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# Mechatronics

Week 1 Day 2



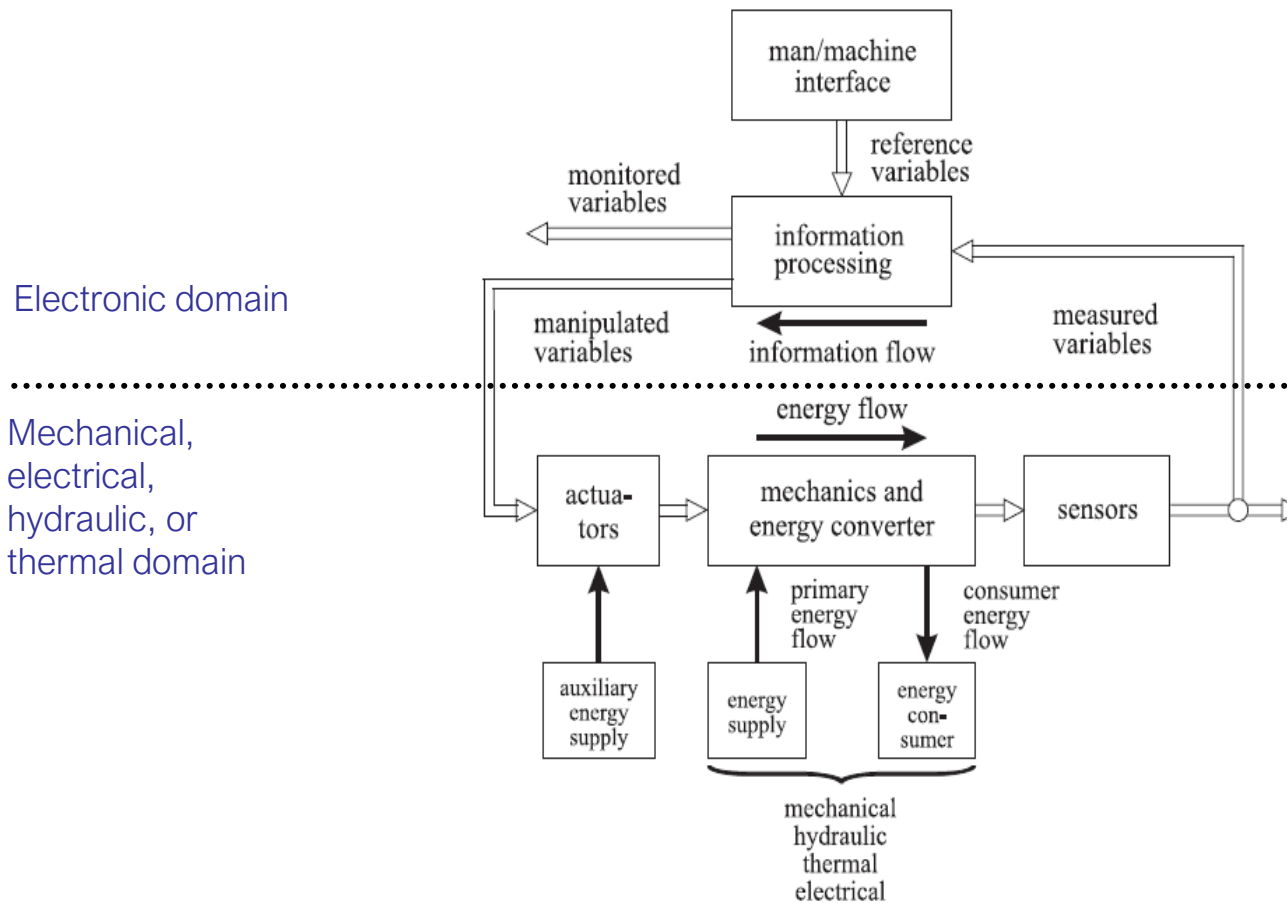
# Sensors, Actuators, and Systems engineering

Learning outcomes:

- Identify components of a mechatronics system
- Familiarize with sensors and actuators while appreciating the concepts of a system, inputs, and outputs
- Describe the concept of systems engineering
- Identify role of systems engineering in the design of mechatronic systems



# Components of a Mechatronics System



The figure is taken from (Isermann, 2008).



