

Laborator 1

• Triunghi ABC cu vârfurile $A(1,1)$, $B(4,1)$, $C(2,3)$.

1. Determinați imaginea ΔABC printr-o scalare simplă neuniformă, de factori de scală $(2,1)$, relativ la punctul $Q(2,2)$, urmată de o rotație de unghi 90° față de origine.

• scalare

$$\text{Scale}(Q, 2, 1) = \text{Trans}(2, 2) \cdot \text{Scale}(2, 1) \cdot \text{Trans}(-2, -2) =$$

$$\text{Trans}(2, 2) = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Trans}(-2, -2) = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Scale}(2, 1) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow \text{Scale}(Q, 2, 1) = \begin{bmatrix} 2 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A' \ B' \ C'] = \text{Scale}(Q, 2, 1) \cdot [A \ B \ C] = \begin{bmatrix} 2 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 6 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\Rightarrow \begin{matrix} A'(0, 1) \\ B'(6, 1) \\ C'(2, 3) \end{matrix}$$

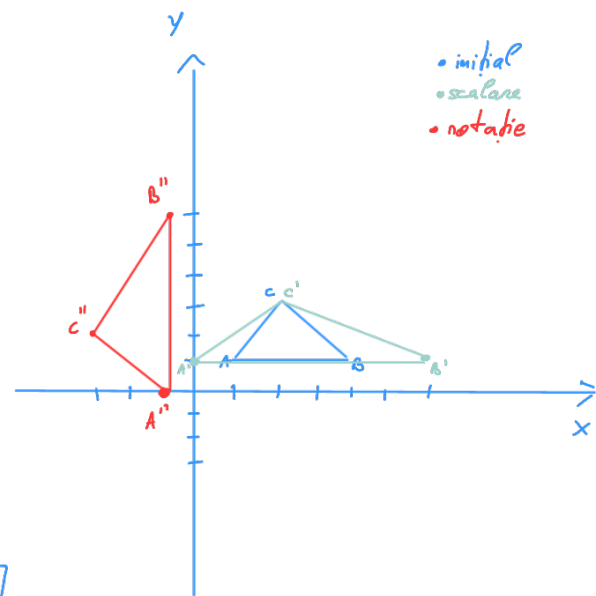
• rotație

$$T = \text{Rot}(90^\circ) \cdot \text{Scale}(Q, 2, 1)$$

$$\text{Rot}(90^\circ) = \begin{bmatrix} \cos 90^\circ & -\sin 90^\circ & 1 \\ \sin 90^\circ & \cos 90^\circ & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow T = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 2 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 2 & 0 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A'' \ B'' \ C''] = T \cdot [A \ B \ C] = \begin{bmatrix} 0 & -1 & 0 \\ 2 & 0 & -2 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} -1 & -1 & -3 \\ 0 & 6 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$



• initial
• scalare
• rotație

2. Det. imag. ΔABC printr-o forfecare de unghi 45° relativ la pct. $Q(2,2)$ in directia vect $v(2,1)$.

$$\text{Shear}(Q, v, \tan \theta) = \begin{pmatrix} 1 + \tan \theta \cdot \frac{v_1}{v_2} & -\tan \theta \cdot \frac{v_1^2}{v_2^2} & \tan \theta \cdot \frac{v_1}{v_2} (v_2 z_2 - v_2 z_1) \\ \tan \theta & 1 - \tan \theta \cdot \frac{v_1}{v_2} & \tan \theta \cdot \frac{v_1}{v_2} (v_2 z_2 - v_2 z_1) \\ 0 & 0 & 1 \end{pmatrix}$$

