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> #ex1:
> e1 := diff(x(t), t) + x(t) =  $\frac{2}{\sqrt{\pi}} \cdot \exp(-t^2 - t)$ ;
      
$$e1 := \frac{d}{dt} x(t) + x(t) = \frac{2 e^{-t^2 - t}}{\sqrt{\pi}} \quad (1)$$

> solution1 := dsolve(e1, x(t));
      
$$solution1 := x(t) = (\operatorname{erf}(t) + c_1) e^{-t} \quad (2)$$

> Sol1 := unapply(rhs(solution1), t, _C1);
      
$$Sol1 := (t, c_1) \mapsto (\operatorname{erf}(t) + c_1) \cdot e^{-t} \quad (3)$$

>
> int(exp(t^2), t);
      
$$\frac{\sqrt{\pi} \operatorname{erfi}(t)}{2} \quad (4)$$

>
> int( $\frac{2}{\sqrt{\pi}} \cdot \exp(-t^2)$ , t);
      
$$\operatorname{erf}(t) \quad (5)$$

> erf(t) + C;
      
$$\operatorname{erf}(t) + C \quad (6)$$

>
> #ex2:
>
> eq2 := diff(x(t), t$2) + 3·diff(x(t), t) + x(t) = 1;
      
$$eq2 := \frac{d^2}{dt^2} x(t) + 3 \frac{d}{dt} x(t) + x(t) = 1 \quad (7)$$

> solution2 := dsolve(eq2, x(t));
      
$$solution2 := x(t) = e^{\frac{(\sqrt{5}-3)t}{2}} c_2 + e^{-\frac{(3+\sqrt{5})t}{2}} c_1 + 1 \quad (8)$$

> Sol2 := unapply(rhs(solution2), t, _C1, _C2);
      
$$Sol2 := (t, c_1, c_2) \mapsto e^{\frac{(\sqrt{5}-3)t}{2}} \cdot c_2 + e^{-\frac{(3+\sqrt{5})t}{2}} \cdot c_1 + 1 \quad (9)$$

> limit(Sol2(t, C1, C2), t = infinity);
      
$$1 \quad (10)$$

>
> #ex3:
>
> eq3 := diff(x(t), t$2) + 4·x(t) = 1;
      
