

DTU



Networked Embedded Systems

Week 12: Industrial Embedded Networks

Xenofon (Fontas) Fafoutis

Professor

xefa@dtu.dk

www.compute.dtu.dk/~xefa

Requirements of (Industrial) Networked Embedded Systems

- Scalability
 - Supported number of embedded systems
- Throughput
 - Bytes received per second
- Reliability (Packet Delivery Ratio, PDR)
 - Number of packets received over packets sent
- Latency/Delay
 - Time interval from the time a packet is sent to the time packet received
- Jitter
 - Variability of latency/delay
- Time-sensitivity or determinism
 - Predictable/bounded latency and jitter
- Energy Efficiency and Consumption
 - All above need energy

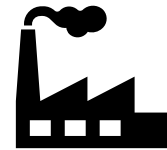
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Trade-offs: There is no solution that optimises all; we need figure out what we can afford to sacrifice

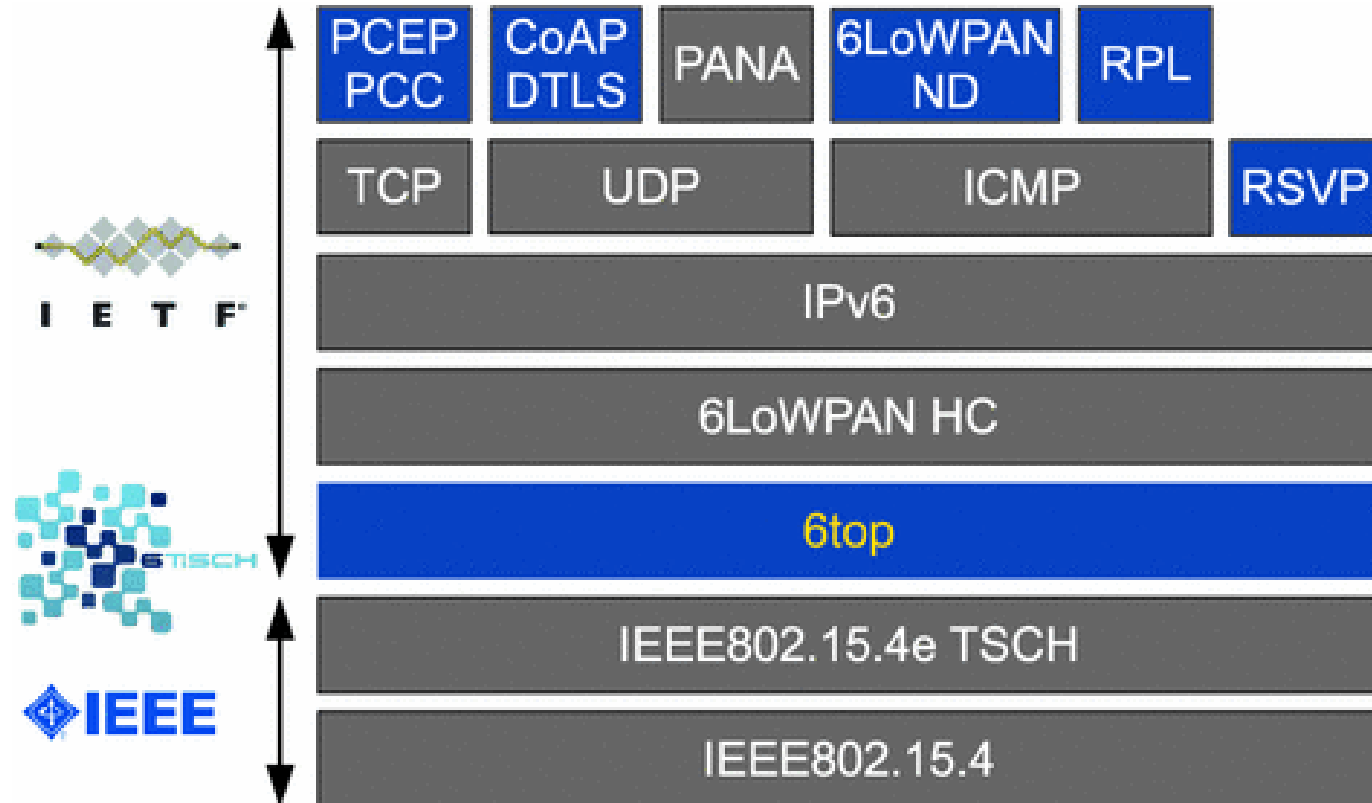
Industrial Embedded Networks

- Industrial Networks carry vital and often safety critical data
 - Tend to prioritise reliability and determinism over throughput and energy efficiency
 - Best-effort data may co-exist (e.g. vehicle sensor data vs entertainment)
- Common features
 - Schedule-based communication (avoid contention-based protocols)
 - Time synchronisation
 - Traffic prioritisation
 - Redundancy
 - Interference mitigation
- Examples
 - TSCH
 - TSN



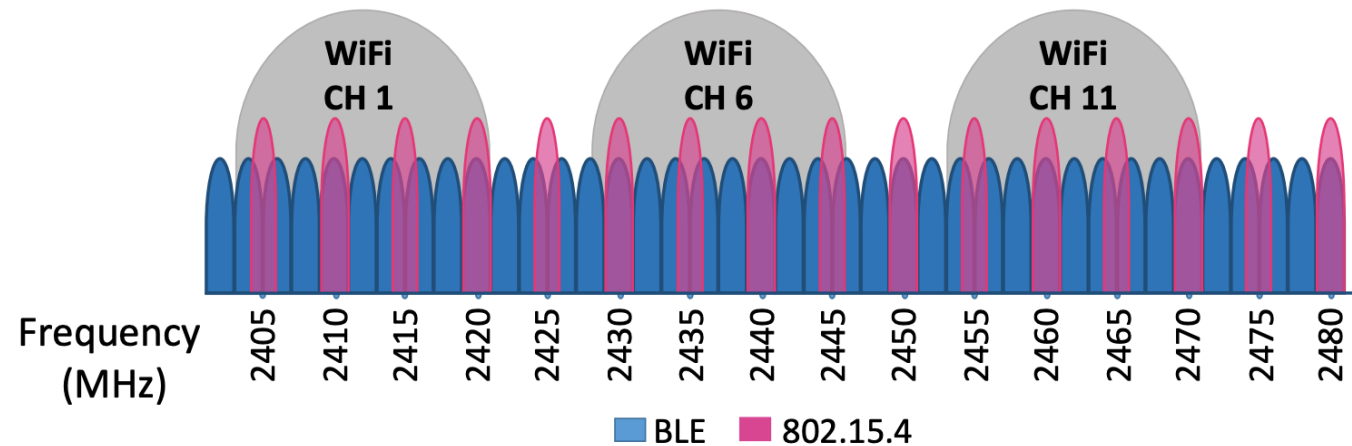
Industrial Wireless Networks

- The 6TiSCH protocol stack
- A collection of IEEE/IETF standards
- Aiming at industrial wireless networks that require high reliability and deterministic delay/jitter
- Main components
 - RPL
 - IPv6
 - 6top
 - IEEE 802.15.4 TSCH



IEEE 802.15.4 PHY

- A low-power wireless standard for Low-Rate Wireless Personal Area Networks (LR-WPANs)
 - Supports two ISM Bands (2.4 GHz, sub-GHz)
 - 250 kbps data rate @ 2.4 GHz
 - 127-byte packets
 - 16 channels @ 2.4 GHz (+ 1 channel @ 868 MHz in Europe)
 - Supports encryption/authentication
- Used in smart home/city/* wireless networks (Thread, Zigbee)
- Used in industrial wireless networks (6TiSCH)



IEEE 802.15.4 MAC

- Traditional IEEE 802.15.4-2011 MAC
 - Based on two classes of devices (asymmetric resources)
 - Full-Function Devices (FFD): Coordinator, frame forwarder
 - Reduced-Function Devices (RFD): Simple, energy-preserving
 - Supports contention-based (CSMA/CA) and contention-free (GTS) communication
- IEEE 802.15.4e MAC Enhancements
 - Enhanced MAC protocols for industrial applications
 - DSME (Deterministic and Synchronous Multi-channel Extension)
 - LLDN (Low Latency Deterministic Network)
 - TSCH (Time Slotted Channel Hopping)

IEEE 802.15.4 TSCH

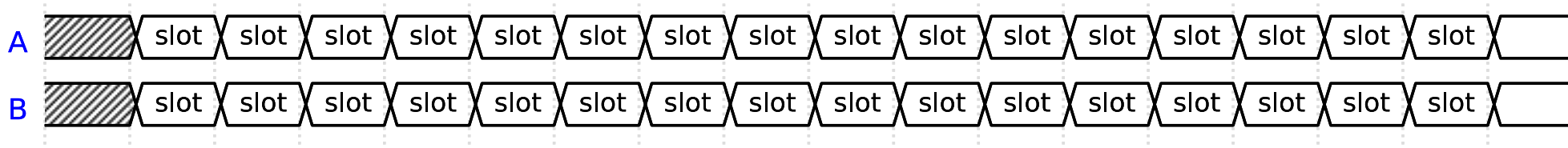
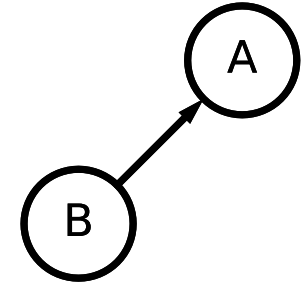
- TSCH (Time-Slotted, Channel Hopping)
 - A MAC protocol based on the IEEE 802.15.4 PHY
- TSCH supports
 - Multi-hop networks (line, tree, mesh) topologies
 - Radio duty cycling in all devices
- TSCH provides
 - Very high reliability (99.99%+ PDR)
 - Interference avoidance
 - Predictable delay/jitter/energy consumption
 - Time synchronisation (10ms)

