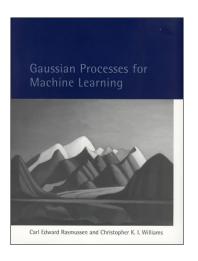
Introduction to Gaussian Processes

Neil D. Lawrence

GPSS 10th June 2013

Book



Rasmussen and Williams (2006)

Outline

The Gaussian Density

Covariance from Basis Functions

Basis Function Representations

Constructing Covariance

GP Limitations

Conclusions

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Conclusion

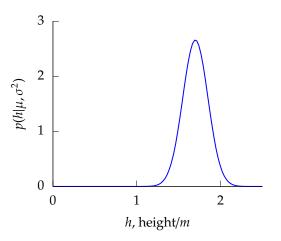
The Gaussian Density

▶ Perhaps the most common probability density.

$$p(y|\mu,\sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y-\mu)^2}{2\sigma^2}\right)$$
$$\stackrel{\triangle}{=} \mathcal{N}\left(y|\mu,\sigma^2\right)$$

► The Gaussian density.

Gaussian Density



The Gaussian PDF with $\mu = 1.7$ and variance $\sigma^2 = 0.0225$. Mean shown as red line. It could represent the heights of a population of students.

Gaussian Density

$$\mathcal{N}(y|\mu,\sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y-\mu)^2}{2\sigma^2}\right)$$

 σ^2 is the variance of the density and μ is the mean.

Sum of Gaussians

▶ Sum of Gaussian variables is also Gaussian.

$$y_i \sim \mathcal{N}\left(\mu_i, \sigma_i^2\right)$$

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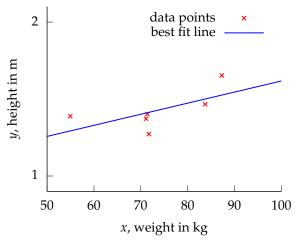
► Scaling a Gaussian leads to a Gaussian.

$$y \sim \mathcal{N}\left(\mu, \sigma^2\right)$$

And the scaled density is distributed as

$$wy \sim \mathcal{N}\left(w\mu, w^2\sigma^2\right)$$

Linear Function

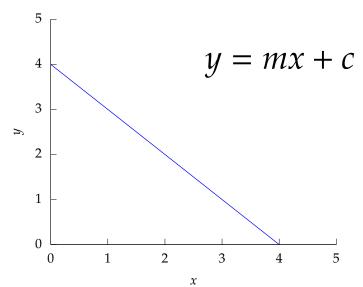


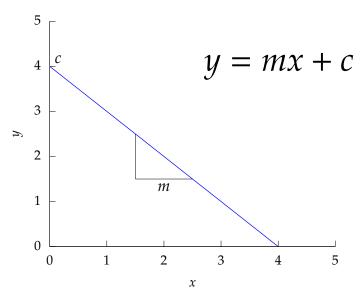
A linear regression between height and weight.

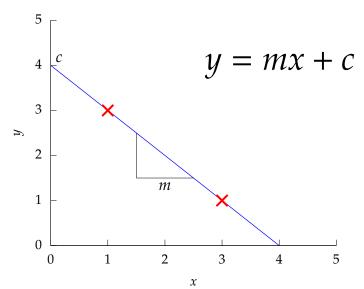
Regression Examples

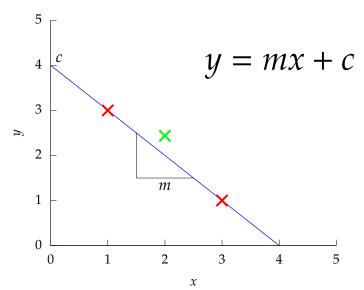
- ▶ Predict a real value, y_i given some inputs x_i .
- Predict quality of meat given spectral measurements (Tecator data).
- ▶ Radiocarbon dating, the C14 calibration curve: predict age given quantity of C14 isotope.
- Predict quality of different Go or Backgammon moves given expert rated training data.

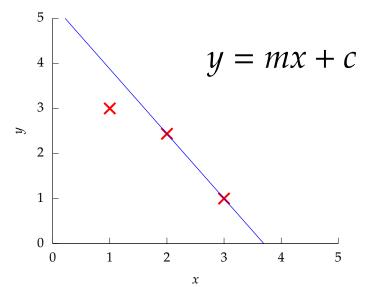
y = mx + c

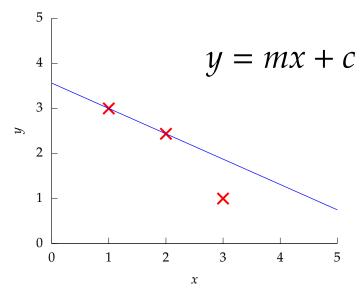


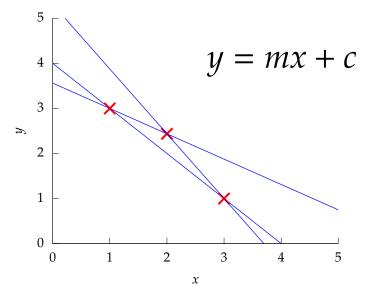












$$y = mx + c$$

point 1:
$$x = 1$$
, $y = 3$
 $3 = m + c$

$$3 = m + c$$
point 2: $x = 3$, $y = 1$

$$1 = 3m + c$$

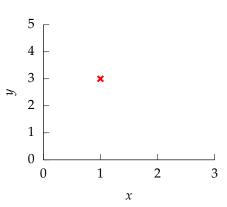
$$1 = 3m + c$$
point 3: $x = 2$, $y = 2.5$

$$2.5 = 2m + c$$

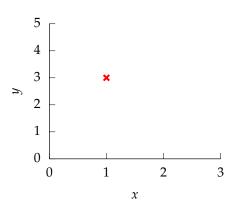
point 1:
$$x = 1$$
, $y = 3$
 $3 = m + c + \epsilon_1$
point 2: $x = 3$, $y = 1$
 $1 = 3m + c + \epsilon_2$
point 3: $x = 2$, $y = 2.5$
 $2.5 = 2m + c + \epsilon_3$

What about two unknowns and *one* observation?

