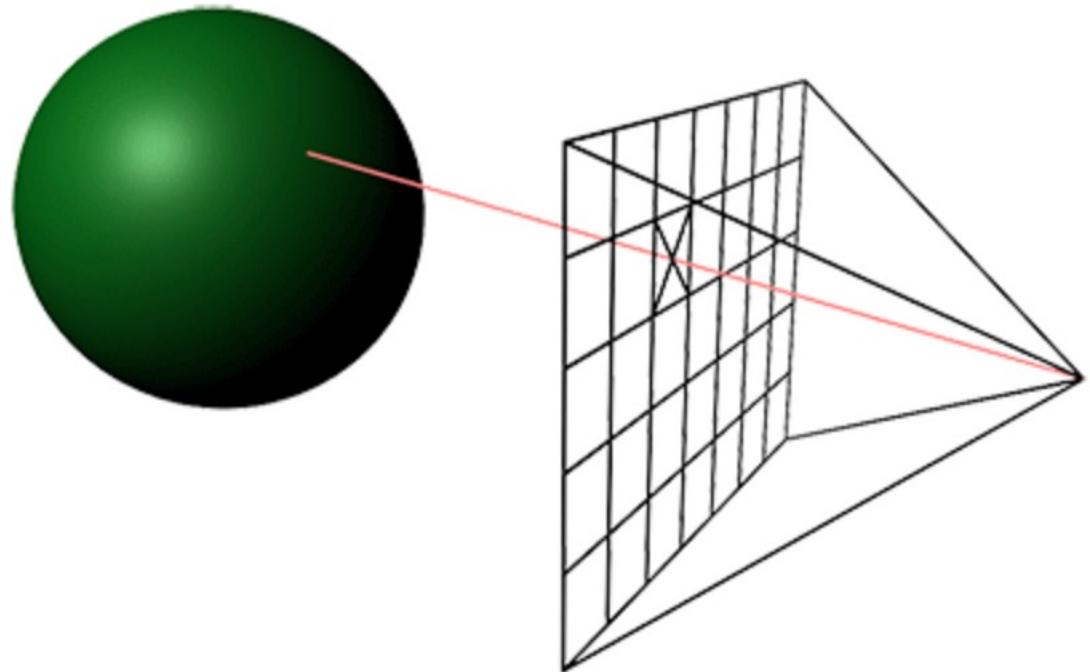


Mestrado em
Engenharia Informática

VI-RT
Perspective Camera
Image

Visualização e Iluminação

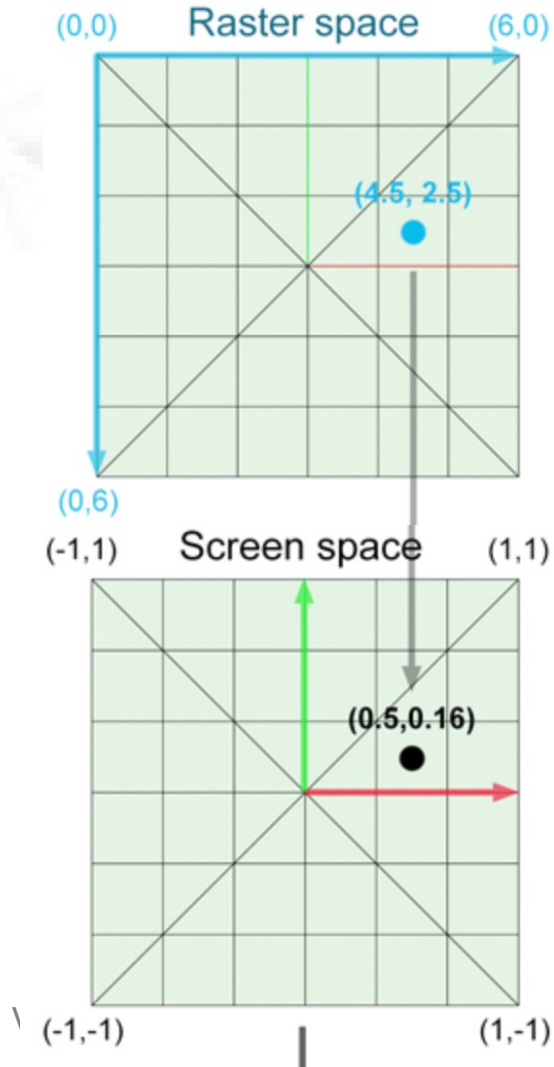
PERSPECTIVE CAMERA



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Raster -> Screen -> Camera Space

Image Resolution = (W,H)



