(p, q)$.

$$\text{Let } \eta_t = \varepsilon_t^2 - h_t \Rightarrow h_t = \varepsilon_t^2 - \eta_t$$

$$\begin{aligned} \Rightarrow \varepsilon_t^2 &= \eta_t + h_t = \eta_t + \alpha_0 + \beta_1 h_{t-1} + \dots + \beta_p h_{t-p} + \alpha_1 \varepsilon_{t-1}^2 + \dots + \alpha_q \varepsilon_{t-q}^2 \\ &= \eta_t + \alpha_0 + \beta_1 (\varepsilon_{t-1}^2 - \eta_{t-1}) + \dots + \beta_p (\varepsilon_{t-p}^2 - \eta_{t-p}) \\ &\quad + \alpha_1 \varepsilon_{t-1}^2 + \dots + \alpha_q \varepsilon_{t-q}^2 \\ &= \alpha_0 + \eta_t - \beta_1 \eta_{t-1} - \dots - \beta_p \eta_{t-p} + \sum_{j=1}^q (\alpha_j + \beta_j) \varepsilon_{t-j}^2 \end{aligned}$$

where $\alpha_j = 0$ if $j > q$, $\beta_j = 0$ if $j > p$

$$\check{\mathbb{E}}\eta_t = \check{\mathbb{E}}\varepsilon_t^2 - \check{\mathbb{E}}h_t = 0$$

$$\begin{aligned} \text{Cov}(\eta_t, \eta_s) &= \check{\mathbb{E}}\eta_t \eta_s - \check{\mathbb{E}}\eta_t \check{\mathbb{E}}\eta_s \\ &= \check{\mathbb{E}}\eta_t \eta_s = \check{\mathbb{E}}(\varepsilon_t^2 - h_t) \check{\mathbb{E}}(\varepsilon_s^2 - h_s) \\ &= \check{\mathbb{E}}(1 - \eta_t^2)(1 - \eta_s^2) h_t h_s = 0 \\ &= \check{\mathbb{E}}(1 - \eta_t^2) \check{\mathbb{E}}(1 - \eta_s^2) h_t h_s = 0 \end{aligned}$$

$$\text{Var}(\eta_t) = \check{\mathbb{E}}\eta_t^2 = \check{\mathbb{E}}(\varepsilon_t^2 - h_t)^2 = \text{Const. (4th order stationary)}$$

$$④ \check{\mathbb{E}}\varepsilon_t^2 = \alpha_0 + \sum_{j=1}^q (\alpha_j + \beta_j) \check{\mathbb{E}}\varepsilon_{t-j}^2$$

$$\check{\mathbb{E}}\varepsilon_t^2 = \frac{\alpha_0}{1 - \sum_{j=1}^q (\alpha_j + \beta_j)}, \quad r = \max(p, q)$$

Prop. $\check{\mathbb{E}}\eta_t \text{ GARCH}(p, q)$: $\sum_{j=1}^q (\alpha_j + \beta_j) < 1 \Rightarrow \text{stationary}$

\checkmark ARCH(q) Stationary if $1 - 2_1 - \dots - 2_q > 0$
 GARCH(q) Stationary if $1 - \sum_{j=1}^q (2_j + \beta_j) > 0 \quad \gamma = \max(p, q)$

\checkmark Ex. AR(1): $\gamma_t = \sigma_t v_t, \quad \sigma_t^2 = \alpha_0 + \alpha_1 \gamma_{t-1}^2$
 α_0, α_1 unknown parameters. v_t iid WN(0, 1)

- ① Verify $\{\gamma_t\}$ serially uncorrelated w/ mean 0
- ② Verify $\text{Cov}(\gamma_t, \gamma_{t-k}^2) = 0, k > 0$
- ③ Verify $\gamma_t^2 = \alpha_0 + \alpha_1 \gamma_{t-1}^2 + \eta_t \sim AR(1)$

Implies when if $\gamma_t^2 \sim AR(1)$ we can use AR(1) to model it.

Lecture 17: ① Properties of GARCH ② Estimation & Forecasting.