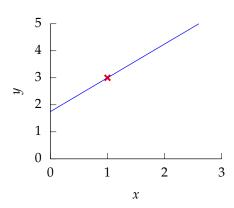
$$y_1 = mx_1 + c$$



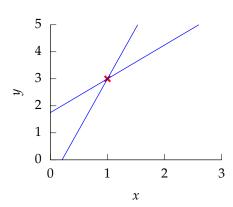
$$m = \frac{y_1 - \alpha}{\gamma}$$



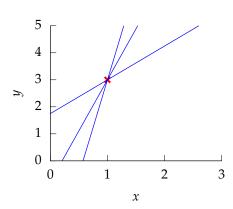
$$c = 1.75 \Longrightarrow m = 1.25$$



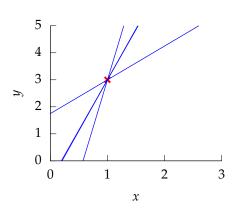
$$c = -0.777 \Longrightarrow m = 3.78$$



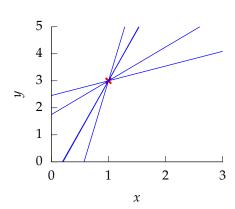
$$c = -4.01 \Longrightarrow m = 7.01$$



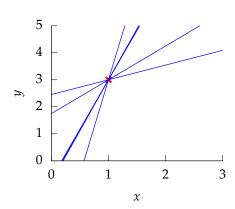
$$c = -0.718 \Longrightarrow m = 3.72$$



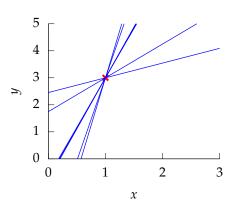
$$c = 2.45 \Longrightarrow m = 0.545$$



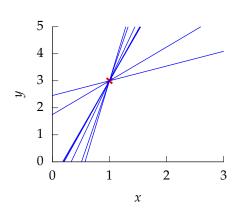
$$c = -0.657 \Longrightarrow m = 3.66$$



$$c = -3.13 \Longrightarrow m = 6.13$$



$$c = -1.47 \Longrightarrow m = 4.47$$

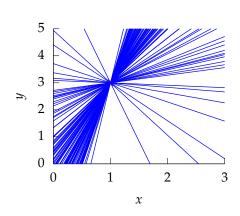


Underdetermined System

Can compute m given c. Assume

$$c \sim \mathcal{N}(0,4)$$
,

we find a distribution of solutions.



Probability for Under- and Overdetermined

- ▶ To deal with overdetermined introduced probability distribution for 'variable', ϵ_i .
- ► For underdetermined system introduced probability distribution for 'parameter', *c*.
- ► This is known as a Bayesian treatment.

Multivariate Prior Distributions

- ► For general Bayesian inference need multivariate priors.
- E.g. for multivariate linear regression:

$$y_i = \sum_i w_j x_{i,j} + \epsilon_i$$

(where we've dropped *c* for convenience), we need a prior over **w**.

- ► This motivates a *multivariate* Gaussian density.
- ▶ We will use the multivariate Gaussian to put a prior *directly* on the function (a Gaussian process).

Multivariate Prior Distributions

- ► For general Bayesian inference need multivariate priors.
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$$y_i = \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i,:} + \epsilon_i$$

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Prior Distribution

- ▶ Bayesian inference requires a prior on the parameters.
- ► The prior represents your belief *before* you see the data of the likely value of the parameters.
- ► For linear regression, consider a Gaussian prior on the intercept:

$$c \sim \mathcal{N}(0, \alpha_1)$$

Gaussian Noise

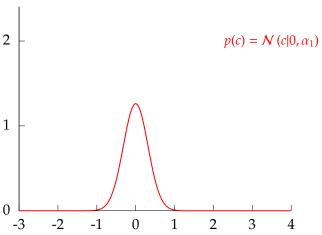


Figure: A Gaussian prior combines with a Gaussian likelihood for a Gaussian posterior.

Gaussian Noise

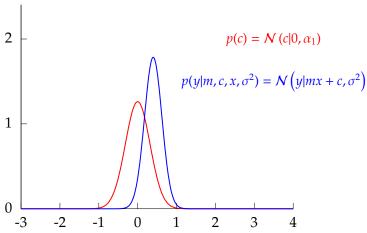


Figure: A Gaussian prior combines with a Gaussian likelihood for a Gaussian posterior.

Gaussian Noise

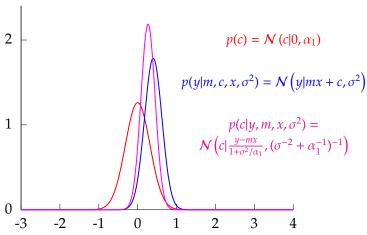


Figure: A Gaussian prior combines with a Gaussian likelihood for a Gaussian posterior.

Stages to Derivation of the Posterior

- Multiply likelihood by prior
 - they are "exponentiated quadratics", the answer is always also an exponentiated quadratic because $\exp(a^2) \exp(b^2) = \exp(a^2 + b^2)$.
- Complete the square to get the resulting density in the form of a Gaussian.
- Recognise the mean and (co)variance of the Gaussian. This is the estimate of the posterior.

Multivariate Regression Likelihood

► Noise corrupted data point

$$y_i = \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i,:} + \epsilon_i$$

Multivariate Regression Likelihood

► Noise corrupted data point

$$y_i = \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i,:} + \epsilon_i$$

► Multivariate regression likelihood:

$$p(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \mathbf{w}^\top \mathbf{x}_{i,i})^2\right)$$

Multivariate Regression Likelihood

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► Now use a multivariate Gaussian prior:

$$p(\mathbf{w}) = \frac{1}{(2\pi\alpha)^{\frac{p}{2}}} \exp\left(-\frac{1}{2\alpha}\mathbf{w}^{\mathsf{T}}\mathbf{w}\right)$$

Two Dimensional Gaussian

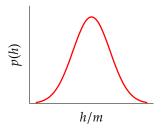
- ▶ Consider height, h/m and weight, w/kg.
- ► Could sample height from a distribution:

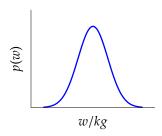
$$p(h) \sim \mathcal{N}(1.7, 0.0225)$$

► And similarly weight:

$$p(w) \sim \mathcal{N}(75, 36)$$

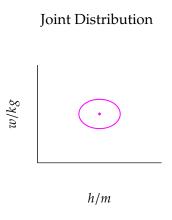
Height and Weight Models

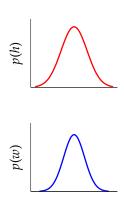




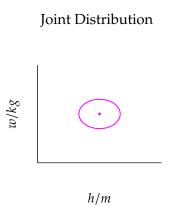
Gaussian distributions for height and weight.