$$eq3 := \frac{d^2}{dt^2} x(t) + 4 x(t) = 1 \quad (11)$$

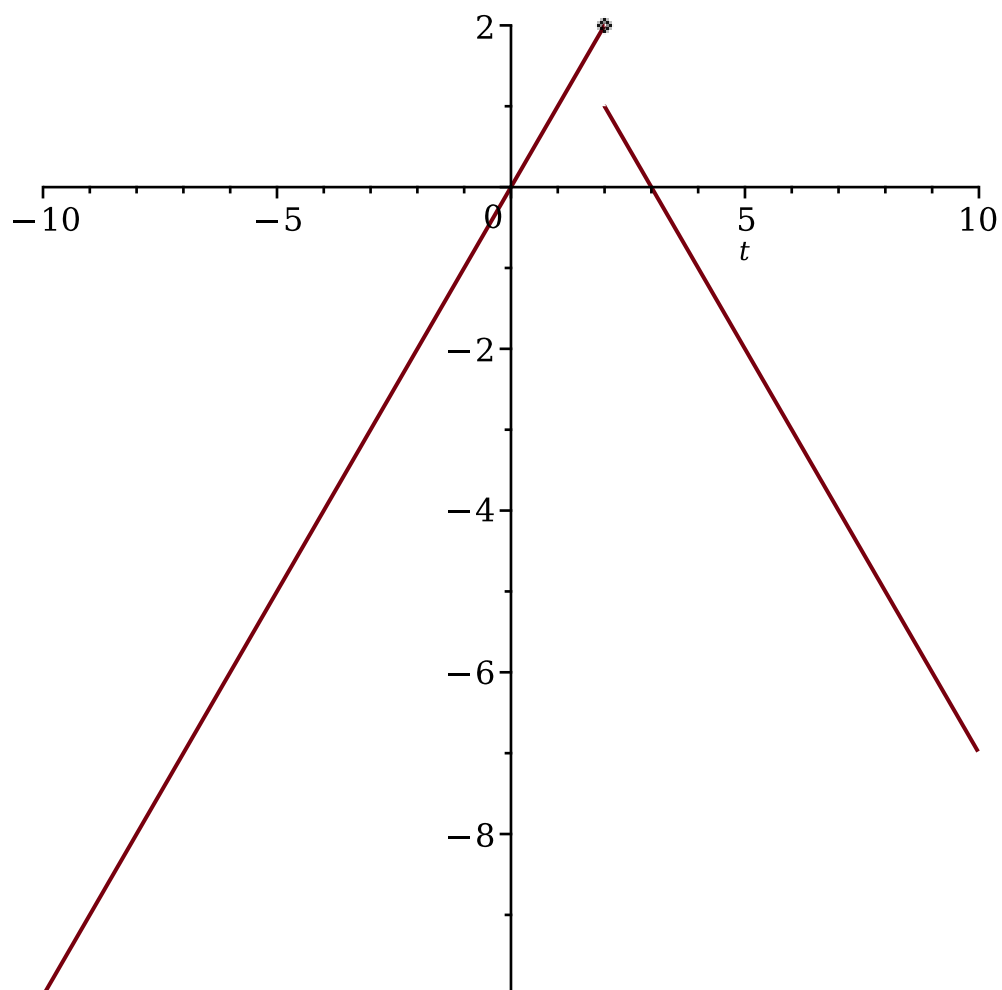

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$$\begin{aligned} &> \text{icl} := D(x)(0) = 0, x(0) = \frac{5}{4} \\ &\qquad\qquad\qquad \text{icl} := D(x)(0) = 0, x(0) = \frac{5}{4} \end{aligned} \tag{12}$$

$$\begin{aligned} &> \text{dsolve}\{\text{eq3}, \text{icl}\}, x(t); \\ &\qquad\qquad\qquad x(t) = \frac{1}{4} + \cos(2t) \end{aligned} \tag{13}$$

$$\begin{aligned} &> \text{\#ex4:} \\ &> \text{eq4} := \text{diff}(x(t), t) = 3 \cdot x(t) + t^3; \\ &\qquad\qquad\qquad \text{eq3} := \frac{d}{dt} x(t) = 3 x(t) + t^3 \end{aligned} \tag{14}$$

$$\begin{aligned} &> \text{\#EX5:} \\ &> \text{f5} := \text{piecewise}(t \leq 2, t, 3 - t); \\ &\qquad\qquad\qquad f5 := \begin{cases} t & t \leq 2 \\ 3 - t & \text{otherwise} \end{cases} \\ &> \text{plot}(f5, \text{discont} = \text{true}); \end{aligned} \tag{15}$$