① Properties of GARCH:

② Kurtosis of GARCH. $\frac{\mathbb{E}[\epsilon_t^4]}{\mathbb{E}[\epsilon_t^2]^2} - 3$

Assume: $V_t \sim N(0, 1) \Rightarrow \mathbb{E}[V_t^{2k}] = (2k-1)!!$

$$\mathbb{E}\epsilon_t^4 = \mathbb{E}h_t^2 V_t^4 = 3 \mathbb{E}h_t^2$$

$$\begin{aligned} \mathbb{E}h_t^2 &= \mathbb{E}(2^2 + \beta_1^2 h_{t-1}^2 + 2^2 \epsilon_{t-1}^4 + 2\beta_1 \beta_2 h_{t-1} + 2\beta_1 \epsilon_{t-1}^2 + 2\beta_2 \epsilon_{t-1}^2) \\ &= \dots \end{aligned}$$

Assume 2nd order stationary: $\mathbb{E}h_t^2 = \frac{(1+2+\beta_1)2^2}{(1-3\beta_1^2-\beta_1^2-2\beta_1\beta_2)(1-2-\beta_1)}$

$$\mathbb{E}\epsilon_t^4 = \frac{32^2(1+2+\beta_1)}{(1-3\beta_1^2-\beta_1^2-2\beta_1\beta_2)(1-2-\beta_1)}$$

$$\text{excess kurtosis} = \frac{\mathbb{E}\epsilon_t^4}{(\mathbb{E}\epsilon_t^2)^2} - 3 = \frac{6\beta_1^2}{(1-3\beta_1^2-\beta_1^2-2\beta_1\beta_2)(1-2-\beta_1)} > 0$$

Summary: It has properties of financial time series:

- ① Heteroscedasticity, volatility, clustering.
- ② Serially uncorrelated
- ③ Squares of ϵ_t show significant correlation. ✓
- ④ Heavy-tail.

Exercise: For a stock return data, we model an AR-GARCH to forecast this stock's return and risk.

The model estimation is as follows:

$$Y_t = 0.1 + 0.2 Y_{t-1} + 0.02 Y_{t-2} + \epsilon_t, \quad \epsilon_t = \sqrt{h_t} V_t$$

p-val 0.991 0.0002 0.23

$$h_t = 0.12 + 0.8 h_{t-1} + 0.21 \hat{\epsilon}_{t-1}^2 + 0.08 \hat{\epsilon}_{t-2}^2$$

$\hat{\epsilon}_t$: expected to be uncorrelated

Zung-Box Q test on standardized $\hat{\epsilon}_t$, p-val = 0.2

Squares of standardized $\hat{\epsilon}_t$, p-val = 0.003.

Is this a good model?

① γ_{t-2} is not significant (by previous exercise)

② $\hat{\beta}_1 + \hat{\beta}_2 = 0.8 + 0.21 = 1.01 > 1 \Rightarrow$ nonstationary.

③ Zung-Box. Squares p-val = 0.003 < 0.05

\Rightarrow Noise term correlated

④ Estimation & Forecasting:

Estimation.

MLE of GARCH:

$$\text{GARCH}(1,1) \begin{cases} r_t = \sqrt{h_t} v_t \\ h_t = \alpha_0 + \alpha_1 r_{t-1}^2 + \beta_1 h_{t-1} \end{cases}$$

$$\text{with } h_1 = \sigma^2 = \frac{\alpha_0}{1-\alpha_1-\beta_1}$$

$$\text{conditional pdf: } f(r_1, \dots, r_n | r_{n-1}, \dots, r_1) = \frac{1}{(2\pi h_1)^{n/2}} \exp(-\frac{r^2}{2h_1})$$

$$\text{joint pdf: } f(r_n, \dots, r_1) = f(r_n | r_{n-1}, \dots, r_1) f(r_{n-1} | r_{n-2}, \dots, r_1)$$

$$\text{likelihood: } \mathcal{L}(\alpha_0, \alpha_1, \beta_1) = -\frac{n}{2} \log(h_1) - \frac{1}{2} \sum_{t=1}^n \left\{ \log(h_t) + \frac{r_t^2}{h_t} \right\}$$

$$\text{Maximize } \mathcal{L}(\alpha_0, \alpha_1, \beta_1) \Rightarrow \hat{\theta}_{MLE}$$

$$\hat{\theta}_{MLE} \sim N(\hat{\theta}_{MLE}, J_{\hat{\theta}_{MLE}}) \quad J_{\hat{\theta}_{MLE}} = \left[\frac{\partial \mathcal{L}(\theta)}{\partial \theta^2} \Big| \theta = \hat{\theta}_{MLE} \right]^{-1}$$

- Consistency. $\hat{\theta}_{MLE} \xrightarrow{P} \theta_0$
- Asymptotically normal $\hat{\theta}_{MLE} \xrightarrow{d} N(\theta_0, J_{\theta}(\hat{\theta}_{MLE}))$
- Efficiency: C-R lower bound.