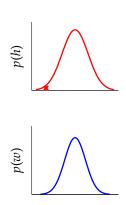
Marginal Distributions



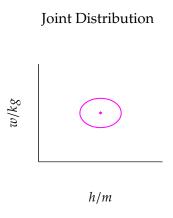


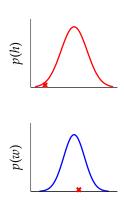
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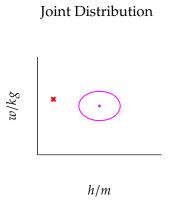


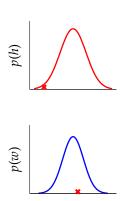
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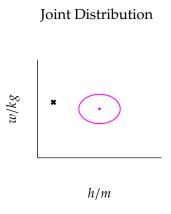


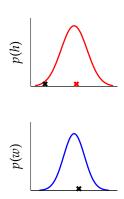
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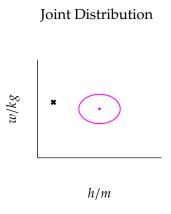


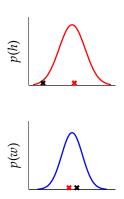
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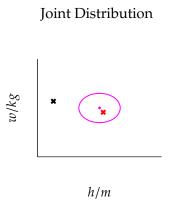


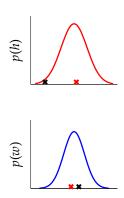
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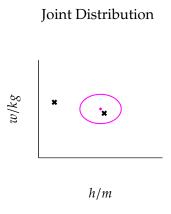


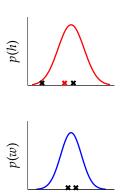
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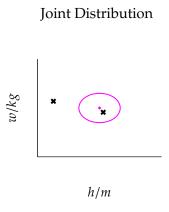


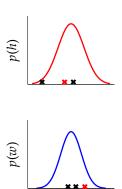
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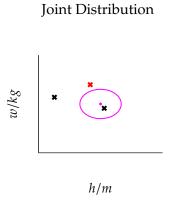


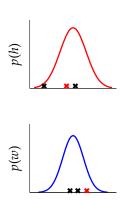
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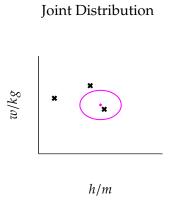


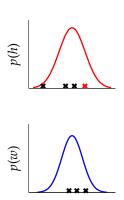
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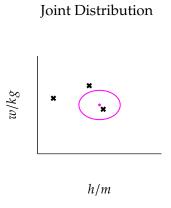


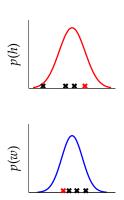
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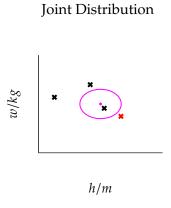


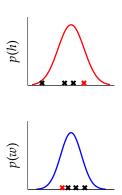
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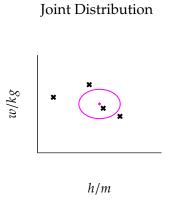


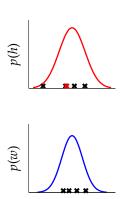
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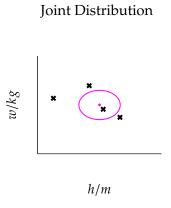


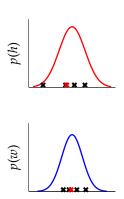
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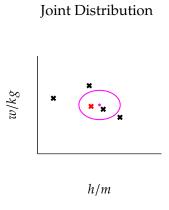


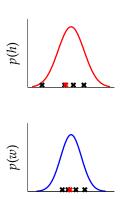
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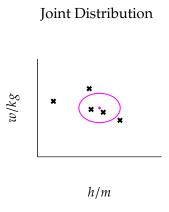


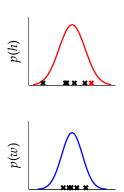
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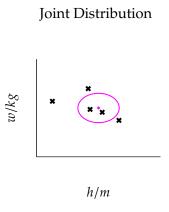


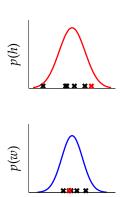
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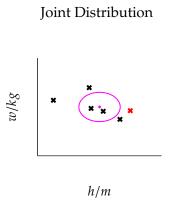


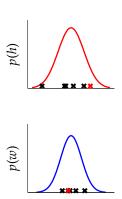
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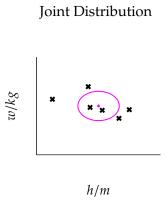


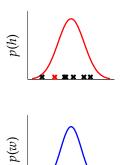
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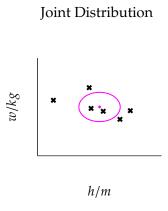


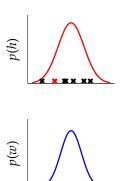
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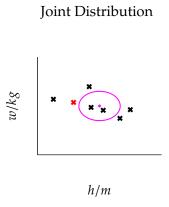


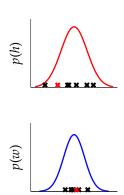
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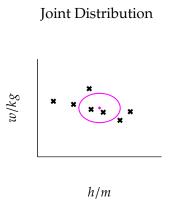


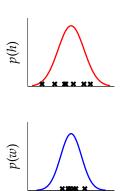
Marginal Distributions





Marginal Distributions





Samples of height and weight

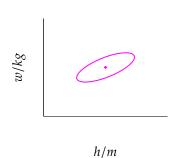
Independence Assumption

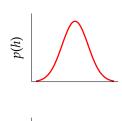
► This assumes height and weight are independent.

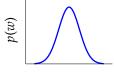
$$p(h, w) = p(h)p(w)$$

► In reality they are dependent (body mass index) = $\frac{w}{h^2}$.