# Defining the concept of a system, inputs, and outputs

# Systems, inputs, and outputs

## What is a system?

- i. A combination of various components that act together to perform a specific objective.
- ii. An entity separable from the rest of the universe (referred to as its environment) through a physical or conceptual boundary.

Some examples of systems are:

- The human body.
- A robotic arm.
- The economy of a country.





# Systems, inputs, and outputs

How does the system interact with environment?



# Systems, inputs, and outputs

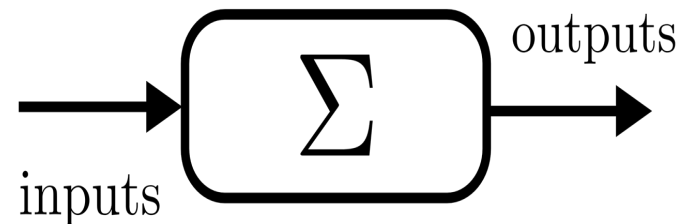
How does the system interact with environment?

## Inputs:

Variables that are not directly dependent on what happens in the system.

## Outputs:

Variables generated by the system as it interacts with its environment

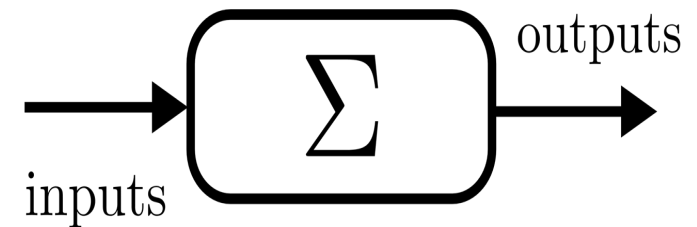


# Systems, inputs, and outputs

How does the system interact with environment?



A human body is a system equipped with capabilities of sight, voice, hearing, receiving or sending electrical impulses from the brain...



Which are inputs and which are outputs?





# Introduction to Sensors and Actuators



# Sensors and actuators

## Sensors:

- Device that measures the output variable or response
- Device that when exposed to physical phenomena produces a **proportional and more suitable signal**

Example: Thermocouple.

**Physical phenomena:** temperature

**Measured signal:** voltage

- Generally require calibration
- Active or passive (power source or not)

# Sensors and actuators

## Actuators:

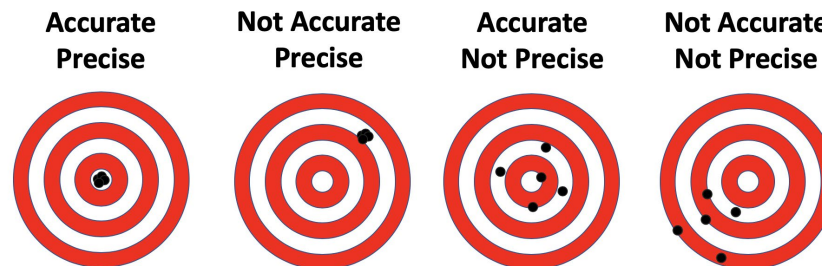
- Device that produces **input** (action) to the system according to *control signal*.
- Device that **accepts control command** (mostly electrical signal) and acts to produce a desirable and specified change in the physical system by generating force, motion, heat, flow...

Actuators are used in conjunction with a power supply and coupling mechanism.

# Sensors and actuators

Sensor and actuator selection criterion, some **definitions**:

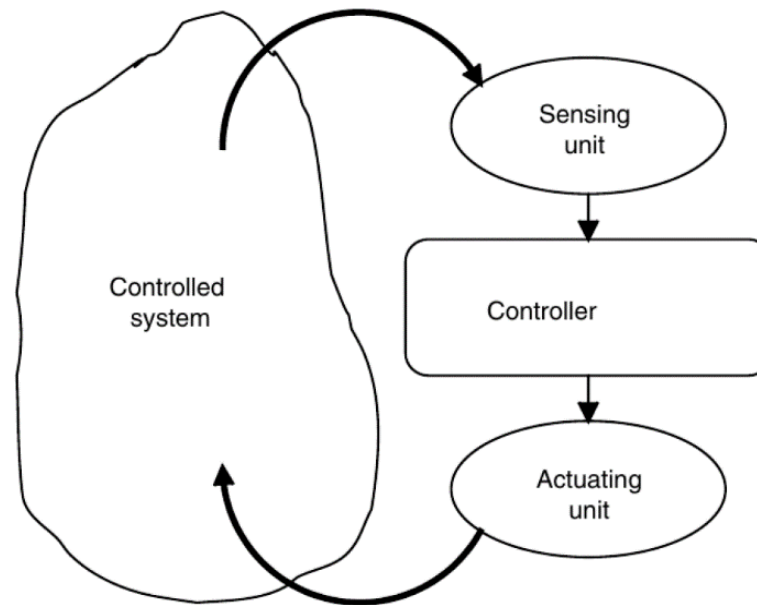
- **Response time**: time lag between input and output
- **Sensitivity**: ratio of change in output to unit change of input
- **Resolution**: smallest change the sensor can differentiate
- **Accuracy**: difference between measured and true value
- **Precision**: ability to repeatedly reproduce a given accuracy



