

BS1820: Maths and Statistics Foundations for Analytics

Linear Algebra 2

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Outline

Section 2: Matrices

- Matrices

- Range and Rank

- Determinant

- Matrix Inverse

2.1 Matrices

Matrices are rectangular arrays of numbers. For example:

- $\mathbf{A} = \begin{bmatrix} 2 & 3 & 7 \\ 1 & 6 & 5 \end{bmatrix}$ is a 2×3 matrix

- $\mathbf{B} = [2 \quad 3 \quad 7]$ is a 1×3 matrix \equiv row vector

- $\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$ is an $\mathbf{m} \times \mathbf{n}$ matrix $\in \mathbb{R}^{\mathbf{m} \times \mathbf{n}}$

- $\mathbf{I}_n = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$ is the $n \times n$ **Identity** matrix

Vectors are clearly also matrices — a special case with one column.

2.2 Matrix Operations: Transpose

Transpose: $\mathbf{A} \in \mathbb{R}^{m \times d}$

$$\mathbf{A}^\top = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1d} \\ a_{21} & a_{22} & \dots & a_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{md} \end{bmatrix}^\top = \begin{bmatrix} a_{11} & a_{21} & \dots & a_{m1} \\ a_{12} & a_{22} & \dots & a_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1d} & a_{2d} & \dots & a_{md} \end{bmatrix} \in \mathbb{R}^{d \times m}$$

- Transpose of a row vector is a column vector

Examples:

- $\mathbf{A} = \begin{bmatrix} 2 & 3 & 7 \\ 1 & 6 & 5 \end{bmatrix}$ a 2×3 matrix and $\mathbf{A}^\top = \begin{bmatrix} 2 & 1 \\ 3 & 6 \\ 7 & 5 \end{bmatrix}$ a 3×2 matrix
- $\mathbf{v} = \begin{bmatrix} 2 \\ 6 \\ 4 \end{bmatrix}$ a column vector and $\mathbf{v}^\top = [2 \ 6 \ 4]$ a row vector

2.2 Matrix Operations: Elementwise

$$\mathbf{A} = \begin{bmatrix} 2 & 3 & 7 \\ 1 & 6 & 5 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 1 & 3 & 2 \\ 4 & 8 & 7 \end{bmatrix}$$

Elementwise operations:

1. Addition: $\mathbf{A} + \mathbf{B} = \begin{bmatrix} 3 & 6 & 9 \\ 5 & 14 & 12 \end{bmatrix}$

2. Subtraction: $\mathbf{A} - \mathbf{B} = \begin{bmatrix} 1 & 0 & 5 \\ -3 & -2 & -2 \end{bmatrix}$

3. Scalar multiplication: $5\mathbf{A} = \begin{bmatrix} 10 & 15 & 35 \\ 5 & 30 & 25 \end{bmatrix}$

4. Hadamard product: $\mathbf{A} \circ \mathbf{B} = \begin{bmatrix} 2 & 9 & 14 \\ 4 & 48 & 35 \end{bmatrix}$

5. Hadamard power: $\mathbf{A}^{\circ 2} = \begin{bmatrix} 4 & 9 & 49 \\ 1 & 36 & 25 \end{bmatrix}$

2.2 Matrix Operations: Multiplication

$\mathbf{A} \in \mathbb{R}^{m \times d}$, $\mathbf{B} \in \mathbb{R}^{d \times p}$ then $\mathbf{C} = \mathbf{AB} \in \mathbb{R}^{m \times p}$ with

$$c_{ij} = \begin{bmatrix} a_{i1} & a_{i2} & \dots & a_{id} \end{bmatrix} \begin{bmatrix} b_{1j} \\ b_{2j} \\ \vdots \\ b_{dj} \end{bmatrix}$$

$$c_{22} = a_{21}b_{12} + a_{22}b_{22} + a_{23}b_{32} + a_{24}b_{42}$$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \\ b_{41} & b_{42} & b_{43} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \end{bmatrix}$$