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>
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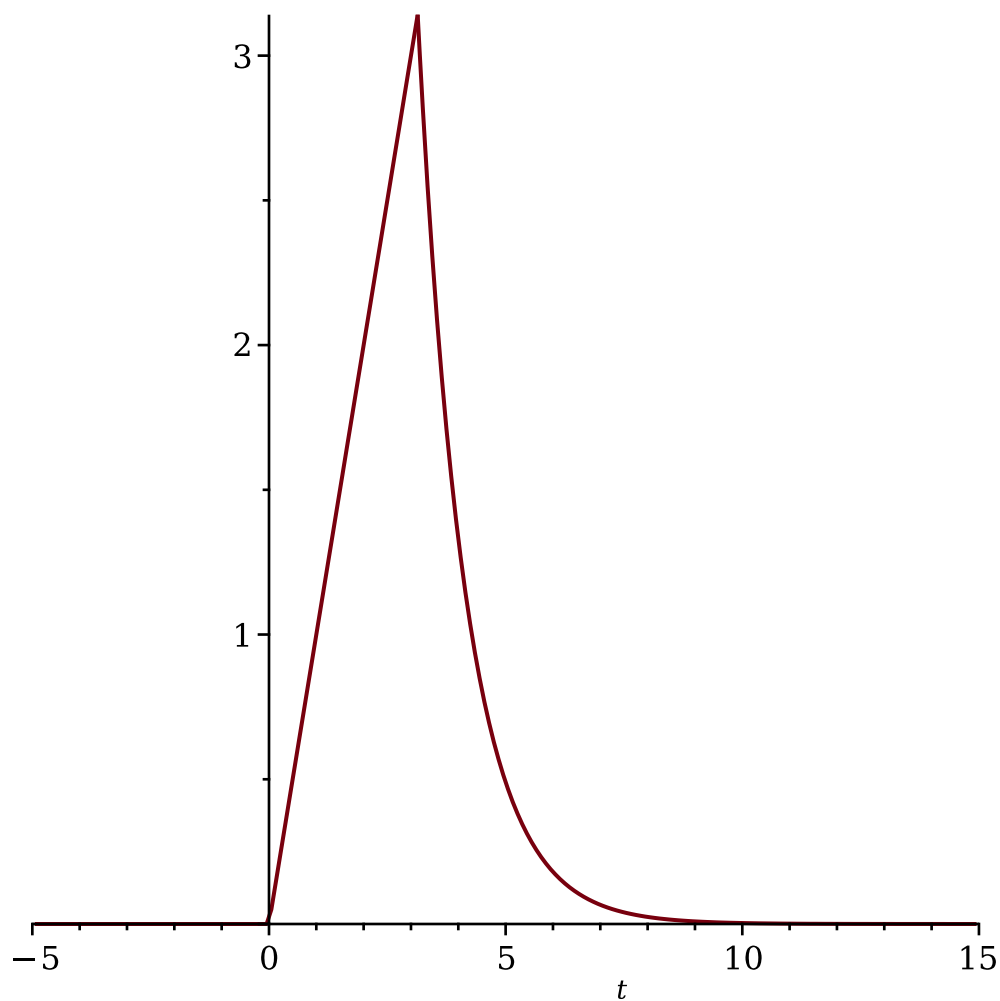
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#EX6:
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> f6 := piecewise(0 ≤ t ≤ Pi, t, t > Pi, Pi exp(Pi - t));
```

$$f6 := \begin{cases} t & 0 \leq t \leq \pi \\ \pi e^{\pi-t} & \pi < t \end{cases}$$

(16)