Focussing: GARCH(1,1)

$$\varepsilon_t = \sqrt{h_t} \nu_t \quad h_t = \alpha + \beta_1 h_{t-1} + \gamma \varepsilon_{t-1}^2$$

$$h_{T+1} = \alpha + \gamma \varepsilon_T^2 + \beta_1 h_T$$

$$h_{T(1)} = \overline{E}(h_{T+1} | \mathcal{F}_T) = \alpha + \gamma \varepsilon_T^2 + \beta_1 h_T$$

$$h_{T(1)} = \alpha + \beta_1 h_T V_T^2 + \beta_1 h_T = \alpha + (\alpha + \beta_1) h_T + 2 h_T (V_0^2 - 1)$$

$$h_{T(2)} = \overline{E}(h_{T+2} | \mathcal{F}_T) = \alpha + (\alpha + \beta_1) h_{T(1)}$$

$$h_{T(l)} = \alpha + (\alpha + \beta_1) h_{T(l-1)} \quad l > 1. \quad (\alpha + \beta_1 < 1)$$

$$= \frac{\alpha (1 + (\alpha + \beta_1)^{l-1})}{1 - \alpha - \beta_1} + (\alpha + \beta_1)^{l-1} h_{T(1)}$$

$$\rightarrow \frac{\alpha}{1 - \alpha - \beta_1} \quad l \rightarrow \infty.$$

Remark ① starting w/o unconditional var of GARCH(1,1):

② This condition holds for general GARCH(p,q)

Review: Properties of GARCH(p,q)

$$\textcircled{1} \quad \mathbb{E} \varepsilon_t = 0$$

$$\text{Var}(\varepsilon_t | \mathcal{F}_{t-1}) = h_t$$

$$\text{Var}(\varepsilon_t) = \frac{\alpha}{1 - \sum_j (\alpha_j + \beta_j)}$$

where $\gamma = \max(p, q)$, $\alpha_j = 0$ if $j > q$, $\beta_j = 0$ if $j > p$.

② GARCH(1,1) is equivalent to ARFIM(∞).

③ $\varepsilon_t \sim \text{GARCH}(p, q) \Rightarrow \varepsilon_t^2 \sim \text{ARMA}(r, p)$ $r = \max(p, q)$

④ Express kurtosis of GARCH > 0 \Rightarrow heavy tail

5.23 Zweite Übungen

Ex. 1. Consider an AR(2) model with normal shocks.

$$\gamma_t = \sqrt{h_t} v_t \quad v_t \text{ iid } N(0, 1)$$

$$h_t = 1 + 0.2 \gamma_{t-1}^2 + 0.2 \gamma_{t-2}^2$$

① Compute the unconditional variance

② $\gamma_0 = 1$, $\gamma_1 = -1$. Compute 95% CI for γ_1 and h_8

$$\text{① } \text{Var}(\gamma_0) = \frac{1}{1 - 0.2 - 0.2} = \frac{5}{3} \quad N(0, 1)$$

$$\text{② } E(\gamma_1 | \gamma_0, \gamma_1) = 0 \quad \gamma_1 = \sqrt{1.4} v_1$$

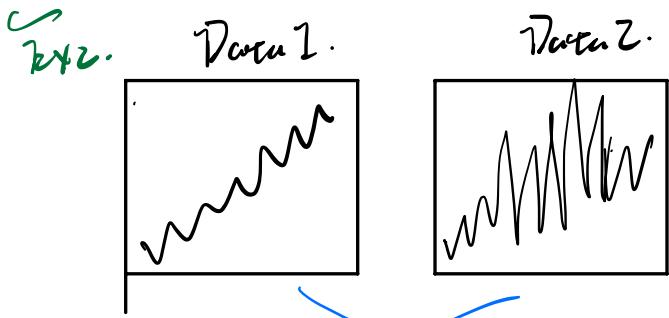
$$E(\gamma_1^2 | \gamma_0, \gamma_1) = 1 + 0.2 \gamma_0^2 + 0.2 \gamma_1^2 = 1.4$$

$$\text{CI: } 0 \pm 2\sqrt{1.4}$$

$$h_8 = 1.2 + 0.2 h_7 \gamma_1^2 = 1.2 + 0.28 \gamma_1^2 \sim \chi^2(1)$$

③ 95% CI of γ_8 ?