2.2 Matrix Operations: Multiplication

Properties:

- Inner product: $\mathbf{v} \cdot \mathbf{w} = \mathbf{v}^\top \mathbf{w}$

E.g. $\begin{bmatrix} 2 \\ 6 \\ 4 \end{bmatrix} \cdot \begin{bmatrix} 7 \\ 2 \\ 8 \end{bmatrix} = \begin{bmatrix} 2 & 6 & 4 \end{bmatrix} \begin{bmatrix} 7 \\ 2 \\ 8 \end{bmatrix} = 2 \times 7 + 6 \times 2 + 4 \times 8 = 58$

- $(\mathbf{AB})^\top = \mathbf{B}^\top \mathbf{A}^\top$

E.g. Consider $\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$ and $\mathbf{B} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$. We have

$$(\mathbf{AB})^\top = \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix}^\top = \begin{bmatrix} 0 & 0 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} = \mathbf{B}^\top \mathbf{A}^\top$$

- $\mathbf{A} \mathbf{I}_n = \mathbf{I}_m \mathbf{A} = \mathbf{A}$ for any $\mathbf{A} \in \mathbb{R}^{m \times n}$

2.2 Matrix Operations: Multiplication






Example A production manager is scheduling 2 products using 3 machines. Each product can be manufactured by any of the three machines. The time (in hours) required to produce each product with each machine is given below:

		Machine Hours		
				
		A	B	C
Product	Product 1 	2	3	7
	Product 2 	1	6	5

Machine hours

$$\mathbf{A} = \begin{bmatrix} 2 & 3 & 7 \\ 1 & 6 & 5 \end{bmatrix}$$

Assume the following production schedule:

		Production (in units)	
		 Product 1	 Product 2
Machine	A 	5	10
	B 	10	0
	C 	0	3

Production plan

$$\mathbf{B} = \begin{bmatrix} 5 & 10 \\ 10 & 0 \\ 0 & 3 \end{bmatrix}$$

2.2 Matrix Operations: Multiplication

Question: What are the total machine hours spent for each product?

Machine Hours				Production (in units)		
Product		A	B	C	Product 1	Product 2
	Product 1	2	3	7	5	10
	Product 2	1	6	5	0	3

Total Machine Hours Spent		
Product	Product 1	Product 2
	$2 \times 5 + 3 \times 10 + 7 \times 0 = 40$	$1 \times 10 + 6 \times 0 + 5 \times 3 = 25$

We calculate the total machine hours for each product by multiplying the hours needed by each machine (rows of matrix **A**) and the production made on each machine (columns of matrix **B**): the diagonal elements of **AB**.

2.2 Matrix Operations: Multiplication

Facts:

1. Not any two matrices can be multiplied; the dimensions should be **conforming**: # columns of the left matrix = # rows of the right matrix.

E.g. $\begin{bmatrix} 2 & 3 & 7 \\ 1 & 6 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} = \begin{bmatrix} 21 \\ 30 \end{bmatrix}$ but $\begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} \begin{bmatrix} 2 & 3 & 7 \\ 1 & 6 & 5 \end{bmatrix}$ is infeasible.

2. Matrix multiplication is **not commutative**, i.e. $\mathbf{AB} \neq \mathbf{BA}$.

E.g. See above.

3. Matrix multiplication is **associative**, i.e. $(\mathbf{AB})\mathbf{C} = \mathbf{A}(\mathbf{BC})$.

4. Matrix multiplication is **distributive** wrt addition, e.g. $\mathbf{A}(\mathbf{B} + \mathbf{C}) = \mathbf{AB} + \mathbf{AC}$.

