

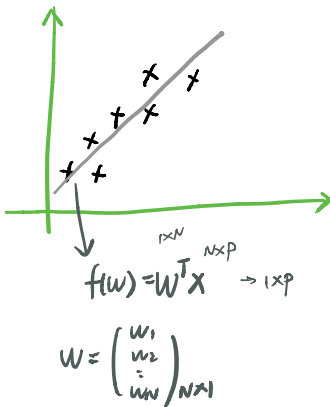
# 线性回归

## 总览

1> 最小二乘法  $\left\{ \begin{array}{l} \text{矩阵表达} \\ \text{几何意义} \end{array} \right.$

2> 概率角度: 最小二乘法  $\Leftrightarrow$  噪声  $w_i$  为 Gaussian MLE ?

3> 正则化  $\left\{ \begin{array}{l} L_1: \text{Lasso} \\ L_2: \text{Ridge regression 岭回归} \end{array} \right.$



$$D = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$$

$$x_i \in \mathbb{R}^P \text{ (特征向量)} \quad y_i \in \mathbb{R} \quad i=1, 2, \dots, N$$

$$X = (x_1, x_2, \dots, x_N)^T \Rightarrow N \times P$$

$$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix}_{N \times 1}$$

$$\begin{pmatrix} x_{11} & x_{12} & \dots & x_{1P} \\ x_{21} & x_{22} & \dots & x_{2P} \\ \vdots & \vdots & \ddots & \vdots \\ x_{N1} & \dots & \dots & x_{NP} \end{pmatrix}_{N \times P}$$

a. 矩阵表达:

$$\text{最小二乘法估计: } L(w) = \sum_{i=1}^N \|w^T x_i - y_i\|^2$$

$$= \sum_{i=1}^N (w^T x_i - y_i)^2$$

$$= (w^T x_1 - y_1 \quad w^T x_2 - y_2 \quad \dots \quad w^T x_N - y_N) \begin{pmatrix} w^T x_1 - y_1 \\ w^T x_2 - y_2 \\ \vdots \\ w^T x_N - y_N \end{pmatrix}$$

$$= \underbrace{w^T (x_1 \ x_2 \ \dots \ x_N) - (y_1 \ y_2 \ \dots \ y_N)}_{\text{}} \begin{pmatrix} w^T x_1 - y_1 \\ w^T x_2 - y_2 \\ \vdots \\ w^T x_N - y_N \end{pmatrix}$$

$$W^T X^T - Y^T$$

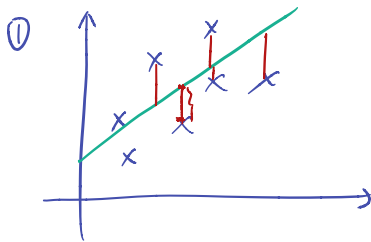
$$(W^T X^T - Y^T)^T = XW - Y$$

$$\begin{aligned} \Rightarrow L(W) &= (W^T X^T - Y^T)(XW - Y) \\ &= W^T X^T XW - W^T X^T Y - Y^T XW + Y^T Y \\ &= W^T X^T XW - \underbrace{2W^T X^T Y}_{?} + Y^T Y \end{aligned}$$

$$\hat{W} = \arg \min L(W)$$

$$\begin{aligned} \hookrightarrow \frac{\partial L(W)}{\partial W} &= 2X^T XW - 2X^T Y = 0 \Rightarrow X^T XW = X^T Y \\ &\Rightarrow W = \underbrace{(X^T X)^{-1}}_{X^+ \text{ 伪逆}} X^T Y \end{aligned}$$

b. 几何表述



$$\begin{aligned} \textcircled{2} \quad f(W) &= W^T X = X^T \beta \\ &\quad \begin{matrix} 1 \times N & N \times p & p \times N & \Rightarrow & p \times 1 \end{matrix} \\ &\quad \downarrow \\ &\quad \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1N} \\ x_{21} & x_{22} & \dots & x_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ x_{p1} & x_{p2} & \dots & x_{pN} \end{pmatrix} \Rightarrow p \times 1 \end{aligned}$$

eg:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} (1 \ 2 \ 3) = \begin{pmatrix} x_1 \\ 2x_2 \\ 3x_3 \end{pmatrix}$$