```
> plot(f6);
```



>

Ex7:

> ode := diff(x(t), t\$2) + x(t) = f6;

$$ode := \frac{d^2}{dt^2} x(t) + x(t) = \begin{cases} t & 0 \leq t \leq \pi \\ \pi e^{\pi-t} & \pi < t \end{cases} \quad (17)$$

> ic1 := x(0) = 0, D(x)(0) = 1;

$$ic1 := x(0) = 0, D(x)(0) = 1 \quad (18)$$

> sol7 := dsolve({ode, ic1}, x(t));

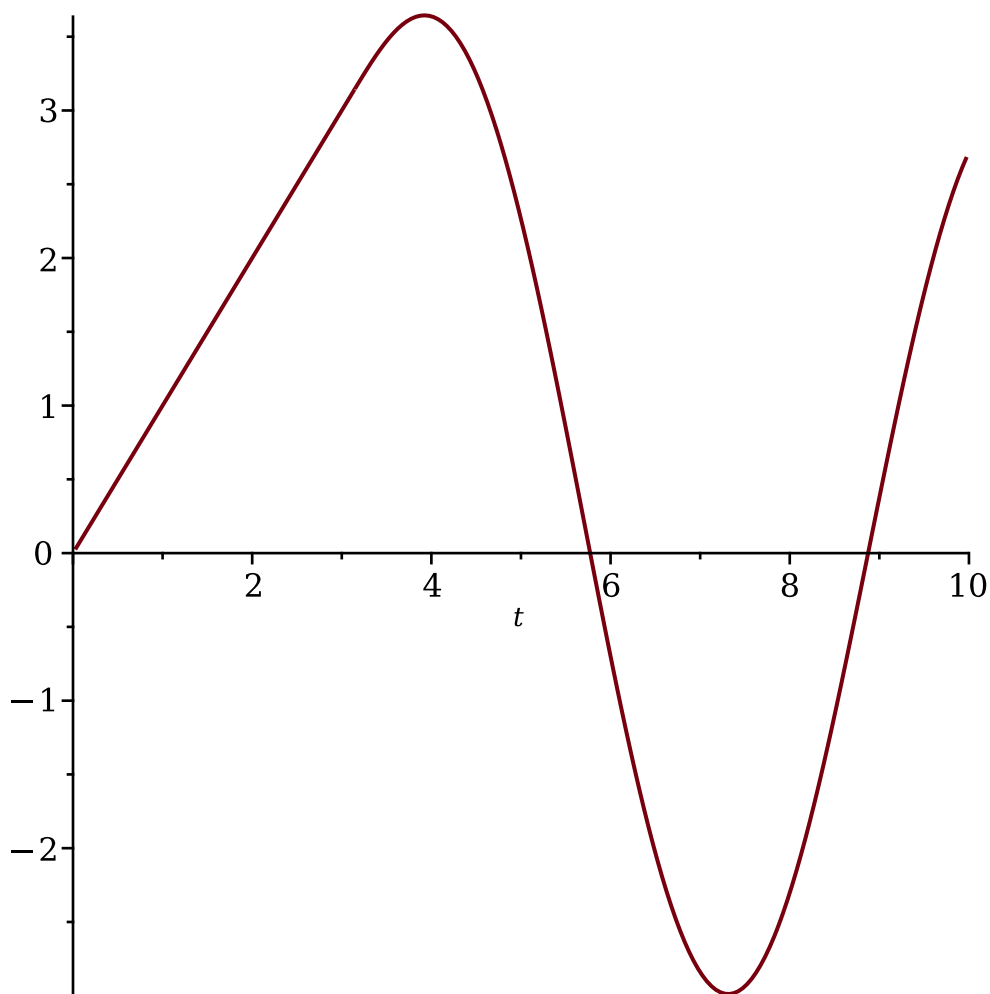
$$sol7 := x(t) = \begin{cases} \sin(t) & t < 0 \\ t & t < \pi \\ -\sin(t) - \frac{\sin(t)\pi}{2} - \frac{\cos(t)\pi}{2} + \frac{\pi e^{\pi-t}}{2} & \pi \leq t \end{cases} \quad (19)$$

> Sol7 := unapply(rhs(sol7), t);

(20)

$$Sol7 := t \mapsto \begin{cases} \sin(t) & t < 0 \\ t & t < \pi \\ -\sin(t) - \frac{\sin(t) \cdot \pi}{2} - \frac{\cos(t) \cdot \pi}{2} + \frac{\pi \cdot e^{\pi-t}}{2} & \pi \leq t \end{cases} \quad (20)$$

plot(Sol7(t), t = 0..10);



$$\begin{aligned} & \text{#EX11:} \\ & \text{restart;} \\ & \text{ode1x} := \text{diff}(x(t), t) = -2 \cdot x(t); \\ & \text{ode1x} := \frac{d}{dt} x(t) = -2 x(t) \end{aligned} \quad (21)$$

