

Room (X, Y)

{
cell (0, 0) .
cell (0, 1) .
~
cell (0, 5) .

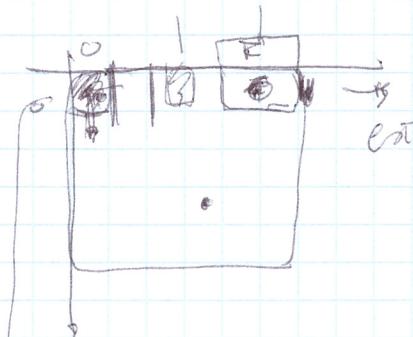
0 1 2 3 4 5

cur Robot Pos (0, 0)
cur Robot Dir (sub) .

frigo
pos (frigo, 0, 5) .

① TestPlan

Player



1h

Pianificare il ms.
comportamento /
percorso

Codifica le mosse

a d w s h

→ [a(w), w , w , w]

TEST PLAN

[

0, 5]

Calibrare

Robot

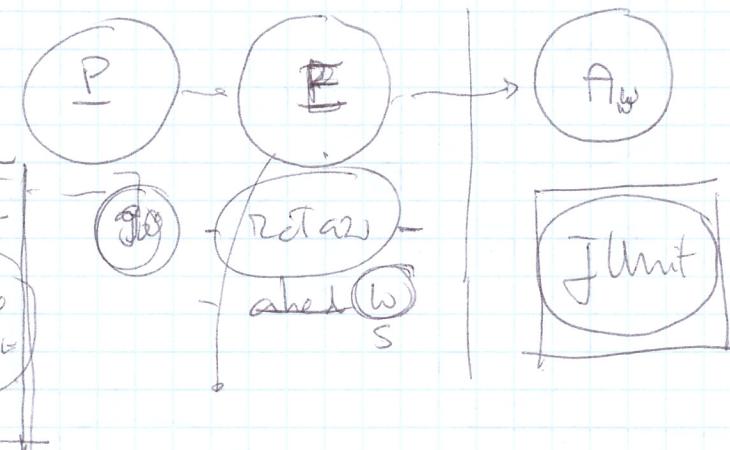
behav

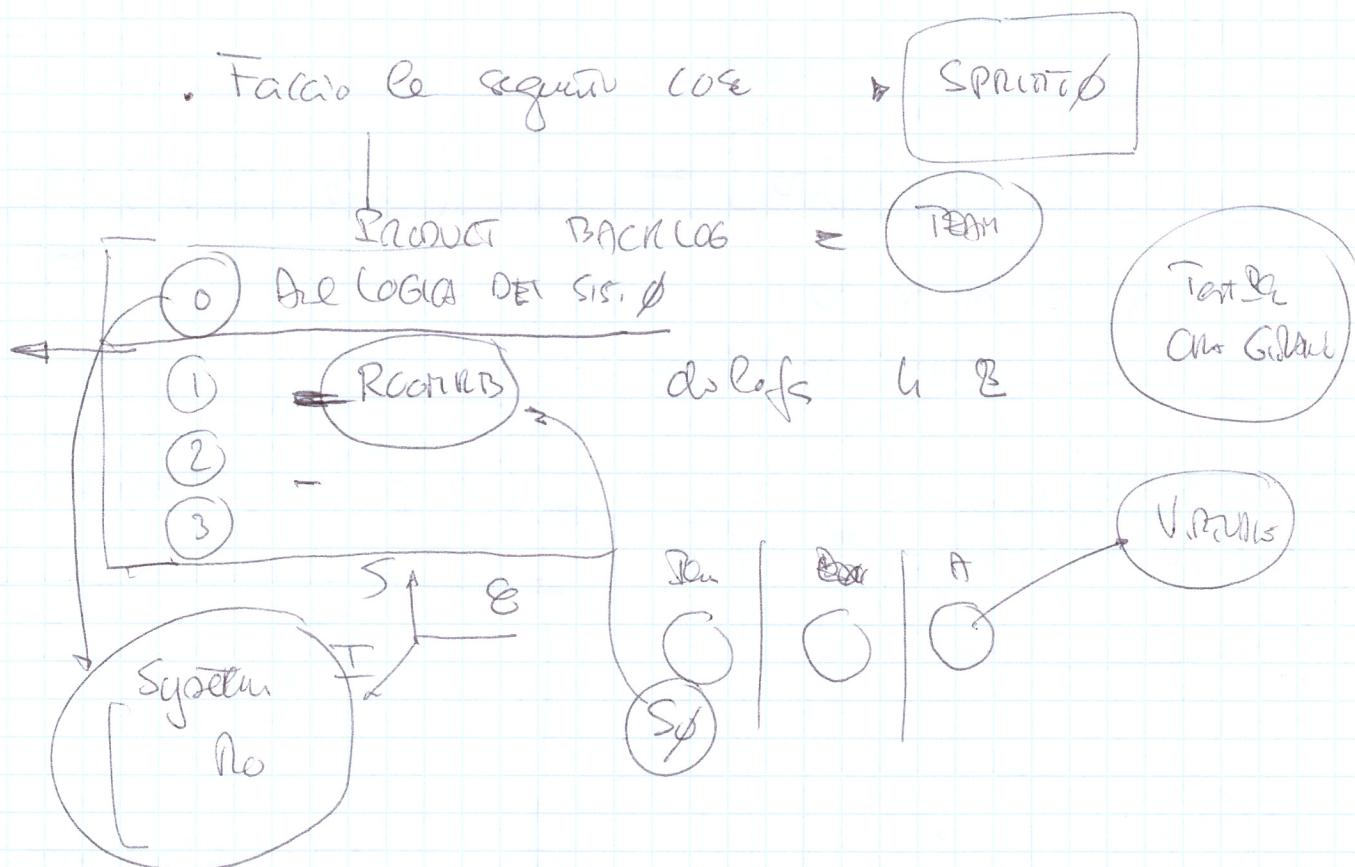
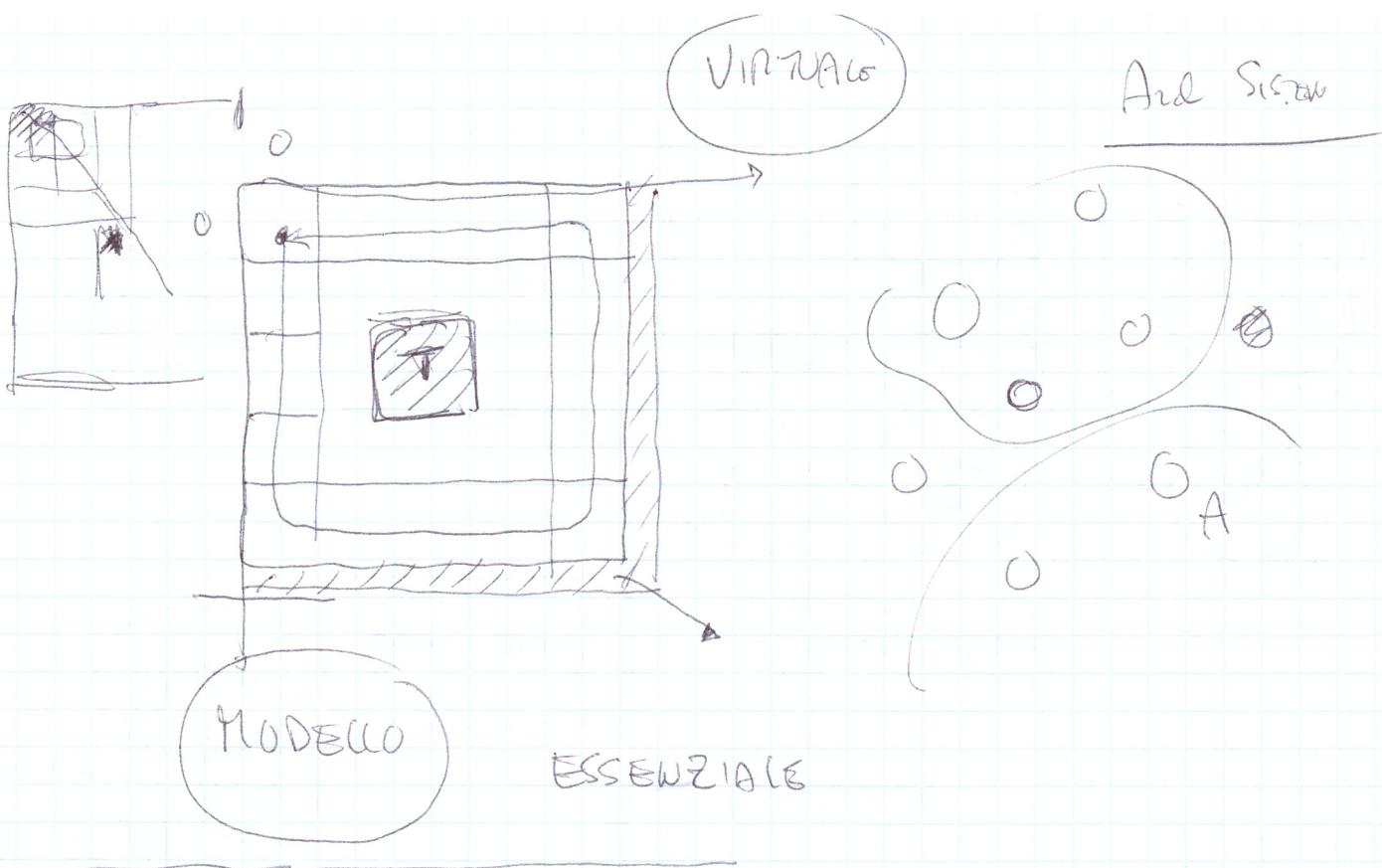
SPRINT 0

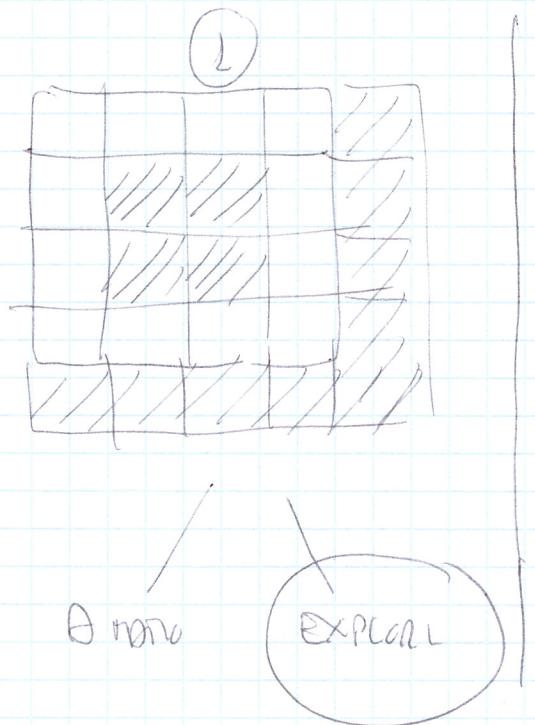
mBot

Auton.

Come attiv?







θ now

EXPLAIN