

Difference Eqs. 1

Difference and differential eqs are versatile tools for modelling dynamical systems

- ↳ They represent well some dynamic phenomena
- ↳ They have a rich mathematical framework (theory)

We will study initially the case where these eqs have a single state variable (one funct. of time)

Obs

- These models can be generalized to more variables
- Single variable models are very useful in many situations + Theory serves for a good background for multivariate generalizations
 - ↳ Single variable models are a good 1st step.

Difference Eqs.

$T_0 \quad r \quad n \quad \dots$ sequence of points

← →

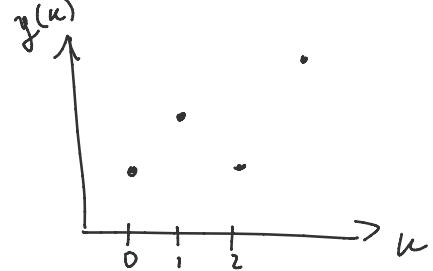
Def

Suppose there is a sequence of points
 - possibly representing equally-spaced time points -
 indexed by k , ($k \in \mathbb{N}^*$. or any discrete set)

Suppose there is a value $y(k) \in \mathbb{R}$ associated
 with each of these points

$$y: \mathbb{N}^* \rightarrow \mathbb{R}$$

$$k \mapsto y(k)$$



A difference equation is an equation
 relating $y(k)$ at point k to values at
 other (usually neighbouring) points.

Def² Let $x: \mathbb{N}^* \rightarrow \mathbb{R}$, a d.e. is an eq. of the form
 $\forall (k, x(k), \dots, x(k+m)) = 0$

Ex: 1) $y(k+1) = a y(k)$, $k = 0, 1, 2, \dots$

\uparrow
ctnt.

2) $k y(k+2) y(k+1) = \frac{1}{2} \sqrt{y(k) y(k-1)}$ $k = 1, 2, 3, \dots$

Obs A difference eq. can be seen as a "rule"
 1) $\dots, 1 - L \dots$

Def A difference +

1) or as a set of eqs.

↳ one for each k .

2) Usually $k \in \mathbb{Z}$, $\underline{k \in \mathbb{N}^*}$, or $k \in \mathbb{N}$

most common.

3) Once the indexing set is define, one can substitute the k 's to obtain explicit eqs. relating the y 's.

Ex: Ex. 1 is equivalent to $y(1) = a y(0)$

$$y(2) = a y(1)$$

:

(How many initial cond. do we need
to generate a solution? (A: 1))

Obs:

If the $y(k)$ are known, the difference eq.
is a relation among values
(short description) d.e. $y(0)$
 $y(1), 3, 9, \dots$

$$y(k+1) = 3 y(k)$$

If the $y(k)$ are unknown the d.e. can
be used to solve for the unknown $y(k)$ based
on initial conditions.

be used to solve for the unknowns
on a set of I.C.

↳ More frequent.

(Relationship to be satisfied by $\underbrace{\text{solution}}_{\text{function}}$)

The name difference eq. comes from the possibility
of expressing y implicitly the differences:

$$\Delta^0(k) = y(k)$$

$$\Delta^1(k) = \Delta^0(k+1) - \Delta^0(k) \quad (y(k+1) - y(k))$$

$$\Delta^2(k) = \Delta^1(k+1) - \Delta^1(k)$$

$$((\Delta^0(k+2) - \Delta^0(k+1)) - (\Delta^0(k+1) - \Delta^0(k)))$$

$$(y(k+2) - y(k+1)) - (y(k+1) - y(k))$$

.

Def The order of a d.e. is the difference
between the highest and the lowest index
that appears.

Ex. Fx_1 has order 1,

Fx_2 has order 3

Def A d.e. is said to be linear if it has the form:

$$a_n(k)y^{(k+n)} + a_{n-1}(k)y^{(k+n-1)} + \dots + a_0(k)y(k) = g(k)$$

a_i 's are coeff., can depend on k
no nonlinear oper. of $y(k)$'s
(unknown y appears linearly)

If the a_i 's don't depend on k the d.e. the eq. is said to have constant coefficients (time-invariant)

$g(k)$ is known as the forcing term

if $g(k)=0$ the d.e. is said to be homogeneous.