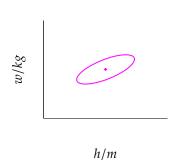
Joint Distribution

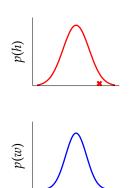




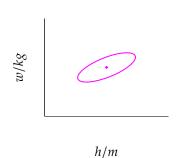


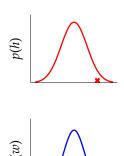
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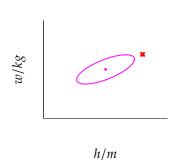


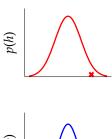
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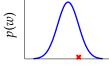




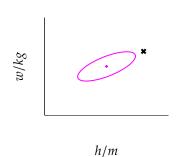
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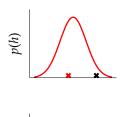


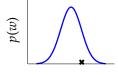




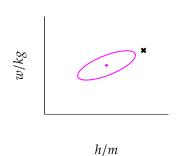


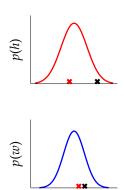




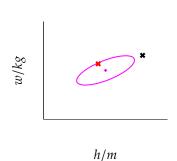


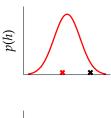


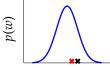




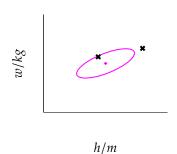
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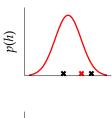






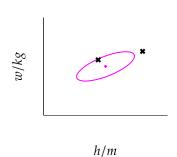


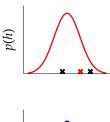






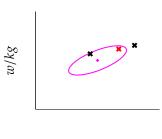




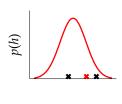


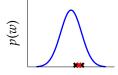


Joint Distribution

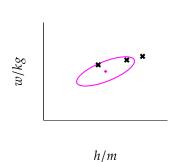


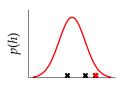
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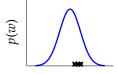




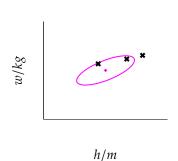
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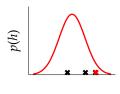


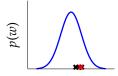




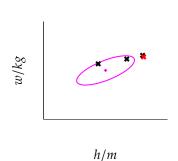
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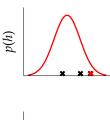


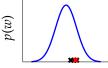




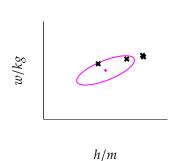
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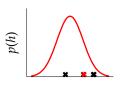


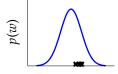




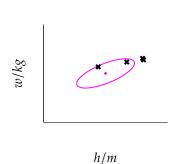
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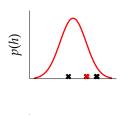


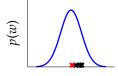




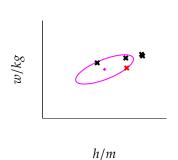
Joint Distribution

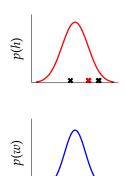




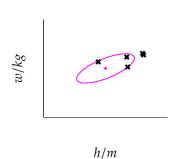


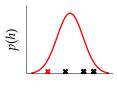
Joint Distribution

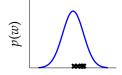




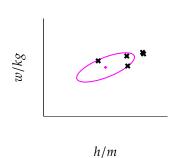
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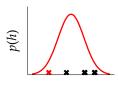


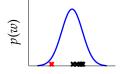




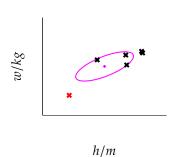
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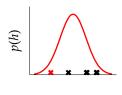


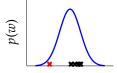




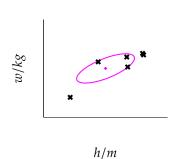
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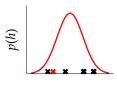


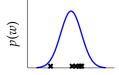




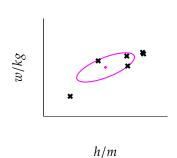
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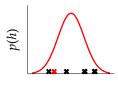


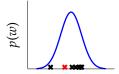




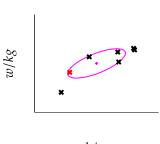
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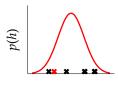


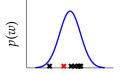


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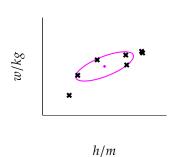


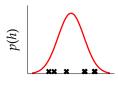
h/m

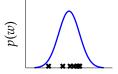




Joint Distribution







$$p(w,h) = p(w)p(h)$$

$$p(w,h) = \frac{1}{\sqrt{2\pi\sigma_1^2}} \left(\frac{1}{\sqrt{2\pi\sigma_2^2}} \exp\left(-\frac{1}{2} \left(\frac{(w-\mu_1)^2}{\sigma_1^2} + \frac{(h-\mu_2)^2}{\sigma_2^2} \right) \right) \right)$$

$$p(w,h) = \frac{1}{2\pi\sqrt{\sigma_1^2\sigma_2^2}} \exp\left(-\frac{1}{2}\begin{pmatrix} \begin{bmatrix} w \\ h \end{bmatrix} - \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}\right)^{\mathsf{T}} \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}^{-1} \begin{pmatrix} \begin{bmatrix} w \\ h \end{bmatrix} - \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}\right)\right)$$

$$p(\mathbf{y}) = \frac{1}{2\pi |\mathbf{D}|} \exp\left(-\frac{1}{2}(\mathbf{y} - \boldsymbol{\mu})^{\top} \mathbf{D}^{-1}(\mathbf{y} - \boldsymbol{\mu})\right)$$

Form correlated from original by rotating the data space using matrix **R**.

$$p(\mathbf{y}) = \frac{1}{2\pi |\mathbf{D}|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(\mathbf{y} - \boldsymbol{\mu})^{\mathsf{T}} \mathbf{D}^{-1}(\mathbf{y} - \boldsymbol{\mu})\right)$$

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this gives a covariance matrix:

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1. Sum of Gaussian variables is also Gaussian.

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Multivariate Consequence

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► Then

$$\mathbf{y} \sim \mathcal{N}\left(\mathbf{W}\boldsymbol{\mu}, \mathbf{W}\boldsymbol{\Sigma}\mathbf{W}^{\top}\right)$$

Sampling a Function

Multi-variate Gaussians

- We will consider a Gaussian with a particular structure of covariance matrix.
- ► Generate a single sample from this 25 dimensional Gaussian distribution, $\mathbf{f} = [f_1, f_2 \dots f_{25}]$.
- ▶ We will plot these points against their index.

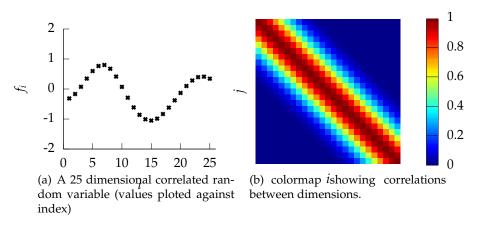


Figure: A sample from a 25 dimensional Gaussian distribution.

