## FYS-STK3155 Project 1

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#### Abstract

We have studied three different regression methods, ordinary least squares, ridge, and lasso, and what affects their learned prediction accuracy. We found  $\dots$ . We have done a bias-variance analysis on OLS using a bootstrap resampling technique and found that  $\dots$ . We then study the cross-validation resampling method and analyze all three regression methods  $\dots$ . Finally we applied our models to real world topographic data and we saw that  $\dots$ .

#### I. INTRODUCTION

In today's modern world machine learning has emerged as a revolutionary technology. Even if just superficially, machine learning has become well known around the world. By allowing computers to learn from supplied data we create powerful tools with incredible real world applications for analyzation and prediction.

In this project we will explore and study low-level machine learning methods. Our focus will be on understanding and optimizing the potential of data regression methods such as ordinary least squares (OLS), ridge regression, and lasso regression. We will look into the factors that influence their accuracy and predictive capabilities, employing a variety of strategies to minimize errors and improve performance. Finally, we will apply our finelytuned algorithms to analyze real-world topographic data.

#### II. THEORY

## A. Design matrix for linear regression

We create a so-called design matrix  $\mathbf{X}$  for the regression methods from two input variables  $\mathbf{x}$  and  $\mathbf{y}$ . This matrix is used to create our linear regression models. Each row in  $\mathbf{X}$  represents polynomial variables from one data sample. We choose a max polynomial degree p with n data samples such that  $\mathbf{X} \in \mathbb{R}^{n \times l}$  where

$$l = floor[\frac{1}{2}(p+1)(p+2)],$$

where the *floor*-function rounds down, and the design matrix is then given by (Hjorth-Jensen, 2023)

$$\mathbf{X} = \begin{bmatrix} 1 & x_0 & y_0 & x_0^2 & x_0y_0 & y_0^2 & \dots & x_0^{p-1} & \dots & y_0^{p-1} \\ 1 & x_1 & y_1 & x_1^2 & x_1y_1 & y_1^2 & \dots & x_1^{p-1} & \dots & y_1^{p-1} \\ \vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 1 & x_{n-1} & y_{n-1} & \dots & \dots & \dots & x_{n-1}^{p-1} & \dots & y_{n-1}^{p-1} \end{bmatrix}$$

We then make our linear regression predictions by creating the polynomials from  $\mathbf{X}$  and the polynomial coefficients  $\boldsymbol{\beta} \in \mathbb{R}^l$  as follows (Hjorth-Jensen, 2023)

$$\tilde{\mathbf{z}} = \mathbf{X}\boldsymbol{\beta} \tag{2}$$

#### B. Regression methods

The different methods have different ways of calculating the optimal  $\beta$ -coefficients which we call  $\hat{\beta}$ . The following expressions are derived in the course lecture notes (Hjorth-Jensen, 2023) unless otherwise noted.

## B1. Ordinary least squares

$$\hat{\boldsymbol{\beta}}_{OLS} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{z} \tag{3}$$

B2. Ridge

$$\hat{\boldsymbol{\beta}}_{Ridge} = \left(\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I}\right)^{-1} \mathbf{X}^T \mathbf{z} \tag{4}$$

where **I** is the identity matrix, and  $\lambda$  is a non-negative regularization parameter.

#### B3. Lasso

For lasso regression we do not have an analytical expression, but we will use the functionalities of the machine learning python module SciKit-Learn.

# C. Measuring error and coefficient of determination

To calculate our regression models' prediction error from the actual data we will be using the mean square error (MSE) defined by

$$MSE(\mathbf{z}, \tilde{\mathbf{z}}_i) = \frac{1}{n} \sum_{i=0}^{n-1} (z_i - \tilde{z}_i)^2, \tag{5}$$

The coefficient of determination, denoted  $R^2$ , is a measure that tells us how well our models can predict new data and is defined as

$$R^{2}(\mathbf{z}, \tilde{\mathbf{z}}_{i}) = 1 - \frac{\sum_{i=0}^{n-1} (z_{i} - \tilde{z}_{i})^{2}}{\sum_{i=0}^{n-1} (z_{i} - \bar{z})^{2}}$$
(6)

where  $\bar{z}$  is the mean value of  $\mathbf{z}$ , and a value of  $R^2 = 1$  will represent the best possible model determination from our regression method.