$$\begin{aligned} & \text{ode1y} := \text{diff}(y(t), t) = -3 \cdot y(t); \\ & \text{ode1y} := \frac{d}{dt} y(t) = -3 y(t) \end{aligned} \quad (22)$$

$$\begin{aligned} & \text{syst1} := \text{ode1x}, \text{ode1y}; \\ & \text{syst1} := \frac{d}{dt} x(t) = -2 x(t), \frac{d}{dt} y(t) = -3 y(t) \end{aligned} \quad (23)$$

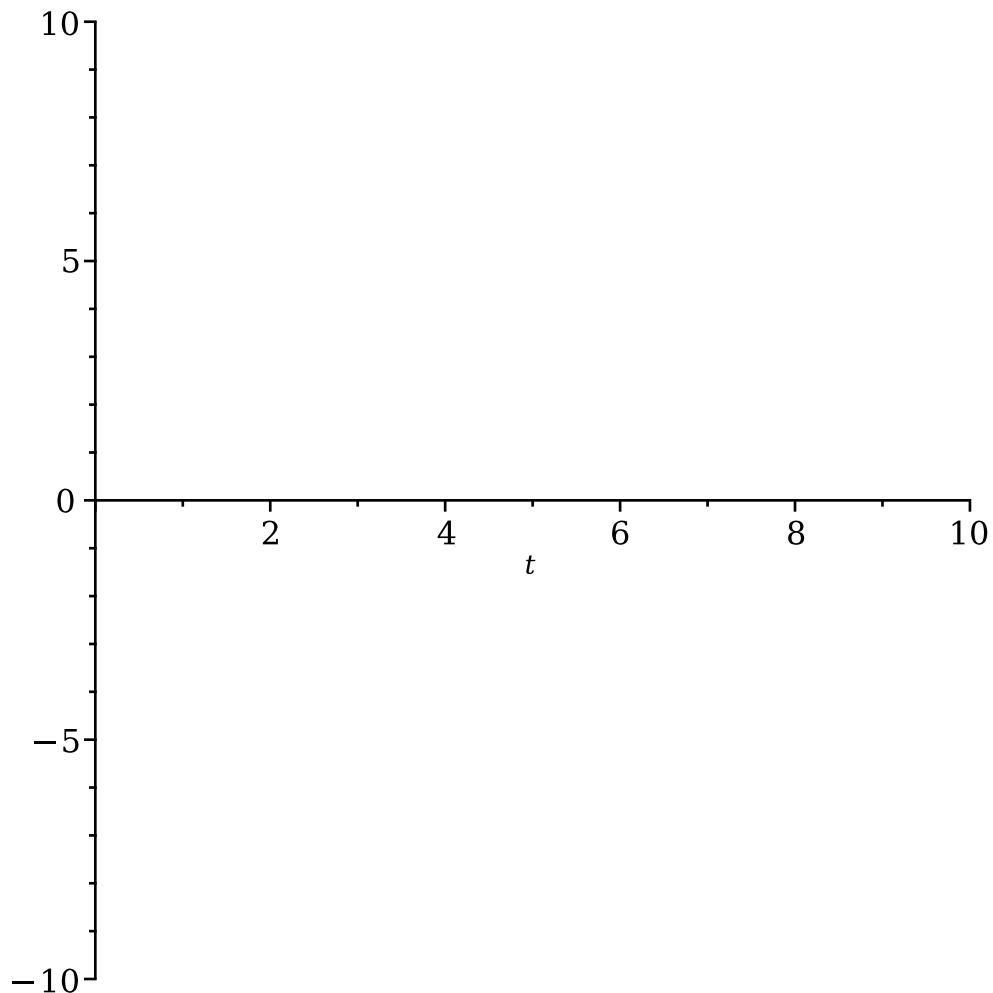
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[> a := x(0) = 1, y(0) = 1;
                                     a := x(0) = 1, y(0) = 1 (24)
```

```
[> sol := dsolve({syst1, a}, {x(t), y(t)});
                                     sol := {x(t) = e-2t, y(t) = e-3t} (25)
```

```
[> Sol1x := unapply(rhs(sol[1]), t);
                                     Sol1x := t ↦ e-2·t (26)
```

```
[> Sol1y := unapply(rhs(sol[2]), t);
                                     Sol1y := t ↦ e-3·t (27)
```

```
[> plot([Sol1x(t), Sol1y(t)], t = 0..10);
Warning, expecting only range variable t in expression Sol1x(t) to
be plotted but found name Sol1x
```



```
[>
[> #EX12:
[> restart;
[> ode1x := diff(x(t), t) = -2·x(t);
```

