EN2550 Assignment 1 on Intensity Transformations and Neighborhood Filtering

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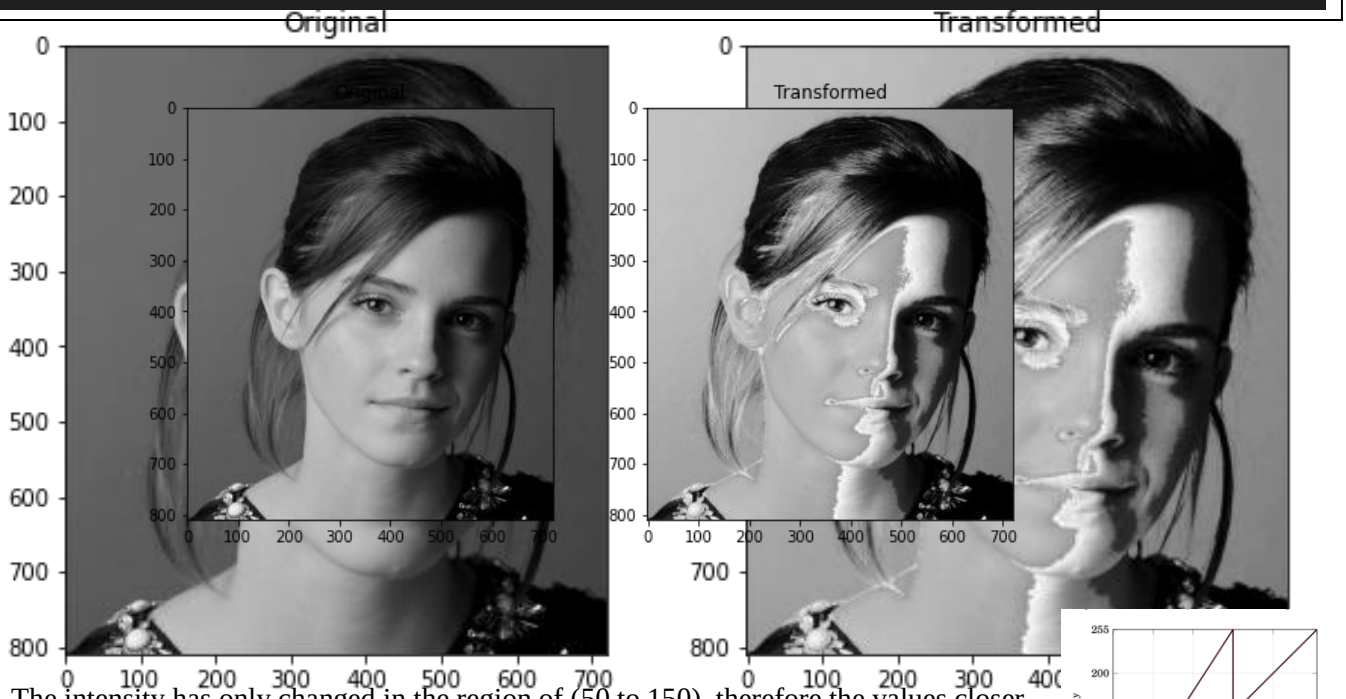
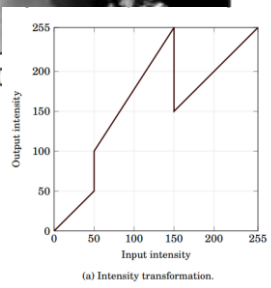
1.

```
#1


import numpy as np
import matplotlib.pyplot as plt
import cv2 as cv

x_1 = np.array([i for i in range(0,50)]).astype(np.uint8)
x_2 = np.array([(100+155/100*(i-50)) for i in range(50,150)]).astype(np.uint8)
x_3 = np.array([i for i in range(150,256)]).astype(np.uint8)
#xa = np.array([i for i in range(0,256)]).astype(np.uint8)
x= np.concatenate((x_1,x_2,x_3),axis=0).astype(np.uint8)
img = cv.imread('emma_gray.jpg')
new_img = cv.LUT(img,x)

fig , ax = plt.subplots(1,2, figsize = (10,5))
ax[0].imshow(img)
ax[0].set_title('Original')
ax[1].imshow(new_img)
ax[1].set_title('Transformed')
```



The intensity has only changed in the region of (50 to 150), therefore the values closer to white and black, hasn't changed. Value closer to gray, has increased closer to white.