#### D. Resampling

Resampling in statistics is data-testing method's which involves re-electing/fitting your data in different ways to create multiple simulation samples of a model, to obtain future predictions. While repeatedly splitting your data into test- and training sections, you take samples from the test- and training sets, and refit them to each new sample. This may allow us to get a better representation of the data error, bias and variance since an average value from all samples will be used, instead of just one sample when calculating. Two famous resampling techniques are bootstrap and cross-validation. (Hjorth-Jensen, 2023)

#### E. Bootstrap

Bootstrapping is a technique where we do a resampling of a dataset, and repeat it for a chosen number of times (bootstraps) from each of the created multiple random samples. (Hjorth-Jensen, 2023)

#### F. Cross-validation

Cross-validation is a resampling technique where a dataset get separated into subsets (folds). One fold are used for testing, and the rest for training. The process is repeated for the amount of folds chosen. If five folds is used, four will first be used as training and one for testing, and thereafter all will be repeated for a different selction of train- and test folds. One common method is k-fold cross-validation, where the subsets are k equally sized folds containing your data.(Hjorth-Jensen, 2023)

#### G. Bias and variance

Expressing (5) as the expectation value

$$MSE = \mathbb{E}[(\mathbf{z} - \tilde{\mathbf{z}})^2]$$

we can rewrite this as

$$MSE = \operatorname{Bias}[\tilde{\mathbf{z}}] + \operatorname{var}[\tilde{\mathbf{z}}] + \sigma^2 \tag{7}$$

where

$$\operatorname{Bias}\left[\tilde{\mathbf{z}}\right] = \mathbb{E}\left[\left(\mathbf{z} - \mathbb{E}\left[\tilde{\mathbf{z}}\right]\right)^{2}\right] \tag{8}$$

and

$$\operatorname{var}\left[\tilde{\mathbf{z}}\right] = \mathbb{E}\left[\left(\tilde{\mathbf{z}} - \mathbb{E}\left[\tilde{\mathbf{z}}\right]\right)^{2}\right] = \frac{1}{n} \sum_{i} (\tilde{z}_{i} - \mathbb{E}\left[\tilde{\mathbf{z}}\right])^{2} \quad (9)$$

Here  $\sigma$  is the standard deviation of our stochastic noise  $\epsilon$ . The derivations of (7) can be found in the appendix section C.

We can use these definitions of bias and variance to preform a bias-variance-tradeoff, where we compare these values to the MSE of a given regression with respect to polynomial degree. For this we will be introducing bootstrap resampling to do a bias-variance trade-off analysis of the OLS regression. Our goal is to recreate figure 1 which shows an example of idealized overfitting with clear regions of low vs high bias and variance.

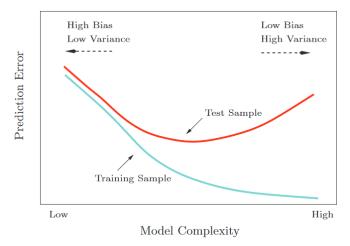


Figure 1: Figure 2.11 from Hastie et al. (2009). This idealized graph shows the bias-variance trade-off for our models, and shows the concept of overfitting model to the training data. This happens when we use too high complexity for the model leading to higher errors and worse prediction capabilities.

#### H. The Franke function

To study our regression methods we will be using the Franke function, which is a two dimensional weighted sum of four exponentials given as

$$f(x,y) = \frac{3}{4} \exp\left[-\frac{(9x-2)^2}{4} - \frac{(9y-2)^2}{4}\right]$$

$$+ \frac{3}{4} \exp\left[-\frac{(9x+1)^2}{49} - \frac{(9y+1)^2}{10}\right]$$

$$+ \frac{1}{2} \exp\left[-\frac{(9x-7)^2}{4} - \frac{(9y-3)^2}{4}\right]$$

$$- \frac{1}{5} \exp\left[-(9x-4)^2 - (9y-7)^2\right]$$
 (10)

## III. METHODS

Our first step is to study how the MSE and  $R^2$  changes as the model complexity changes using our three regression methods. For this we will vary the complexity by changing the maximum polynomial degree p in our design matrix  $\mathbf{X}$ , where we will go up to p=6.

We will be using the Franke function (10) with  $x_i, y_i \in [0,1]$  while simulating a stochastic noise from a normal distribution  $\epsilon \sim \mathcal{N}(0,1)$ . We will split our data into a training set and a testing set using Scikit-Learn's model\_selection.train\_test\_split function.

Firstly we will do the OLS regression, writing our own code from (3), then we will do a ridge regression from (4) with varying  $\lambda$ -parameter, to find the error in each case. Thirdly we will use Scikit-Learn's implementation of Lasso regression to do the same analysis; analysing model-prediction with respect to varying polynomial

degrees.

Next up we will be introducing bootstrap resampling where we use Scikit-Learn's utils.resample method, for 1000 bootstraps. Thereafter we do our bias-variance trade-off analysis of the OLS regression, and recreate the theoretical low vs high bias and variance. From this we will find how the mean square error changes with respect to polynomial degree.