Raster -> Screen -> Camera Space

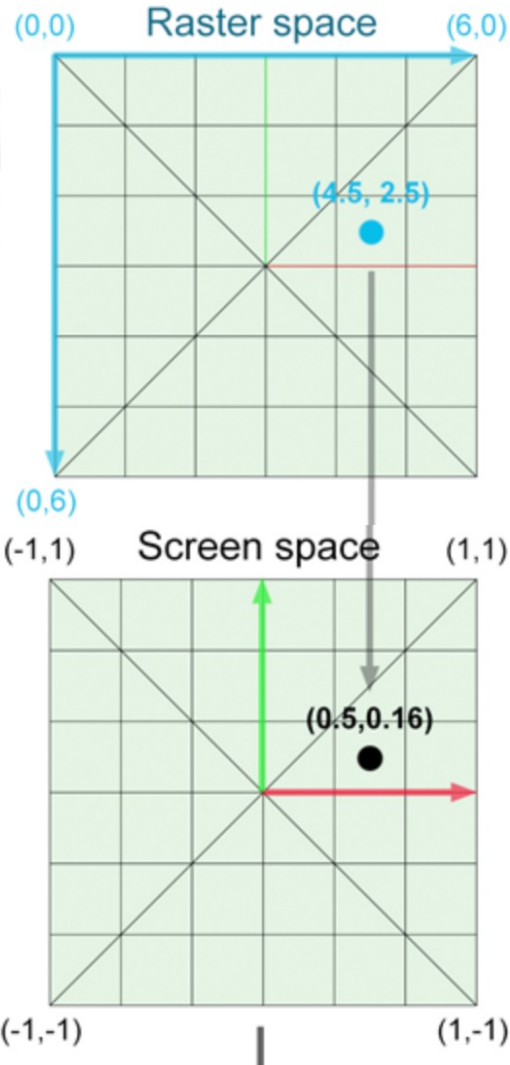


Image Resolution = (W,H)

$$x_s = \frac{2(x+0.5)}{W} - 1 \quad y_s = \frac{2(y+0.5)}{H} - 1$$

Raster -> Screen -> Camera Space

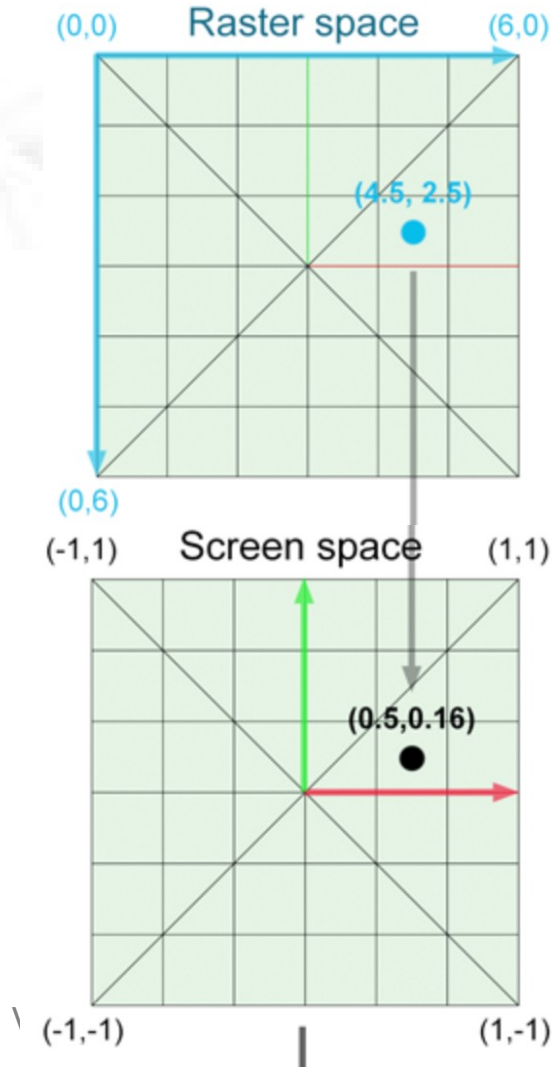
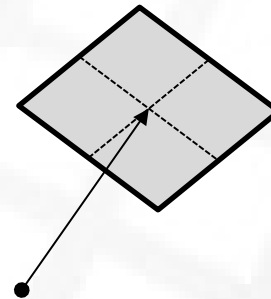


