

Laborator 1

• triunghi ABC cu vârfurile A(1,1), B(4,1), C(2,3).

1. Determinați imaginea ΔABC printr-o scalare simplă neuniformă, de factori de scală (2,1), relativ la punctul Q(2,2), urmată de o rotație de unghi 90° față de origine.

$$\text{Scale}(Q, 2, 1) = \text{Trans}(2, 2) \cdot \text{Scale}(2, 1) \cdot \text{Trans}(-2, -2) =$$

$$\text{Trans}(2, 2) = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Trans}(-2, -2) = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Scale}(2, 1) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow \text{Scale}(Q, 2, 1) = \begin{bmatrix} 2 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A' \ B' \ C'] = \text{Scale}(Q, 2, 1) \cdot [A \ B \ C] = \begin{bmatrix} 2 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} A' & B' & C' \\ 0 & 6 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\Rightarrow \begin{aligned} A' & (0, 1) \\ B' & (6, 1) \\ C' & (2, 3) \end{aligned}$$

- initial
- scalare
- rotație

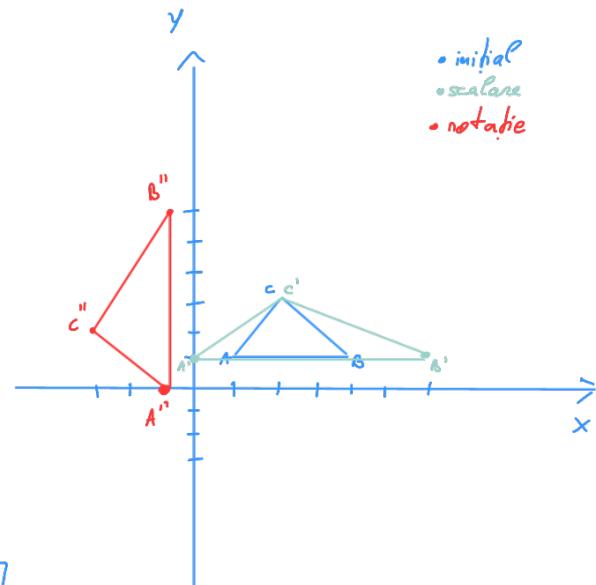
• rotație

$$T = \text{Rot}(90^\circ) \cdot S(Q, 2, 1)$$

$$\text{Rot}(90^\circ) = \begin{bmatrix} \cos 90^\circ & -\sin 90^\circ & 0 \\ \sin 90^\circ & \cos 90^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow T = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 2 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 2 & 0 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A'' \ B'' \ C''] = T \cdot [A \ B \ C] = \begin{bmatrix} 0 & -1 & 0 \\ 2 & 0 & -2 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} A'' & B'' & C'' \\ -1 & 6 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$



$$= \begin{bmatrix} A'' & B'' & C'' \\ -1 & 6 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

2. Det. imag. $\triangle ABC$ prin transformare de similitudine cu unghi 45° , relativ la pct. $Q(2,2)$ în direcția vect $v(2,1)$

$$\text{Shean}(Q, v, \operatorname{tg} \theta) = \begin{pmatrix} 1 + \operatorname{tg} \theta \cdot v_1 \cdot v_2 & -\operatorname{tg} \theta \cdot v_1^2 & \operatorname{tg} \theta \cdot v_1 (v_1 \cdot 2_2 - v_2 \cdot 2_1) \\ \operatorname{tg} \theta \cdot v_2^2 & 1 - \operatorname{tg} \theta \cdot v_1 \cdot v_2 & \operatorname{tg} \theta \cdot v_2 (v_1 \cdot 2_2 - v_2 \cdot 2_1) \\ 0 & 0 & 1 \end{pmatrix}$$