Now we create a code for the cross-validation resampling method, where we use Scikit-Learn's model\_selection.KFold method. Here we will study the MSE of all three regression methods using cross-validation with different fold parameters  $k \in [5, 10]$ , and thereafter compare the error with the result found using the bootstrap method.

The final thing we will preform is using the three regression methods discussed, on a real data set over Oslo, Norway. This way we will try to make predictions.

#### IV. RESULTS

Firstly we find the following results from the OLS-regression shown in figure 2.

Then we find the related results from the Ridgeregression shown in figure 3.

For the Lasso regression we find the following shown in figure 4.

We then do the bias-variance-tradeoff, and get the results in figure  $\dots$ 

Thereafter we do the cross-validation, which end up producing the error in figure ... Here we have done the resampling over  $k \in [5, 10]$ , but only included k = 5, 10 because we see a steady progression of the graphs.

We now find the data for the real-data problem...

## V. DISCUSSION

#### VI. CONCLUSION

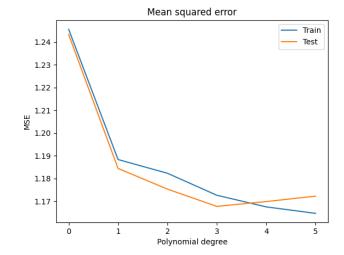
## Appendix A. Github repository

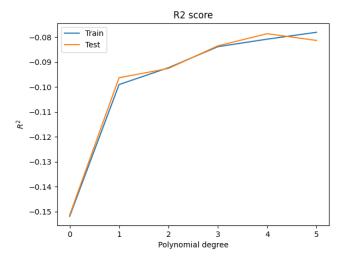
https://github.com/LassePladsen/FYS-STK3155-projects/tree/main/project1

#### Appendix B. List of source code

Here is a list of the code we have developed in this project which can be found in the above Github repository:

• ...





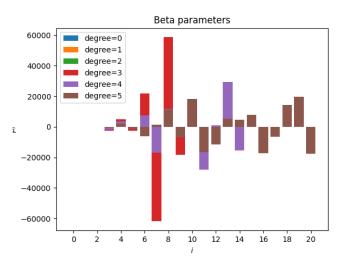
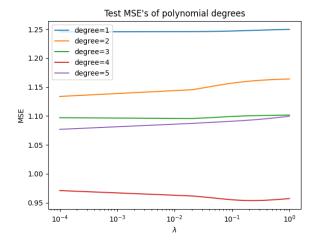


Figure 2: Caption.

• ...

• ...



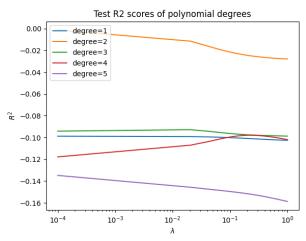


Figure 3: Caption.

## Appendix C. Analytical derivations

Subsection 1 is for part e of the project, and all the other subsections are for part d.

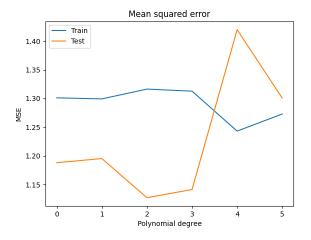
## C1. Bias-variance: equation (7)

This is the derivation of equation (7) for part e of the project. First we write the MSE (5) as the following expectation value

$$MSE = \mathbb{E}[(z - \tilde{z})^2]$$

the we multiply the paranthesis and split the expression to three expectation values. For the rest of these derivations in this project we will write vectors and matrices without boldface for ease of writing  $\mathbf{z}=z, \mathbf{X}=X$  etc. We write

$$\begin{split} MSE &= \mathbb{E} \left[ z^2 - 2z\tilde{z} + \tilde{z} \right] \\ &= \mathbb{E}[z^2] - 2\mathbb{E}[z\tilde{z}] + \mathbb{E}[\tilde{z}^2] \\ &= \mathbb{E}[z^2] - 2\mathbb{E}[z\tilde{z}] + \mathbb{E}[\tilde{z}^2] \end{split}$$



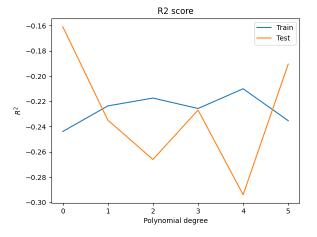


Figure 4: Caption.