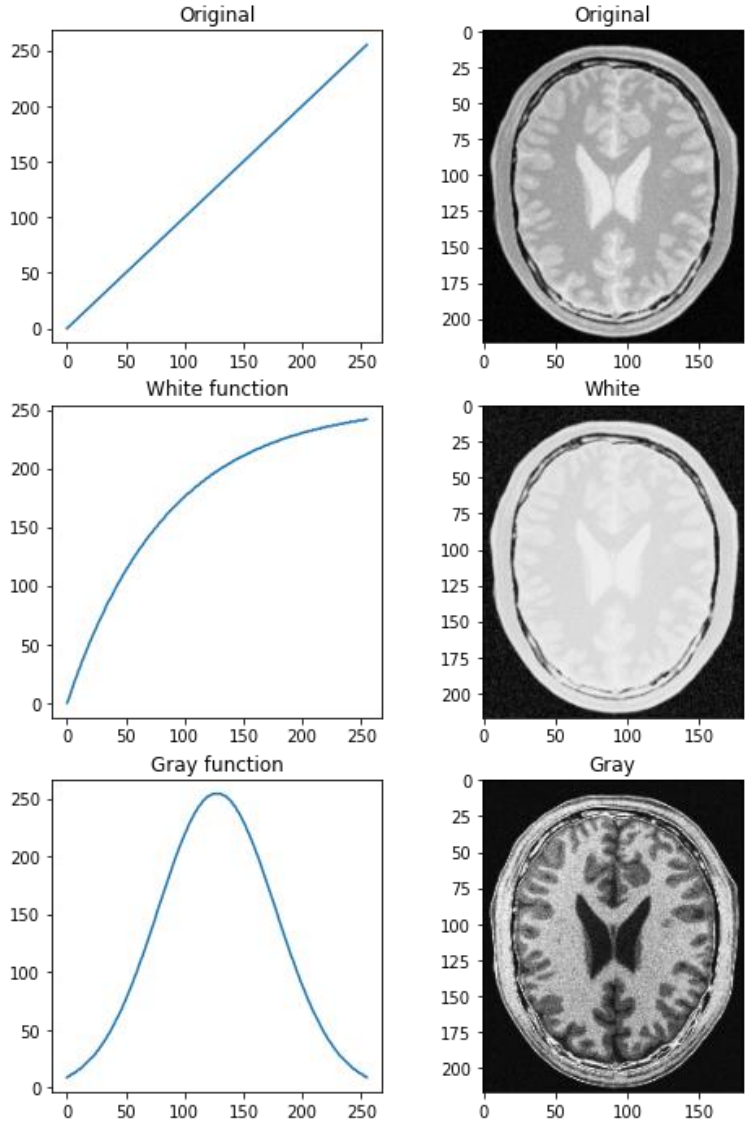


2.

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
import cv2 as cv

x = np.array([i for i in range(0,256)]).astype(np.uint8)
img = cv.imread('brain_proton_density_slice.png')
#function for white
f_w = np.array([(1-1/np.exp(3*i/255))*255 for i in
range(0,256)]).astype(np.uint8)
#print(f_w)
img_w = cv.LUT(img,f_w)
#function for grey
f_g = np.array([(np.exp(-13*(i/255-0.5)**2))*255 for i in
range(0,256)]).astype(np.uint8)
img_g = cv.LUT(img,f_g)

