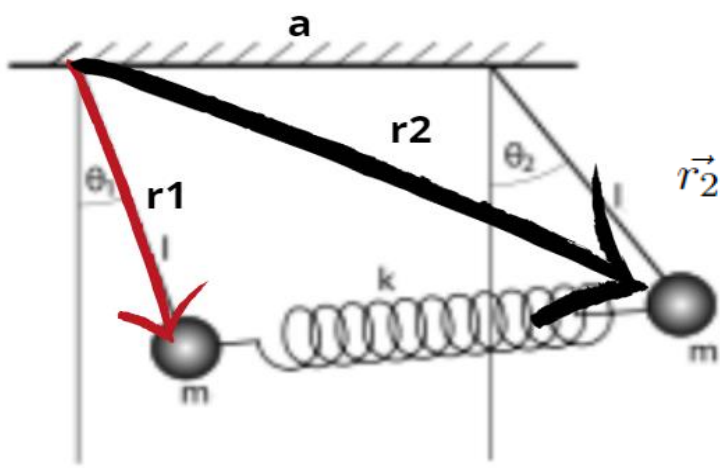


Análisis de un sistema de dos péndulos acoplados

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$$\vec{r}_1 = b \sin(\theta_1) \hat{i} - b \cos(\theta_1) \hat{j}$$

$$\vec{r}_2 = \vec{a} + \vec{b} = (a + b \sin(\theta_2)) \hat{i} - b \cos(\theta_2) \hat{j}$$

$$T = \frac{1}{2} m (\dot{r}_1^2 + \dot{r}_2^2) = \frac{1}{2} m b^2 (\dot{\theta}_1^2 + \dot{\theta}_2^2)$$

$$V = \frac{1}{2} k \Delta x^2 + mgb(1 - \cos \theta_1) + mgb(1 - \cos \theta_2)$$