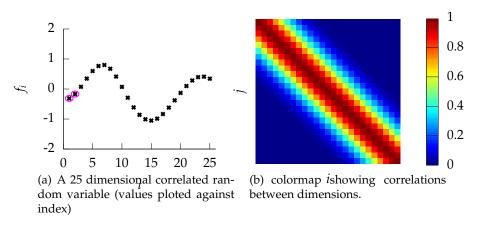


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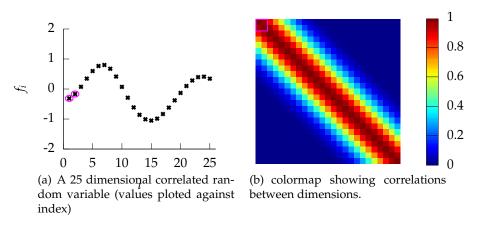


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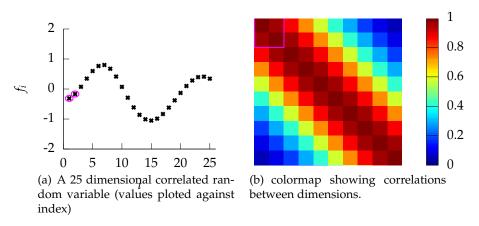


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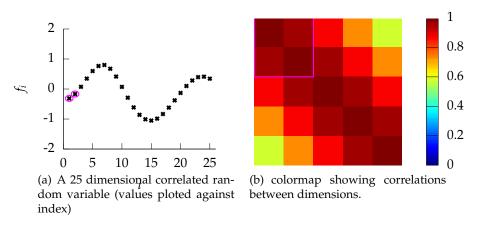


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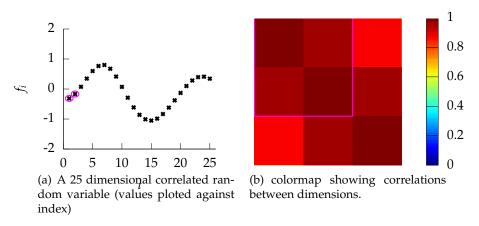


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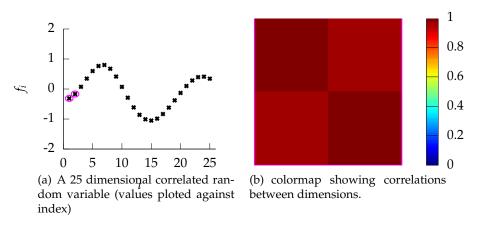


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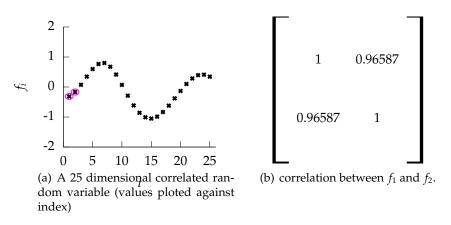
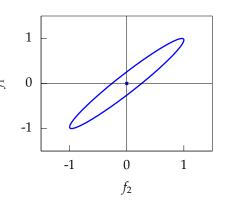
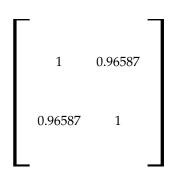
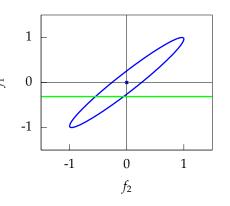


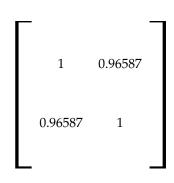
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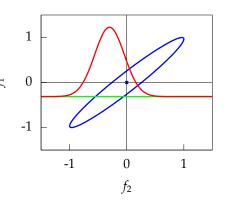


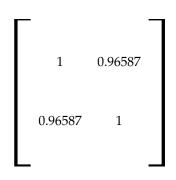
► The single contour of the Gaussian density represents the joint distribution, $p(f_1, f_2)$.



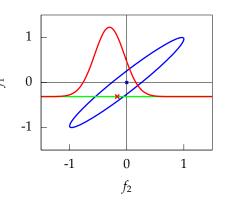


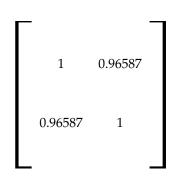
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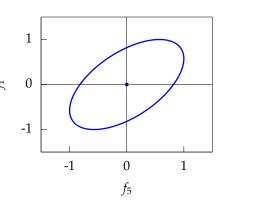
Prediction with Correlated Gaussians

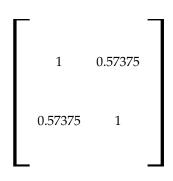
- ▶ Prediction of f_2 from f_1 requires conditional density.
- ▶ Conditional density is *also* Gaussian.

$$p(f_2|f_1) = \mathcal{N}\left(f_2|\frac{k_{1,2}}{k_{1,1}}f_1, k_{2,2} - \frac{k_{1,2}^2}{k_{1,1}}\right)$$

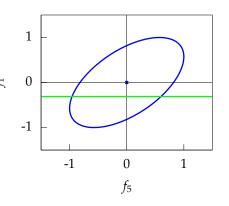
where covariance of joint density is given by

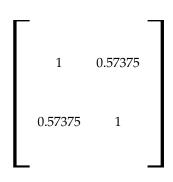
$$\mathbf{K} = \begin{bmatrix} k_{1,1} & k_{1,2} \\ k_{2,1} & k_{2,2} \end{bmatrix}$$



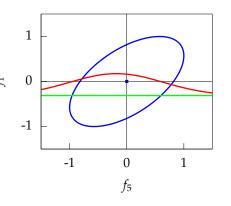


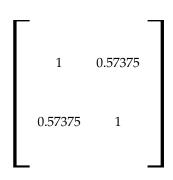
► The single contour of the Gaussian density represents the joint distribution, $p(f_1, f_5)$.