# Sensors and actuators

## Sensors selection criteria:

- Response time
- Sensitivity
- Accuracy
- Precision
- Resolution



## Actuators selection criteria:

- Power requirement
- Accuracy
- Range of motion
- Resolution
- Durability



# Introduction to Coupling Devices

# Coupling devices

Devices use for conversion from one physical domain to another.  
For example, from mechanical to electrical (and vice versa) or from fluid to mechanical (and vice versa)

- They involve **energy conversion** from a type to another
- If very small amount of energy is converted, they are referred to as **signal-converting transducers**
- Usually couple electrical domain to and from physical domain (mechanical-fluid-thermal)
- **Actuators and sensors** are considered **coupling devices**



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# Actuators



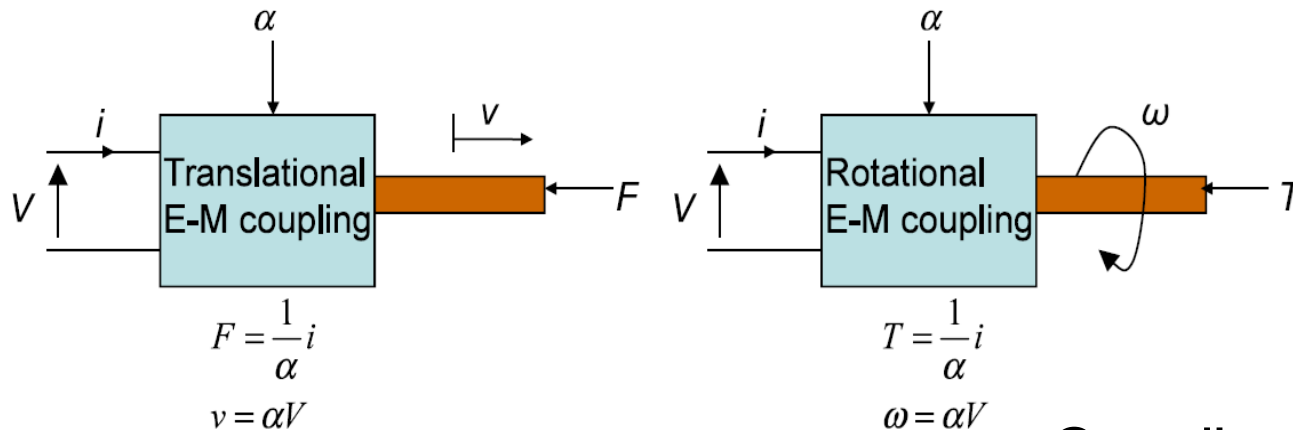


# Electro-mechanical coupling as an actuator

- Coupling between **mechanical and electrical** elements is provided through a **magnetic field**
- The magnetic field can be generated by inductors (with coils), or by permanent magnets
- **Motor:** Magnetic field makes mechanical side move
- **Generator:** Mechanical movement changes magnetic field which makes current flow
- **Lorentz law** is the basis for this

# Electro-mechanical coupling as an actuator

Diagram of **ideal (power in= power out)** electromechanical coupling:



Coupling:

- Electrical power:  $V \cdot i$
- Mech translational power:  $F \cdot v$
- Mech rotational power:  $T \cdot \omega$