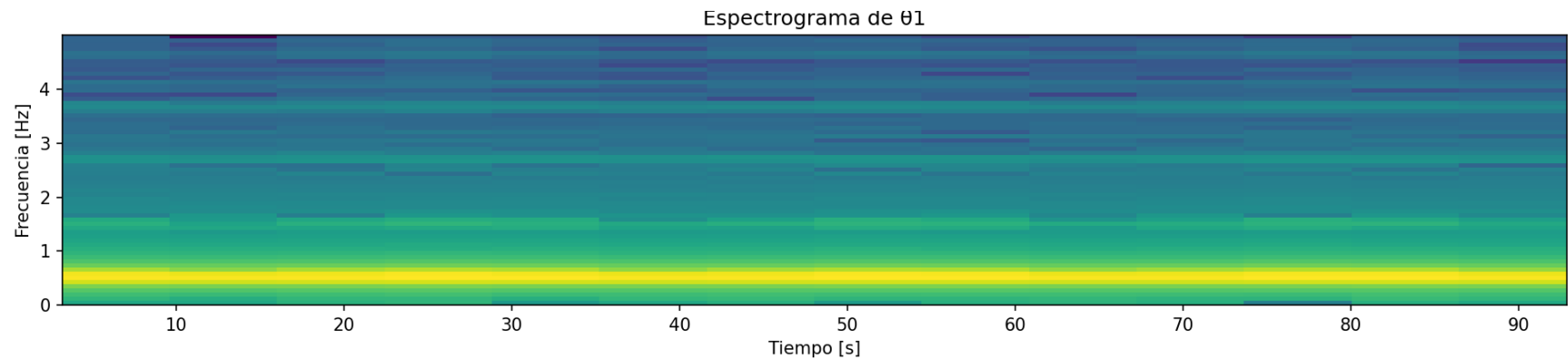
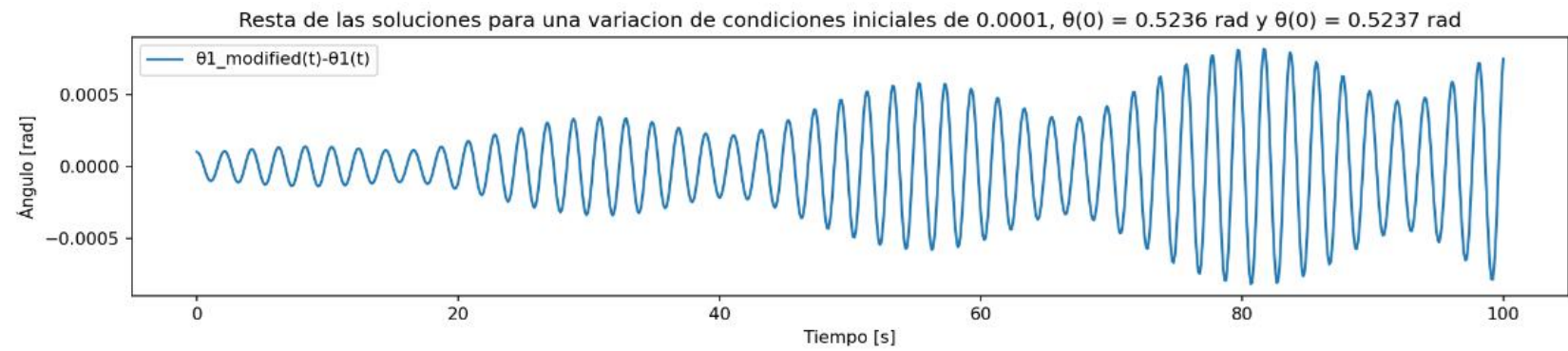
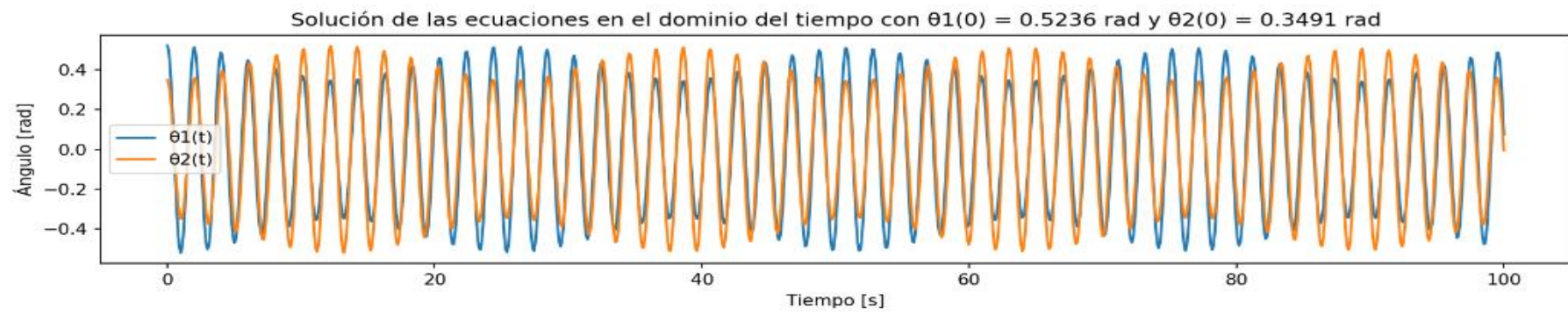
En donde nuestro Δx estará dado por:

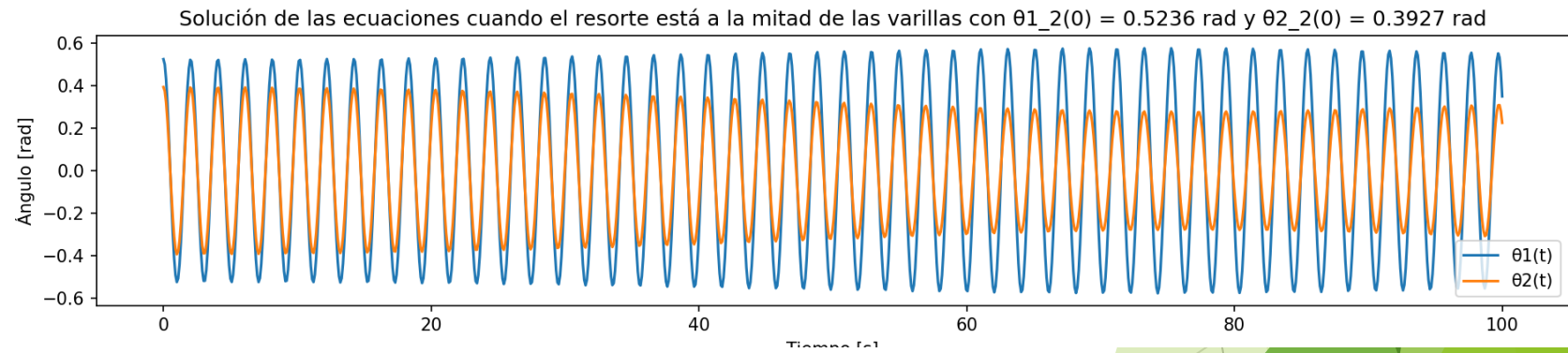
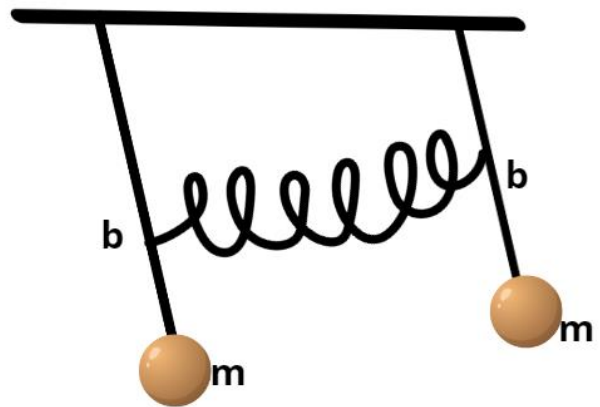
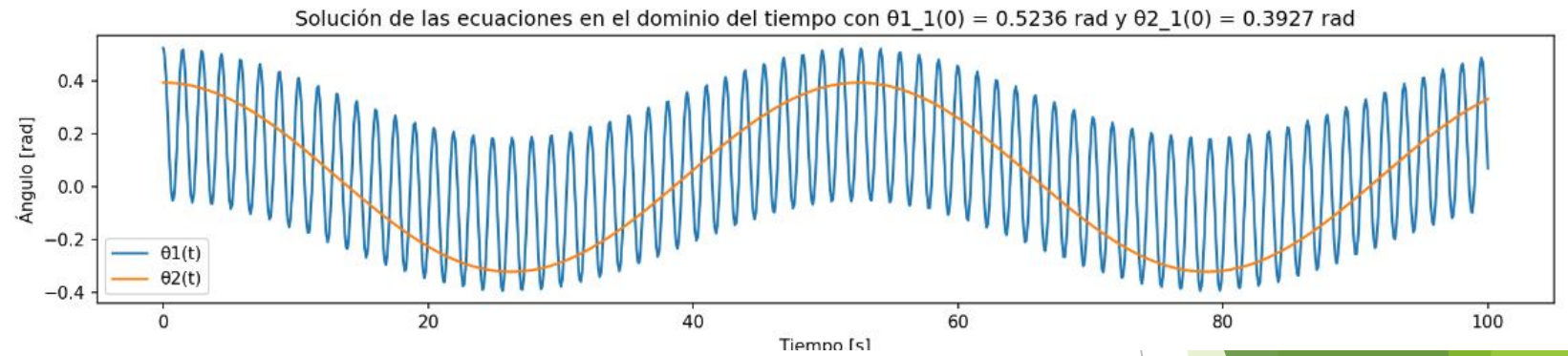
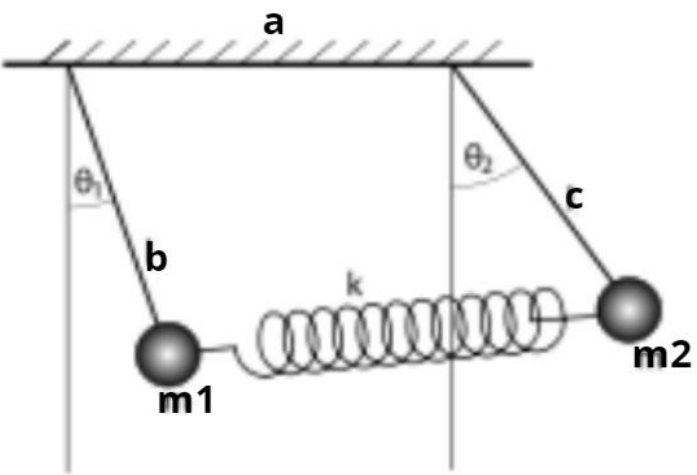
$$\Delta x = |\vec{r}_1 - \vec{r}_2| - a \longrightarrow \left((b \sin \theta_1 - a - b \sin \theta_2)^2 + (b \cos \theta_2 - b \cos \theta_1)^2 \right)^{1/2} - a$$