$$ode1x := \frac{d}{dt} x(t) = -2 x(t) \quad (28)$$

$$> ode1y := diff(y(t), t) = 3 \cdot y(t);$$

$$ode1y := \frac{d}{dt} y(t) = 3 y(t) \quad (29)$$

$$> syst1 := ode1x, ode1y;$$

$$syst1 := \frac{d}{dt} x(t) = -2 x(t), \frac{d}{dt} y(t) = 3 y(t) \quad (30)$$

$$> a := x(0) = 1, y(0) = 1;$$

$$a := x(0) = 1, y(0) = 1 \quad (31)$$

$$> sol := dsolve(\{syst1, a\}, \{x(t), y(t)\});$$

$$sol := \{x(t) = e^{-2t}, y(t) = e^{3t}\} \quad (32)$$

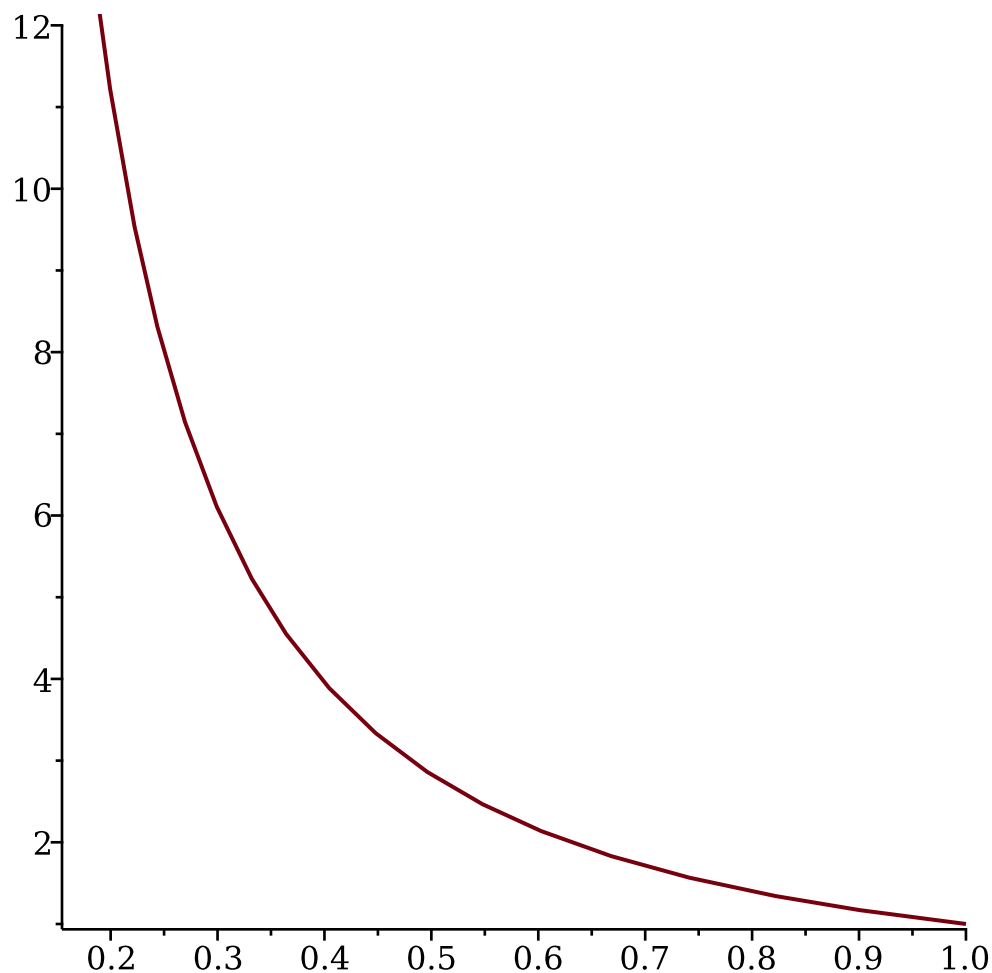
$$> Sol1x := unapply(rhs(sol[1]), t);$$

$$Sol1x := t \mapsto e^{-2 \cdot t} \quad (33)$$

$$> Sol1y := unapply(rhs(sol[2]), t);$$

$$Sol1y := t \mapsto e^{3 \cdot t} \quad (34)$$

$$> plot([Sol1x(t), Sol1y(t), t = 0..10]);$$