TSCH Mechanics

- A combination of TDMA and FDMA
- Time-Slotted: Synchronous schedule-based channel access
 - Predictable channel access, possible to eliminate collisions
- Channel Hopping: Use of multiple frequency channel in a rotating fashion
 - Resilience to external interference
- TSCH traces its roots to older industrial wireless standards
 - Time Synchronized Mesh Protocol (TSMP, 2006) by Dust Networks (proprietary)
 - WirelessHART (2007) by the HART Communication Foundation
 - ISA100.11a (2009) by the International Society of Automation (ISA)

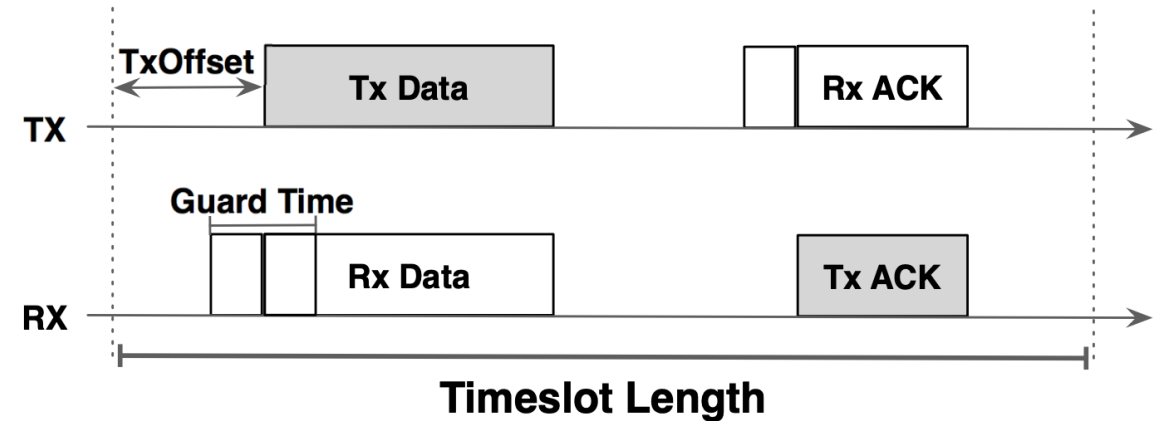
TSCH: Timeslots and Time Synchronisation

- Network-wide Time Synchronisation
 - All devices in a TSCH network are time synchronised with each other
 - Relative time synchronisation based on the implicit synchronisation technique
- Time is split into timeslots
 - Each slot is long enough to support:
 - Transmission of a frame of maximum size (~ 4 ms)
 - An acknowledgement (~ 0.35 ms)
 - The guard time (~ 2 ms)
 - Time required to switch from TX to RX mode, encryption/decryption
 - The duration of the timeslot is not imposed by the standard
 - Typical slot size is 10 ms
 - Some older radios are slow at switching from TX to RX mode and need 15ms



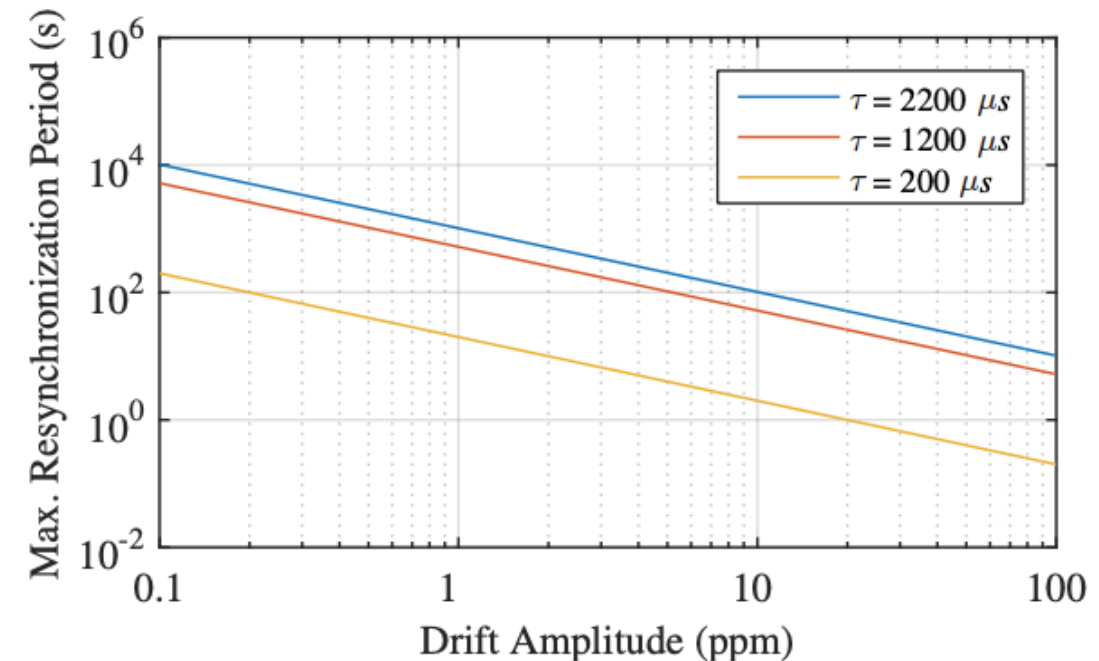
TSCH: Timeslot

- A timeslot defines a transmission opportunity
 - An actual frame transmission may not happen if there is nothing to transmit!
- The sender initiates the frame transmission at *TxOffset* after the beginning of the timeslot
- The receiver listens to the channel for the time defined by the *Guard Time*
 - The guard time is equally spaced around the expected transmission time to account for both positive and negative drift
 - If a preamble is captured within the guard time, the receiver stays on to capture the full frame
 - Otherwise, the receiver goes to sleep
- After a frame transmission, sender and receiver swap the modes of their radios for the ACK



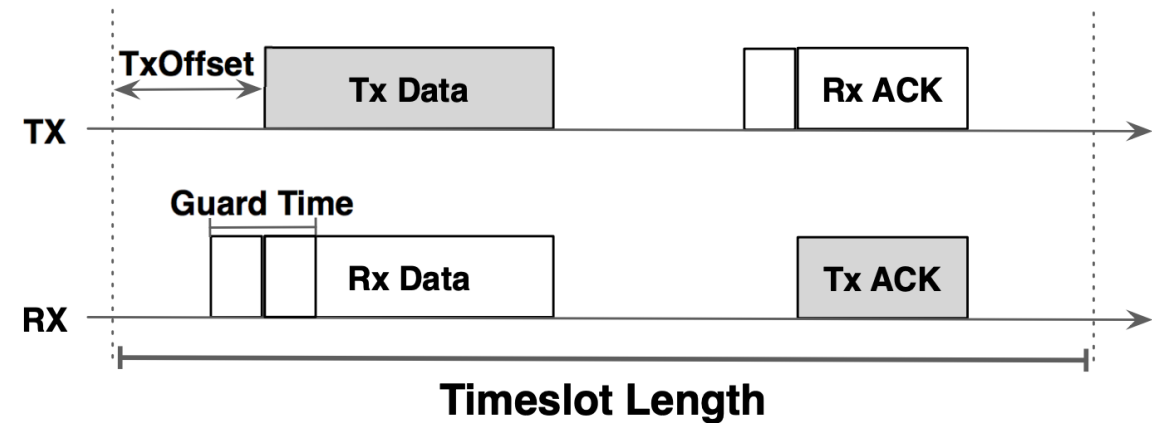
TSCH: Guard Time

- The guard time allows for a certain degree of synchronisation error
 - Periodic synchronisation is required
- Longer Guard Time
 - More robust to synchronisation errors
 - Less frequent synchronisation required
 - More idle listening, more energy consumption
 - Occupy the channel, bigger slots
 - Fewer slots per second, less data
- Ideally as short as possible, but long enough to maintain robust synchronisation



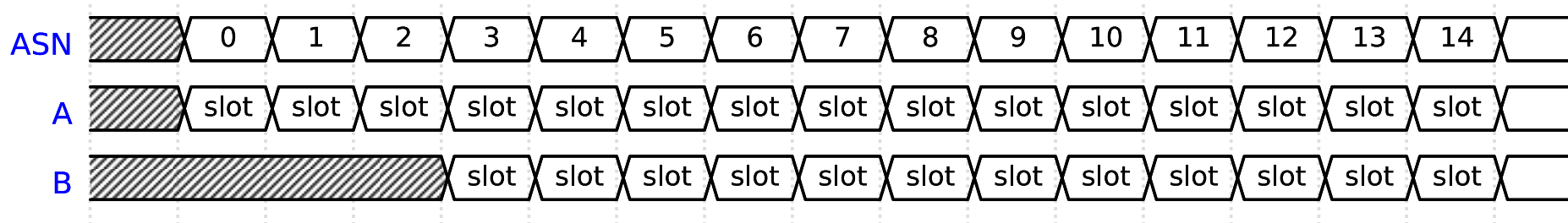
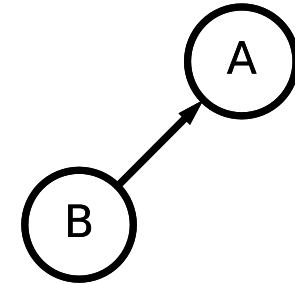
TSCH: Frame-Based and ACK-Based Synchronisation