$$\mathcal{L} = \frac{1}{2} m b^2 (\dot{\theta}_1^2 + \dot{\theta}_2^2) - mgb(1 - \cos \theta_1) - mgb(1 - \cos \theta_2) - \frac{k}{2} \left((-2b^2(\cos(\theta_2 - \theta_1)) + 2b^2 + a^2 + 2ba(\sin \theta_2 - \sin \theta_1)) - 2a(-2b^2 \cos(\theta_2 - \theta_1) + 2b^2 + a^2 + 2ba(\sin \theta_2 - \sin \theta_1))^{1/2} \right) + a^2$$

$$\theta_1 \longrightarrow m b \ddot{\theta}_1 + mgb \sin \theta_1 - k \left(b^2 \sin(\theta_2 - \theta_1) + ba \cos \theta_1 \right) + \frac{ak}{2} \left(2b^2 + a^2 + 2ab(\sin \theta_2 - \sin \theta_1) - 2b^2 \cos(\theta_2 - \theta_1)^{-1/2} (2b^2 \sin(\theta_2 - \theta_1) + 2ba \cos \theta_1) \right) = 0$$

$$\theta_2 \longrightarrow m b \ddot{\theta}_2 + mgb \sin \theta_2 + k \left(b^2 \sin(\theta_2 - \theta_1) + ba \cos \theta_2 \right) - \frac{ka}{2} \left((2b^2 + a^2 + 2ba(\sin \theta_2 - \sin \theta_1) - 2b^2 \cos(\theta_2 - \theta_1)^{-1/2} (b^2 \sin(\theta_2 - \theta_1) + 2ba \cos \theta_2) \right) = 0$$





$$\theta_1 \Rightarrow 2mb\ddot{\theta}_1 + mgb\theta_1 - kb^2(\theta_2 - \theta_1) + ba + \frac{ak}{2}((2b^2 + a^2 +$$

$$2ab((\theta_2 - \theta_1) - 2b^2\theta_2\theta_1)^{-1/2}(2b^2(\theta_2 - \theta_1) + 2ba) = 0$$

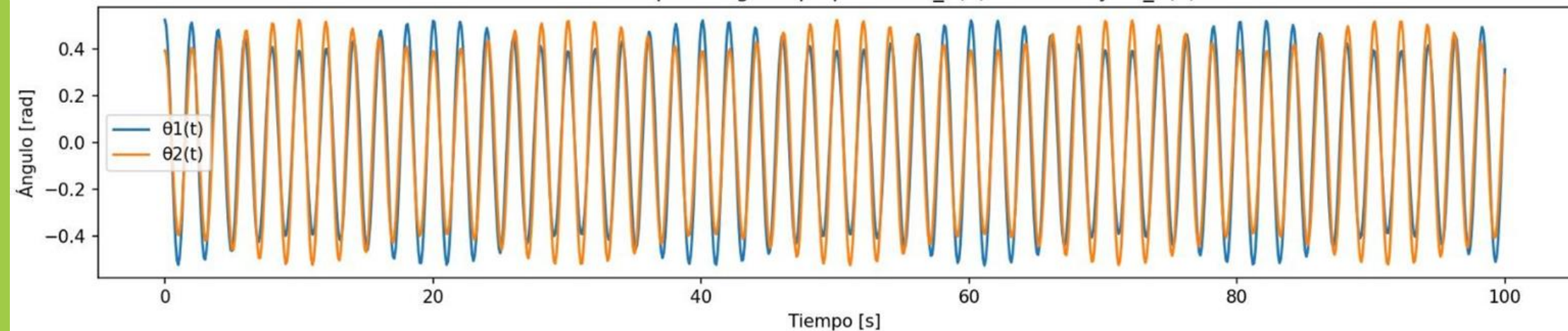
$$\theta_2 \Rightarrow mb\ddot{\theta}_2 + mgb\theta_2 + kb^2(\theta_2 - \theta_1) + ba - ka/2(2b^2 + a^2 +$$

