

# Homework 10

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Introduction to Analysis II

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## Problem 1.

- (a) Suppose that  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is of class  $C^1$  and  $Df(x_0)$  has rank  $m$ . Show that there exist a whole neighborhood of  $f(x_0)$  lying in the image of  $f$ .
- (b) Suppose that  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is of class  $C^1$  is one-to-one and  $Df(x_0)$  is one-to-one. Show that  $f$  is one-to-one a neighborhood of  $x_0$ .

*Proof.* (a) Let  $f(x_1, x_2, \dots, x_n) = \begin{pmatrix} f_1(x_1, x_2, \dots, x_n) \\ \vdots \\ f_m(x_1, x_2, \dots, x_n) \end{pmatrix}$ . Since  $\text{rank}(Df(x_0)) = m$ , we can select  $m$  of

the column vector of  $Df(x_0)$  such that the vector space it forms has dimension  $m$ , without loss of generality, suppose the first  $m$  column of  $Df(x_0)$  are linearly independent. Let  $g(x_1, x_2, \dots, x_n) =$

$$\begin{pmatrix} f_1(x_1, x_2, \dots, x_n) \\ \vdots \\ f_m(x_1, x_2, \dots, x_n) \\ x_{m+1} \\ \vdots \\ x_n \end{pmatrix}, \text{ then } Dg(x_0) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_m} & \frac{\partial f_1}{\partial x_{m+1}} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_m} & \frac{\partial f_m}{\partial x_{m+1}} & \cdots & \frac{\partial f_m}{\partial x_n} \\ 0 & & & 1 & & \\ & 0 & & & 1 & \\ & & \ddots & & & \ddots \\ & & & 0 & & 1 \end{pmatrix} \text{ then } \det(Dg(x_0)) \neq$$

0. since the product of the first  $m$  column is independent, and since  $f(x_1, x_2, \dots, x_n)$  is  $C^1$ ,  $g(x_1, x_2, \dots, x_n)$  is  $C^1$ . By Inverse function theorem, there exist  $U = B_\delta(x_0) \subset \mathbb{R}^n$  and  $V = B_\epsilon(g(x_0)) \subset \mathbb{R}^n$  such that

$$f(U) = V. \text{ Choose } y \in B_\epsilon(f(x_0)) \in \mathbb{R}^m. \text{ Define } y' = \begin{pmatrix} y \\ x_{m+1} \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n, \text{ since } \|f(x_0) - y\| = \|g(x_0) - y'\| <$$

$\epsilon$ , then there exist  $x^* \in U$  such that  $g(x^*) = y'$ . By comparing the component of the vector, we see that  $y = f(x^*)$ . Hence  $y \in \text{im}(f)$ . Therefore,  $f$  is an open mapping.

- (b) Since  $Df(x_0)$  is injective,  $\text{nullity}(Df(x_0)) = 0$ , by rank and nullity theorem  $\text{rank}(Df(x_0)) = n \leq m$ ,

without loss of generality suppose the first  $n$  column  $Df(x_0)$  is linearly independent. let  $f(x) = \begin{pmatrix} f_1(x) \\ f_2(x) \\ \vdots \\ f_m(x) \end{pmatrix}$

, define  $g(x) = \begin{pmatrix} f_1(x) \\ f_2(x) \\ \vdots \\ f_n(x) \end{pmatrix}$ , then  $\det(Dg(x_0)) \neq 0$ . By inverse function theorem, there exists  $U = B_\delta(x_0) \subset \mathbb{R}^n$  and  $V = B_\delta(g(x_0))$  such that  $g$  is one-to-one on  $U$ . Suppose  $f(x) = f(y)$  where  $x, y \in U$ , then since

$f(x) = \begin{pmatrix} g(x) \\ f_{n+1}(x) \\ f_{n+2}(x) \\ \vdots \\ f_m(x) \end{pmatrix}$ , comparing the component, since  $g(x) = g(y)$ , it follows that  $x = y$ . Hence  $f$  is one-to-one on  $U$ . we are done. □

## Problem 2.

Use Inverse Function Theorem to determine whether the system

$$\begin{aligned} u(x, y, z) &= x + xyz \\ v(x, y, z) &= y + xy \\ w(x, y, z) &= z + 2x + 3z^2 \end{aligned}$$

can be solved for  $x, y, z$  in terms of  $u, v, w$  near  $p = (0, 0, 0)$

*Proof.* Since  $u(x, y, z), v(x, y, z), w(x, y, z)$  is polynomial of  $x, y, z$  then  $u, v, w$  is  $C^1$ . The derivative of the system  $f(x, y, z) = \begin{pmatrix} u(x, y, z) \\ v(x, y, z) \\ w(x, y, z) \end{pmatrix}$  is  $\begin{pmatrix} 1 + yz & xz & xy \\ y & 1 + x & 0 \\ 2 & 0 & 1 \end{pmatrix}$ , and thus  $J_f(0, 0, 0) = 1 \neq 0$ . By inverse function theorem, there exists a open set  $U$  contains  $(0, 0, 0)$  and open set  $V$  that contains  $f(0, 0, 0) = (0, 0, 0)$  such that  $f : U \rightarrow V$  is an isomorphism. Given  $y = f(x)$  and since  $Df^{-1}(y) = [Df(x)]^{-1}$ ,

$$Df^{-1}(x, y, z) = \frac{1}{1 + yz - 2xy - x} \begin{pmatrix} 1 + x & -y & -2(1 + x) \\ -xz & 1 + yz - 2xy & 2xz \\ -xy(1 + x) & xy^2 & 1 + x + yz \end{pmatrix}$$

Notice that the expression is in terms of  $x, y, z$  not  $u, v, w$ , and is not possible to do substitution to eliminate other variables thus the system can not be solved for  $x, y, z$  in terms of  $u, v, w$ . □