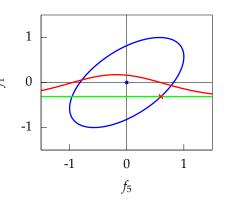


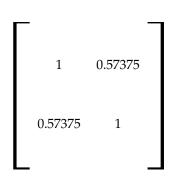
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Prediction with Correlated Gaussians

- Prediction of f* from f requires multivariate conditional density.
- Multivariate conditional density is also Gaussian.

$$p(\mathbf{f}_*|\mathbf{f}) = \mathcal{N}\left(\mathbf{f}_*|\mathbf{K}_{*,f}\mathbf{K}_{f,f}^{-1}\mathbf{f}, \mathbf{K}_{*,*} - \mathbf{K}_{*,f}\mathbf{K}_{f,f}^{-1}\mathbf{K}_{f,*}\right)$$

Here covariance of joint density is given by

$$\mathbf{K} = \begin{bmatrix} \mathbf{K}_{f,f} & \mathbf{K}_{*,f} \\ \mathbf{K}_{f,*} & \mathbf{K}_{*,*} \end{bmatrix}$$

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- Multivariate conditional density is also Gaussian.

$$p(\mathbf{f}_*|\mathbf{f}) = \mathcal{N}\left(\mathbf{f}_*|\boldsymbol{\mu}, \boldsymbol{\Sigma}\right)$$
$$\boldsymbol{\mu} = \mathbf{K}_{*,f} \mathbf{K}_{f,f}^{-1} \mathbf{f}$$
$$\boldsymbol{\Sigma} = \mathbf{K}_{*,*} - \mathbf{K}_{*,f} \mathbf{K}_{f,f}^{-1} \mathbf{K}_{f,*}$$

Here covariance of joint density is given by

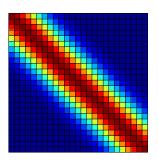
$$\mathbf{K} = \begin{bmatrix} \mathbf{K}_{f,f} & \mathbf{K}_{*,f} \\ \mathbf{K}_{f,*} & \mathbf{K}_{*,*} \end{bmatrix}$$

Where did this covariance matrix come from?

Exponentiated Quadratic Kernel Function (RBF, Squared Exponential, Gaussian)

$$k(\mathbf{x}, \mathbf{x}') = \alpha \exp\left(-\frac{\|\mathbf{x} - \mathbf{x}'\|_2^2}{2\ell^2}\right)$$

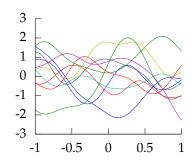
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$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_1 = -3.0, x_1 = -3.0$$

$$k_{1,1} = 1.00 \times \exp\left(-\frac{(-3.0 - 3.0)^2}{2 \times 2.00^2}\right)$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$.

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$$0.110$$

$$k_{2,1} = 1.00 \times \exp\left(-\frac{(1.20 - 3.0)^2}{2 \times 2.00^2}\right)$$

 $x_1 = -3.0$, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$.

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$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_2 = 1.20, x_2 = 1.20$$

$$0.110$$

$$k_{2,2} = 1.00 \times \exp\left(-\frac{(1.20 - 1.20)^2}{2 \times 2.00^2}\right)$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_2 = 1.20, x_2 = 1.20$$

$$0.110$$

$$1.00$$

$$0.110$$

$$k_{2,2} = 1.00 \times \exp\left(-\frac{(1.20 - 1.20)^2}{2 \times 2.00^2}\right)$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_1 = -3.0$$

$$0.110$$

$$k_{3,1} = 1.00 \times \exp\left(-\frac{(1.40 - 3.0)^2}{2 \times 2.00^2}\right)$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_1 = -3.0$$

$$0.110$$

$$0.110$$

$$0.0889$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_1 = -3.0$$

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$$0.110 \quad 1.00$$

$$0.0889$$

$$x_1 = -3.0, x_2 = 1.20, \text{ and } x_3 = 1.40 \text{ with } \ell = 2.00 \text{ and } \alpha = 1.00.$$

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, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_2 = 1.20$$

$$0.110 \quad 1.00$$

$$k_{3,2} = 1.00 \times \exp\left(-\frac{(1.40 - 1.20)^2}{2 \times 2.00^2}\right)$$

$$0.0889$$

$$x_1 = -3.0, x_2 = 1.20, \text{ and } x_3 = 1.40 \text{ with } \ell = 2.00 \text{ and } \alpha = 1.00.$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_2 = 1.20$$

$$0.110 \quad 0.0889$$

$$k_{3,2} = 1.00 \times \exp\left(-\frac{(1.40 - 1.20)^2}{2 \times 2.00^2}\right)$$

$$0.0889 \quad 0.995$$

$$x_1 = -3.0$$
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$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_2 = 1.20$$

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$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$x_3 = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$

$$0.0889 \quad 0.995$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 2.00$ and $\alpha = 1.00$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_3 = 1.40$$

$$0.110 \quad 0.0889$$

$$k_{3,3} = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$

$$0.0889 \quad 0.995$$

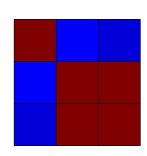
$$1.00$$

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$$x_3 = 1.40, x_3 = 1.40$$

$$k_{3,3} = 1.00 \times \exp\left(-\frac{(1.40 - 1.40)^2}{2 \times 2.00^2}\right)$$



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$$x_1 = -3$$
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$$k_{1,1} = 1.0 \times \exp\left(-\frac{(-3--3)^2}{2 \times 2.0^2}\right)$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_{i}, x_{j}) = \alpha \exp\left(-\frac{\|x_{i} - x_{j}\|^{2}}{2\ell^{2}}\right)$$

$$x_{1} = -3, x_{1} = -3$$

$$k_{1,1} = 1.0 \times \exp\left(-\frac{(-3 - -3)^{2}}{2 \times 2.0^{2}}\right)$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

Where did this covariance matrix come from?

$$k(x_{i}, x_{j}) = \alpha \exp\left(-\frac{\|x_{i} - x_{j}\|^{2}}{2\ell^{2}}\right)$$

$$x_{2} = 1.2, x_{1} = -3$$

$$k_{2,1} = 1.0 \times \exp\left(-\frac{(1.2 - 3)^{2}}{2 \times 2.0^{2}}\right)$$

$$k(x_{i}, x_{j}) = \alpha \exp\left(-\frac{\|x_{i} - x_{j}\|^{2}}{2\ell^{2}}\right)$$

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$$k_{2,2} = 1.0 \times \exp\left(-\frac{(1.2 - 1.2)^2}{2 \times 2.0^2}\right)$$

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Where did this covariance matrix come from?