Exercises

Question 1: Write the following linear equations in matrix multiplication form.

$$\begin{cases} a_{11}x_1 + a_{12}x_2 = y_1 \\ a_{21}x_1 + a_{22}x_2 = y_2 \end{cases}$$

Question 2: Find a matrix that, through matrix multiplication, transforms the following 3×2 matrix to another whose two columns are the sum and difference of the original two columns, respectively.

$$\begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1+4 & 1-4 \\ 2+5 & 2-5 \\ 3+6 & 3-6 \end{bmatrix}$$

Exercises

Question 1: Write the following linear equations in matrix multiplication form.

$$\begin{cases} a_{11}x_1 + a_{12}x_2 = y_1 \\ a_{21}x_1 + a_{22}x_2 = y_2 \end{cases}$$

Answer:

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

Question 2: Find a matrix that, through matrix multiplication, transforms the following 3×2 matrix to another whose two columns are the sum and difference of the original two columns, respectively.

$$\begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1+4 & 1-4 \\ 2+5 & 2-5 \\ 3+6 & 3-6 \end{bmatrix}$$

Answer: Right multiplied by

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

2.3 Range and Rank

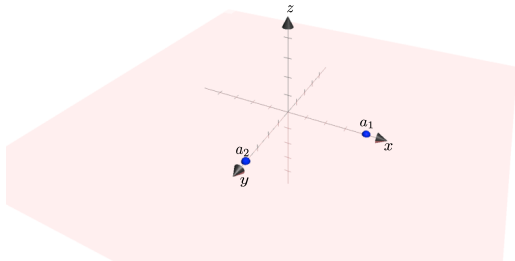
Let $\mathbf{A} \in \mathbb{R}^{m \times n}$, then for any $\mathbf{x} \in \mathbb{R}^n$

$$\mathbf{Ax} = x_1 \mathbf{a}_1 + \cdots + x_n \mathbf{a}_n$$

where \mathbf{a}_i is the i^{th} column of \mathbf{A} and x_i the i^{th} component of \mathbf{x} .

Hence \mathbf{Ax} is a **linear combination** of the **columns** of \mathbf{A} .

Example: Consider $\mathbf{A} = \begin{bmatrix} 4 & 0 \\ 0 & 4 \\ 0 & 0 \end{bmatrix} \in \mathbb{R}^{3 \times 2}$ with $\mathbf{a}_1 = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix}$ and $\mathbf{a}_2 = \begin{bmatrix} 0 \\ 4 \\ 0 \end{bmatrix}$.



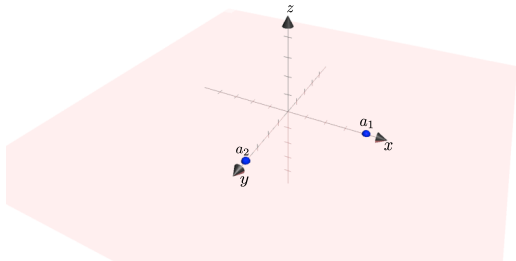
2.3 Range and Rank

Definition. The **range** of $\mathbf{A} \in \mathbb{R}^{m \times n}$, denoted by $\mathcal{R}(\mathbf{A})$, is the **set of vectors** in \mathbb{R}^m that can be obtained as a **linear combination of the columns of \mathbf{A}** :

$$\mathcal{R}(\mathbf{A}) := \{\mathbf{Ax} : \mathbf{x} \in \mathbb{R}^n\}.$$

Clearly $\mathcal{R}(\mathbf{A}) = \text{span}(\{\mathbf{a}_1, \dots, \mathbf{a}_n\})$ and is a **subspace** of \mathbb{R}^m . The dimension of this subspace is the **rank** of \mathbf{A} .

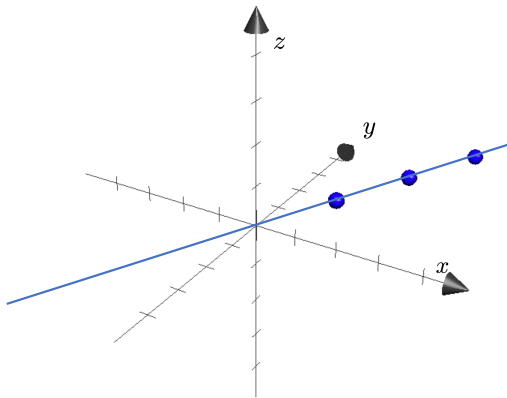
Running example: $\text{span}(\{\mathbf{a}_1, \mathbf{a}_2\}) = \mathbb{R}^2$, $\text{rank}(\mathbf{A}) = 2$.