fig, ax = plt.subplots(3,2, figsize= (8,12))
ax[0,0].plot(x,x)
ax[0,0].set_title('Original')
ax[1,0].plot(x,f_w)
ax[1,0].set_title('White function')
ax[2,0].plot(x,f_g)
ax[2,0].set_title('Gray function')

ax[0,1].imshow(img)
ax[0,1].set_title('Original')
ax[1,1].imshow(img_w)
ax[1,1].set_title('White')
ax[2,1].imshow(img_g)
ax[2,1].set_title('Gray')
```

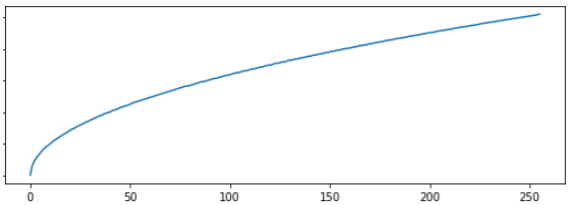


3.

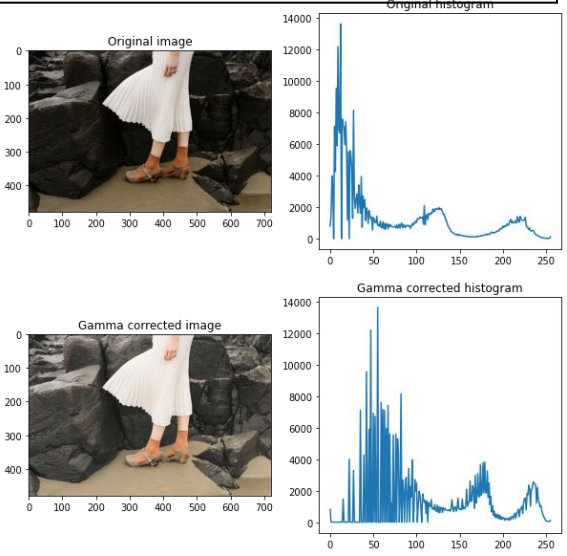
```
import numpy as np
```

```
import cv2 as cv
import matplotlib.pyplot as plt

img = cv.imread('highlights_and_shadows.jpg')
assert img is not None

lab_img = cv.cvtColor(img, cv.COLOR_BGR2LAB)
(L,A,B) = cv.split(lab_img)

gamma = 0.5
t = np.array([((i/255)**gamma)*255) for i in range (0,256)]).astype(np.uint8)
new_L = cv.LUT(L,t)
corrected_img = cv.merge([new_L,A,B])

fig , ax = plt.subplots(2,2, figsize=(10,10))

ax[0][0].imshow(cv.cvtColor(img, cv.COLOR_BGR2RGB))
ax[0][0].set_title("Original image")

ax[1][0].imshow(cv.cvtColor(corrected_img, cv.COLOR_LAB2RGB))
ax[1][0].set_title("Gamma corrected image")

ax[0][1].plot(cv.calcHist([L],[0],None,[256],[0,256]))
ax[0][1].set_title("Original histogram")

ax[1][1].plot(cv.calcHist([new_L],[0],None,[256],[0,256]))
ax[1][1].set_title("Gamma corrected histogram")
```

The intensity mapping graph is not linear.



Due to this gamma curve, the intensity has slightly changed.



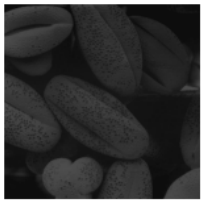
4.

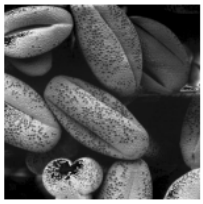
```
def equalize(img):

    hist = cv.calcHist([img],[0],None, [256],
[0,256])  #original histogram
    max_id =0
    max_num=0
    for i in range (0,256):
        if hist[i]> max_num:
            max_num= hist[i]
            max_id = i