Image Resolution = (W,H)

$$x_s = \frac{2(x+0.5)}{W} - 1 \quad y_s = \frac{2(y+0.5)}{H} - 1$$



Raster -> Screen -> Camera Space

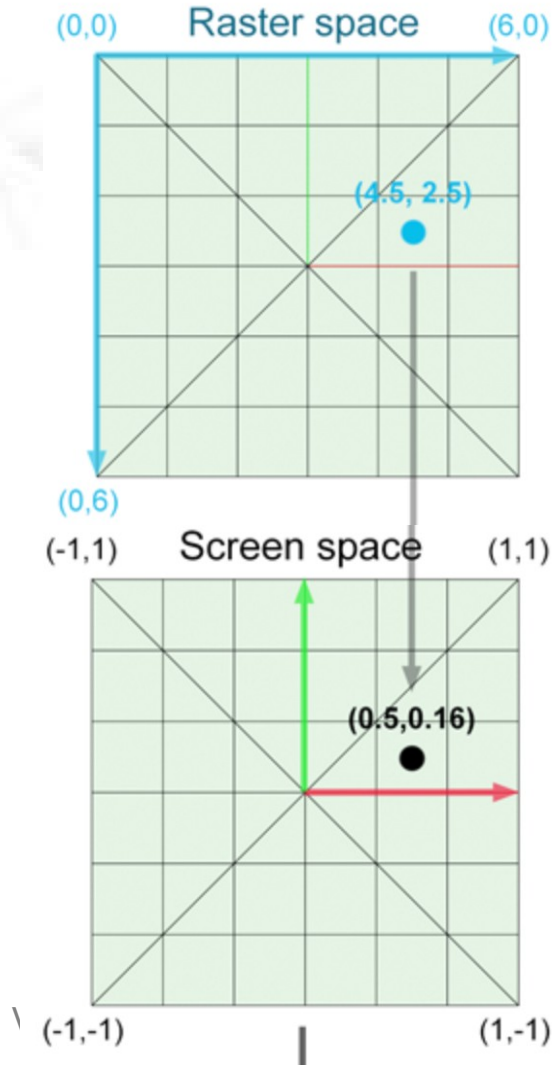
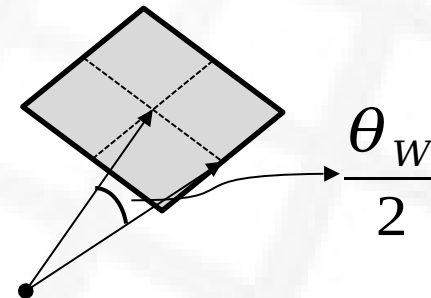


Image Resolution = (W,H)

$$x_s = \frac{2(x+0.5)}{W} - 1 \quad y_s = \frac{2(y+0.5)}{H} - 1$$



Raster -> Screen -> Camera Space

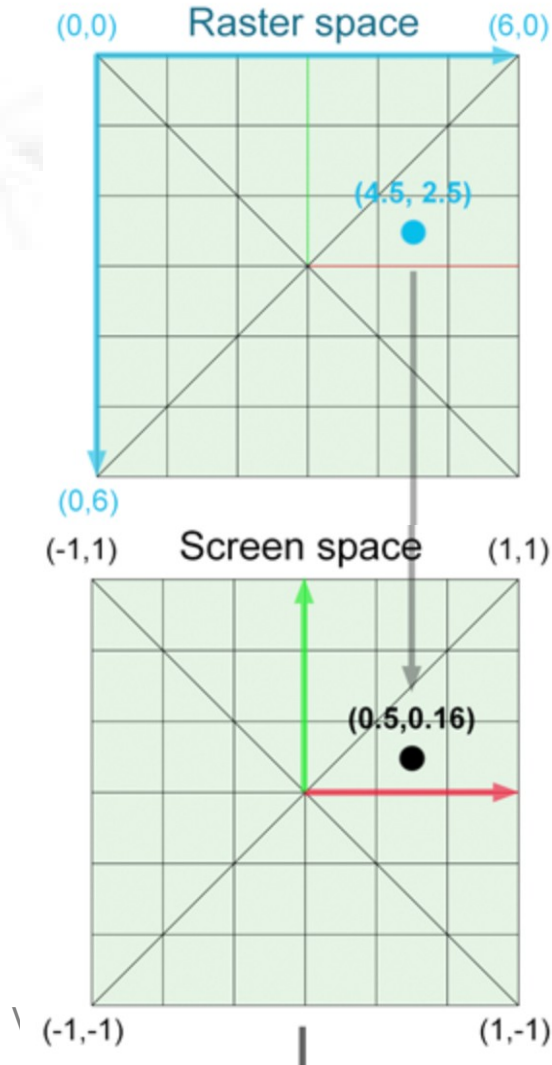
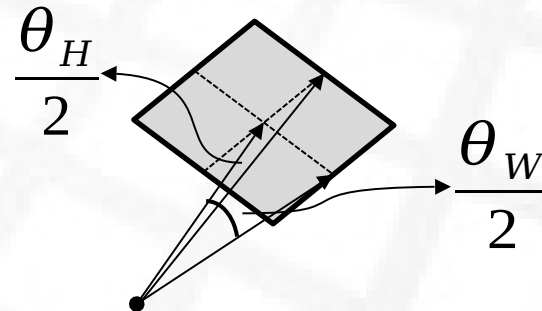


