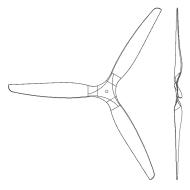


## **Product sheet**

Rev.: 00 2024-05-28





18 g Mass



8.7 kgf Max Thrust



12.0" Diameter



Multicopter

Engine type: Electric Folding/Fixed Fixed

Rotational direction: Counter-clockwise and Clockwise

available

Weight [g]:  $18\,\pm\,10.0\%$ 

Moment of inertia [kgm<sup>2</sup>]: 1.39e-04

Center hole [mm]:

Max drilling diameter [mm]:

Mounting: link to possible patterns

Limit RPM (0.7 Mach at blade tip) 15000

> Working temperature [°C] from -45°C to 65°C

> > Materials used: carbon fiber, glass fiber, roving,

polyurethane, epoxy

Tests performed: balancing, visual Inspection, structural

integrity (ATO)

Formula used to calculate moment of

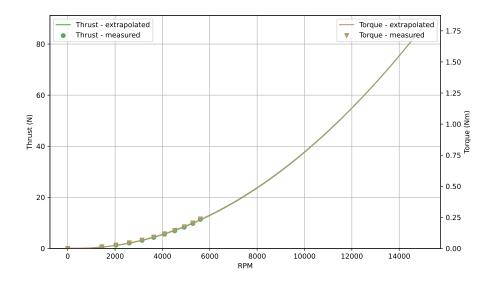
inertia:

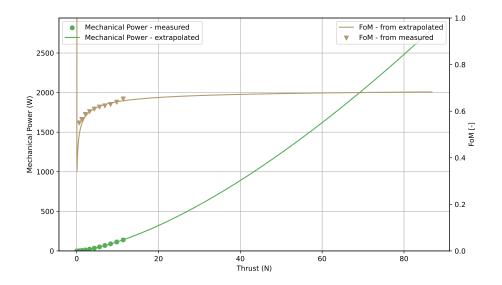
 $I = \frac{1}{12} \cdot mass \cdot diameter^2$ 



## **Measured data**

Static test result





$$\begin{array}{ll} \text{Thrust (RPM)} &= 4.05666e - 07 \cdot RPM^2 + -0.000303889 \cdot RPM + 0.10176 \\ \text{Torque (RPM)} &= 8.26266e - 09 \cdot RPM^2 + -5.13881e - 06 \cdot RPM + 0.00195 \\ \text{Mechanical power (RPM)} &= 1.02474e - 09 \cdot RPM^3 + -1.78525e - 06 \cdot RPM^2 + 0.00247 \cdot RPM + -0.20868 \\ \end{array}$$

Formulas used to calculate FOM:

$$C_T = \frac{T}{\rho \cdot RPS^2 \cdot D^4}$$

$$C_P = \frac{P_{mech}}{\rho \cdot RPS^3 \cdot D^5}$$

$$C_T = \frac{T}{\rho \cdot RPS^2 \cdot D^4} \qquad \qquad C_P = \frac{P_{mech}}{\rho \cdot RPS^3 \cdot D^5} \qquad FOM = \sqrt{\frac{2}{\pi}} \frac{C_T^{\frac{3}{2}}}{C_P}$$