- TSCH uses implicit synchronisation with a neighbour on each frame transmissions
- The receiver calculates the difference between the expected and actual time of frame arrival
- In frame-based synchronisation, the receiver uses this offset to synchronise to the clock of the sender
- In ACK-based synchronisation, the receiver adds this offset in the acknowledgement frame and the sender uses it to synchronise to the clock of the receiver
- In the absence of data, devices need to exchange an empty *Keep-Alive* frame to re-synchronise
 - Significant overhead in applications that transmit very infrequently, e.g. smart metering



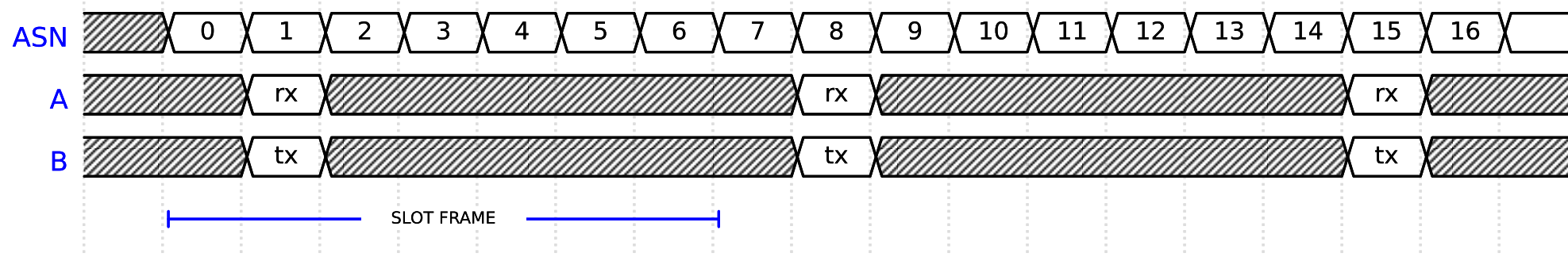
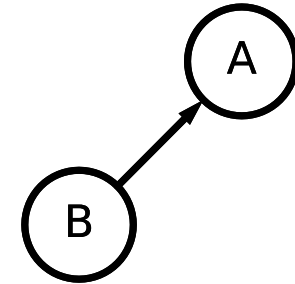
TSCH: Absolute Slot Number

- A number that counts slots since the formation of the network
 - 5 bytes so that it can increment for hundreds of years without wrapping
- ASN Synchronisation
 - ASN is initialised to 0 by the device that forms the network
 - Devices learn the current value of ASN when they join the network
 - Since they are synchronised, all devices know the current value of ASN at any time



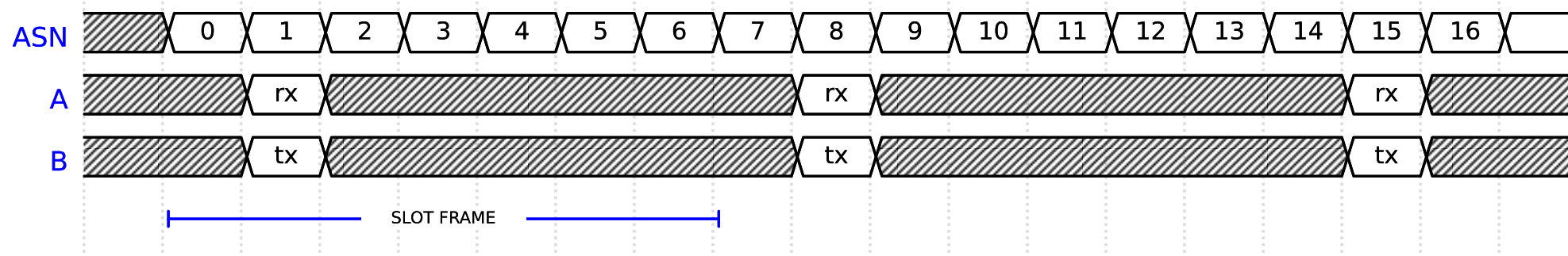
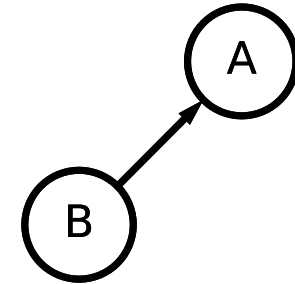
TSCH: Slot frame and Schedule

- Time slots are organised in a slot frame
 - A slot frame is a continuously repeating pattern of slots
 - Slot frame size (not defined by the standard, tailored to the application)
 - $[\text{slot offset}] = [\text{ASN}] \% [\text{slot frame size}]$
- Communication is based on a schedule, for example:
 - Slot frame size = 7
 - B transmits to A in slot offset = 1



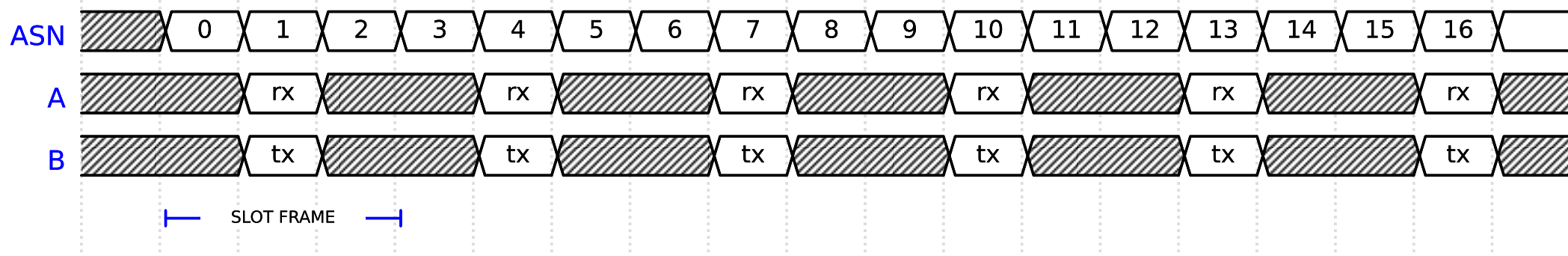
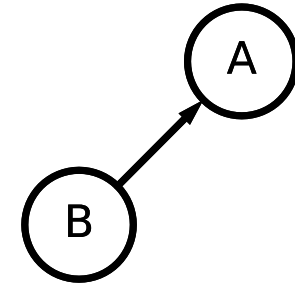
TSCH: The Schedule Controls Several Performance Metrics

- Assuming timeslot size 10 ms and frame size 7...
- Link Capacity: $100 / 7 = 14.28$ packets per second
- Energy Consumption: $1 / 7 = 14.28\%$ radio duty cycle
- Latency: up to $7 \times 10 \text{ ms} = 70 \text{ ms}$



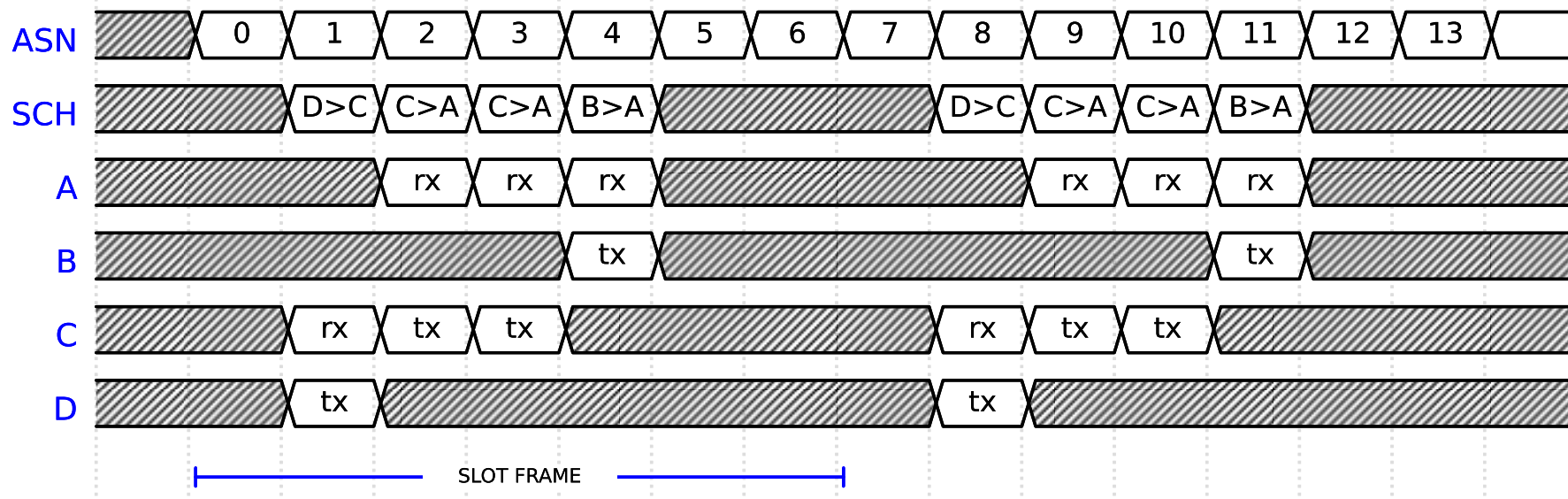
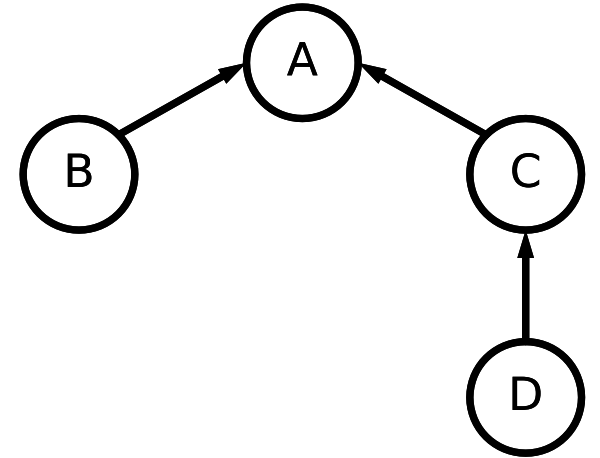
TSCH: Slot Frame Size