Solutions of d.e's.

A solution is a function $y(k)$ that reduces the eq. to an identity (satisfies the d.e. $\forall k$).

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Ex 3: $y(k+1) = a y(k)$

Then $y(k) = a^k$ is a sol. since

$$y(k+1) = a^{k+1} = a \cdot a^k = a y(k)$$

Ob A sequence can be seen as a sequence of numbers.

Ex For ex. 3 if $a = \frac{1}{2}$ a solution can be a seq.

$$1, \frac{1}{2}, \frac{1}{4}, \frac{1}{8}, \dots$$

which can be written as $\frac{1}{2}^k, k=0, 1, \dots$
 $\left\{\frac{1}{2}^k\right\}_{k \in \mathbb{N}^*}$.

Obs

In general finding a simple representation for the sol. is unviable.

Ex 4 Consider the linear diff. eq.

$$(k+1)y(k+1) - k y(k) = 1 \quad k=1, 2, \dots$$

A solution is $y(k) = 1 - \frac{1}{k}$

$$\text{Verification: } y(k) = \frac{k-1}{k}, \quad y(k+1) = \frac{k}{k+1}$$

$$\text{hence } (k+1)y(k+1) - ky(k) = k - (k-1) = 1$$

(only one?)

There are other solutions,

$$\text{Indeed, } y(k) = 1 - A/k, \quad A \neq 0$$

is a solution

Ex 2: A nonlinear d.e (arising in Genetics)

$$y(k+1) = \frac{y(k)}{1+y(k)} \quad k=0, 1, 2, \dots$$

A family of sols is.

$$y(k) = \frac{A}{1+Ak}, \quad A \in \mathbb{R}$$

Ex 3 Consider the nonlin. d.e

$$y(k+1)^2 + y(k)^2 = -1$$

The d.e has no real solutions

Existence and Uniqueness of solutions

like other eqs. there can be no sols. or multiple solutions.

We will examine these concepts more generally

Initial Conditions

Obs One essential characteristic of d.e's is that over a finite interval of time (indexed by k) there are more unknowns than eqs.

e.g. if we have

$$y(k+1) = 2y(k)$$

for $k=0, 1,$

$$y(1) = 2y(0)$$

$$y(2) = 2y(1)$$

(unique)

\Rightarrow To derive an explicit solution it is necessary to assign a value to one of the unknowns

If more eqs. are added 1 unknown added

If more eqs. are added 1 unknown added per equation.

↳ No matter how long seq. is (# eqs)
unknowns is larger than # eqs.

In general,

if for a d.e., for each k the eq. has
n+1 unknown variables (the y 's)
(successive points)
there are n more unknowns than eqs. in
any finite set.

(Any new eq. adds one unknown and one eq.)
at least
⇒ surplus is n

The surplus of n allows the values of n var.
to be specified arbitrarily (n degrees of freedom)

These values are set as arbitrary constants in the expression
of the general solution.

Observe Any n arbitrary components of the sol. can

Σ Any n arbitrary ~~ump~~ ...
be specified

It is conventional to specify first n .

$$(y(0), \dots, y(n-1))$$



Initial conditions

Ex. 1) $y(k+1) = a y(k)$ (geom. growth.)

gen. sol: $y(k) = C \cdot a^k$

But $y(0) = C \cdot a^0 = C$, so gen. sol

is $y(k) = y(0) a^k$.

2) $y(k+2) = y(k)$ (order 2)

(can be written as $y(k+2) + \underbrace{c_1 y(k+1) + c_2 y(k)}_{\text{have successive values}} = 0$)

2 I.C are needed

(one for even # k's, one for odd k's)

Specifying $y(0), y(1)$

yields gen. sol:

$$y(k) = \frac{(y(0) + y(1))}{2} + (-1)^k \left(\frac{y(0) - y(1)}{2} \right)$$

Existence and uniqueness Thm

- D.E. can have or not sols.
- One does not need to explicitly find sol. to show (infer) its existence
- Also, existence does not guarantee uniqueness-
(part. sol. from I.C.)