Image Resolution = (W,H)

$$x_s = \frac{2(x+0.5)}{W} - 1 \quad y_s = \frac{2(y+0.5)}{H} - 1$$



Raster -> Screen -> Camera Space

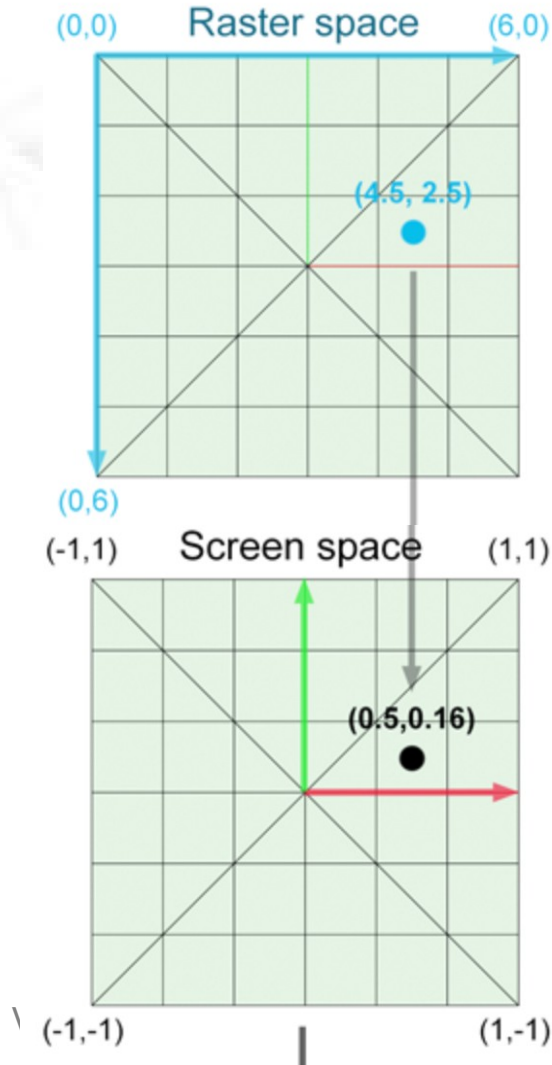
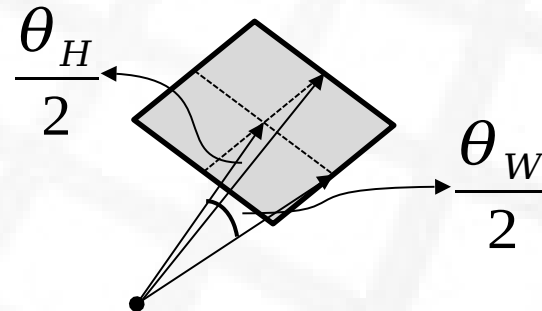


Image Resolution = (W,H)

