

---

PROBLEM #1.

Calc H.

$$f(x,y) = x^3y + x + 2y \quad J = [3x^2y + 1, x^3 + 2]$$

$$H = \begin{bmatrix} \partial_{x_1}x_1f & \partial_{x_1}x_2f \\ \partial_{x_2}x_1f & \partial_{x_2}x_2f \end{bmatrix} \quad H = \begin{bmatrix} 6xy & 3x^2 \\ 3x^2 & 0 \end{bmatrix}$$

---

PROBLEM #2.

(calc. H.)

$$f(x,y) = e^x \cos(y)$$

$$H = \begin{bmatrix} \partial_{x_1}x_1f & \partial_{x_1}x_2f \\ \partial_{x_2}x_1f & \partial_{x_2}x_2f \end{bmatrix}$$

$$J = [e^x \cos(y), -\sin(y)e^x]$$

$$H = \begin{bmatrix} e^x \cos(y) & -\sin(y)e^x \\ -e^x \sin(y) & -\cos(y)e^x \end{bmatrix}$$

---

PROBLEM #3.(calc. H. calc  $\frac{1}{2}[x,y]H\begin{bmatrix} x \\ y \end{bmatrix}$ ).

$$f(x,y) = \frac{x^2}{2} + xy + \frac{y^2}{2} \quad J = [x+y, x+y]$$

$$H = \begin{bmatrix} \partial_{x_1}x_1f & \partial_{x_1}x_2f \\ \partial_{x_2}x_1f & \partial_{x_2}x_2f \end{bmatrix}$$

$$H = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\frac{1}{2}[x, y] \begin{bmatrix} x+y \\ x+y \end{bmatrix} = \frac{x(x+y)}{2} + \frac{y(x+y)}{2}$$

$$= \frac{x^2 + xy + y^2 + xy}{2}$$

$$= \frac{x^2}{2} + xy + \frac{y^2}{2}$$

(\*) 2nd order derivative equals  $f(x)$ . Similar to  $e^x$ ...

---

PROBLEM #4.

Calc. H.

$$f(x, y, z) = x^2 e^{-y} \cos z$$

$$\mathcal{J} = [2x e^{-y} \cos z, -e^{-y} x^2 \cos z, -\sin z x^2 e^{-y}]$$

$$H = \begin{bmatrix} \partial_{x_1} x_1 f & \partial_{x_1} x_2 f & \partial_{x_1} x_3 f \\ \partial_{x_2} x_1 f & \partial_{x_2} x_2 f & \partial_{x_2} x_3 f \\ \partial_{x_3} x_1 f & \partial_{x_3} x_2 f & \partial_{x_3} x_3 f \end{bmatrix}$$

$$H = \begin{bmatrix} 2e^{-y} \cos z & -e^{-y} 2x \cos z & -\sin z 2x e^{-y} \\ -2x e^{-y} \cos z & e^{-y} x^2 \cos z & \sin z x^2 e^{-y} \\ -2x \sin z e^{-y} & e^{-y} x^2 \sin z & -\cos z x^2 e^{-y} \end{bmatrix}$$

---

PROBLEM #5.

Calc. H.

$$f(x, y, z) = xe^y + y^2 \cos(z)$$

$$\mathcal{J} = [e^y, e^y x + 2y \cos z, -\sin z y^2]$$

$$H = \begin{bmatrix} \partial_{x_1} x_1 f & \partial_{x_1} x_2 f & \partial_{x_1} x_3 f \\ \partial_{x_2} x_1 f & \partial_{x_2} x_2 f & \partial_{x_2} x_3 f \\ \partial_{x_3} x_1 f & \partial_{x_3} x_2 f & \partial_{x_3} x_3 f \end{bmatrix}$$

$$H = \begin{bmatrix} 0 & e^y & 0 \\ e^y & e^y x + 2y \cos z & 2y(-\sin z) \\ 0 & -2y \sin z & -\cos z y^2 \end{bmatrix}$$