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>
> #EX13:
> restart;
> ode1x := diff(x(t), t) = -y(t);
```

$$\text{ode1x} := \frac{d}{dt} x(t) = -y(t) \quad (35)$$

```
> ode1y := diff(y(t), t) = 4·x(t);
```

$$\text{ode1y} := \frac{d}{dt} y(t) = 4 x(t) \quad (36)$$

```
> syst1 := ode1x, ode1y;
```

$$\text{syst1} := \frac{d}{dt} x(t) = -y(t), \frac{d}{dt} y(t) = 4 x(t) \quad (37)$$

```
> a := x(0) = 1, y(0) = 1;
```

$$a := x(0) = 1, y(0) = 1 \quad (38)$$

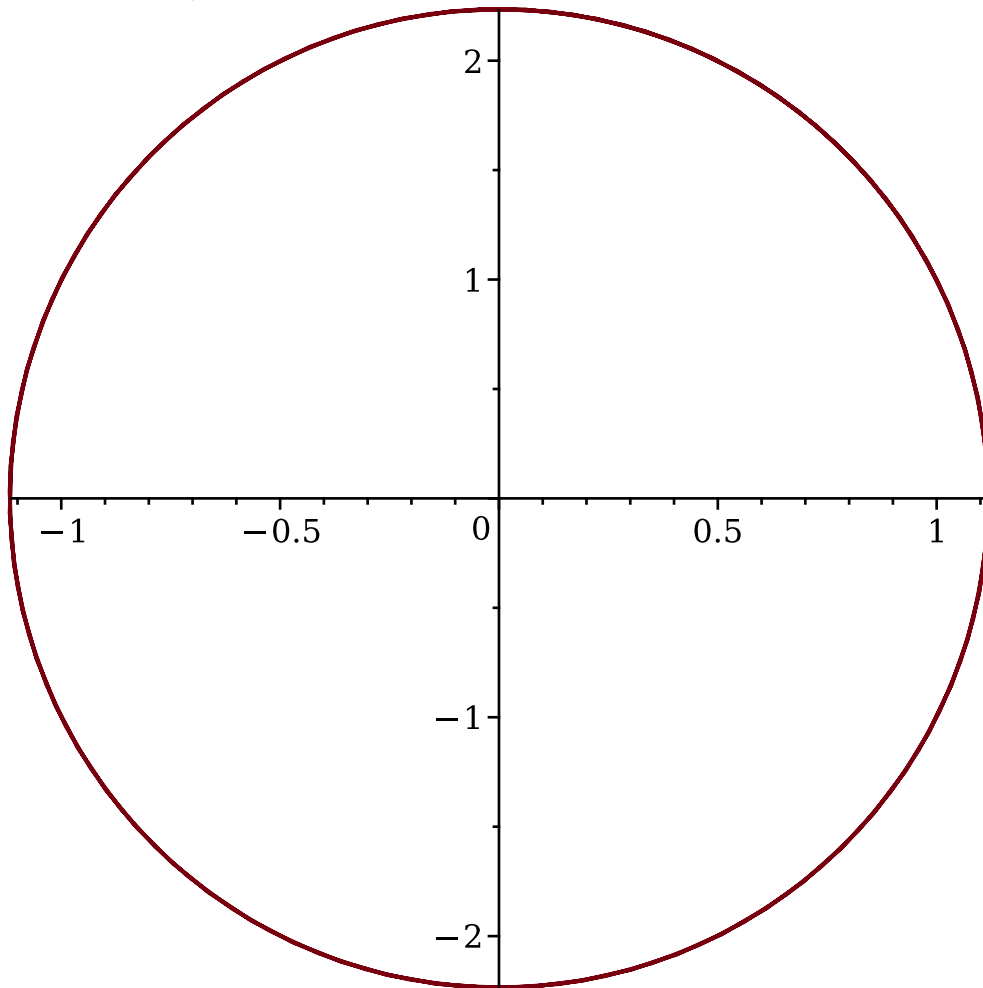
```
> sol := dsolve({syst1, a}, {x(t), y(t)});
```

$$\text{sol} := \left\{ x(t) = -\frac{\sin(2t)}{2} + \cos(2t), y(t) = \cos(2t) + 2 \sin(2t) \right\} \quad (39)$$