$$x_s = \frac{2(x+0.5)}{W} - 1 \quad y_s = \frac{2(y+0.5)}{H} - 1$$



$$x_c = x_s * \tan \frac{\theta_W}{2}$$

$$y_c = y_s * \tan \frac{\theta_H}{2}$$

Raster -> Screen -> Camera Space

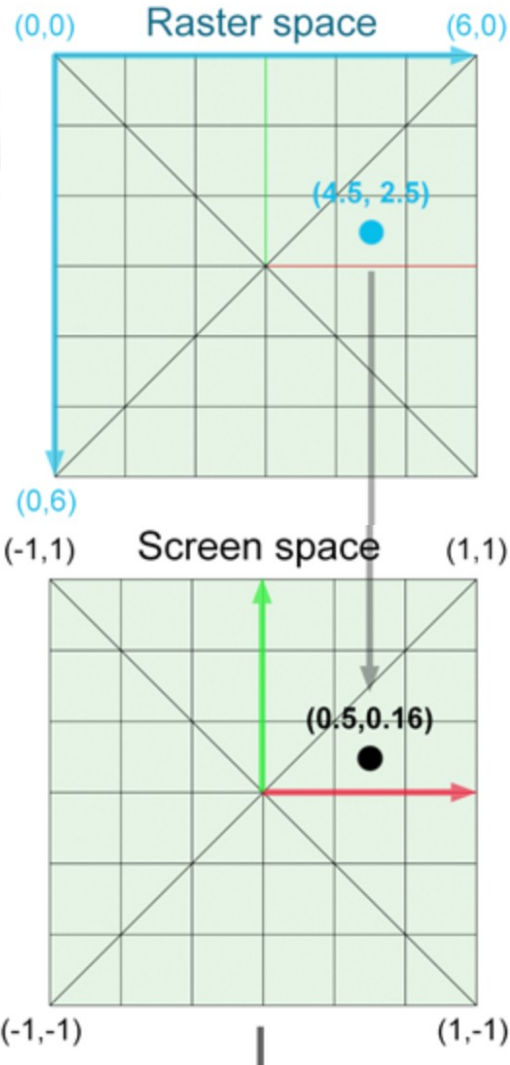
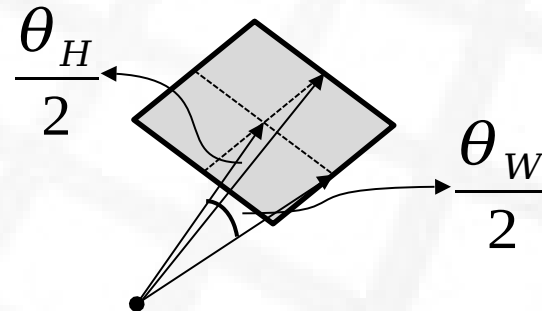


Image Resolution = (W,H)