We will split this up and take on these three terms one by one, firstly we write  $z=f+\epsilon$  which represents our data with noise. For the first term:

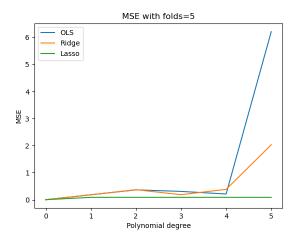
$$\begin{split} \mathbb{E}[z^2] &= \mathbb{E}[(f+\epsilon)^2] \\ &= \mathbb{E}[f^2 + 2f\epsilon + \epsilon^2] \\ &= \mathbb{E}[f^2] + \mathbb{E}[2f\epsilon] + \mathbb{E}[\epsilon^2] \end{split}$$

here we use that  $\mathbb{E}[\epsilon]=0,\mathbb{E}[\epsilon^2]=\sigma^2$  since  $\epsilon\sim\mathcal{N}(0,\sigma^2).$ 

$$\begin{split} &= \mathbb{E}[f^2] + 2f\mathbb{E}[\epsilon] + \sigma^2 \\ &= \underline{\mathbb{E}[f^2] + \sigma^2} \end{split}$$

Now for the second term:

$$\begin{split} \mathbb{E}[z\tilde{z}] &= \mathbb{E}[(f+\epsilon)\tilde{z}] \\ &= \mathbb{E}[f\tilde{z}+\epsilon\tilde{z}] \\ &= \mathbb{E}[f\tilde{z}] + \mathbb{E}[\epsilon\tilde{z}] \\ &= \mathbb{E}[f\tilde{z}] + \mathbb{E}[\epsilon]\mathbb{E}[\tilde{z}] \\ &= \mathbb{E}[f\tilde{z}] \end{split}$$



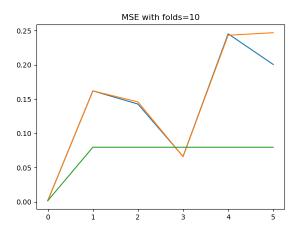


Figure 5: Caption.

Now for the third and final term:

$$\mathbb{E}[\tilde{z}^2] = var[\tilde{z}] + (\mathbb{E}[\tilde{z}])^2$$

where we have used the definition of variance  $var(x) = \mathbb{E}[x^2] - (\mathbb{E}[x])^2$ .

We now put these three terms into our expression for MSE:

$$\begin{split} MSE &= \mathbb{E}\left[(z-\tilde{z})^2\right] \\ &= \mathbb{E}[z^2] - 2\mathbb{E}[z\tilde{z}] + \mathbb{E}[\tilde{z}^2] \\ &= \mathbb{E}[f^2] + \sigma^2 - 2\mathbb{E}[f\tilde{z}] + var[\tilde{z}] + (\mathbb{E}[\tilde{z}])^2 \\ &= \mathbb{E}[f^2] - 2f\mathbb{E}[\tilde{z}] + (\mathbb{E}[\tilde{z}])^2 + \sigma^2 + var[\tilde{z}] \\ &= \mathbb{E}\left[(f - \mathbb{E}[\tilde{z}])^2\right] + var[\tilde{z}] + \sigma^2 \\ &\simeq \mathbb{E}\left[(z - \mathbb{E}[\tilde{z}])^2\right] + var[\tilde{z}] + \sigma^2 \\ &= Bias[\tilde{z}] + var[\tilde{z}] + \sigma^2 \end{split}$$

here we approximated  $f \simeq z$  and used the expressions for Bias (8) and variance (9).

#### C2. Expectation value of y

We will show that  $\mathbb{E}(y_i) = X_{i,*}\beta$  by using  $y = f + \epsilon \simeq X\beta + \epsilon$  and separating the expectation value of a sum. Here we approximated f with  $X\beta$  using OLS. Then taking a value of y with index i we get  $y_i = \sum_j X_{ij}\beta_j + \epsilon_i$ :

$$\mathbb{E}(y_i) = \mathbb{E}(\Sigma_j X_{ij} \beta_j + \epsilon_i)$$

$$= \mathbb{E}(\Sigma_j X_{ij} \beta_j) + \mathbb{E}(\epsilon_i)$$

$$= \mathbb{E}(\Sigma_j X_{ij} \beta_j)$$

$$= \Sigma_j X_{ij} \beta_j$$

$$= X_{i,*} \beta$$

## C3. Variance of y

Using the same method as above we will now show  $Var(y_i) = \sigma^2$  where  $\sigma^2$  is the variance of our data's stochastic noise  $\epsilon$ . Here we use the definition of variance being  $Var(x) = \mathbb{E}(x^2) - \mathbb{E}(x)^2$ :