    look_up= np.array([0 for i in range
(0,256)])
    for p in range (10,246):
        if p< max_id:
            new_val = p-((max_id - p)**2)/20
            if new_val>=0:
                look_up[p] = round(new_val)
        elif p> max_id:
            new_val = p+((p- max_id)**2)/20
            if new_val>=0:
                look_up[p] = round(new_val)
    a = np.array([i for i in range (0,256)])
    img_2 =cv.LUT(img,look_up).astype(np.uint8)
    return(img_2)
```

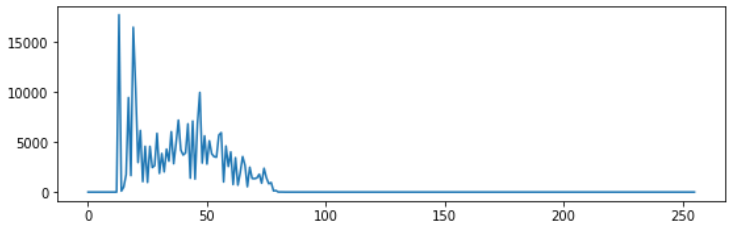
```
img_eq= equalize(img)

hist_1 = cv.calcHist([img], [0], None, [256],
[0,256])
hist_2 = cv.calcHist([img_eq], [0], None,
[256], [0,256])

fig, ax = plt.subplots(2,2,figsize = (20,6))
```

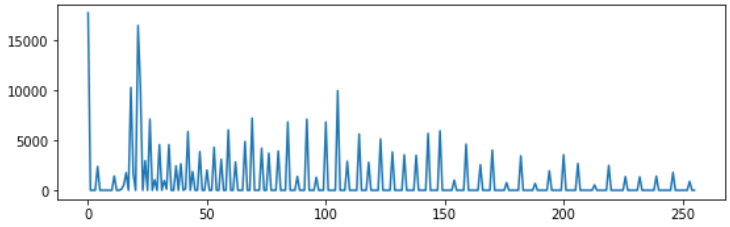
```
ax[0][0].imshow(cv.cvtColor(img,
cv.COLOR_GRAY2RGB))
ax[0][0].axis('off')
ax[0][1].plot(hist_1)
ax[1][0].imshow(cv.cvtColor(img_eq.astype(np.ui
nt8), cv.COLOR_GRAY2RGB))
ax[1][1].plot(hist_2)
ax[1][0].axis('off')
```

The equalizing function is used to equalize, instead of “equalizeHist()” function.









6.

```
img = cv.imread('einstein.png', cv.IMREAD_GRAYSCALE).astype('float32')
```

```
assert img is not None

sobel_v = np.array([[1,2,1],[0,0,0],[-1,-2,-1]], dtype = np.float32)
img_v = cv.filter2D(img,-1,sobel_v)

sobel_h = np.array([[1,0,-1],[2,0,-2],[1,0,-1]], dtype = np.float32)
img_h = cv.filter2D(img,-1,sobel_h)
gradient_img = np.sqrt(img_v**2 + img_h**2)
```

```
def sobel(img, kernel):
```

```
    #getting the dimentions of image and kernal
    (i_y , i_x) = img.shape[:2]
    (k_y , k_x) = kernel.shape[:2]

    # make empty array for output image
    # "border" :- borders of input image
    border = (k_x-1)//2
    img = cv.copyMakeBorder(img, border, border, border, border,cv.BORDER_REPLICATE)
    output = np.zeros((i_y,i_x), dtype = "float32")

    #loop over the image (sliding kernal)
    for y in np.arange(border, i_y + border):
        for x in np.arange(border, i_x + border):

            #extract the rrgion of interest of the image
            ROI = img[y - border:y + border + 1, x - border:x + border + 1]

            #convolution
            con = (ROI* kernel).sum()

