

# Tensor Algebra

University Federal do Ceará

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## Homework 5

### Kronecker Product Singular Value Decomposition (KPSVD)

#### 1 Problem 1

On practice 04 we implement the LS-KF (Least Square Kronecker Factorization) algorithm, now we will go to implement a generalization of that. Let

$$\mathbf{X} = \begin{pmatrix} \mathbf{X}_{1,1} & \cdots & \mathbf{X}_{1,c_2} \\ \vdots & \ddots & \vdots \\ \mathbf{X}_{r_2,1} & \cdots & \mathbf{X}_{r_2,c_2} \end{pmatrix}, \mathbf{X}_{i_2,j_2} \in \mathbb{R}^{r_1 \times c_1}.$$

Implement the KPSVD for the matrix  $\mathbf{X}$  by computing  $\sigma_k$ ,  $\mathbf{U}_k$ ,  $\mathbf{V}_k$  such that

$$\mathbf{X} = \sum_{k=1}^{r_{KP}} \sigma_k \mathbf{U}_k \otimes \mathbf{V}_k$$

#### Results

The first step of the Solution is to implement a method for transforming a given matrix  $\mathbf{X} \in \mathbb{C}^{MP \times NQ}$  such that  $\mathbf{X} = \mathbf{A} \otimes \mathbf{B}$  into the reshaped format  $\tilde{\mathbf{X}} \in \mathbb{C}^{PQ \times MN}$  such that  $\mathbf{X} = \text{vec}(\mathbf{B})\text{vec}(\mathbf{A})^T$ . This matrix format is rank-1. Listing 1 contains this method.

```
1 def X_tilde_reshape(X, h_splits, v_splits):
2     """
3     This method reshapes an A_kron_B matrix
4     into a vec(A)vec(B)^T shaped matrix
5
6     Inputs:
7         X: Matrix to be reshaped
8         h_splits: Number of horizontal splits
9         v_splits: Number of vertical splits
10
11     Outputs:
12         X_til: X reshaped as vec(A)vec(B)^T
13     """
14
15     X_til = []
16
17     for n_matrix in np.hsplit(X, h_splits):
18         for a_B in np.vsplit(n_matrix, v_splits):
19             X_til.append(a_B.T.reshape(1, -1)[0])
20
21     X_til = np.array(X_til).T
22
23     return X_til
```

Listing 1:  $\mathbf{X} \rightarrow \tilde{\mathbf{X}}$  method

This method takes in an input matrix  $\mathbf{X}$ , the number of horizontal splits and the number of vertical splits. These split numbers refer to the amount of "block" matrices that  $\mathbf{X}$  will get divided into, so that each of these blocks gets vectorized in the final  $\tilde{\mathbf{X}}$  form. This is essentially the  $(r_2, c_2)$  shape of  $\mathbf{A}$  when  $\mathbf{X} = \mathbf{A} \otimes \mathbf{B}$ .

```

1 def KPSVD(X, r1, c1, k):
2     '''
3     Calculates the Kronecker Product
4     Singular Value Decompositon
5
6     Inputs:
7         X: Input matrix
8         r1: Number of rows of KP block matrix
9         c1: Number of columns of KP block matrix
10        k: Desired rank of output
11
12    Outputs:
13        result: Resulting matrix made up of
14              Sigma*kron(U, Vh)
15
16    '''
17    v_splits = int(X.shape[0]/r1)
18    h_splits = int(X.shape[1]/c1)
19    X_til = X_tilde_reshape(X, h_splits, v_splits)
20
21    U, S, Vh = svd(X_til)
22
23    Rl_matrices = []
24
25    for i in range(k):
26        Rl_matrices.append(
27            S[i]*kron(Vh[i, :].reshape(h_splits, v_splits).T, U[:, i].reshape(c1, r1).T)
28        )
29
30    result = np.sum(np.array(Rl_matrices), axis=0)
31
32    return result

```

Listing 2: Calculation of KPSVD

The KPSVD method consists of calculating the SVD of  $\tilde{\mathbf{X}}$

$$\tilde{\mathbf{X}} = \mathbf{U}\Sigma\mathbf{V}^H = \sum_{k=1}^{r_{KP}} \sigma_k \mathbf{u}_k \mathbf{v}_k^H$$