- Defines the number of idle slots in a frame
- Shorter slot frame size
 - More transmission opportunities -> higher capacity for data
 - More re-transmission opportunities -> higher reliability
 - Shorter average and worst-case latency
 - More unused slots -> worse energy-efficiency
 - Less room for other devices -> worse scalability



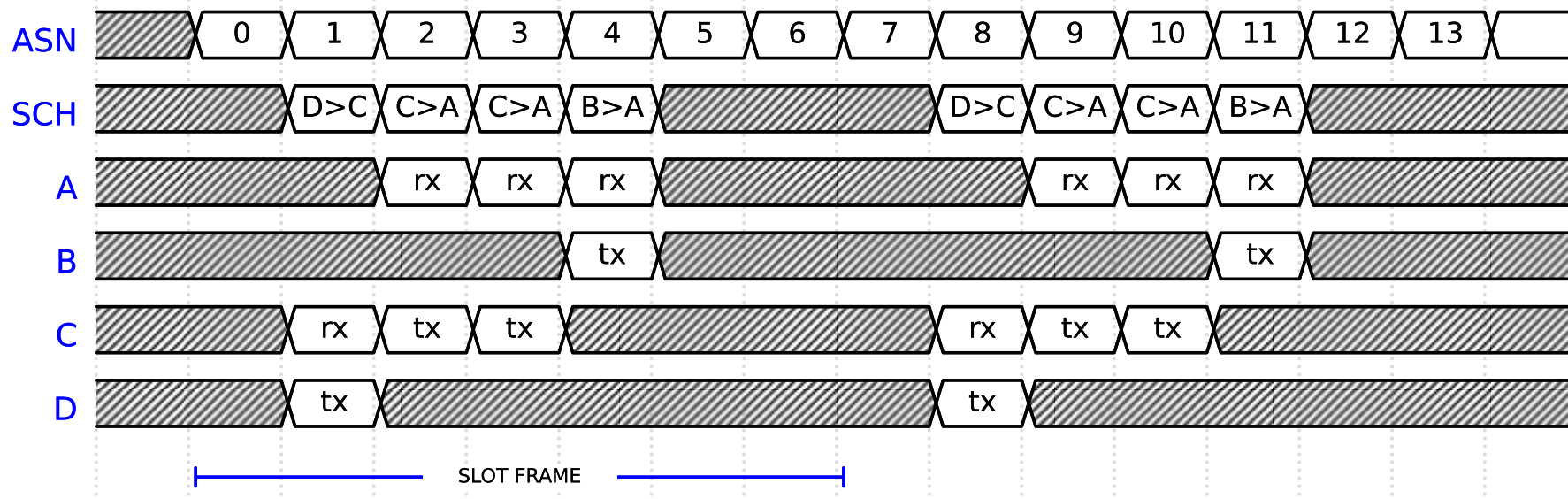
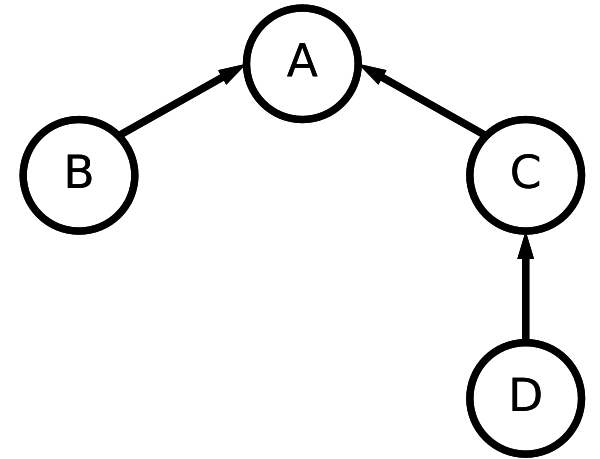
TSCH Schedule: Dedicated Slots

- In each slot, a device can transmit (Tx), receive (Rx), or sleep (idle)
- Dedicated slots (Contention-free)
 - Slot dedicated to a specific link
 - One assigned transmitter -> no collisions
 - Example: B>A, means B transmits (Tx) and A receives (Rx)

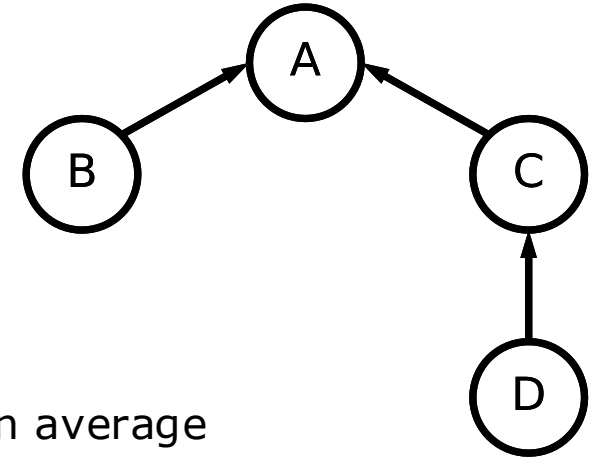


TSCH Schedule: How many slots?

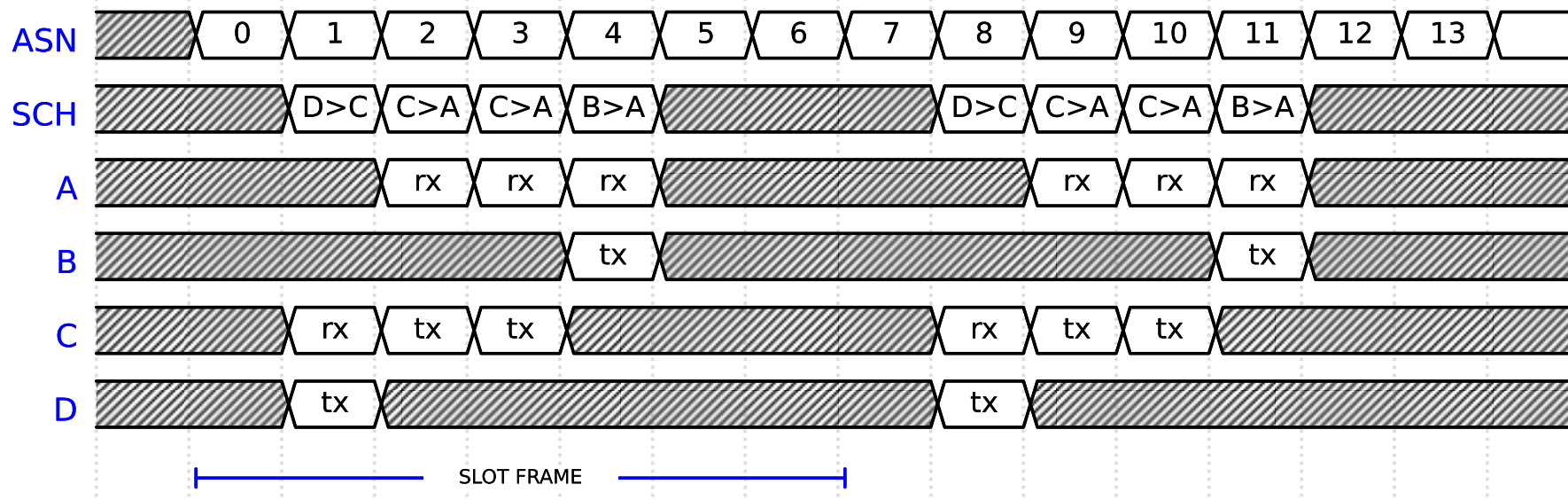
- Why did I allocate 2 slots per frame for link C>A?
- How many slots per frame I need generally?



TSCH Schedule: How many slots?