$$x_s = \frac{2(x+0.5)}{W} - 1 \quad y_s = \frac{2(y+0.5)}{H} - 1$$

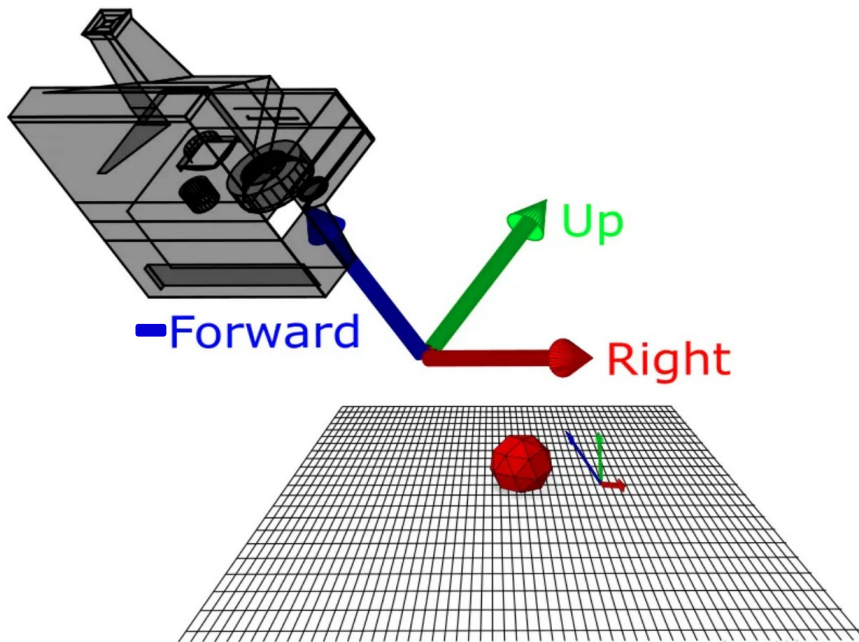


$$x_c = x_s * \tan \frac{\theta_W}{2}$$

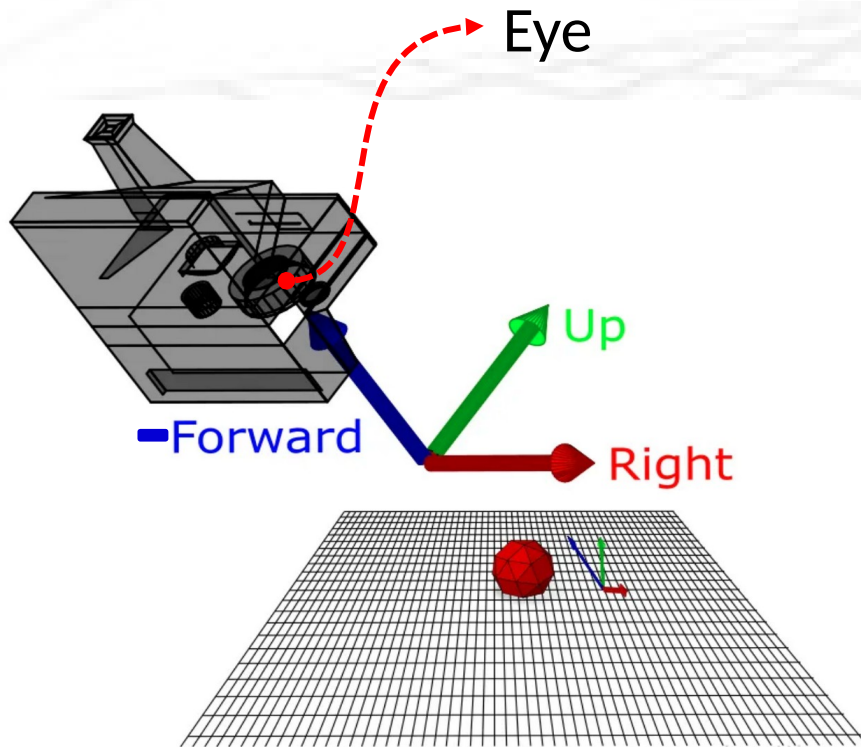
$$y_c = y_s * \tan \frac{\theta_H}{2}$$

$$\begin{pmatrix} x_c \\ y_c \\ 1 \end{pmatrix}$$

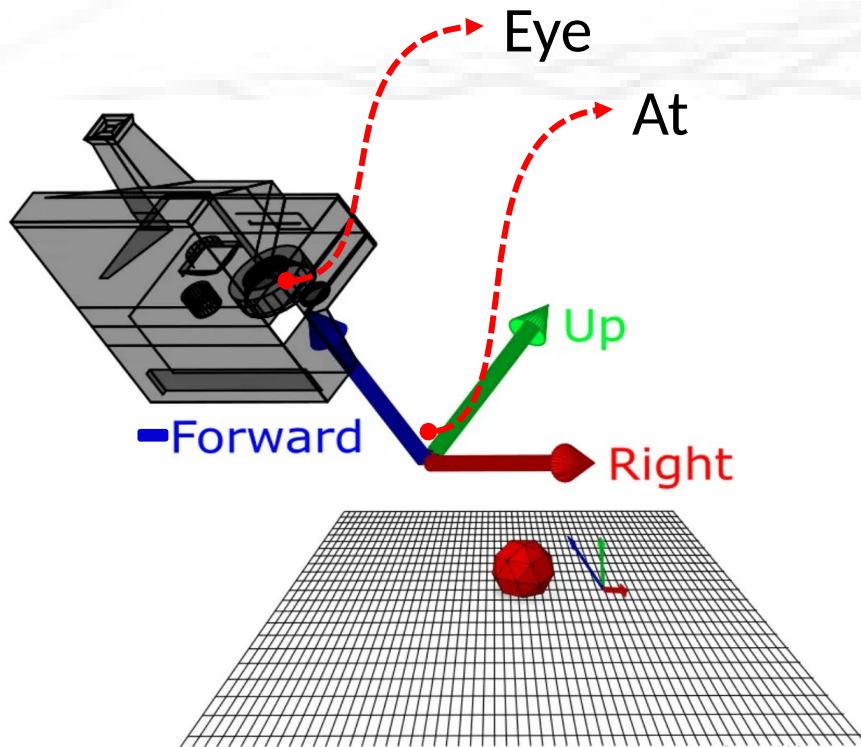
Camera Setup



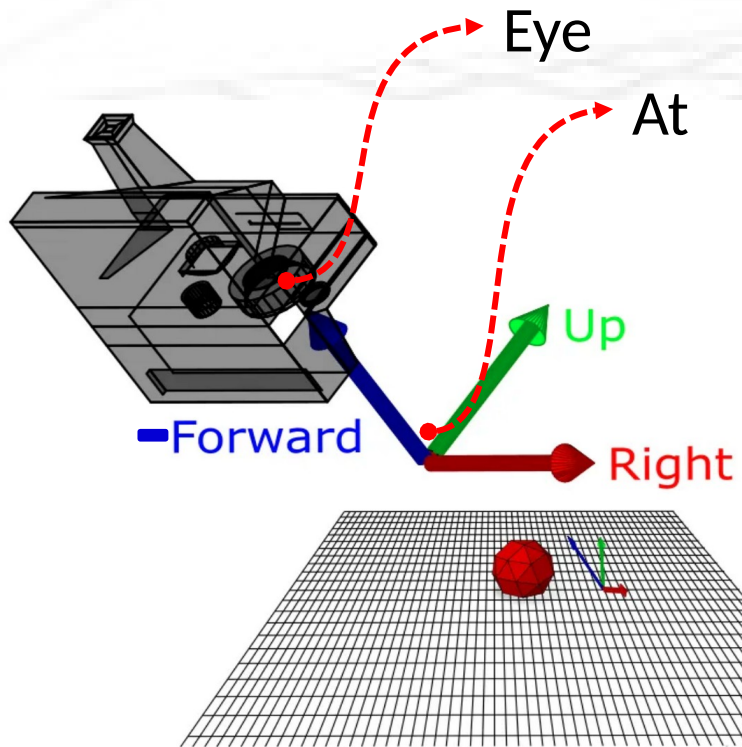
Camera Setup



Camera Setup

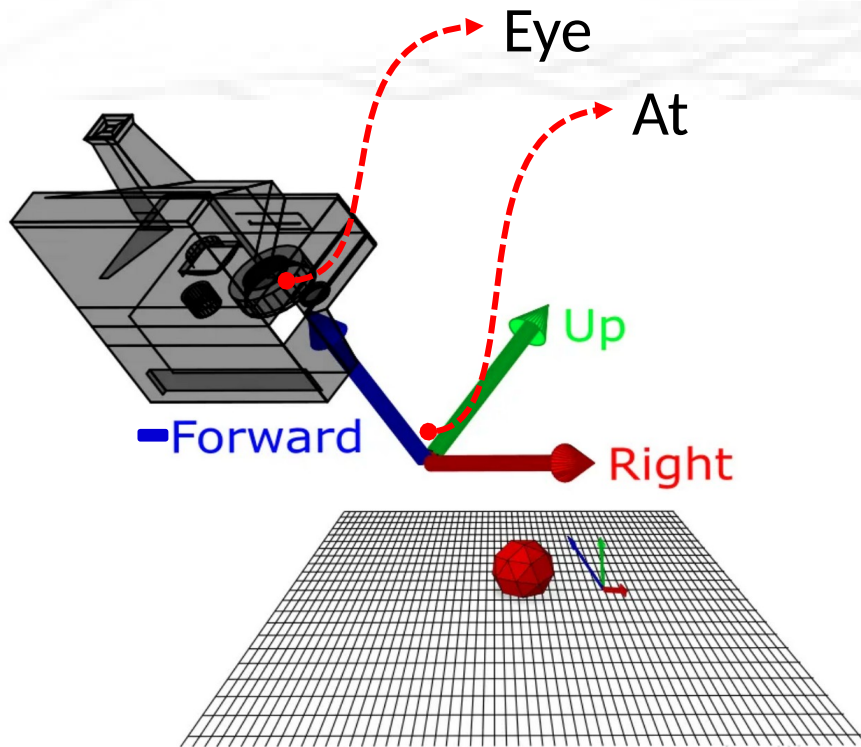


Camera Setup



$$F = \text{normalize}(At - Eye)$$

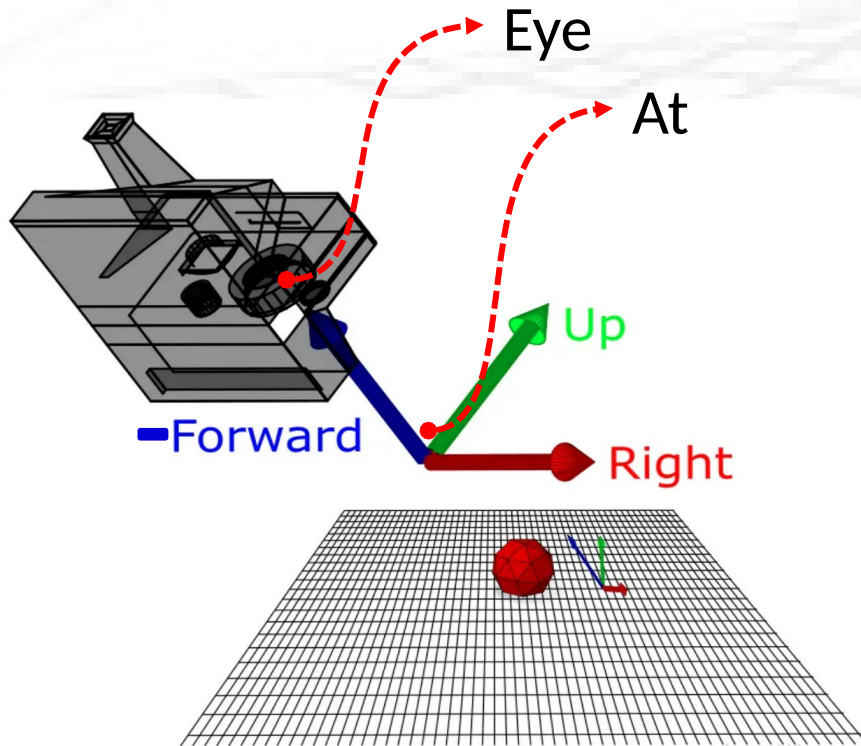
Camera Setup



$$F = \text{normalize}(At - Eye)$$

R

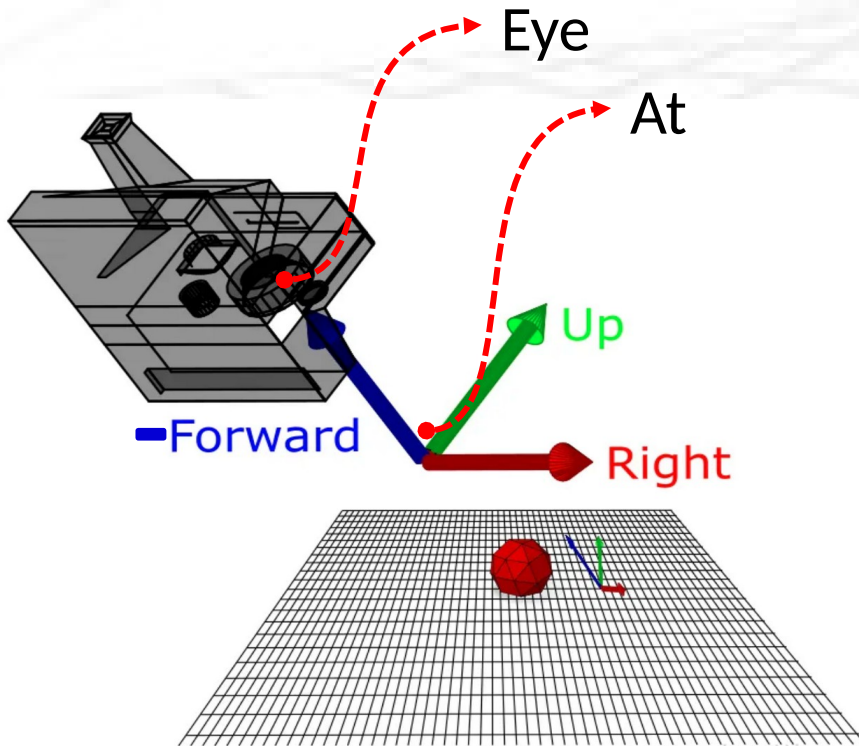
Camera Setup



$$F = \text{normalize}(At - Eye)$$

$$R = \begin{bmatrix} R_x & R_y & R_z \\ U_x & U_y & U_z \\ F_x & F_y & F_z \end{bmatrix}$$

Camera Setup



$$F = \text{normalize}(At - Eye)$$

$${}^c_2w = \begin{matrix} R \\ U \\ F \end{matrix} = \begin{bmatrix} R_x & R_y & R_z \\ U_x & U_y & U_z \\ F_x & F_y & F_z \end{bmatrix}$$

$$ray.o = eye$$

Code – camera.hpp