2.3 Range and Rank

Example:

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \end{bmatrix}, \quad \text{range}(\mathbf{A}) = \left\{ \lambda \begin{bmatrix} 1 \\ 2 \end{bmatrix} : \lambda \in \mathbb{R} \right\}, \quad \text{rank}(\mathbf{A}) = 1$$



2.3 Range and Rank

Properties: For $\mathbf{A} \in \mathbb{R}^{m \times n}$,

Column rank of \mathbf{A} = max number of linearly independent **columns** of \mathbf{A}
= size of the basis (dimension) of **column space** $\mathcal{R}(\mathbf{A})$

Row rank of \mathbf{A} = max number of linearly independent **rows** of \mathbf{A}
= size of the basis (dimension) of **row space** $\mathcal{R}(\mathbf{A}^T)$

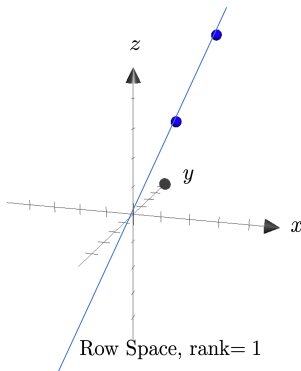
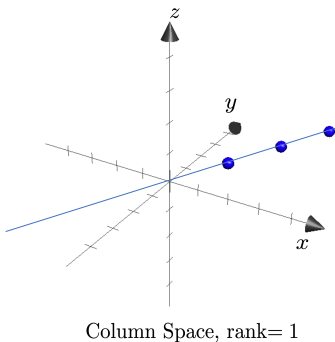
Rank := Column rank of $\mathbf{A} \equiv$ Row rank of $\mathbf{A} \leq \min\{m, n\}$.

2.3 Range and Rank

Rank := Column rank of $\mathbf{A} \equiv$ Row rank of $\mathbf{A} \leq \min\{m, n\}$.

Example:

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \end{bmatrix}$$



2.4 Null Space

Recall: the **column vectors** of matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ span the **column space (range)**:

$$\mathcal{R}(\mathbf{A}) = \text{span}(\{\mathbf{a}_1, \dots, \mathbf{a}_n\}) = \{\mathbf{Ax} : \mathbf{x} \in \mathbb{R}^n\}.$$

How about the vectors $\mathbf{x} \in \mathbb{R}^n$ that satisfy $\mathbf{Ax} = \mathbf{0}$?

The space spanned by such vectors is called the **null space (kernel)** of \mathbf{A} :

$$\mathcal{N}(\mathbf{A}) := \{\mathbf{x} \in \mathbb{R}^n : \mathbf{Ax} = \mathbf{0}\}$$

Fact: Dimension of **column space** ($\text{rank}(\mathbf{A})$) + dimension of **null space** = # of **columns**:

$$\dim(\mathcal{R}(\mathbf{A})) + \dim(\mathcal{N}(\mathbf{A})) = n.$$

Example:

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \end{bmatrix} \Rightarrow \mathcal{N}(\mathbf{A}) = \{\mathbf{x} \in \mathbb{R}^3 : x_1 + 2x_2 + 3x_3 = 0\}$$

It is a plane! $\dim(\mathcal{N}(\mathbf{A})) = 2$.

2.5 Determinant

Consider a 2×2 square matrix

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}.$$

The determinant of \mathbf{A} , denoted by $\det(\mathbf{A})$, is defined as

$$\det(\mathbf{A}) := a_{11}a_{22} - a_{12}a_{21}.$$

Any $\mathbf{x} \in \mathbb{R}^2$ is transformed/mapped to $\mathbf{y} \in \mathbb{R}^2$ by $\mathbf{A}\mathbf{x} = \mathbf{y}$. The unit square in \mathbb{R}^2 gets mapped to a parallelogram in \mathbb{R}^2 with area = $|\det(\mathbf{A})|$.