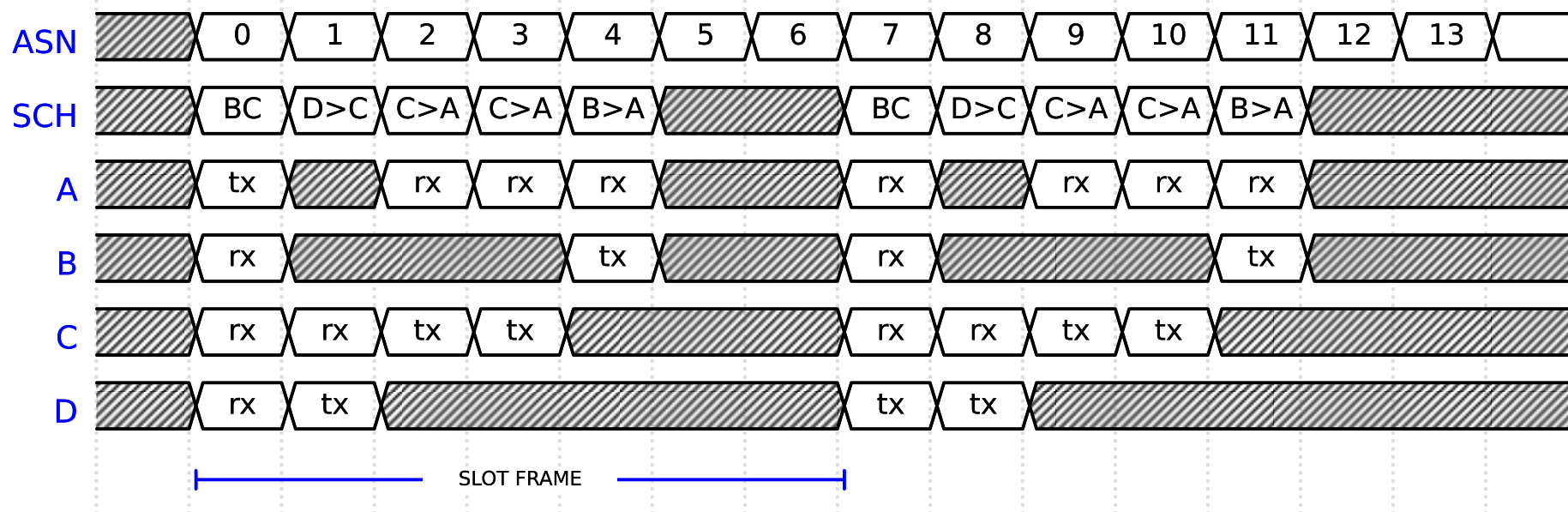
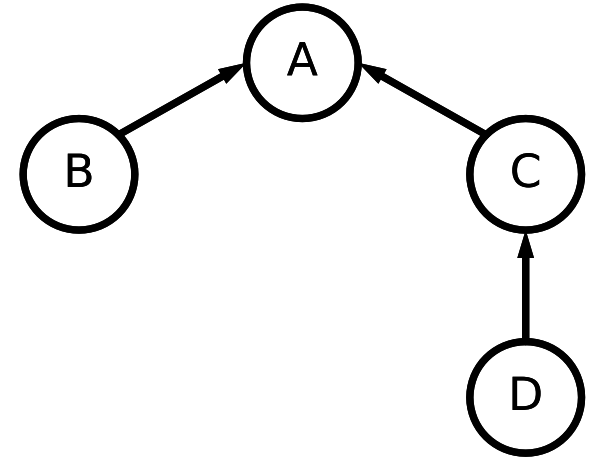


- Slots in the schedule should be able to have capacity for:
 - Packets generation rate by the transmitter
 - Packets forwarding rate by the transmitter
 - Retransmissions (ETX, Expected Transmission Count)
 - $ETX = 1/p$ where p is packet reception probability
 - Example: if $p=20\%$, I have to retransmit each packet 5 times on average



TSCH Schedule: Broadcast Slots

- Broadcast slots (every node active)
 - If I have something to broadcast, I transmit
 - If I have nothing to broadcast, I listen/receive
 - Typically, the first slot of the frame
 - Collisions may happen
 - Transmitters cannot receive broadcasts of others

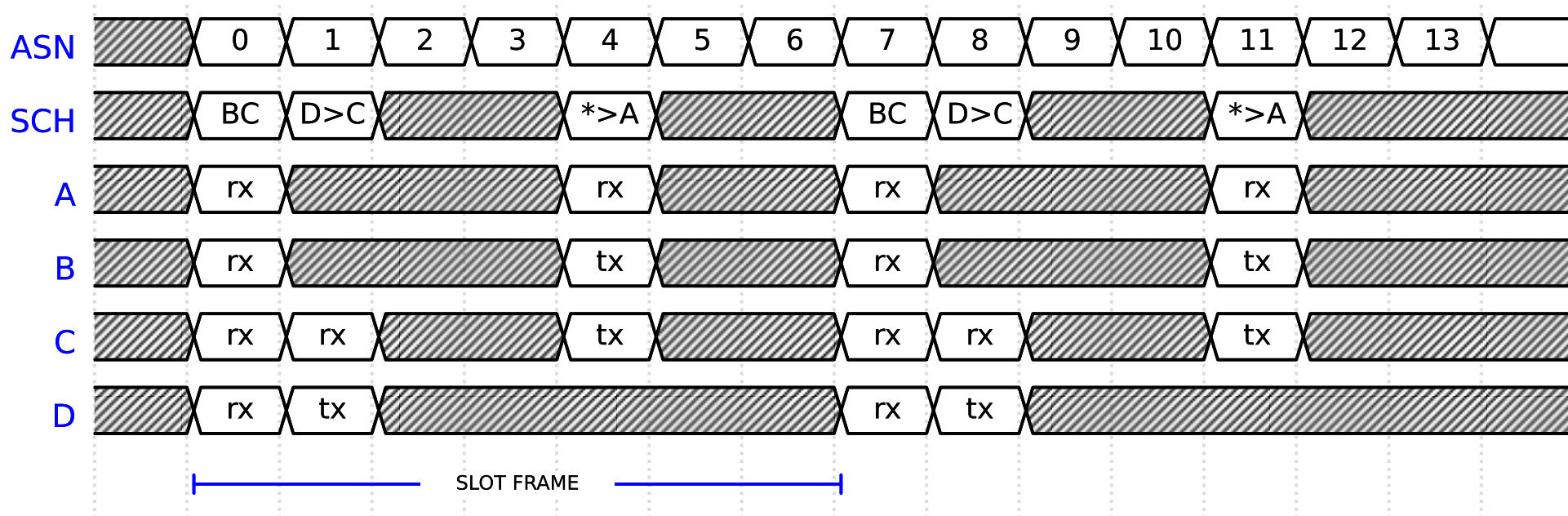
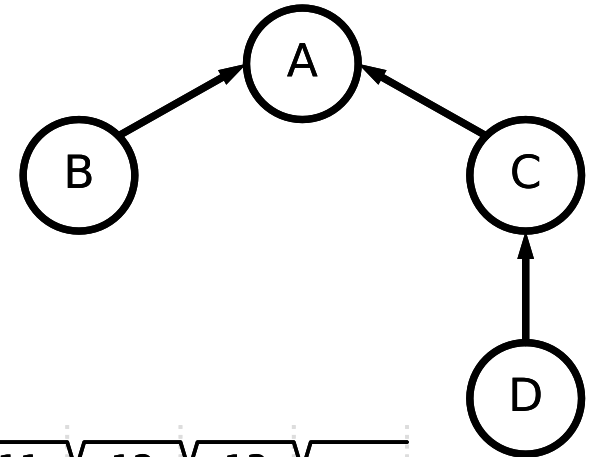


TSCH: Slots Are Limited

- Assuming a time slot of 10 ms, there are only 100 slots per second
 - Permit for maximum 100 packets per second
- What can do if we run out of slots, and we want to support more devices, traffic or retransmissions?

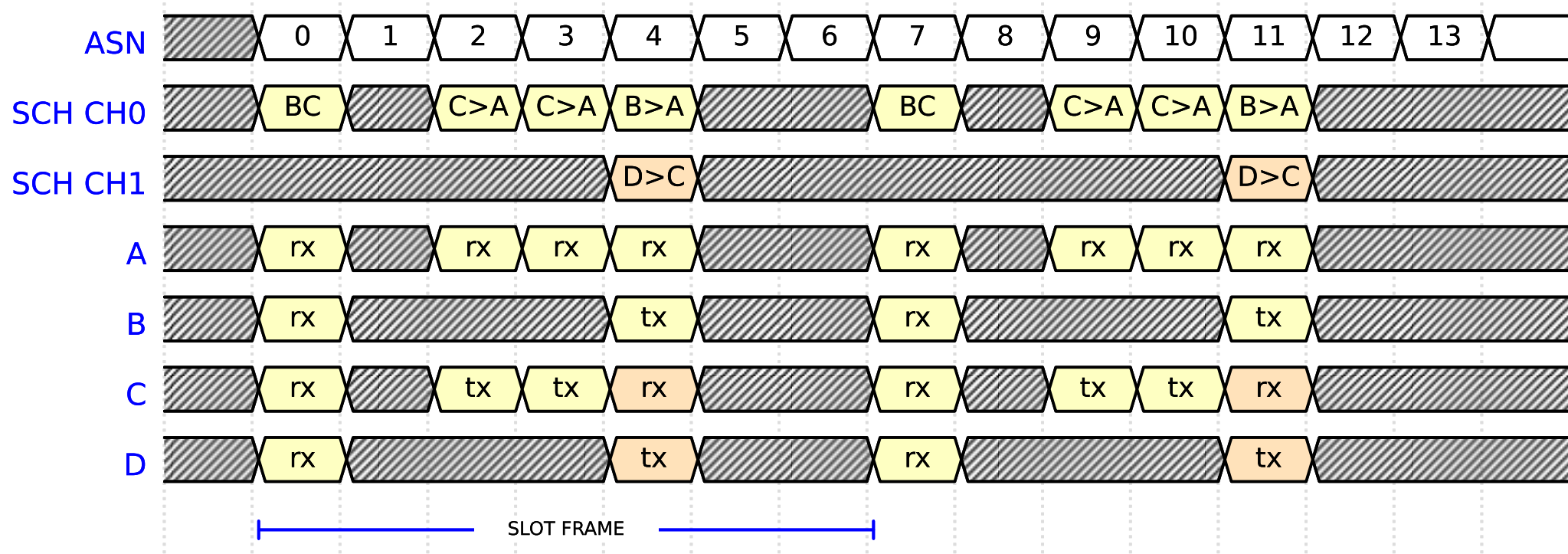
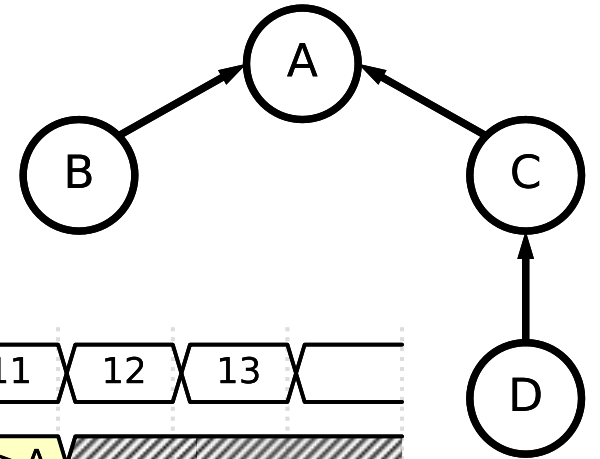
TSCH Schedule: Shared Slots