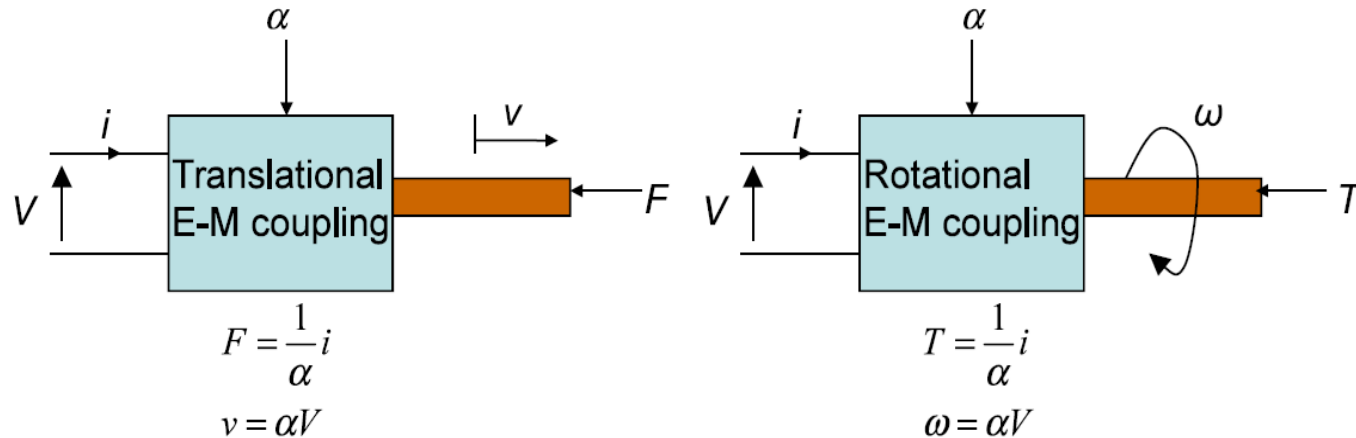


$$V \cdot i = F \cdot v$$

or

$$V \cdot i = T \cdot \omega$$

# Electro-mechanical coupling as an actuator



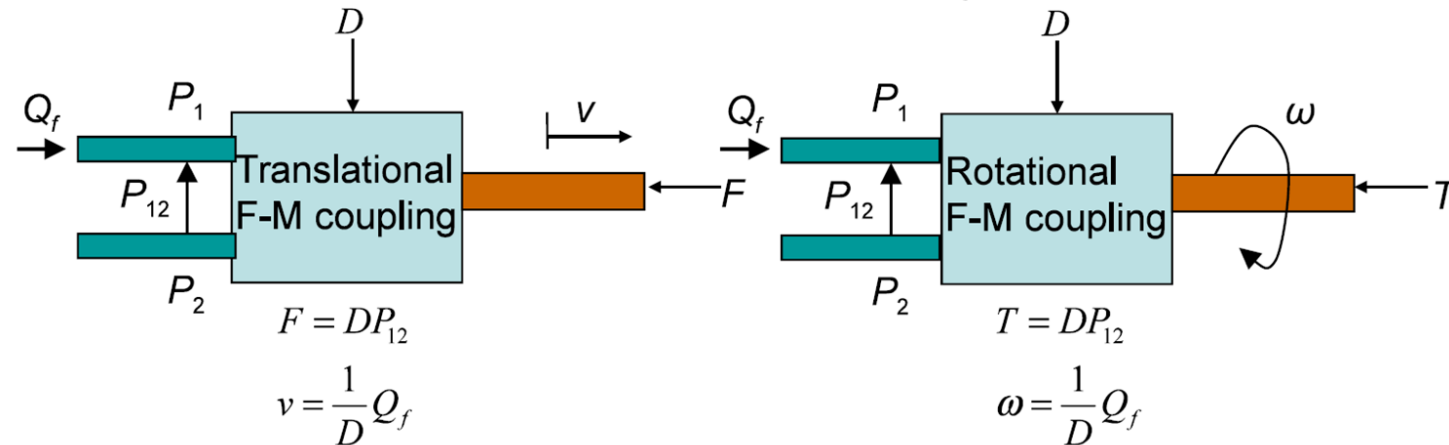
Using above convention for arrows:

- **Positive power** implies the coupling acts as a **motor**.
- **Negative power** makes the coupling a **generator**.

In DC motor, constant  $1/\alpha$  is referred as **torque constant**.  
Constant  $\alpha$  is referred to as **speed constant**.