$\tan 45 = 1$

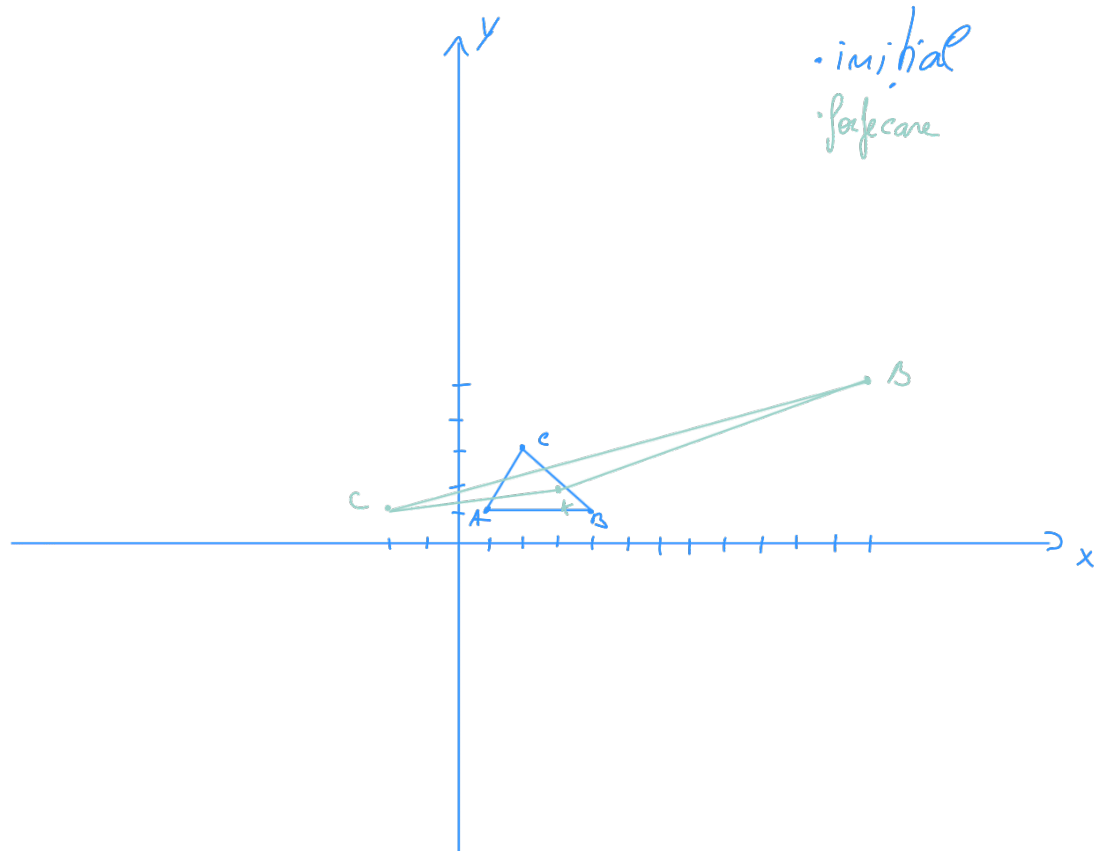
$$\text{Shear}(Q, v, \tan \theta) = \begin{pmatrix} 3 & -4 & 4 \\ 1 & -1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$[A' \ B' \ C'] = \text{Shear}(Q, v, \tan \theta) \cdot [A \ B \ C] = \text{Shear}(Q, v, \tan \theta) \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 3 & 12 & -2 \\ 2 & 5 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

\Rightarrow

$$\begin{aligned} A' & (3, 2) \\ B' & (12, 5) \\ C' & (-2, 1) \end{aligned}$$



3. Det. imag. $\triangle ABC$ prin reflexia relativ la dreapta $2x+3y-5=0$.

$$d: 2x+3y-5=0 \quad \vec{m}(2,3) \quad \Rightarrow A(1,1) \in d, \quad \vec{v}(-3,2)$$

$$\text{tg } \theta = -\frac{2}{3} \quad \Rightarrow \theta = \arctg\left(-\frac{2}{3}\right)$$

1) $\text{Trans}(-1,-1) = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \text{translatie de vector } (0, \frac{c}{5})$

2) notine cu $-\theta$

$$R(-\theta) = \begin{bmatrix} \cos(-\theta) & -\sin(-\theta) & 0 \\ \sin(-\theta) & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