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$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.4, x_1 = -3$$

$$k_{3,1} = 1.0 \times \exp\left(-\frac{(1.4 - -3)^2}{2 \times 2.0^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 \\
0.11 & 1.0 \\
0.089
\end{bmatrix}$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

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$$0.11 \quad 1.0$$

$$0.089$$

$$k_{3,2} = 1.0 \times \exp\left(-\frac{(1.4 - 1.2)^2}{2 \times 2.0^2}\right)$$

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.4, x_2 = 1.2$$

$$k_{3,2} = 1.0 \times \exp\left(-\frac{(1.4 - 1.2)^2}{2 \times 2.0^2}\right)$$

$$1.0 \quad 0.11 \quad 0.089$$

$$0.11 \quad 1.0$$

$$0.089 \quad 1.0$$

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.4, x_2 = 1.2$$

$$k_{3,2} = 1.0 \times \exp\left(-\frac{(1.4 - 1.2)^2}{2 \times 2.0^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 \\
0.11 & 1.0 & 1.0 \\
0.089 & 1.0
\end{bmatrix}$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_3 = 1.4, x_3 = 1.4$$

$$0.11 \quad 1.0 \quad 1.0$$

$$0.089 \quad 1.0$$

$$k_{3,3} = 1.0 \times \exp\left(-\frac{(1.4 - 1.4)^2}{2 \times 2.0^2}\right)$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

Where did this covariance matrix come from?

$$k(x_{i}, x_{j}) = \alpha \exp\left(-\frac{\|x_{i} - x_{j}\|^{2}}{2\ell^{2}}\right)$$

$$x_{3} = 1.4, x_{3} = 1.4$$

$$0.11 \quad 1.0 \quad 1.0$$

$$0.089 \quad 1.0 \quad 1.0$$

$$k_{3,3} = 1.0 \times \exp\left(-\frac{(1.4 - 1.4)^{2}}{2 \times 2.0^{2}}\right)$$

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_1 = -3$$

$$x_4 = 2.0, x_1 = -3$$

$$0.11 \quad 1.0 \quad 1.0$$

$$0.089 \quad 1.0 \quad 1.0$$

$$0.089 \quad 1.0 \quad 1.0$$

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$$x_4 = 2.0, x_1 = -3$$

$$0.11 \quad 1.0 \quad 1.0$$

$$0.089 \quad 1.0 \quad 1.0$$

$$k_{4,1} = 1.0 \times \exp\left(-\frac{(2.0 - 3)^2}{2 \times 2.0^2}\right)$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_1 = -3$$

$$k_{4,1} = 1.0 \times \exp\left(-\frac{(2.0 - 3)^2}{2 \times 2.0^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 & 0.044 \\
0.11 & 1.0 & 1.0 \\
0.089 & 1.0 & 1.0 \\
0.044
\end{bmatrix}$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_2 = 1.2$$

$$k_{4,2} = 1.0 \times \exp\left(-\frac{(2.0 - 1.2)^2}{2 \times 2.0^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 & 0.044 \\
0.11 & 1.0 & 1.0 \\
0.089 & 1.0 & 1.0 \\
0.044
\end{bmatrix}$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_2 = 1.2$$

$$k_{4,2} = 1.0 \times \exp\left(-\frac{(2.0 - 1.2)^2}{2 \times 2.0^2}\right)$$

$$0.044$$

$$0.092$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_2 = 1.2$$

$$k_{4,2} = 1.0 \times \exp\left(-\frac{(2.0 - 1.2)^2}{2 \times 2.0^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 & 0.044 \\
0.11 & 1.0 & 1.0 & 0.92 \\
0.089 & 1.0 & 1.0 \\
0.044 & 0.92
\end{bmatrix}$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_3 = 1.4$$

$$k_{4,3} = 1.0 \times \exp\left(-\frac{(2.0 - 1.4)^2}{2 \times 2.0^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 & 0.044 \\
0.11 & 1.0 & 1.0 & 0.92 \\
0.089 & 1.0 & 1.0 \\
0.044 & 0.92
\end{bmatrix}$$

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_3 = 1.4$$

$$0.11 \quad 1.0 \quad 0.92$$

$$0.089 \quad 1.0 \quad 1.0$$

$$0.044 \quad 0.92 \quad 0.96$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_3 = 1.4$$

$$x_4 = 2.0, x_3 = 1.4$$

$$0.11 \quad 1.0 \quad 0.92$$

$$0.089 \quad 1.0 \quad 1.0 \quad 0.96$$

$$0.044 \quad 0.92 \quad 0.96$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_4 = 2.0$$

$$k_{4,4} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

$$\begin{bmatrix}
1.0 & 0.11 & 0.089 & 0.044 \\
0.11 & 1.0 & 1.0 & 0.92 \\
0.089 & 1.0 & 1.0 & 0.96 \\
0.044 & 0.92 & 0.96
\end{bmatrix}$$

$$x_1 = -3$$
, $x_2 = 1.2$, $x_3 = 1.4$, and $x_4 = 2.0$ with $\ell = 2.0$ and $\alpha = 1.0$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

$$x_4 = 2.0, x_4 = 2.0$$

$$x_4 = 2.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$

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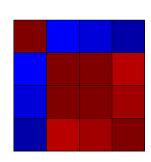
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$$k_{4,4} = 1.0 \times \exp\left(-\frac{(2.0 - 2.0)^2}{2 \times 2.0^2}\right)$$



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$$x_1 = -3.0, x_1 = -3.0$$

$$k_{1,1} = 4.00 \times \exp\left(-\frac{(-3.0 - -3.0)^2}{2 \times 5.00^2}\right)$$

$$x_1 = -3.0$$
, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 5.00$ and $\alpha = 4.00$.

Where did this covariance matrix come from?

$$k(x_i, x_j) = \alpha \exp\left(-\frac{\|x_i - x_j\|^2}{2\ell^2}\right)$$

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$$x_2 = 1.20, x_2 = 1.20$$

$$2.81$$

$$k_{2,2} = 4.00 \times \exp\left(-\frac{(1.20 - 1.20)^2}{2 \times 5.00^2}\right)$$

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 $x_1 = -3.0$, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 5.00$ and $\alpha = 4.00$.

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 $x_1 = -3.0$, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 5.00$ and $\alpha = 4.00$.

$$k(x_{i}, x_{j}) = \alpha \exp\left(-\frac{\|x_{i} - x_{j}\|^{2}}{2\ell^{2}}\right)$$

$$x_{3} = 1.40, x_{1} = -3.0$$

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$$x_1 = -3.0, x_2 = 1.20, \text{ and } x_3 = 1.40 \text{ with } \ell = 5.00 \text{ and } \alpha = 4.00.$$

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, $x_2 = 1.20$, and $x_3 = 1.40$ with $\ell = 5.00$ and $\alpha = 4.00$.

$$k(x_i, x_j) = \alpha \exp\left(-\frac{||x_i - x_j||^2}{2\ell^2}\right)$$

$$x_3 = 1.40, x_2 = 1.20$$

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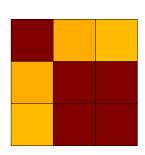
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Outline

The Gaussian Density

Covariance from Basis Functions

Basis Function Representations

Constructing Covariance

GP Limitations

Conclusion

Basis Function Form

Radial basis functions commonly have the form

$$\phi_k(\mathbf{x}_i) = \exp\left(-\frac{\left|\mathbf{x}_i - \boldsymbol{\mu}_k\right|^2}{2\ell^2}\right).$$

 Basis function maps data into a "feature space" in which a linear sum is a non linear function.