            #store the new value in output
            output[y-border, x-border] = con

    # rescale the output image to be in the range [0,255]
    #output = rescale_intensity(output, in_range=(0, 255))
    #output = (output * 255).astype("uint8")

    return output
```

‘Sobel() ‘ is the function that is manually convoluting an image with a given kernel.

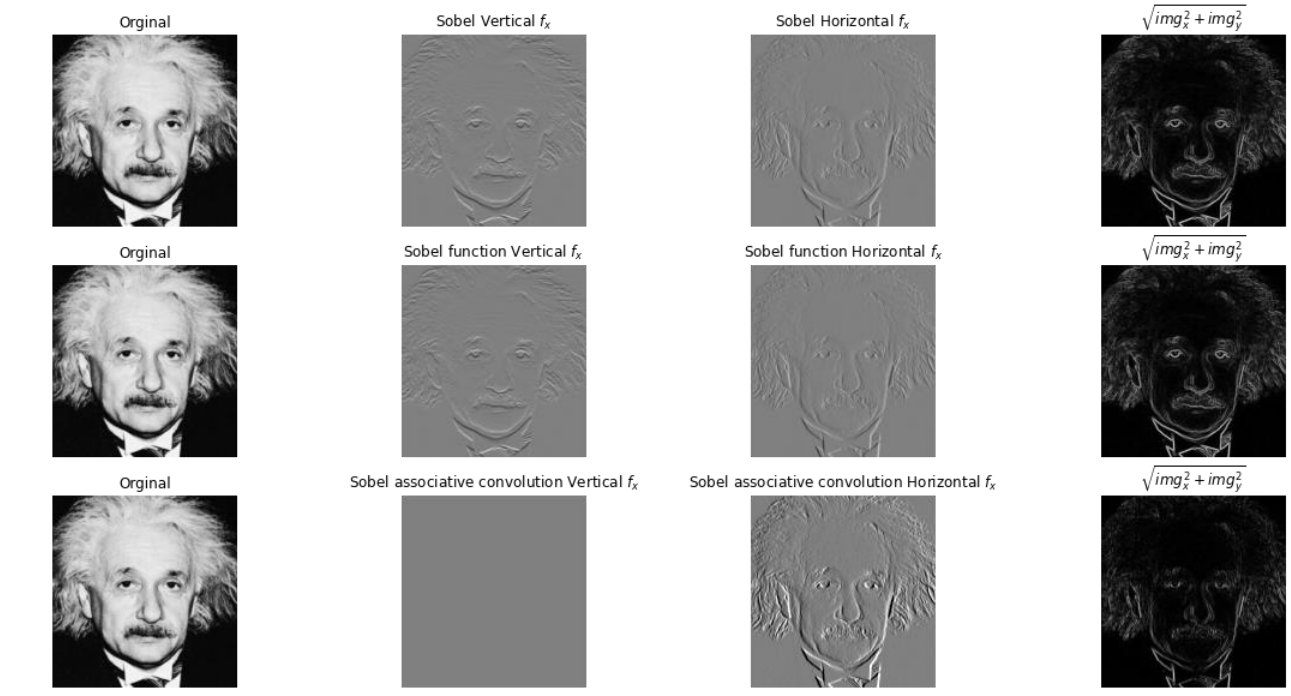
```
img_v_2 = sobel(img, sobel_v)
img_h_2 = sobel(img, sobel_h)
gradient_img2= np.sqrt((img_v_2)**2 + (img_h_2)**2)
```

The manually calculated gradient is given by “gradient_img2”.

Part c

Using the associative nature of convolution, the gradient is calculated by using the “sobel()” function twice.

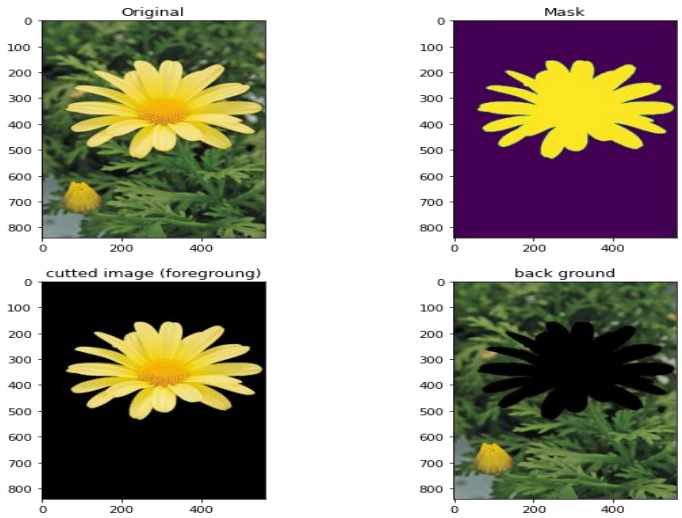
```
# c