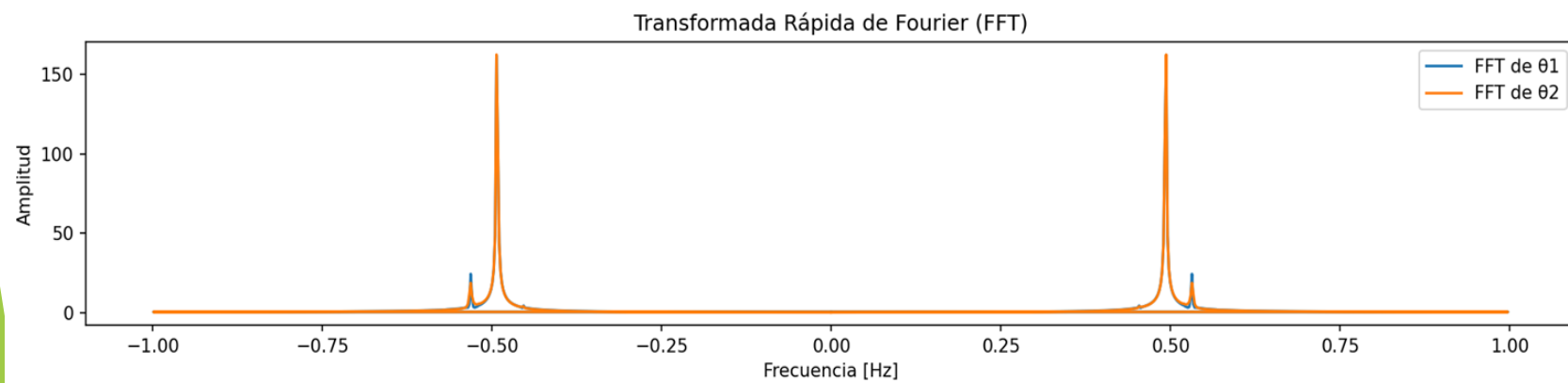
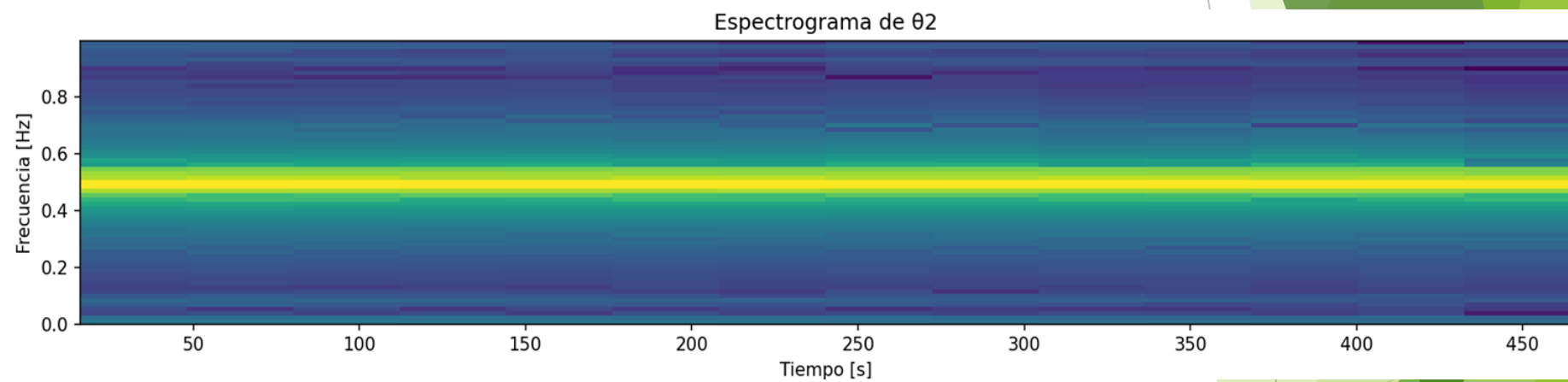
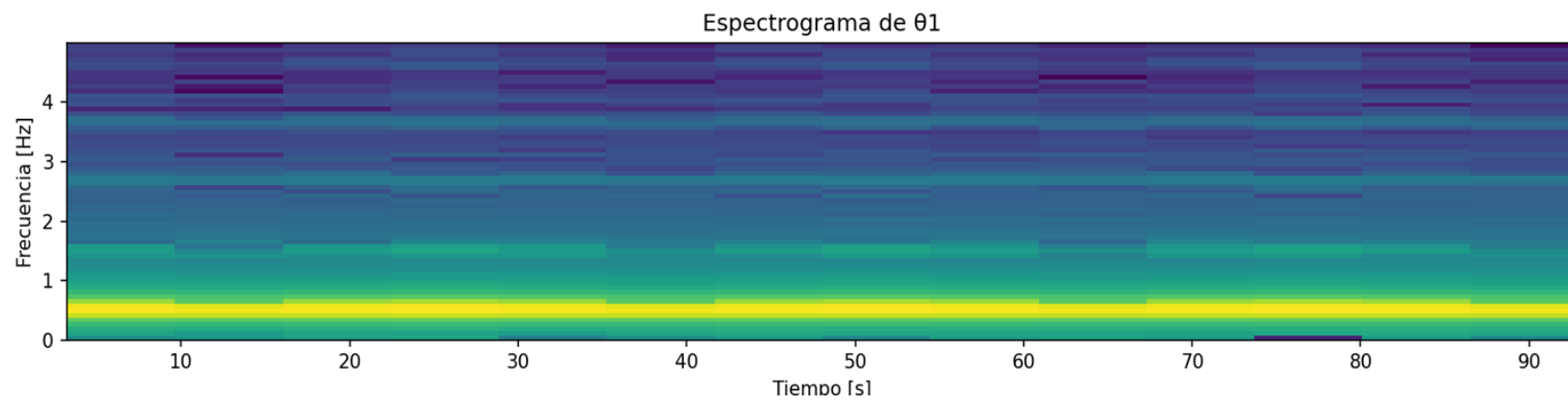
$$2ba(\theta_2 - \theta_1) - 2b^2\theta_2\theta_1)^{-1/2}(b^2(\theta_2 - \theta_1) + 2ba) = 0$$

