Homework 12

due date: 5/3/12 8pm

Send the notebook file of solutions to itsuko@binghamton.edu as an e-mail attachment with subject "Phys468/568 YOUR NAME HW-12".

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1. Show that the Fourier series expansion of $f(x) = x^2 (-\pi < x < \pi)$ is given as

$$x^2 = \frac{\pi^2}{3} + 4\sum_{n=1}^{\infty} (-1)^n \, \frac{\cos n\pi}{n^2} \ .$$

Plot the original function f(x) and Fourier Series up to n=1,5,10 in a same graph.

Note that the Fourier series expansion is defined as follows:

Fourier Series

$$f(x) = \frac{a_0}{2} + \sum_{r=1}^{\infty} \left[a_r \cos\left(\frac{2\pi rx}{L}\right) + b_r \sin\left(\frac{2\pi rx}{L}\right) \right],\tag{4.4}$$

$$a_r = \frac{2}{L} \int_{x_0}^{x_0 + L} f(x) \cos\left(\frac{2\pi rx}{L}\right) dx, \tag{4.7}$$

$$b_r = \frac{2}{L} \int_{x_0}^{x_0 + L} f(x) \sin\left(\frac{2\pi rx}{L}\right) dx, \tag{4.8}$$

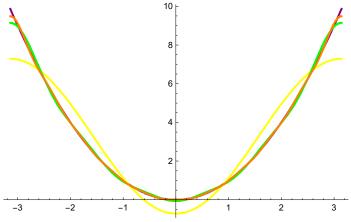
$$\sin n\pi = 0$$
, $\sin \left(n + \frac{1}{2}\right)\pi = (-1)^n$, (4.5)

$$\cos n\pi = (-1)^n, \quad \cos\left(n + \frac{1}{2}\right)\pi = 0.$$
 (4.6)

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$$x\theta = -\pi$$
; L = 2π ;

$$\begin{split} &f[x_{-}] := x^2 \\ &a[r_{-}] := \frac{2}{L} \int_{x\theta}^{x\theta + L} f[x] \, \text{Cos} \Big[\frac{2 \, \pi \, r \, x}{L} \Big] \, dx \\ &b[r_{-}] := \frac{2}{L} \int_{x\theta}^{x\theta + L} f[x] \, \text{Sin} \Big[\frac{2 \, \pi \, r \, x}{L} \Big] \, dx \\ &ar = a[r]; \\ &br = b[r]; \\ &F[n_{-}] := \frac{a[\theta]}{2} + \sum_{r=1}^{n} \left(ar \, \text{Cos} \Big[\frac{2 \, \pi \, r \, x}{L} \Big] + br \, \text{Sin} \Big[\frac{2 \, \pi \, r \, x}{L} \Big] \right) \\ &F1 = F[1]; \\ &F5 = F[5]; \\ &F10 = F[10]; \\ &Plot[\{f[x], F1, F5, F10\}, \{x, \pi, -\pi\}, \\ &PlotStyle \rightarrow \{\{Purple, Thick\}, \{Yellow, Thick\}, \{Green, Thick\}, \{Orange, Thick\}\}] \end{split}$$



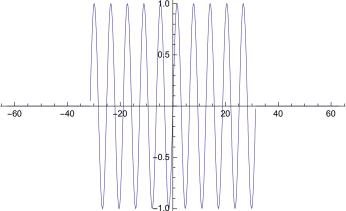
2. Calculate the Fourier Transform of the following function:

g[t] = Sin[
$$\omega$$
0 t] for |t| < $\frac{N\pi}{\omega_0}$ and g[t] = 0 for |t| > $\frac{N\pi}{\omega_0}$

And make plots of g[t] as a function of t (-20 π < t < 20 π) and Im G[ω] as a function of ω (0 < ω < 2). Choose ω 0=1 and N=10.

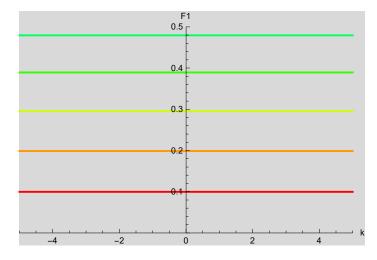
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\omega 0 = 1; n = 10;
x = \frac{n \pi}{\omega 0};
g[t_] = Sin[\omega 0 t] * (UnitStep[t + x] - UnitStep[t - x]);
Plot[g[t], \{t, -20\pi, 20\pi\}]
G1 = FourierTransform[g[t], x, k, FourierParameters \rightarrow {0, -1}] // Simplify[#, t > 0] &
Plot[Evaluate[Table[g[t], \{t, 0.1, 1.0, 0.1\}]], \{k, -5, 5\},
 PlotStyle \rightarrow Table[{Hue[0.1i], Thick}, {i, 0, 10}], PlotRange \rightarrow {{-5, 5}, {0, 0.5}},
 AxesLabel → {"k", "F1"}, Background → LightGray]
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$$\sqrt{\frac{\pi}{2}}$$
 DiracDelta[k] Sin[t] -

$$\sqrt{\textit{2}\,\pi}\,\, \texttt{DiracDelta[k]} \, \times \, \texttt{HeavisideTheta[-10}\,\pi + \texttt{t]} \,\, \texttt{Sin[t]} \,\, + \,\, \frac{\texttt{Sin[t]} \,\, (-\,\texttt{i}\,\, \texttt{Cos[k\,t]} \, + \,\, \texttt{Sin[k\,t]} \,)}{\texttt{k}\,\, \sqrt{2\,\pi}}$$



3. Show your own work on Animate/Manipulate!

```
\& 0 = a0; "Gl = bladl; *g" \delta : -9.8; y0 = 0;
 \begin{array}{l} Graphics [\{Arrow[\{\{0,0\},\{0,5\}\}\},Arrow[\{\{0,0\},\{10,0\}\}],Blue, \\ x[t] = x0+vt;y[t] = y0+vt+-gt^2 \\ Disk[\{.5,1.5\},.5],Black,Polygon[\{\{0,0\},\{1,1\},\{1,3\},\{0,2\}\}]\}] \end{array} 
Animate[Graphics[{Arrow[{{0,0}, {0,5}}],
     Arrow[\{\{0,\,0\},\,\{1+x[t],\,0\}\}],\,Red,\,Disk[\{x[t]+.5,\,y[t]+1.5\},\,.5],
     Black, Polygon[{{0, 0}, {1, 1}, {1, 3}, {0, 2}}]}], {t, 0, 2.2}]
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$$\begin{split} & \times 0 = 0; \ v = 10; \ g = -9.8; \ y0 = 0; \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt + \frac{1}{2} g \, t^2 \\ & \times [t_{-}] = x0 + vt; \ y[t_{-}] = y0 + vt; \ y[t_{-}] = y0$$

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 $10 t - 4.9 t^2$