- Shared slots (Contention-based)
 - Slot assigned to multiple transmitters
 - Collisions are possible, need CSMA/CA



TSCH Schedule: Multiple Channels

- Parallel transmissions are possible in different channels
 - A transmitter and receiver can only tune to one specific channel

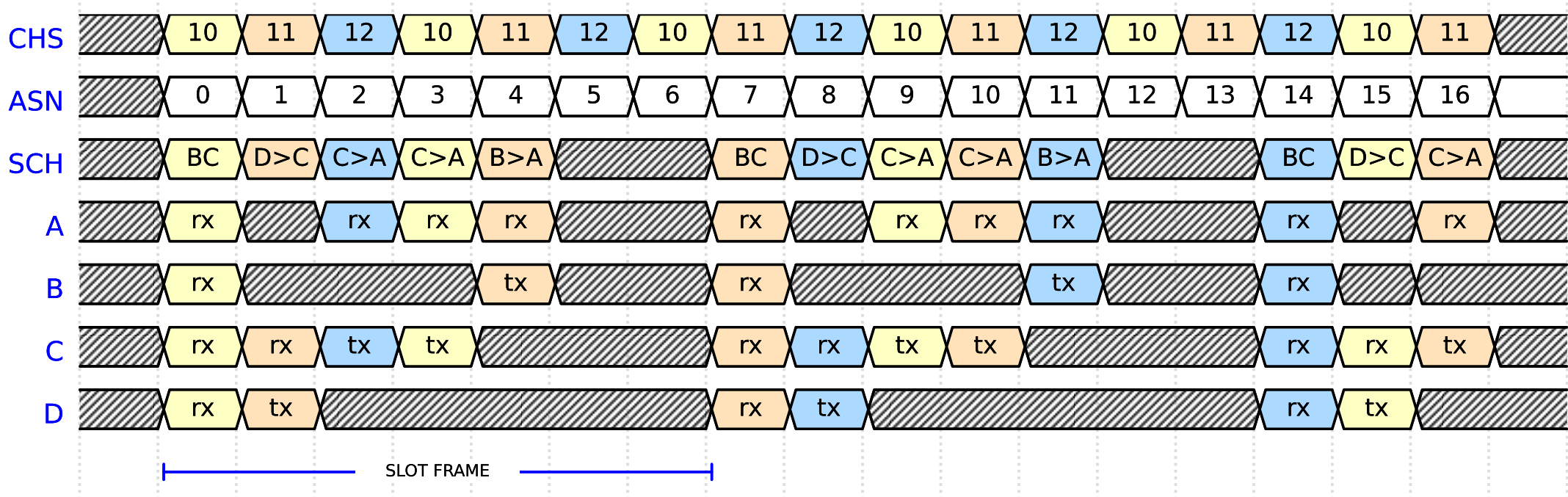
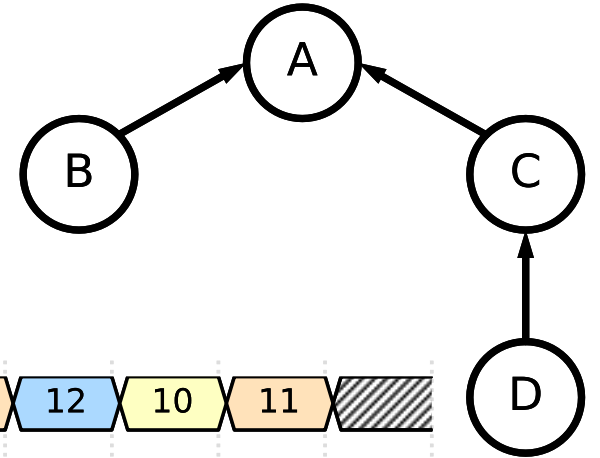


Some Channels are better than others

- IEEE 802.15.4 use retransmissions to combat channel errors
- Interference and fading errors are correlated in time
 - If a channel experiences a lot of interference now, it is very likely to experience a lot of interference in the next frame
- Yet, interference and fading of different channels are often uncorrelated
 - If a channel experiences a lot of interference now, it is very likely that another channel will not be affected by the same source of in the next frame
- Idea: Change channels for each retransmission to enhance reliability

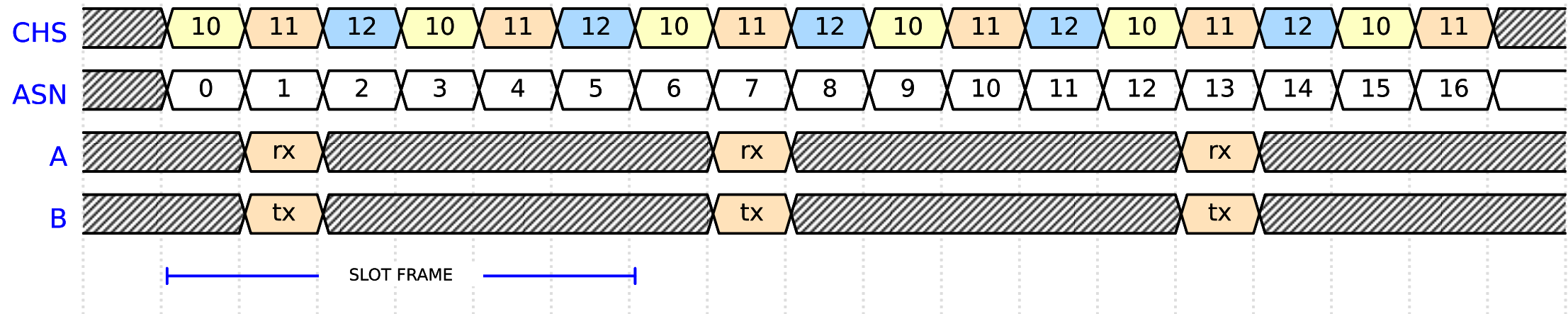
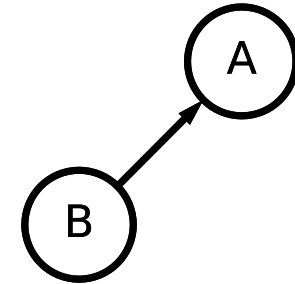
TSCH: Channel Hopping

- Channels change following a pre-agreed pseudo-random order
- All nodes agree on a Channel Hopping Sequence (CHS), e.g. 10-11-12
- Channel = CHS[index], where index = ASN mod len(CHS)



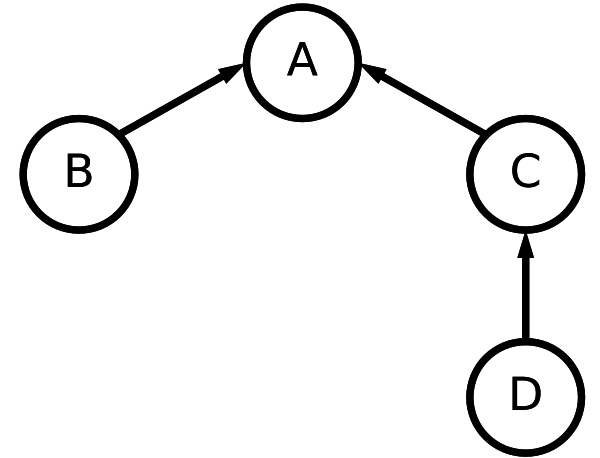
Slot Frame Size vs Channel Hopping Sequence Size

- The Slot Frame Size and CHS size must be relatively prime
 - Their highest common factor should be 1
- Otherwise, there is no channel hopping!
- Example: frame size is 6 and CHS size is 3



