

# TIP8419 - Tensor Algebra

## Homework 9

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### Multidimensional Least-Squares Kronecker Factorization (MLS-KronF)

On practice 4 we implement the LS-KronF (Least Square Kronecker Factorization) algorithm, now we will go to implement the MLS-KronF (Multidimensional Least Square Kronecker Factorization) algorithm. Then, Let  $\mathbf{X} \approx \mathbf{A}^{(1)} \otimes \mathbf{A}^{(2)} \dots \otimes \mathbf{A}^{(N)} \in \mathbb{C}^{I_1 I_2 \dots I_N \times J_1 J_2 \dots J_N}$  be a matrix composed by Kronecker product of  $N$  matrices  $\mathbf{A}^{(n)} \in \mathbb{C}^{I_n \times J_n}$ , with  $n = 1, 2, \dots, N$ . For  $N = 3$  and  $I_n$  and  $J_n$  arbitrary implement the MLS-KronF for that estimate  $\mathbf{A}^{(1)}, \mathbf{A}^{(2)}$  and  $\mathbf{A}^{(3)}$  by solving the following problem.

$$(\hat{\mathbf{A}}^{(1)}, \hat{\mathbf{A}}^{(2)}, \hat{\mathbf{A}}^{(3)}) = \min_{\mathbf{A}, \mathbf{B}} \|\mathbf{X} - \mathbf{A}^{(1)} \otimes \mathbf{A}^{(2)} \otimes \mathbf{A}^{(3)}\|_F^2.$$

Compare the estimate matrices  $\hat{\mathbf{A}}^{(1)}, \hat{\mathbf{A}}^{(2)}$  and  $\hat{\mathbf{A}}^{(3)}$  with the original ones. What can you conclude? Explain the results.

Hint: Use the file “kronf\_matrix\_3D.mat” to validate your result.

**Problem 1** Assuming 1000 Monte Carlo experiments, generate  $\mathbf{X}_0 = \mathbf{A} \otimes \mathbf{B} \otimes \mathbf{C} \in \mathbb{C}^{I_1 I_2 I_3 \times J_1 J_2 J_3}$ , for randomly chosen  $\mathbf{A} \in \mathbb{C}^{I_1 \times J_1}$ ,  $\mathbf{B} \in \mathbb{C}^{I_2 \times J_2}$  and  $\mathbf{C} \in \mathbb{C}^{I_3 \times J_3}$ , whose elements are drawn from a normal distribution. Let  $\mathbf{X} = \mathbf{X}_0 + \alpha \mathbf{V}$  be a noisy version of  $\mathbf{X}_0$ , where  $\mathbf{V}$  is the additive noise term, whose elements are drawn from a normal distribution. The parameter  $\alpha$  controls the power (variance) of the noise term, and is defined as a function of the signal to noise ratio (SNR), in dB, as follows

$$\text{SNR}_{\text{dB}} = 10 \log_{10} \left( \frac{\|\mathbf{X}_0\|_F^2}{\|\alpha \mathbf{V}\|_F^2} \right). \quad (1)$$

Assuming the SNR range  $[0, 5, 10, 15, 20, 25, 30]$  dB, find the estimates  $\hat{\mathbf{A}}, \hat{\mathbf{B}}$  and  $\hat{\mathbf{C}}$  obtained with the MLS-KRF algorithm for the configurations  $I_1 = J_1 = 2, I_2 = J_2 = 3$  and  $I_3 = J_3 = 4$ . Let us define the normalized mean square error (NMSE) measure as follows

$$\text{NMSE}(\mathbf{X}_0) = \frac{1}{1000} \sum_{i=1}^{1000} \frac{\|\hat{\mathbf{X}}_0(i) - \mathbf{X}_0(i)\|_F^2}{\|\mathbf{X}_0(i)\|_F^2}, \quad (2)$$

where  $\mathbf{X}_0(i)$  e  $\hat{\mathbf{X}}_0(i)$  represent the original data matrix and the reconstructed one at the  $i$ th experiment, respectively. For each SNR value and configuration, plot the NMSE vs. SNR curve. Discuss the obtained results.

Note: For a given SNR (dB), the parameter  $\alpha$  to be used in your experiment is determined from equation (1).