④ CI for general GARCH?



$$\textcircled{1} \quad X_t = W_1 + \dots + W_t \quad \text{Model 1.} \quad X_t = a + b + W_t \quad \text{Model 2} \quad \text{which model?}$$

\textcircled{2} Model 1 stationary? No. Var diff $X_t(1-B) = W_t$
 $\Rightarrow \gamma_{20t} = 1$

\textcircled{3} Basic linear prediction of $X_t = W_1 + \dots + W_t$

$$E(X_{n+1} | X_1, \dots, X_n) = E(X_n + W_{n+1} | P_n) = X_n$$

Ex3. $\{X_t\} \sim AR(2)$. process with $X_t(1 + 0.75B - 0.125B^2) = W_t$

Find PACF

$$X_t = -0.75 X_{t-1} + 0.125 X_{t-2} + W_t$$

$$\textcircled{1} \quad PACF(h) = 0 \text{ for } h > p$$

$$\textcircled{2} \quad PACF(p) = \phi_p = 0.125$$

$$\textcircled{3} \quad PACF(1) = ACF(1) = \rho(1)$$

$$X_t = -0.75 X_{t-1} + 0.125 X_{t-2} + W_t$$

Take Compare Cov X_t, X_{t-1} in both sides.

$$\text{Cov}(X_t, X_{t-1}) = -0.75 \rho(0) + 0.125 \rho(1) \Rightarrow \rho(1) = 6/7$$

$$\checkmark \text{Ex 4 } Y_t = S_t + W_t, \quad S_t = S_{t-d}$$

① Show $X_t = Y_t - Y_{t-d}$ is a stationary process

$$Y_t = S_t + W_t - S_{t-d} - W_{t-d} = W_t - W_{t-d} \quad W_t = X_t + W_{t-d}$$

$$\mathbb{E}(Y_t) = 0 \quad \text{Var}(Y_t) = 2 \quad R(h) = 0 \text{ for } h \neq d$$

$$R(d) = \text{Cov}(W_{t-d} - W_t, W_t - W_{t-d}) = -1 \Rightarrow \text{weak memory}$$

② Best linear predictor for X_{nd+1} in terms of X_1, \dots, X_d

$$\text{equals } \frac{1}{n+1} (-X_1 - 2X_{1+d} - \dots - nX_{1+(n-1)d})$$

$$\text{Verify } \hat{X}_{nd+1} - X_{nd+1} = \vec{\gamma} \perp X_i \quad \text{Cov}(\vec{\gamma}, X_i) = 0$$

$$\mathbb{E}(X_{nd+1} | \mathcal{F}_d) = -W_{t-d} = -Y_{t-d} - W_{t-d}$$

$$= -Y_{t-d} - Y_{t-2d} - W_{t-2d}$$

③ Compute Pmf of $\{X_t\}$.

Best linear prediction of y_t given X_{t-1}, \dots

$$\psi_{hb} = \begin{cases} -\frac{1}{n+1}, & h = nd \\ 0, & h \neq nd \end{cases}$$

Final exam:

- ① One double-side chewing piece
- ② Coverage: everything in this semester

Lecture 21: 5/30/2023.

Review Session:

* · Concepts.

- ① mean variance · kurtosis · (excess)
- ② cuf. part (sampled)
- ③ stationary
- ④ causal · / invertible

* EDA · { Scatter plot
Histogram \Rightarrow understand ·
Sampled cuf.

What can you read from plots?