k_1=  np.array([[1],[2],[1]])
k_2 = np.array([[1,0,-1]])
trans_k_1=k_1.T
trans_k_2=k_2.T

img_v_3 = sobel(sobel(img,trans_k_2), trans_k_1)
img_h_3 = sobel(sobel(img,k_1), k_2)
gradient_img3= np.sqrt((img_v_3)**2 + (img_h_3)**2)
```



7. a)

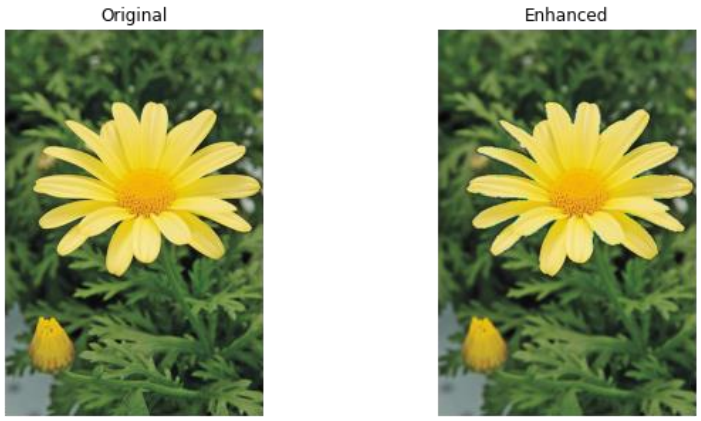
```
import numpy as np
```

```
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('daisy.jpg')
img = cv.cvtColor(img, cv.COLOR_BGR2RGB)
mask = np.zeros(img.shape[:2],np.uint8)
bgd_Model = np.zeros((1,65),np.float64)
fgd_Model = np.zeros((1,65),np.float64)
rect = (25,125,530,450)
cv.grabCut(img,mask,rect,bgd_Model,fgd_Model,5,cv.GC_BGD ) #cv.GC_INIT_WITH_RECT)
mask2 = np.where((mask==2)|(mask==0),0,1).astype('uint8')

#cutted image
img_cut = img*mask2[:,:,np.newaxis]
#background
back_gnd = img - img_cut
#plot
fig, ax = plt.subplots(2,2, figsize=(10,10))
ax[0,0].imshow(img)
ax[0,1].imshow(mask2)
ax[1,0].imshow(img_cut)
ax[1,1].imshow(back_gnd)

ax[0,0].set_title('Original')
ax[0,1].set_title('Mask')
ax[1,0].set_title('cutted image (foregroung)')
ax[1,1].set_title('back ground')
plt.show()
```



b) f

```
# enhancing


kernel_size = 11
sigma = 2

blur_background = cv.GaussianBlur(back_gnd, (kernel_size,kernel_size),sigma)
img_enhanced = blur_background + img_cut

fig, ax_1 = plt.subplots(1,2, figsize= (10,5))
ax_1[0].imshow(img)
ax_1[0].set_title('Original')
ax_1[0].axis('off')

ax_1[1].imshow(img_enhanced)
ax_1[1].set_title('Enhanced')
ax_1[1].axis('off')

plt.plot()
```



c) In the enhanced image, the outline is not much dark, but it is clear that the outline is not very smooth. It is because the “grabCut()” function cannot exactly detect the edges 100% accurately.