3) reflexie relativ la Ox

$$R_{Ox} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

4) notine cu θ

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

5) $\text{Trans}(1,1) = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

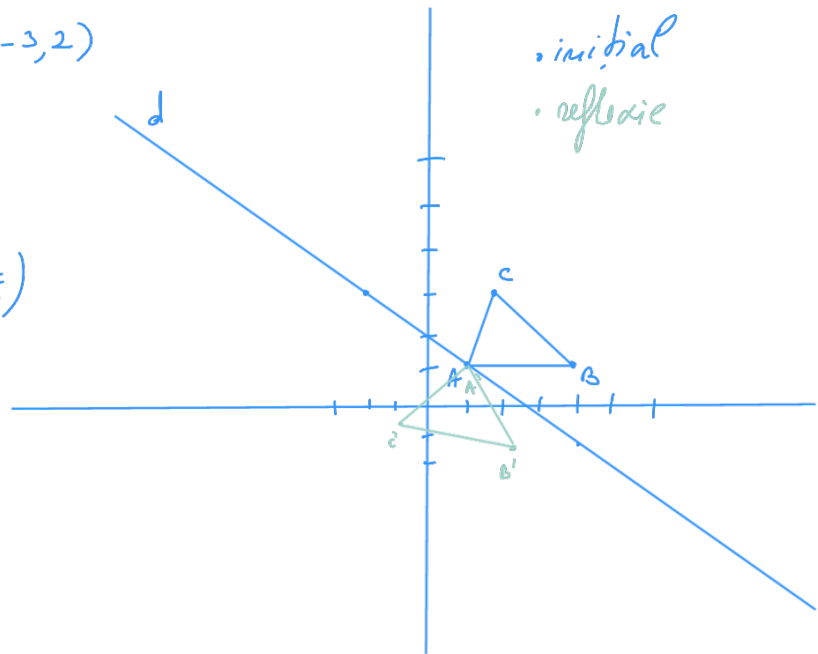
$$R_f = \text{Trans}(-1,-1) \cdot R(-\theta) \cdot R_{Ox} \cdot R(\theta) \cdot \text{Trans}(1,1) = \begin{bmatrix} \frac{5}{13} & -\frac{12}{13} & \frac{20}{13} \\ -\frac{12}{13} & -\frac{5}{13} & \frac{30}{13} \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A' \ B' \ C'] = R_f \cdot [A \ B \ C] = R_f \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & \frac{28}{13} & -\frac{6}{13} \\ 1 & -\frac{23}{13} & -\frac{9}{13} \\ 1 & 1 & 1 \end{bmatrix}$$

$\Rightarrow A'(1,1)$

$B'(\frac{28}{13}, -\frac{23}{13})$

$C'(-\frac{6}{13}, -\frac{9}{13})$



$$\cos \theta = -\frac{3}{\sqrt{3^2+2^2}} = -\frac{3}{\sqrt{13}}$$

$$\sin \theta = \frac{2}{\sqrt{13}}$$

4. Det. imag. $\triangle ABC$ prin rotația cu 90° în jurul punctului C , urmată de reflexia relativ la dreapta AB .

• notate 90°

$$\text{Rot}(90^\circ) = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{Trans}(2,3) = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Trans}(-2,-3) = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T_1 = \text{Trans}(2,3) \cdot \text{Rot}(90^\circ) \cdot \text{Trans}(-2,-3) = \begin{bmatrix} 0 & -1 & 5 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A' \ B' \ C'] = T_1 \cdot [A \ B \ C] = T_1 \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 4 & 2 \\ 2 & 5 & 3 \\ 1 & 1 & 1 \end{bmatrix} \rightarrow \begin{matrix} A'(4,2) \\ B'(4,5) \\ C'(2,3) \end{matrix}$$

• reflexie față de $AB: y=1$

$$T_{\downarrow} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T_{\uparrow} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$R_{Ox} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$T_2 = T_{\downarrow} \cdot R_{Ox} \cdot T_{\uparrow} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T = T_2 \cdot T_1 = \begin{bmatrix} 0 & -1 & 5 \\ -1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A'' \ B'' \ C''] = T \cdot [A \ B \ C] = T \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 4 & 2 \\ 0 & -3 & -1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\rightarrow \begin{matrix} A''(4,0) \\ B''(4,-3) \\ C''(2,-1) \end{matrix}$$