The TSCH Schedule

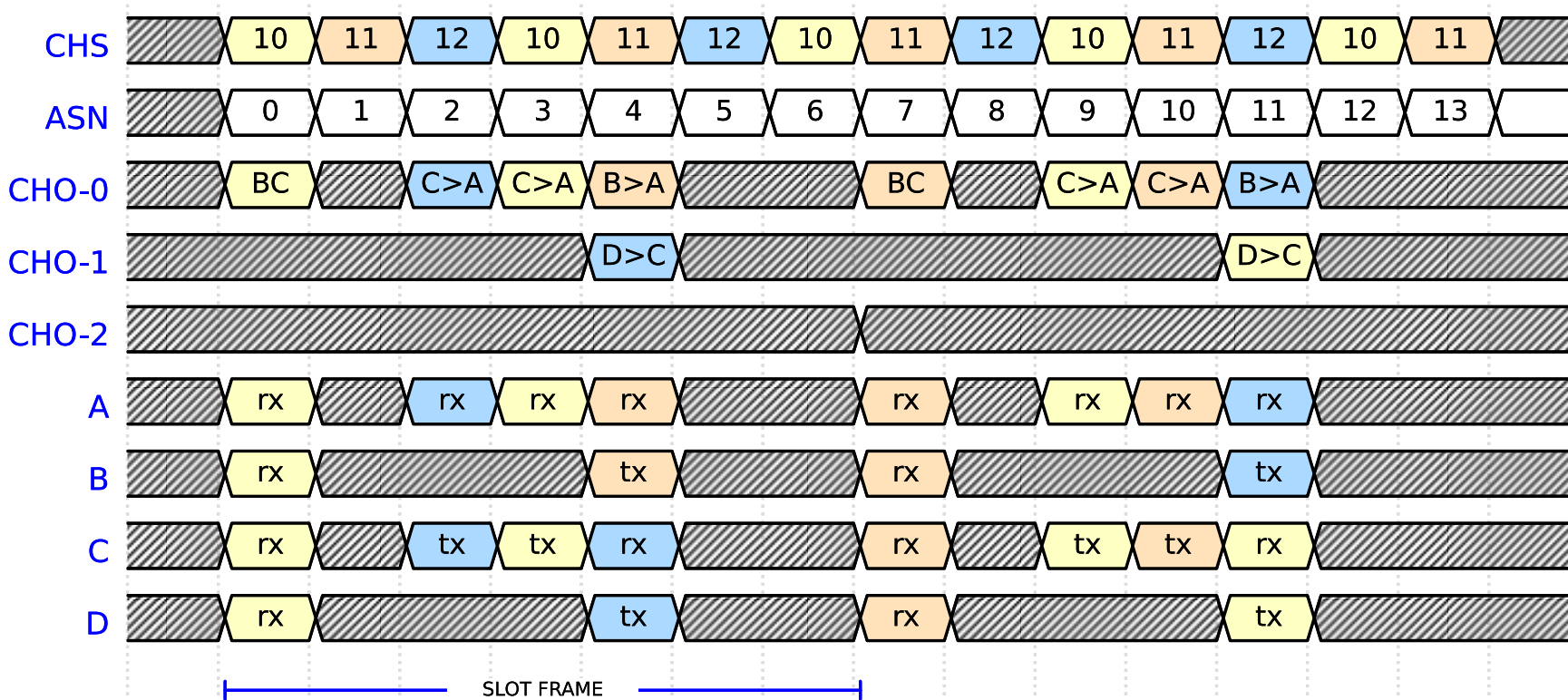
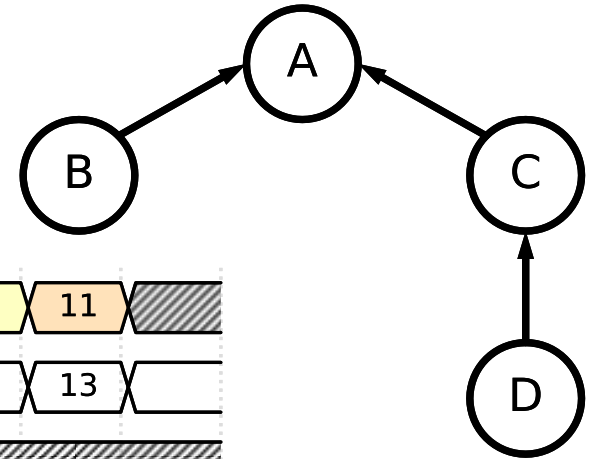
- A N-by-M table where N is the slot frame size and M is the CHS size
 - Each column represents a slot offset (SO)
 - Each row represents a channel offset (CHO)
- Channel = CHS[index], where $\text{index} = (\text{ASN} + \text{CHO}) \bmod \text{len}(\text{CHS})$



CHO \ SO	0	1	2	3	4	5	6
0	BC		C > A	C > A	B > A		
1					D > C		
2							

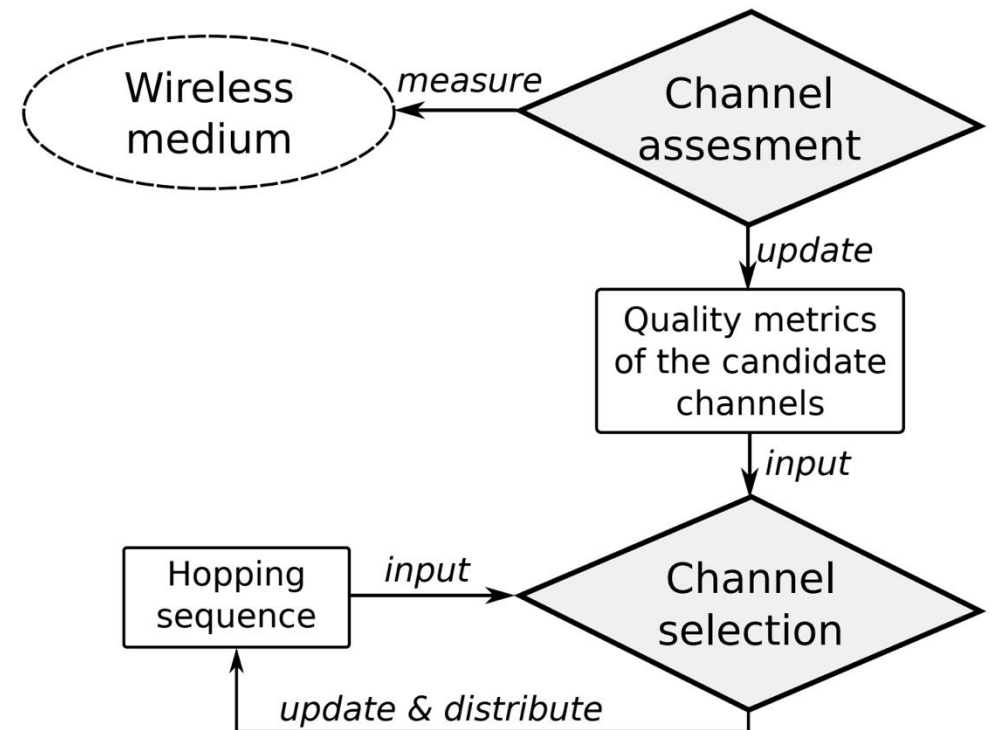
TSCH Schedule

- Channel = CHS[index], where $\text{index} = (\text{ASN} + \text{CHO}) \bmod \text{len}(\text{CHS})$



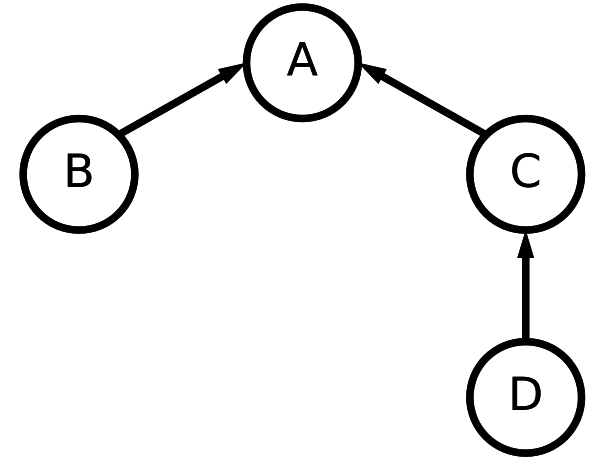
Channel Selection

- Consider a channel with a lot of interference
 - Using as the only single channel is very bad
 - Using it as part of the CHS is better, but inefficient
- How can we select which channels to use?
 - Some channels are more busy than others
 - This quality of the channels changes over time
- Adaptive Channel Selection
 - Measure the quality of channels
 - Update metrics with statistics
 - Select the best channels (blacklist/whitelist)
 - Distribute changes to the channel hopping sequence



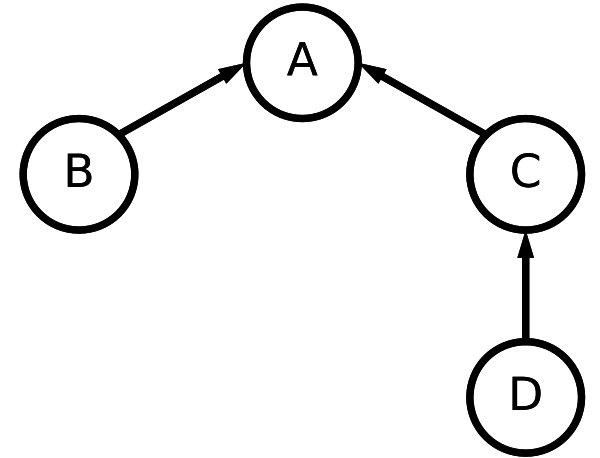
TSCH Scheduler

- A TSCH Scheduler is an algorithm that determines the TSCH schedule
- The Scheduler is not defined by the standard (flexible)
- Schedules are tailored to the use case
- Types of TSCH Scheduling
 - Static Scheduling
 - Dynamic Scheduling
 - Centralised Scheduling
 - Distributed Scheduling
 - Autonomous Scheduling



Static Scheduling

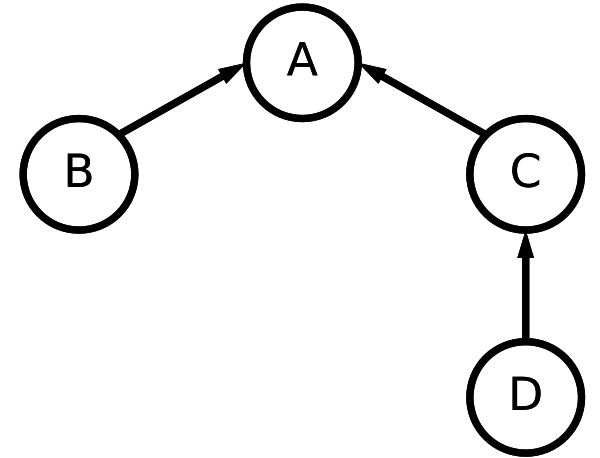
- Schedule is hardcoded on the firmware of the devices
- A static schedule can be handcrafted or algorithmically derived
- Makes sense only in relatively static TSCH networks
 - No. of devices, topology, traffic patterns, expected retransmissions



CHO \ SO	0	1	2	3	4	5	6
0	BC		C > A	C > A	B > A		
1					D > C		
2							

Dynamic Scheduling

- A minimal schedule with shared slots is defined
 - Hardcoded or installed when joining the network
- Dedicated slots are allocated dynamically
- Centralised Scheduling
 - The root node collects information about the nodes via these shared slots
 - Having the global picture of the network, it allocates dedicated slots to specific links
 - Such decisions can be determined using machine learning or reinforcement learning
- Distributed Scheduling
 - Neighbouring nodes exchange information and agree on which slots to use between them



IETF Minimal Schedule and 6top

- Minimal Schedule
 - One broadcast slot in offset (0,0)
 - The slot frame size and channel sequence size is undetermined
 - Hardcoded or installed when joining the network

CHO \ SO	0	1	2	3	4	5	...
0	BC						
1							
...							

