



# Sistemas de ED 2x2 homogéneos y no homogéneos

Valores Propios |A-λI| Vejemos Propios Ax=λx

Variación de Parámetros  $X_p = u_1 V_1 e^{\lambda_1 t} + u_2 V_2 e^{\lambda_2 t}$

$$\begin{aligned} x' &= 3x - y + 4e^{2t} \\ y' &= -x + 3y + 4e^{2t} \end{aligned}$$

$$\left| \begin{array}{l} X' = \begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix} X + \begin{pmatrix} 4e^{2t} \\ 4e^{2t} \end{pmatrix} \\ \lambda_1 = 4, \lambda_2 = -1 \end{array} \right.$$

$$V_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, V_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$X_p = u_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t} + u_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t}$$

$$u_1 = \frac{4e^{2t} - 4e^{2t}}{4e^{2t} - e^{-t}} = 4, u_1 = \int 4dt = 4t, u_2 = \int \frac{4e^{2t} - 4e^{2t}}{e^{2t} - e^{-t}} dt = 0$$

$$u_2 = \int 0 dt = 0 \Rightarrow X_p = \begin{pmatrix} 4t \\ 4t \end{pmatrix} e^{4t}$$

Coefficientes Indeterminados

$$X = \begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix} t + \begin{pmatrix} 4t \\ 4t \end{pmatrix} = \begin{pmatrix} 3 & 3 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3a + 3b \\ 3a + 3b \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 3 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -3 - 3b \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$X_c = C_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t} + C_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t}$$

$$X_p = \begin{pmatrix} 4t \\ 4t \end{pmatrix} e^{4t}$$

$$(t-2)^2 = (-2)t^2 + (0)t + (0) \quad X_p = \begin{pmatrix} 0 \\ 0 \end{pmatrix} t^2 + \begin{pmatrix} b \\ c \end{pmatrix} t + \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad X_p' = 2\begin{pmatrix} 0 \\ 0 \end{pmatrix} t + \begin{pmatrix} c \\ a \end{pmatrix}$$

$$2\begin{pmatrix} 0 \\ 0 \end{pmatrix} t + \begin{pmatrix} c \\ a \end{pmatrix} = \frac{1}{(t-2)^2} \left[ \begin{pmatrix} 0 \\ 0 \end{pmatrix} t^2 + \begin{pmatrix} b \\ c \end{pmatrix} t + \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right] + \frac{(-2)^2}{(t-2)^2} = \frac{1}{(t-2)^2} \left[ \begin{pmatrix} 0 \\ 0 \end{pmatrix} t^2 + \begin{pmatrix} b \\ c \end{pmatrix} t + \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right] + \frac{(t-2)^2}{(t-2)^2} = \frac{(t-2)^2}{(t-2)^2} = 1$$

$$\begin{pmatrix} a(t-2)^2 + b(t-2) + c(t-2)^2 + d(t-2) + e(t-2)^2 + f(t-2)^2 \\ 3(a(t-2)^2 + b(t-2) + c(t-2)^2 + d(t-2) + e(t-2)^2 + f(t-2)^2) \end{pmatrix} = \begin{pmatrix} (a+3b-2)t^2 + (c+3d)t + (e+f) \\ 3(a+b)t^2 + (3c+6d)t + (3e+3f) \end{pmatrix} = \begin{pmatrix} 2at+2c \\ 2bt+a \end{pmatrix}$$

$$2at+2c = 2a-2, 2bt+a = 2b-2, a=1, b=1, c=1, d=1, e=-2, f=0 \Rightarrow X = X_c + X_p$$

Transformada de Laplace  $\frac{d}{dt} \frac{t^{n-1} e^{at}}{(a-\alpha)^n} = \frac{1}{(a-\alpha)^n}$

$f(t)$	$d(f)$	$f(t)$	$d(f)$	$f(t)$	$d(f)$
$\frac{1}{t}$	$\frac{1}{t^2}$	$t^n e^{at}$	$\frac{n!}{(a-\alpha)^{n+1}}$	$a \cos(\omega t) + \frac{K}{\omega} \sin(\omega t)$	$\frac{a\alpha + b}{\alpha^2 + K^2}$
$\frac{1}{t^n}$	$\frac{n!}{t^{n+1}}$	$\sin(\omega t)$	$\frac{K}{\alpha^2 + K^2}$	$e^{at} \sin(\omega t)$	$\frac{K}{(\alpha-a)^2 + K^2}$
$\frac{1}{(n-1)!}$	$\frac{1}{t^n}$	$\cos(\omega t)$	$\frac{1}{\alpha^2 + K^2}$	$e^{at} \cos(\omega t)$	$\frac{(\alpha-a)}{(\alpha-a)^2 + K^2}$
$e^{at}$	$1$	$\sinh(\omega t)$	$\frac{K}{\alpha^2 - K^2}$	$t \sin(\omega t)$	$\frac{2K\alpha}{\alpha^2 + K^2}$
$e^{-at}$	$\frac{1}{t \alpha + \omega}$	$\cosh(\omega t)$	$\frac{1}{\alpha^2 - K^2}$	$t \cosh(\omega t)$	$\frac{1}{(\alpha^2 + K^2)^2}$

\*  $d\{f(t)\} = \int_0^\infty e^{-at} f(t) dt$  \*  $d(a f(t) + b g(t)) = a d(f) + b d(g)$

Traslación 1:  $d\{e^{at} f(t)\} = d\{f(t)\}|_{t=a} \cdot d^{-1}\{F(a-\alpha)\} = e^{at} d^{-1}\{F(a)\}$

