

In the following exercises, all coordinates and components are given with respect to a right-oriented orthonormal frame  $\mathcal{K}$ .

**8.1.** Consider the affine transformation

$$\phi(\mathbf{x}) = \frac{1}{\sqrt{13}} \begin{bmatrix} 2 & -3 \\ 3 & 2 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 1 \\ -2 \end{bmatrix}.$$

Explain why it is a rotation. Calculate the cosine of the rotation angle and determine  $\phi^{-1}$ .

**8.2.** Let  $T$  be the isometry obtained by applying a rotation of angle  $-\frac{\pi}{3}$  around the origin after a translation with vector  $(-2, 5)$ . Determine the inverse transformation,  $T^{-1}$ .

**8.3.** Consider the affine transformation

$$\phi(\mathbf{x}) = \frac{1}{3} \begin{bmatrix} -1 & 2 & -2 \\ -2 & -2 & -1 \\ -2 & 1 & 2 \end{bmatrix} \mathbf{x} + \begin{bmatrix} \lambda \\ 0 \\ 1 \end{bmatrix}.$$

Explain why it is an isometry. Discuss the type of the isometry in terms of the parameter  $\lambda$ .

**8.4.** Using rotations around the coordinate axes, give a parametrization of a cone containing the line  $\ell = \{(0, t, t) : t \in \mathbb{R}\}$  and with axis the  $z$ -axis.

**8.5.** Using Euler-Rodrigues formula, write down the matrix form of a rotation around the axis  $\mathbb{R}\mathbf{v}$  where  $\mathbf{v} = (1, 1, 0)$ . Use this matrix form to give a parametrization of a cylinder with axis  $\mathbb{R}\mathbf{v}$  and diameter  $\sqrt{2}$ .

**8.6.** A rotation with angle  $\theta$  around the origin after a reflection in the  $x$ -axis is a reflection in the line  $y = \tan(\theta/2)x$ . (Hint: this is Lemma 7.15, you need to fill in the details in that proof)

**8.7.** Let  $\text{Rot}_{\theta_1, C_1}$  and  $\text{Rot}_{\theta_2, C_2}$  be rotations with angles  $\theta_1, \theta_2$  and centers  $C_1, C_2$  respectively. Show that the composition of these two rotations is a (possibly trivial) translation if and only if  $\theta_1 + \theta_2 = 2k\pi$  for some integer  $k$ .

**8.8.** Discuss, in dimension 2, the possible isometries obtained by composing a reflection in a line  $\ell_1$  with a reflection in a line  $\ell_2$  in terms of the relative positions of the two lines.