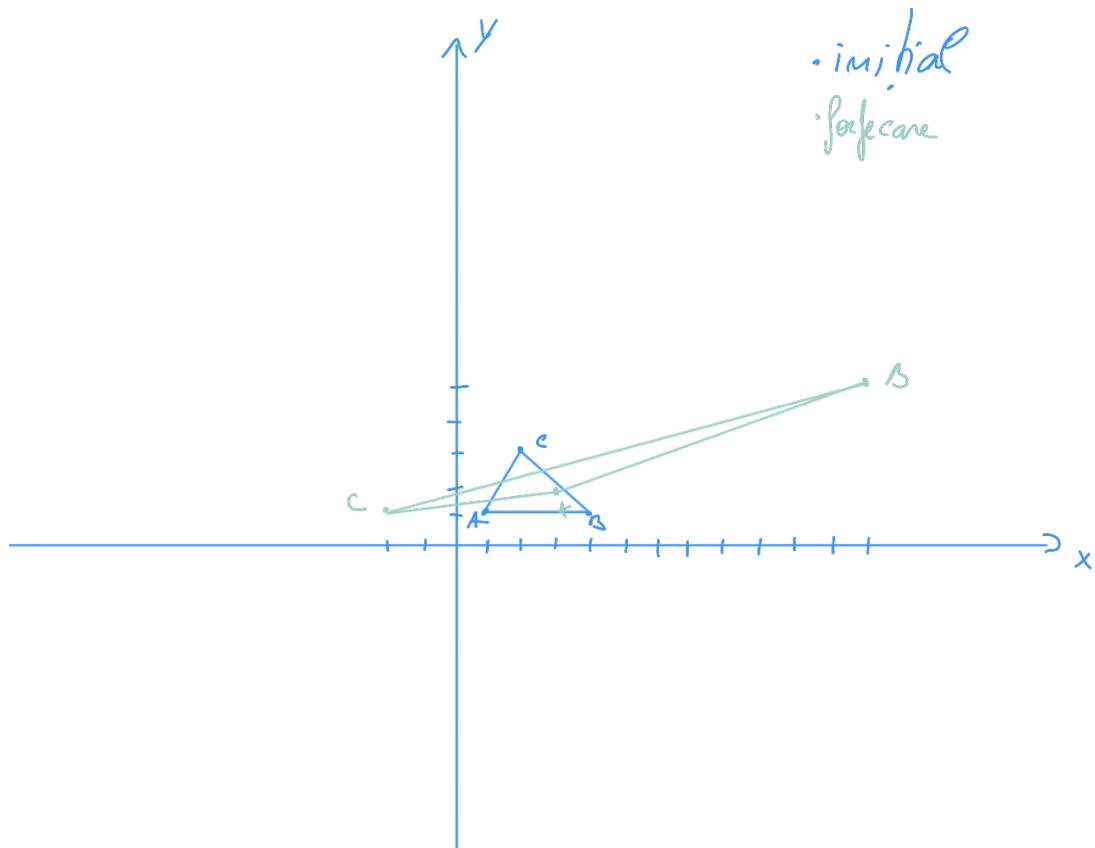
$\operatorname{tg} 45^\circ = 1$

$$\text{Shean}(Q, v, \operatorname{tg} \theta) = \begin{pmatrix} 3 & -4 & 4 \\ 1 & -1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{bmatrix} A' & B' & C' \end{bmatrix} = \text{Shean}(Q, v, \operatorname{tg} \theta) \cdot \begin{bmatrix} A & B & C \end{bmatrix} = \text{Shean}(Q, v, \operatorname{tg} \theta) \cdot \begin{bmatrix} 1 & 9 & 2 \\ 1 & 1 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 3 & 12 & -2 \\ 2 & 5 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\Rightarrow \begin{aligned} A' & (3, 2) \\ B' & (12, 5) \\ C' & (-2, 1) \end{aligned}$$



3. Det. imag. $\triangle ABC$ prin reflexia relativ la dreapta $2x+3y-5=0$.

$$d: 2x+3y-5=0 \quad | \Rightarrow A(1,1) \in d, \vec{v}(-3,2)$$

$$\tan \theta = -\frac{2}{3} \Rightarrow \theta = \arctg\left(-\frac{2}{3}\right)$$

$$1) \text{Trans}(-1,-1) = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \text{translate de vector } (0, \frac{c}{5})$$

2) rotire cu $-\theta$

$$R(-\theta) = \begin{bmatrix} \cos(-\theta) & -\sin(-\theta) & 0 \\ \sin(-\theta) & \cos(-\theta) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