* Non-stationary pattern \Rightarrow Stationarity ·

① Trending { OLS
Smoothing
differencing

① Stationarity {
 modelling.
 Smoothing
 Seasonal differencing
 ARIMA: differencing

↗ Modeling {
 MAF(q)
 AR(p) } properties: ACF, PACF.
 ARMA(p, q), {
 ② Roots of characteristic functions.
 ③ Any stationary model can be approximated by ARMA

↗ Fitting: {
 ML { Consistency.
 asymptotic normality.
 Least squares.
 Monic method

↗ Diagnostic {
 residual analysis { scatter plot
 acf/pacf
 Ljung - Box
 Q-Q plot
 outlier as a test

↗ Forecasting {
 Base linear predictor
 Base prediction.

↗ Inference {
 predictors asymptotic distn. (C.I)
 Prediction · lines

↗ Heterogeneous noise {
 ARH.
 GARCH. (Kurtosis)

Format of Final Exam:

- ① $\bar{T} + \bar{F}$
- ② Residuals \rightarrow Model: $\bar{A}\bar{T} \rightarrow \bar{A}\bar{P}_M\bar{A}$ (relationship)
- ③ Graph Analysis
- ④ Computation: $\bar{A}\bar{P}_M\bar{A}$

Exercise:

- ① True / False.

(a) Estimating the parameters of a seasonal ARIMA(p, q)_s model is equivalent to estimating B equivalent to estimate ARMA(p, q). where $p = p_s$, $q = q_s$

False

(b)

- ② Give two polynomials $\phi(z)$ and $\theta(z)$ so the ARMA $\phi(B)Y_t = \theta(B)W_t$ is stationary, causal, invertible and whose ACF $P_x(h)$ satisfies

$$P_x(h) = 0.4 \text{ for } |h|=1 \text{ and } P_x(h) \geq 0 \text{ for } |h| > 1$$

(b) How above $P_x(h) > 0$ for $|h| \in \{0, 1, 11, 12\}$

and $P_x(h) = 0$. O.W. $Y_t = W_t + W_{t-1} + W_{t-12}$

$$Z(1 + Z'') + 1 = 0$$

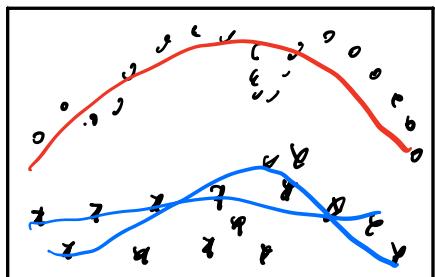
$$X_{t-11} = W_{t-11} + W_{t-12} + \dots$$

$$Z(1 + Z'') + 1 = 0$$

$$W_{t-12} = W_{t-12} -$$

③

OVS & OVB



(a) Find two properties suggesting non-Gaussianity

(b) For each property, suggest a way to modify $\{X_t\}$ to inverse the property

(c) Suppose that the estimate of the mean function in the figure was computed using a kernel smoothing method. What the function would look like if bandwidth \downarrow

④ Computation.

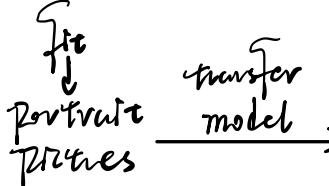
(a) Let $\{X_t\}$ be an AR(1) process w/ $|b| < 1$. What is the best linear prediction of X_{51} in terms of X_1, \dots, X_{50} ?

(b) Write an expression for the mean squared error of the prediction of X_{51} computed in (a)

状态随机模型

* Take-away of Time-series analysis.

- Stationary \leftrightarrow generalize
- Direction: time follows forward
- Ar/ml: overfitting. Do too much in one domain.

① Computer vision: 
Portrait pictures $\xrightarrow{\text{transfer model}}$ skeleton pictures

Domain B stable

Mp: harder

- ② Physics: Newton: overfitting
- ③ Time series: domain always changes
 before stationary parts remain unchanged
- Distribution shift very quickly

Time:

$$\text{return} \approx \frac{P_t}{P_{t-1}} - 1$$

$\gamma_i = \text{Country return}(t) + \text{Industry return}$

+ Style return + Stationary
 Like some Axiom.

Style Exposure: $\frac{1}{\lambda} \sum p_i^2 \hat{\beta}_i^2$

$\hat{\beta}_i$ is the style, $\frac{1}{\lambda} \sum p_i^2$ non-stationary part $\hat{\beta}_i$.