

State:	$\sigma(t) = (\psi, \rho, \omega, \chi, \tau)^\top \in \mathbb{R}^5$
Potential:	$V(\sigma) = \frac{1}{2}\ \sigma\ ^2 + \eta H(\sigma) - \lambda F(\sigma, \sigma^*)$
Entropy:	$H(\sigma) = -\sum_{i=1}^5 p_i \ln p_i, \quad p_i = \frac{ \sigma_i }{\sum_j \sigma_j }$
Coherence:	$F(\sigma, \sigma^*) = \sum_{i=1}^5 \sigma_i \sigma_i^*$
Dynamics:	$\dot{\sigma} = -\nabla_\sigma V(\sigma) + R(\sigma, t) + \sum_i O_i(\sigma, t)$
Operators:	$\begin{cases} O_{\text{DK}} = \mathcal{R}_{\psi\rho}(\frac{\pi}{2}) \mathcal{R}_{\omega\chi}(\frac{\pi}{2}) \\ O_{\text{SW}} = (1 + \beta(m_c - m)) \mathbb{I}_5 \\ O_{\text{PI}} = (1 - \kappa) \mathbb{I}_5 \\ O_{\text{WT}} = (\mathbb{I}_5 + k \hat{e}_\tau \otimes \hat{e}_\tau) + k f(t) \hat{e}_\tau \end{cases}$
Resonance:	$m = \frac{F(\sigma, \sigma^*)}{\ \sigma\ \ \sigma^*\ }, \quad m \geq m_c \Rightarrow \ddot{\sigma} = -\nabla_\sigma V$
Energy:	$E(t) = \frac{1}{2}\ \dot{\sigma}\ ^2 + V(\sigma), \quad \frac{dE}{dt} = -\ \nabla_\sigma V\ ^2 + \dot{\sigma} \cdot R$
Stability:	$\mathbb{T}_{ij} = \frac{\partial^2 V}{\partial \sigma_i \partial \sigma_j}, \quad \lambda_i = \text{eig}(\mathbb{T}),$ $0 < \lambda_i < 1 \Rightarrow \text{stable}, \det \mathbb{T} = 0 \Rightarrow \text{singularity}$
Projection (visual):	$\mathbf{x} = \mathbf{P}\sigma, \quad \mathbf{P} = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 & 0 \\ 1 & 0 & -1 & 0 & 1 \end{pmatrix}$
Color Encoding:	$(H, S, V, \alpha) = (\frac{1}{2}(1 + \Phi_E), m, 1 - e^{-V}, \Phi_E), \quad \Phi_E = \frac{E_K - E_P}{E_K + E_P}$
Integration:	$\sigma_{t+1} = \sigma_t - \frac{dt}{2} [\nabla_\sigma V(\sigma_t) + \nabla_\sigma V(\sigma_t - dt \nabla_\sigma V)] + dt(R + \sum_i O_i)$
Summary:	$\begin{cases} \text{TIC: } \nabla_\sigma V = 0 \\ \text{Singularity: } \det \mathbb{T} = 0 \\ \text{Energy: } E = \frac{1}{2}\ \dot{\sigma}\ ^2 + V \\ \text{Projection: } \mathbf{x} = \mathbf{P}\sigma \end{cases}$

$\eta = 0.05, \lambda = 0.9, \beta = 0.1, \kappa = 0.15, m_c = 0.65$. All derivatives, transformations and mappings are defined within this sheet.