Transformada Derivada  $d\{f^{(n)}(t)\} = t^n F'(1) - t^{n-1} F'(0) - \dots - t F^{(n-1)}(0) \rightarrow d\{f^{(n)}(t)\} = t^n F'(1) - t^{n-1} F'(0) - \dots - t F^{(n-1)}(0)$

Escalar Unitario  $U(t-\alpha) = \begin{cases} 0, & 0 \leq t < \alpha \\ 1, & t \geq \alpha \end{cases}$   $d(U(t-\alpha)) = \frac{e^{-a\alpha}}{\alpha}$

Trazos  $f(t) = \begin{cases} g(t), & 0 \leq t < a \\ h(t), & t \geq a \end{cases} \Rightarrow f(t) = g(t) - g(t)aU(t-a) + h(t)U(t-a)$

$f(t) = \begin{cases} 0, & 0 \leq t < b \\ g(t), & t \geq b \end{cases} \Rightarrow f(t) = g(t)U(t-b) - g(t)aU(t-b)$

Traslación 2:  $d\{f(t-a)U(t-a)\} = e^{-a\alpha} F(a)$  ó  $d\{g(t)U(t-a)\} = e^{-a\alpha} d\{g(t+a)\}$

Convolución  $f * g = \int_0^t f(\tau) g(t-\tau) d\tau$

Teorema Convolución  $d\{f(t) * g(t)\} = d(f(t)) \cdot g(t) = F(s) G(s)$

$d^{-1}\{F(s) \cdot G(s)\} = d^{-1}\{F(s)\} * d^{-1}\{G(s)\} = f * g$

Integrales  $d\{\int_0^t f(\tau) d\tau\} = \frac{F(s)}{s}$   $d^{-1}\{\frac{F(s)}{s}\} = \int_0^t f(\tau) d\tau$

Integral de Volterra  $f(t) = g(t) + \int_0^t g(\tau) h(t-\tau) d\tau$

$d\{\sin(t)U(t-\frac{\pi}{2})\} = e^{-\frac{\pi}{2}a}$   $d\{\sin(t-\frac{\pi}{2})\} = e^{-\frac{\pi}{2}a} d(\sin(t)) \cos(\frac{\pi}{2}) + \cos(t) \sin(\frac{\pi}{2}) = \frac{e^{-\frac{\pi}{2}a}}{2}$

$d\{\cos(t)U(t-\pi)\} = e^{-\pi a}$   $d\{\cos(t+\pi)\} = e^{-\pi a} - \frac{1}{\pi^2 + 1}$

$d\{\cos(t) \cdot U(t-\pi)\} = e^{-\pi a} \cdot \frac{1}{\pi^2 + 1}$   $d^{-1}\{\frac{e^{-\pi a}}{\pi^2 + 1}\} = U(t-\pi)$

$d\{\frac{e^{2\pi}}{\pi^2 + 1} U(t+2)\} \Rightarrow d^{-1}\{\frac{1}{\pi^2 + 1}\} = \frac{1}{2} \operatorname{sech}(2t) \Rightarrow d^{-1}\{\frac{e^{2\pi}}{\pi^2 + 1}\} = \frac{1}{2} U(t+2) \operatorname{sech}(2(t+2))$

$y' + y = f(t), y(0) = S, f(t) = \sum_{n=0}^{\infty} a_n t^n, t = \pi \Rightarrow f(t) = 3 \cos(t) \cdot U(t-\pi)$

$Y - S + Y = -3e^{-\pi a} \cdot \frac{1}{\pi^2 + 1} \Rightarrow (2\pi a)Y = S - 3e^{-\pi a} \cdot \frac{1}{\pi^2 + 1} \Rightarrow Y = \frac{S}{2\pi a} - \frac{3e^{-\pi a}}{2\pi a(\pi^2 + 1)}$

$A = \begin{bmatrix} 1 & 3 \\ 3 & 1 \end{bmatrix}, A_1 = \begin{bmatrix} \frac{1}{2} & 3 \\ \frac{3}{2} & 1 \end{bmatrix}, A_2 = \begin{bmatrix} 1 & \frac{1}{2} \\ 3 & \frac{1}{2} \end{bmatrix}, |A_1| = \frac{4-3a}{2}, |A_2| = 1-1 \cdot \frac{3}{2}, |A| = \frac{1}{2}$

$x = \frac{\frac{4-3a}{2} - \frac{4}{1-a}}{1-a} - \frac{3}{1-a} \Rightarrow x = \frac{4}{9} [-1 + \operatorname{cosh}(3t)] - \operatorname{senh}(3t)$

$x = -\frac{4}{9} + \frac{4}{9} \left[ \frac{e^{3t} + e^{-3t}}{2} \right] - \frac{e^{3t} - e^{-3t}}{2} = -\frac{4}{9} + \frac{5}{18} e^{3t} + \frac{13}{18} e^{-3t} = x(t)$

$y = \frac{1-1 \cdot \frac{3}{2}}{1-a} = \frac{1}{1-a} - \frac{1}{1-a} - \frac{3}{1-a} = \frac{1}{1-a} - \frac{1}{1-a} - 3 \left( -\frac{1}{9k^2} + \frac{1}{9k(1-a)} \right)$

$y(t) = \operatorname{cosec}(3t) - \frac{1}{3} \operatorname{senh}(3t) - \frac{1}{9} [-3t + \operatorname{senh}(3t)]$

$y(t) = \frac{5}{18} e^{3t} + \frac{13}{18} e^{-3t} + \frac{t}{3}$