```
> Sol1x := unapply(rhs(sol[1]), t);
      Sol1x := t ↦ -  $\frac{\sin(2 \cdot t)}{2}$  + cos(2·t) (40)
```

```
> Sol1y := unapply(rhs(sol[2]), t);
      Sol1y := t ↦ cos(2·t) + 2·sin(2·t) (41)
```

```
> plot([Sol1x(t), Sol1y(t), t = 0..10]);
```



```
> #EX14:
> restart;
> ode1x := diff(x(t), t) = -2·x(t);
      ode1x :=  $\frac{d}{dt} x(t) = -2 x(t)$  (42)
```

```
> ode1y := diff(y(t), t) = -3·y(t);
      ode1y :=  $\frac{d}{dt} y(t) = -3 y(t)$  (43)
```

```
> syst1 := ode1x, ode1y; (44)
```

$$\left[\begin{array}{l} \text{ } \\ \text{ } \end{array} \right. \quad \text{sys1} := \frac{d}{dt} x(t) = -2 x(t), \frac{d}{dt} y(t) = -3 y(t) \quad (44)$$

$$\left[\begin{array}{l} \text{ } \\ \text{ } \end{array} \right. \quad \begin{array}{l} a := x(0) = 1, y(0) = 1; \\ \text{ } \end{array} \quad \begin{array}{l} a := x(0) = 1, y(0) = 1 \\ \text{ } \end{array} \quad (45)$$

$$\left[\begin{array}{l} \text{ } \\ \text{ } \end{array} \right. \quad \begin{array}{l} \text{sol} := \text{dsolve}(\{\text{sys1}, a\}, \{x(t), y(t)\}); \\ \text{ } \end{array} \quad \begin{array}{l} \text{sol} := \{x(t) = e^{-2t}, y(t) = e^{-3t}\} \\ \text{ } \end{array} \quad (46)$$

$$\left[\begin{array}{l} \text{ } \\ \text{ } \end{array} \right. \quad \begin{array}{l} \text{Sol1x} := \text{unapply}(\text{rhs}(\text{sol}[1]), t); \\ \text{ } \end{array} \quad \begin{array}{l} \text{Sol1x} := t \mapsto e^{-2t} \\ \text{ } \end{array} \quad (47)$$

$$\left[\begin{array}{l} \text{ } \\ \text{ } \end{array} \right. \quad \begin{array}{l} \text{Sol1y} := \text{unapply}(\text{rhs}(\text{sol}[2]), t); \\ \text{ } \end{array} \quad \begin{array}{l} \text{Sol1y} := t \mapsto e^{-3t} \\ \text{ } \end{array} \quad (48)$$

$$\left[\begin{array}{l} \text{ } \\ \text{ } \end{array} \right. \quad \text{plot}([\text{Sol1x}(t), \text{Sol1y}(t), t = 0..10]);$$

$\left[\begin{array}{l} \text{ } \\ \text{ } \\ \text{ } \\ \text{ } \\ \text{ } \end{array} \right. \quad \begin{array}{l} \text{ } \\ \text{ } \\ \text{ } \\ \text{ } \\ \text{ } \end{array}$