THE COMMANDS SUPPORTED BY THE 6TOP PROTOCOL (6P)

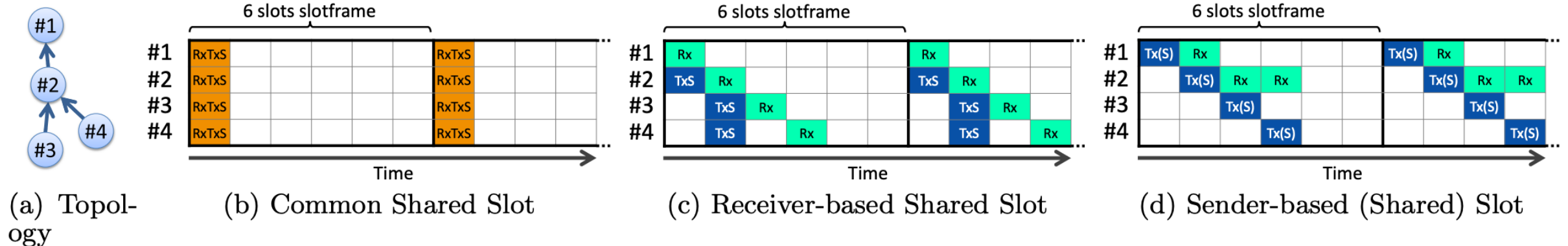
Command	Code	Description
ADD	1	Add cell(s) between the two neighbors. The CellOptions bitmap indicates the type of cell(s) to add.
DELETE	2	Delete cell(s) from the schedule.
RELOCATE	3	Relocate cell(s) in the schedule. Used to handle schedule collisions.
COUNT	4	Count the cells with a particular CellOptions.
LIST	5	List the cells with a particular CellOptions.
SIGNAL	6	Placeholder for SF-specific commands.
CLEAR	7	Clears all cells between the two neighbors. Possibly used to handle schedule inconsistencies.

- 6top (6TiSCH Operation Sublayer Protocol)
 - A protocol to exchange messages for distributed scheduling

Image source: <https://doi.org/10.1109/COMST.2019.2939407>

Autonomous Scheduling

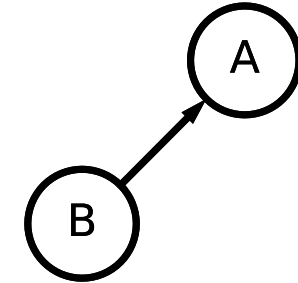
- Each node derives and changes its schedule autonomously
 - No need to exchange messages
- Shared slots are used for the routing protocol to determine parent nodes
 - Nodes autonomously determine when to transmit/receive using routing information
 - Devices hash the Node ID or MAC address (of sender or receiver) modulo frame size to determine which slot to use
- Orchestra is a widely used autonomous scheduler (albeit not a standard)



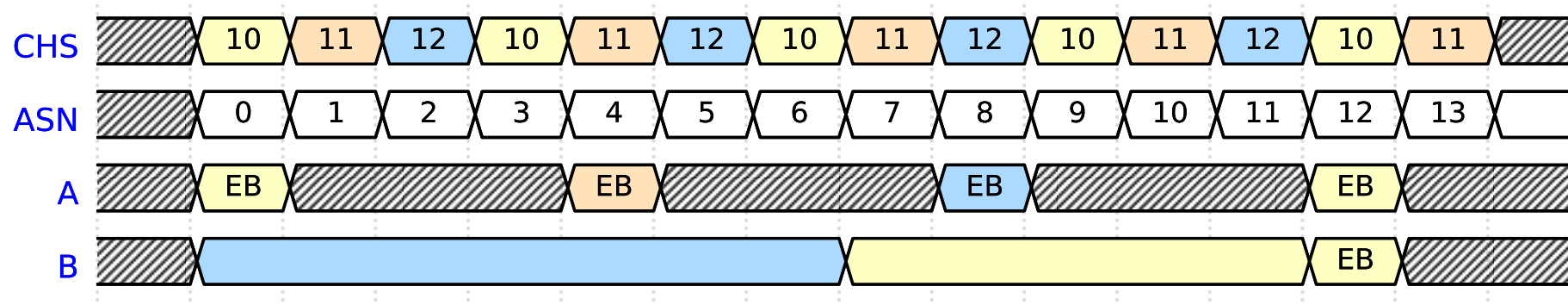
Joining a TSCH Network

- How does a new device joins a TSCH network?
- A new device that wants to join a TSCH network:
 - Does not know the schedule (unless static scheduling is used)
 - Does not know the current ASN
 - Does not know when the beginning of a frame/slot is (not in sync)
- Enhanced Beacon (EB)
 - Devices of the TSCH network periodically broadcast an EB to advertise the network
 - EB includes the current ASN and (part of) the schedule
- The joining device scans the wireless medium for an EB but without knowing the time and channel of the transmission

Searching for an EB packet

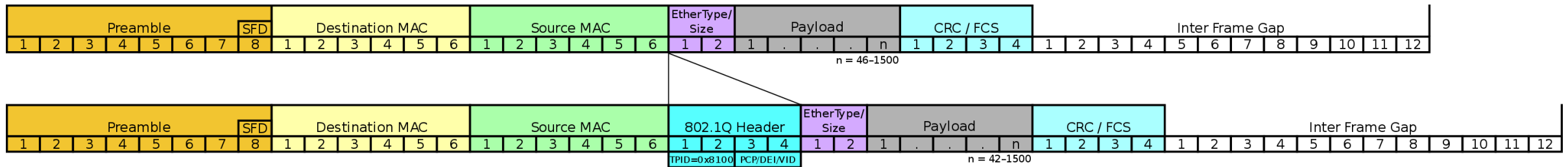


- The joining node scans sequentially all the channels until it receives an EB
 - If the CHS is fixed, the joining node needs to search only those channels
 - Otherwise, it needs to search all 16 channels
- Upon the reception of the first EB, the joining node keeps scanning for a potentially better parent until a timeout or a maximum number of candidate parents is reached
- The joining process is notoriously slow and inefficient
 - But often considered insignificant in static TSCH networks as it ideally happens just once



Industrial Wired Networks

- IEEE 802.1Q
 - Supports Virtual LANs (VLAN) over Ethernet (IEEE 802.3)
 - VLAN Tagging with 8 priority classes
- Time-Sensitive Networking (TSN)
 - A set of extensions on top of IEEE 802.1Q



Time Sensitive Networking (TSN)

- IEEE 802.1AS Timing and Synchronization for Time-Sensitive Applications
 - Precise time synchronisation based on PTP
- IEEE 802.1Qbv Enhancements to Traffic Scheduling: Time-Aware Shaper (TAS)
 - Synchronised TDMA-based medium access
 - Time is organised in repeating cycles of time slices
 - Time slices can be allocated to specific VLAN priorities for exclusive access
 - Time-critical traffic can be separated from non-critical background traffic

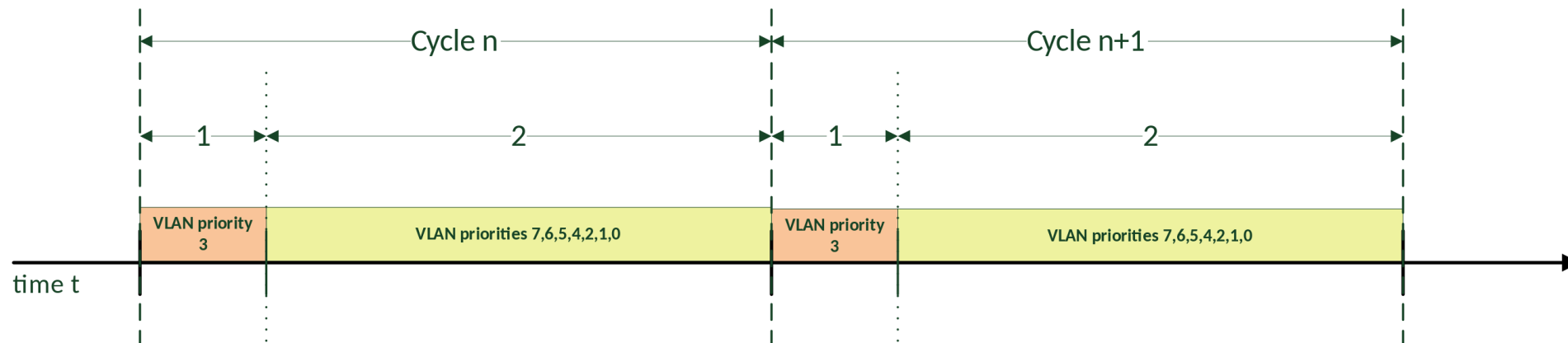


Image source: Wikipedia