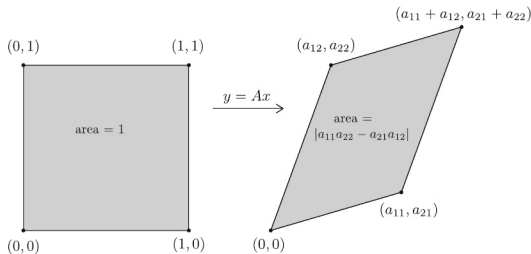


Figure 3.7 from Calafiore and El Ghaoui's *Optimization Models*: Linear mapping of the unit square.

2.5 Determinant

Definition. For a square matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$, its **determinant** is defined *inductively* via the formula

$$\det(\mathbf{A}) = \sum_{j=1}^n (-1)^{i+j} a_{ij} \det(\mathbf{A}_{(i,j)}), \quad \text{for any } i = 1, \dots, n,$$

where $\mathbf{A}_{(i,j)} \in \mathbb{R}^{(n-1) \times (n-1)}$ is \mathbf{A} with its i^{th} row and j^{th} column removed.

- For $\mathbf{A} \in \mathbb{R}^{3 \times 3}$, a unit cube \mapsto a parallelotope in \mathbb{R}^3 with volume $|\det(\mathbf{A})|$.
- Generally, $\mathbf{A} \in \mathbb{R}^{n \times n}$ maps a unit cube in $\mathbb{R}^n \mapsto$ to a parallelotope in \mathbb{R}^n with volume $|\det(\mathbf{A})|$.

2.5 Determinant: Properties

Definition. A square matrix \mathbf{A} is **singular** if $\det(\mathbf{A}) = 0$, **non-singular** otherwise.

For $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$ and $\alpha \in \mathbb{R}$ we have:

1. $\det(\mathbf{A}) = \det(\mathbf{A}^T)$.

E.g. $\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow \det(\mathbf{A}) = a \times d - b \times c$,

$\mathbf{A}^T = \begin{bmatrix} a & c \\ b & d \end{bmatrix} \Rightarrow \det(\mathbf{A}^T) = a \times d - b \times c$

2. $\det(\mathbf{AB}) = \det(\mathbf{BA}) = \det(\mathbf{A})\det(\mathbf{B})$.

3. $\det(\alpha\mathbf{A}) = \alpha^n \det(\mathbf{A})$.

4. $\det(\mathbf{I}_n) = 1$.

E.g. $\mathbf{I}_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ and $\det(\mathbf{I}_2) = 1 \times 1 - 0 \times 0 = 1$

Exercise: Pick square matrices \mathbf{A} and \mathbf{B} to check properties 2 and 3.

2.6 Matrix Inverse

Definition. We say a square matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ is **invertible** if there exists a matrix $\mathbf{A}^{-1} \in \mathbb{R}^{n \times n}$ such that

$$\mathbf{A}^{-1}\mathbf{A} = \mathbf{A}\mathbf{A}^{-1} = \mathbf{I}_n.$$

Such a matrix (if exists) is **unique** and is called the inverse of \mathbf{A} .

Theorem. For a square matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ the following are **equivalent**:

1. \mathbf{A} is **invertible**.
2. \mathbf{A} has **full rank**, i.e. $\text{rank}(\mathbf{A}) = n$.
3. The **column space** of \mathbf{A} is \mathbb{R}^n , i.e. $\mathcal{R}(\mathbf{A}) = \mathbb{R}^n$.
The **null space** of \mathbf{A} only contains the zero vector, i.e. $\mathcal{N}(\mathbf{A}) = \{\mathbf{0}\}$.
4. The **determinant** of \mathbf{A} is **non-zero** (**non-singular**), i.e. $\det(\mathbf{A}) \neq 0$.