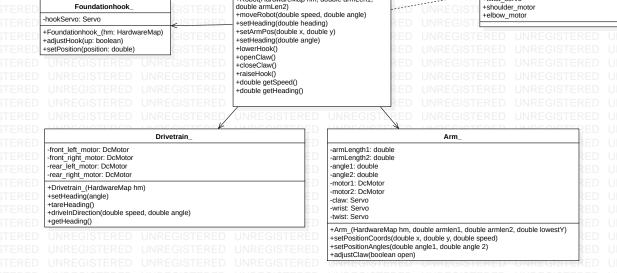
Team 4965 Robot Code Structure V1

-Drivetrain: Drivetrain_ -hardwareMap: HardwareMap

-Foundationhook: Foundationhook

-Arm: Arm



Robot

+Robot(HardwareMap hm, double armLen1,

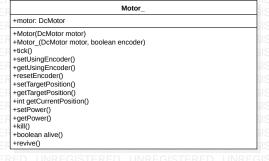
HardwareMap

+front_right_motor +front_left_motor

+rear_right_motor +rear_left_motor

wrist servo

+twist_servo



```
Driver-Controlled
        Autonomous
                                                      +Robot: Robot_
+Robot: Robot_
```