Thm: Let a difference equation of the form-

$$y(k+n) + f(y(k+n-1), \dots, y(k), k) = 0 \quad (1)$$

where f is an arbitrary function ($\text{Im}(f) \subseteq \mathbb{R}$) .

Suppose the d.e. is defined over a finite or infinite sequence of integer values

$$(k=k_0, k_0+1, k_0+2, \dots)$$

The eq. has one and only one solution

Corresponding to each arbitrary specification of n initial values $y(k_0), \dots, y(k_0+n-1)$.

Proof

(uses the axiom of choice)

Suppose the values $y(k_0), \dots, y(k_0+n-1)$ are specified.

Then the d.e. with $k=k_0$ can be solved uniquely for $y(k_0+h)$ ($y(k_0+h) = f(\dots)$)

Then the d.e. can be used to solve for $y(k_0+n+1)$, with $k=k_0+1$.

Continuing inductively one can generate the successive values of the seq. \square

Ob

- * No restrictions are required on f .
- * linear eqs. have form of (1)
(f is a lin. comb.)
 \Rightarrow Lin. d.e. have a unique sol. for every set of I.C.

— / —

Generating sols. of eq. of order 1.

Consider the eq.

$$y(k+1) = a y(k) + b.$$

(linear with constant coeff.)

To find general sol. suppose $y_0 = 0$

$$y(0) = y_0 \quad (\text{order } 1 \rightarrow 1 \text{ I.C})$$

$$y(1) = ay(0) + b = ay_0 + b$$

$$y(2) = ay(1) + b = a(ay_0 + b) + b = a^2y_0 + ab + b$$

$$y(3) = ay(2) + b = a(a^2y_0 + ab + b) + b = a^3y_0 + a^2b + ab + b$$

⋮

$$y(k) = a^k y_0 + b(a^{k-1} + \dots + a + 1)$$

$$= \begin{cases} y_0 + b \cdot K & , a = 1 \\ a^k y_0 + \frac{1-a^k}{1-a} b & , a \neq 1 \end{cases}$$

$$\hookrightarrow D a^k + \frac{b}{1-a} \quad , D = y_0 - \left(\frac{b}{1-a} \right)$$

Chain letters and amortization (Examples)

Ex1.

Suppose you receive a chain letter
with 6 names and addresses

- You have to send it to 1st person
- You can then create a new letter with
the first name deleted and your name
and ...

the first name deleted and you
added at the bottom
↳ Send letter to 5 friends

You are promised \$1562.50.

Sol.

Let $y(k)$: # letters in k th generation

(letter you receive is $y(0) = 1$)

Each letter introduces 5 more in next gen.

$$y(k+1) = 5y(k).$$

Solution is $y(k) = 5^k$

Since all recipients of 6th gen. send you

10+, you get $10 \cdot y(6) = 10 \cdot \frac{15,625}{5^6} = 1562.5$.

Ex 2

Accumulation of bank deposits with simple interest. (Deposits made each year at the beg)

$y(k)$: Amount at beginning of year k .

If no interest:

$$y(k+1) = y(k) + \underbrace{b(k)}_{\text{deposit made at start of year}}$$

$y(k+1) = y(k) + \underbrace{b}_{\text{deposit made at start of year}}$
 if $b(k) = b$, growth is linear.

If interest is compounded annually:

$$y(k+1) = y(k)(1+i) + \underbrace{b}_{\text{constant deposit}}$$

Ex 3 Amortization

If payment B is made at the end
 of each year

$$d(k+1) = (1+i)d(k) - B$$

where $d(0) = D$; initial debt

If we want to pay in n years
 we need B such that $d(n) = 0$

Using gen. sol.

$$d(n) = D(1+i)^n - \frac{1-(1+i)^n}{1-(1+i)} B$$

$$d(n) = 0 \Rightarrow B = \frac{iD}{1-(1+i)^n}$$