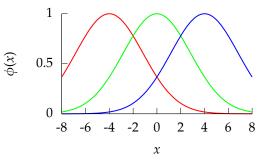


Figure: A set of radial basis functions with width $\ell = 2$ and location parameters $\mu = [-4 \ 0 \ 4]^{\mathsf{T}}$.

Basis Function Representations

Represent a function by a linear sum over a basis,

$$f(\mathbf{x}_{i,:}; \mathbf{w}) = \sum_{k=1}^{m} w_k \phi_k(\mathbf{x}_{i,:}), \tag{1}$$

▶ Here: *m* basis functions and $\phi_k(\cdot)$ is *k*th basis function and

$$\mathbf{w} = [w_1, \dots, w_m]^\top.$$

► For standard linear model: $\phi_k(\mathbf{x}_{i,:}) = x_{i,k}$.

Random Functions

Functions derived using:

$$f(x) = \sum_{k=1}^{m} w_k \phi_k(x),$$

where **W** is sampled from a Gaussian density,

$$w_k \sim \mathcal{N}(0, \alpha)$$
.

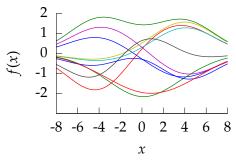


Figure: Functions sampled using the basis set from figure 3. Each line is a separate sample, generated by a weighted sum of the basis set. The weights, **w** are sampled from a Gaussian density with variance $\alpha = 1$.

Use matrix notation to write function,

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 $\Phi \in \Re^{n \times p}$ is a design matrix

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f is Gaussian distributed.

► We have

$$\langle f \rangle = \Phi \langle w \rangle$$
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giving

$$\langle \mathbf{f} \mathbf{f}^{\mathsf{T}} \rangle = \mathbf{\Phi} \langle \mathbf{w} \mathbf{w}^{\mathsf{T}} \rangle \mathbf{\Phi}^{\mathsf{T}},$$

$$\mathbf{K} = \gamma' \mathbf{\Phi} \mathbf{\Phi}^{\mathsf{T}}.$$

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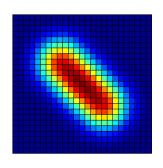
$$k\left(\mathbf{x}_{i}, \mathbf{x}_{j}\right) = \gamma' \sum_{k=1}^{m} \exp \left(-\frac{\left|\mathbf{x}_{i} - \boldsymbol{\mu}_{k}\right|^{2} + \left|\mathbf{x}_{j} - \boldsymbol{\mu}_{k}\right|^{2}}{2\ell^{2}}\right).$$

RBF Basis Functions

$$k(\mathbf{x}, \mathbf{x}') = \alpha \phi(\mathbf{x})^{\top} \phi(\mathbf{x}')$$

$$\phi_i(x) = \exp\left(-\frac{\left\|x - \mu_i\right\|_2^2}{\ell^2}\right)$$

$$\mu = \begin{bmatrix} -1\\0\\1 \end{bmatrix}$$

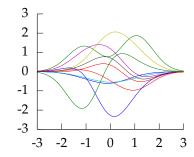


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- Need to choose
 - 1. location of centers
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- Consider uniform spacing over a region:

$$k(x_i, x_j) = \gamma \Delta \sum_{k=1}^{m} \exp\left(-\frac{x_i^2 + x_j^2 - 2\mu_k(x_i + x_j) + 2\mu_k^2}{2\ell^2}\right),$$

Restrict analysis to 1-D input, *x*.

Uniform Basis Functions

Set each center location to

$$\mu_k = a + \Delta \mu \cdot (k-1).$$

Uniform Basis Functions

Set each center location to

$$\mu_k = a + \Delta \mu \cdot (k-1).$$

Specify the basis functions in terms of their indices,

$$k(x_i, x_j) = \gamma \Delta \mu \sum_{k=0}^{m-1} \exp\left(-\frac{x_i^2 + x_j^2}{2\ell^2}\right)$$
$$-\frac{2(a + \Delta \mu \cdot k)(x_i + x_j) + 2(a + \Delta \mu \cdot k)^2}{2\ell^2}.$$

Infinite Basis Functions

► Take
$$\mu_0 = a$$
 and $\mu_m = b$ so $b = a + \Delta \mu \cdot (m-1)$.

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- ► Take $\mu_0 = a$ and $\mu_m = b$ so $b = a + \Delta \mu \cdot (m-1)$.
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$$k(x_i, x_j) = \gamma \int_a^b \exp\left(-\frac{x_i^2 + x_j^2}{2\ell^2} + \frac{2\left(\mu - \frac{1}{2}\left(x_i + x_j\right)\right)^2 - \frac{1}{2}\left(x_i + x_j\right)^2}{2\ell^2}\right) d\mu,$$

where we have used $k \cdot \Delta \mu \rightarrow \mu$.

Result

▶ Performing the integration leads to

$$k(x_{i},x_{j}) = \gamma \frac{\sqrt{\pi \ell^{2}}}{2} \exp\left(-\frac{\left(x_{i} - x_{j}\right)^{2}}{4\ell^{2}}\right)$$
$$\times \left[\operatorname{erf}\left(\frac{\left(b - \frac{1}{2}\left(x_{i} + x_{j}\right)\right)}{\ell}\right) - \operatorname{erf}\left(\frac{\left(a - \frac{1}{2}\left(x_{i} + x_{j}\right)\right)}{\ell}\right)\right],$$

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▶ Now take limit as $a \to -\infty$ and $b \to \infty$

$$k(x_i, x_j) = \alpha \exp\left(-\frac{(x_i - x_j)^2}{4\ell^2}\right).$$

where
$$\alpha = \gamma \sqrt{\pi \ell^2}$$
.

Infinite Feature Space

► An RBF model with infinite basis functions is a Gaussian process.

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- An RBF model with infinite basis functions is a Gaussian process.
- ► The covariance function is given by the exponentiated quadratic covariance function.

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Infinite Feature Space

- An RBF model with infinite basis functions is a Gaussian process.
- ► The covariance function is the exponentiated quadratic.
- ▶ **Note:** The functional form for the covariance function and basis functions are similar.
 - this is a special case,
 - in general they are very different

Similar results can obtained for multi-dimensional input models Williams (1998); Neal (1996).

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