- This file has been changed, such that it no longer refers to classes deriving from `Image`
- Images are now created in the `main` program, passed to the `Renderer` and then eventually saved by the `main` program
- Please update this file either from `github` or from the elearning system

Code - perspective.[cpp,hpp]

- The `Perspective` class will implement a perspective camera, according to what has just been defined
- Initial files for this class are provided (elearning or github)

Code – Image.hpp , ImagePPM.[cpp,hpp]

- It is proposed that on an initial approach images are saved as .ppm files (this is one of the simplest bitmap image formats).
- Details and code on .ppm files can be found at:
<https://www.scratchapixel.com/lessons/digital-imaging/simple-image-manipulations/reading-writing-images.html>
- Initial files for these classes are provided (elearning or github)

[see next slide for further details]

Images and Tone Mapping

- Our renderer produces floating point values for each channel (R, G and B) of each pixel. These are positive real numbers
- The ppm file format only supports unsigned char values for each channel, in the set $\{0, 1, 2, \dots, 255\}$
- The operation of compressing the large values on an image to much smaller values, such that they can be displayed, is referred to as **Tone Mapping**
- `ImagePPM.cpp` includes the simplest (and less effective) tone mapper, such that your images can be saved. Everything should be OK if your lights accumulated power does not exceed 1.0 per channel.
- More on this later on the semester

Code – main.cpp , Renderer.hpp

- The main routine was edited to reflect the fact that Image is now created and accessed outside Camera

```
int main(int argc, const char * argv[]) {  
    //Load scene  
    //Create ImagePPM  
    //Create Perspective (camera)  
    Renderer myRender (cam, &scene, img);  
    myRender.Render();  
    // save the image  
    img->Save("MyImage.ppm");  
    return 0;  
}
```

- Initial files are provided (elearning or github)