$$\begin{aligned} \theta_1 \Rightarrow & m_1\ddot{\theta}_1b^2 + m_1gb\theta_1 - k(cb(\theta_2 - \theta_1) + ab) \\ & + ak/2(c^2 + a^2 + b^2 - 2cb\theta_2\theta_1) + 2a(c\theta_2 - b\theta_1)^{-1/2} \\ & (cb(\theta_2 - \theta_1) + ab) = 0 \end{aligned}$$

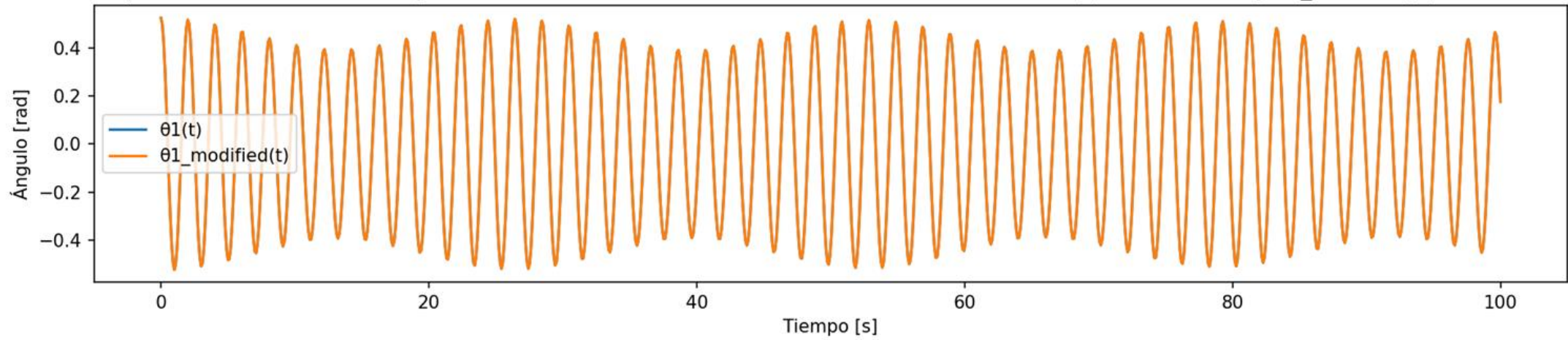
$$\begin{aligned} \theta_2 \Rightarrow & m_2\ddot{\theta}_2c^2 + m_2gc\theta_2 + k(cb(\theta_2 - \theta_1) + ac) \\ & - k/2a(c^2 + a^2 + b^2 - 2bc(\theta_2\theta_1) + 2a(c\theta_2 - b\theta_1)^{-1/2} \\ & (cb(\theta_2 - \theta_1) + ac) = 0 \end{aligned}$$

Solución de las ecuaciones para ángulos pequeños $\theta_{1_3}(0) = 0.3$ rad y $\theta_{2_3}(0) = 0.2$ rad





Comparacion de las soluciones para una variacion de condiciones iniciales de 0.0001 con $\theta_1(0) = 0.5236$ rad y $\theta_{1_modified}(0) = 0.5237$ rad



Resta de las soluciones para una variacion de condiciones iniciales de 0.0001, $\theta(0) = 0.5236$ rad y $\theta(0) = 0.5237$ rad