Then, for  $k \in \{1, \dots, r_{kp}\}$ ,  $\mathbf{U}_k$  and  $\mathbf{V}_k$  can be defined as

$$\begin{aligned} \mathbf{U}_k &= \text{unvec}_{M \times N} \{v_k^T\} \\ \mathbf{V}_k &= \text{unvec}_{P \times Q} \{u_k\} \end{aligned}$$

The code in Listing 2 applies this method. It takes an input matrix  $\mathbf{X}$ , a shape  $(r_1, c_1)$  corresponding to the size of the "block" matrix in  $\mathbf{X}$  (size of  $\mathbf{B}$  in  $\mathbf{X} = \mathbf{A} \otimes \mathbf{B}$ ), and  $k$  which is the nearest rank- $r$  such that  $r \leq r_{kp}$ . The result returned is the summation  $\sigma_1 \mathbf{U}_1 \otimes \mathbf{V}_1 + \sigma_2 \mathbf{U}_2 \otimes \mathbf{V}_2 + \dots + \sigma_k \mathbf{U}_k \otimes \mathbf{V}_k$ .

```

1 np.random.seed(0) # set a seed so that random matrices fixed
2
3 r2, c2 = 3, 3
4 r1, c1 = 3, 3
5
6 A = randn(r2, c2)
7 B = randn(r1, c1)
8
9 X = kron(A, B)
10
11 norm(X - KPSVD(X, r1, c1, 1))

```

Listing 3: Test for KPSVD

The code in Listing 3 defines a simple test for the KPSVD function using  $\mathbf{X} \in \mathbb{R}^{9 \times 9}$  such that  $\mathbf{X} = \mathbf{A} \otimes \mathbf{B}$ , being  $\mathbf{A} \in \mathbb{R}^{3 \times 3}$  and  $\mathbf{B} \in \mathbb{R}^{3 \times 3}$ . Since  $\tilde{\mathbf{X}}$  is rank-1 for a Kronecker Product matrix  $\mathbf{X}$ , considering  $r = 1$  for the KPSVD should return a matrix equals to  $\mathbf{X}$ . The `norm()` indicated in the code returns 1.979e-15, which is sufficiently close to zero and such a small error is most likely due to data type castings or irrelevant numerical errors.

## 2 Problem 2

At the above problem, set  $r_1 = r_2 = c_1 = c_2 = 3$  and choose  $\mathbf{A}_{i,j} = \text{rand}(r_1, c_1)$ ,  $1 \leq i \leq r_2$ ,  $1 \leq j \leq c_2$ . Then compute the KPSVD and  $r_{KP}$  of  $\mathbf{A}$  by using your KPSVD prototype function. Consider  $r \leq r_{KP}$ . Compute the nearest rank- $r$  for the matrix  $\mathbf{A}$ .

### Results

The code in Listing 4 creates  $\mathbf{A} \in \mathbb{R}^{9 \times 9}$ . The value of  $r_{KP}$  calculated for  $\tilde{\mathbf{X}}$  is 9, which means that it is full-rank, and the nearest rank- $r$  matrix for  $\mathbf{A}$  is in  $\mathbb{R}^{9 \times 9}$ . This behavior is much different than with a Kronecker Product matrix, which is expected, since a random number matrix is not necessarily rank-1 or even low-rank.

```

1 np.random.seed(0) # set a seed so that random matrices fixed
2
3 r2, c2 = 3, 3
4 r1, c1 = 3, 3
5
6 A = randn(r1*r2, c1*c2)
7 R_kp = matrix_rank(X_tilde_reshape(A, c2, r2))
8
9 errors = []
10 for i in range(1, R_kp):
11     errors.append(norm(A - KPSVD(A, r1, c1, i))**2)

```

Listing 4: Problem 2 code

The loop in line 10 performs a squared error calculation for each rank- $r$  decomposition of  $\mathbf{A}$ . The results can be seen in graph 1. Expectedly, there is a large error for a rank-1 decomposition of a full-rank matrix, and the error steadily decreases as higher rank matrices are used.

Figure 1: Squared Error vs nearest rank-r matrix