$$Var(y_{i}) = \mathbb{E}(y_{i}^{2}) - \mathbb{E}(y_{i})^{2}$$

$$= \mathbb{E}[(X_{i,*}\beta + \epsilon_{i})^{2}] - (X_{i,*}\beta)^{2}$$

$$= \mathbb{E}[(X_{i,*}\beta^{2} + \epsilon_{i}^{2} + 2X_{i,*}\beta\epsilon_{i}] - (X_{i,*}\beta)^{2}$$

$$= \mathbb{E}[(X_{i,*}\beta)^{2}] + \mathbb{E}[\epsilon_{i}^{2}] + \mathbb{E}[2X_{i,*}\beta\epsilon_{i}] - (X_{i,*}\beta)^{2}$$

$$= (X_{i,*}\beta)^{2} + \mathbb{E}[\epsilon_{i}^{2}] + 2X_{i,*}\beta\mathbb{E}[\epsilon_{i}] - (X_{i,*}\beta)^{2}$$

$$= \mathbb{E}[\epsilon_{i}^{2}]$$

$$= Var(\epsilon_{i}) + \mathbb{E}(\epsilon)^{2}$$

$$= Var(\epsilon_{i})$$

$$= \sigma^{2}$$

## C4. Expectation value of $\beta_{OLS}$

Here we will show that the expectation value for the optimal  $\beta$  for OLS,  $\hat{\beta}_{OLS}$ , equals  $\beta_{OLS}$ :

$$\mathbb{E}(\hat{\beta}_{OLS}) = \mathbb{E}[(X^T X)^{-1} X^T y]$$

$$= (X^T X)^{-1} X^T \mathbb{E}[y]$$

$$= (X^T X)^{-1} X^T X \beta_{OLS}$$

$$= \beta_{OLS}$$

Here we used that the expectation value of the non-stochastic matrix is just the matrix itself ( $\mathbb{E}(X) = X$ ) since it has zero variance (non-stochastic).

## C5. Variance of $\beta_{OLS}$

Here we will show  $Var(\hat{\beta}_{OLS}) = \sigma^2(X^TX)^{-1}$ :

$$Var(\hat{\beta}_{OLS}) = \mathbb{E}[(\hat{\beta}_{OLS})^2] - \mathbb{E}[\hat{\beta}_{OLS}]^2$$

$$= \mathbb{E}[(X^T X)^{-1} X^T y)^2] - \beta^2$$

$$= \mathbb{E}[(X^T X)^{-1} X^T y) (X^T X)^{-1} X^T y)^T] - \beta^T \beta$$

$$= \mathbb{E}[(X^T X)^{-1} X^T y y^T X (X^T X)^{-1}] - \beta^T \beta$$

$$= (X^T X)^{-1} X^T \mathbb{E}[y y^T] X (X^T X)^{-1} - \beta^T \beta$$

Here we will calculate  $\mathbb{E}[yy^T]$  separately for ease:

$$\mathbb{E}[yy^T] = \mathbb{E}[(X\beta + \epsilon)(X\beta + \epsilon)^T]$$

$$= \mathbb{E}[(X\beta\beta^TX^T + \epsilon\epsilon^T + X\beta\epsilon^T + \epsilon\beta^TX^T]$$

$$= X\beta\beta^TX^T + \mathbb{E}[\epsilon\epsilon^T] + X\beta\mathbb{E}[\epsilon^T] + \mathbb{E}[\epsilon]\beta^TX^T$$

$$= X\beta\beta^TX^T + \mathbb{E}[\epsilon\epsilon^T]$$

$$= X\beta\beta^TX^T + \sigma^2I$$

Now we put this back into the Variance expression:

$$Var(\hat{\beta}_{OLS}) = (X^T X)^{-1} X^T (X \beta \beta^T X^T + \sigma^2 I) X (X^T X)^{-1} - \beta^T \beta$$

$$= [\beta \beta^T X^T + (X^T X)^{-1} X^T \sigma^2] X (X^T X)^{-1} - \beta^T \beta$$

$$= [\beta \beta^T + \sigma^2 (X^T X)^{-1}] - \beta^T \beta$$

$$= \sigma^2 (X^T X)^{-1}$$

#### References

Hastie, T., Tibshirani, R., & Friedman, J. (2009). The elements of statistical learning: Data mining, inference and prediction. Springer Verlag, Berlin. Retrieved from https://github.com/CompPhysics/MLErasmus/blob/master/doc/Textbooks/elementsstat.pdf

Hjorth-Jensen, M. (2023). Applied data analysis and machine learning. https://compphysics.github.io/MachineLearning/doc/LectureNotes/\_build/html/intro.html. ([Online; accessed 30-September-2023])