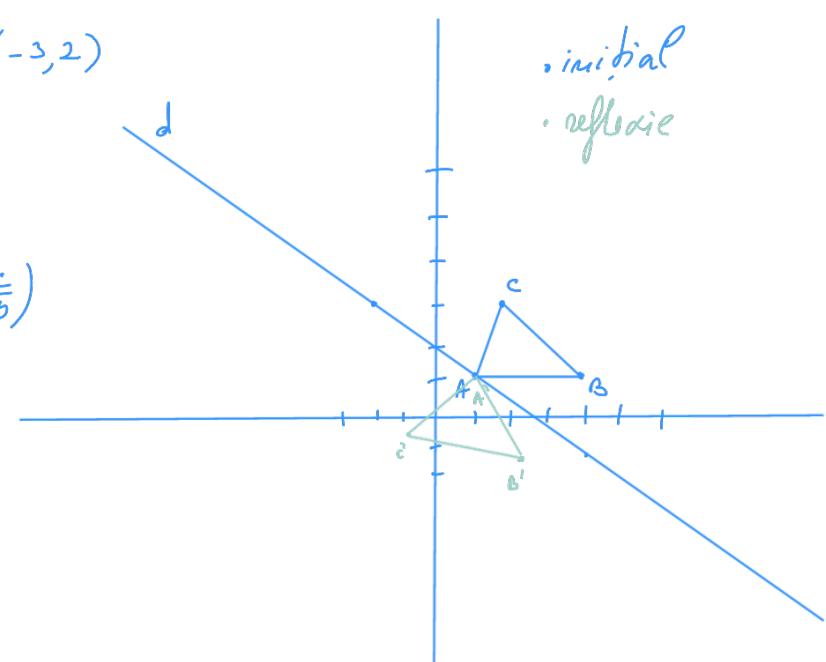
3) reflexie relativ la Ox

$$R_{Ox} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$4) \text{rotire cu } \theta$$

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$5) \text{Trans}(1,1) = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$



$$\cos \theta = -\frac{3}{\sqrt{3^2+2^2}} = -\frac{3}{\sqrt{13}}$$

$$\sin \theta = \frac{2}{\sqrt{13}}$$

$$R_f = \text{Trans}(-1,-1) \cdot R(-\theta) \cdot R_{Ox} \cdot R(\theta) \cdot \text{Trans}(1,1) = \begin{bmatrix} \frac{5}{13} & -\frac{12}{13} & \frac{20}{13} \\ -\frac{12}{13} & -\frac{5}{13} & \frac{30}{13} \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A' \ B' \ C'] = R_f \cdot [A \ B \ C] = R_f \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & \frac{28}{13} & \frac{20}{13} \\ 1 & -\frac{23}{13} & -\frac{5}{13} \\ 1 & -\frac{9}{13} & 1 \end{bmatrix}$$

$$A'(1,1)$$

$$B'\left(\frac{28}{13}, -\frac{23}{13}\right)$$

$$C'\left(-\frac{6}{13}, -\frac{9}{13}\right)$$

4. Det. imag. $\triangle ABC$ prin rotatia cu 90° în jurul punctului C , urmata de reflexia relativ la dreapta AB .

• notatie 90°

$$\text{Rot}(90^\circ) = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Trans}(2,3) = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Trans}(-2,-3) = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T_1 = \text{Trans}(2,3) \cdot \text{Rot}(90) \cdot \text{Trans}(-2,-3) = \begin{bmatrix} 0 & -1 & 5 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A' \ B' \ C'] = T_1 \cdot [A \ B \ C] = T_1 \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 5 & 2 \\ 2 & 5 & 3 \\ 1 & 1 & 1 \end{bmatrix} \Rightarrow \begin{array}{l} A'(4,2) \\ B'(4,5) \\ C'(2,3) \end{array}$$

• reflexie fata de $AB : y=1$

$$T_{\downarrow} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$T_{\uparrow} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_{Ox} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$T_2 = T_{\downarrow} \cdot R_{Ox} \cdot T_{\uparrow} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$T = T_2 \cdot T_1 = \begin{bmatrix} 0 & -1 & 5 \\ -1 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A'' \ B'' \ C''] = T \cdot [A \ B \ C] = T \cdot \begin{bmatrix} 1 & 4 & 2 \\ 1 & 1 & 3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 5 & 2 \\ 0 & -3 & -1 \\ 1 & 1 & 1 \end{bmatrix} \Rightarrow \begin{array}{l} A''(4,0) \\ B''(4,-3) \\ C''(2,-1) \end{array}$$

$$\begin{aligned} &= A''(4,0) \\ &B''(4,-3) \\ &C''(2,-1) \end{aligned}$$