# Fluid-mechanical coupling as an actuator

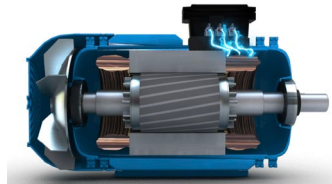
Diagram of **ideal** fluid-mechanical coupling:



- Constant  $D$  is interpreted as the amount of displaced volume per displacement of output shaft.  $Q_f = Dv$
- Model only **valid** when **compressibility** of the fluid is **negligible**
- **Coupling** based on static fluid pressure applied to moving parts
- Devices called **hydrostatic energy converters**

# Electro mechanical VS fluid-mechanical coupling

## Electric motor:



Electro-mechanical coupling

Electric energy translated to mechanical rotational

- Lower forces
- Smaller (Most compact size together with piezo-electric actuators)

## Hydraulic actuator:



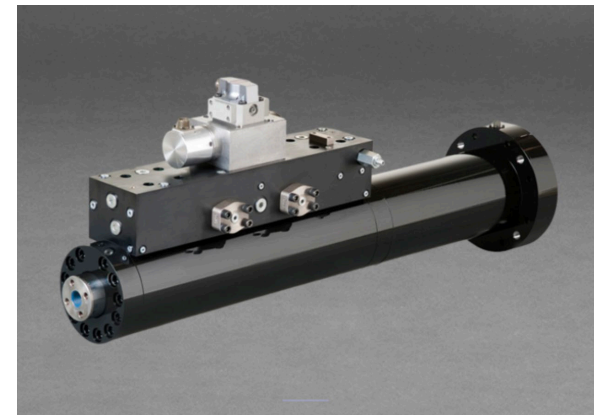
Fluid-mechanical coupling

Hydraulic power translated to mechanical rotational

- Higher forces
- Require pressure sources and/or accumulators
- Bigger

# Electrohydraulic servo actuator

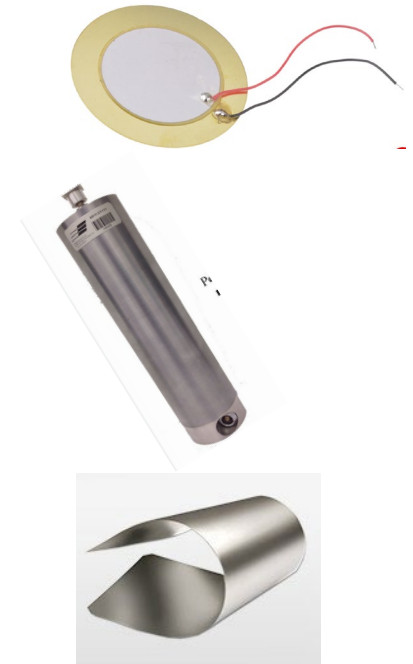
- Used to control powerful hydraulic cylinders with a small electrical signal
- **Controls** how **hydraulic fluid** is sent to an actuator
- Used in aerospace and robotic systems
- Servo valves can provide precise control of position, velocity, pressure and force



Hydraulic: a liquid moving in a confined space under pressure

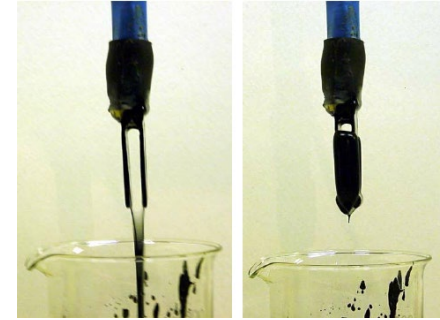
# Smart material actuators

- **Piezoelectric and electrostrictive actuators:** convert electrical signal into physical displacement.
- **Magnetostrictive actuators:** convert electromagnetic energy into mechanical energy. Example material: Terfenol-D
- **Shape memory alloys:** electrically powered, can enable movement of soft robots. Example: copper-aluminium-nickel



# Smart material actuators

- **Electrorheological fluids:** change of viscosity due to electrical field.  
Example: cornflour + vegetable oil
- **Ultrasonic piezo-motors:** create rotary or linear motion by electrical excitation of piezo elements.  
Example material: lead zirconate titanate



Uncharged vs charged







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# Sensors

# Sensor classification

Classified according to measurement objectives

## Temperature

(Thermocouple,  
Thermistor, RTD,  
thermo-diode,  
infrared...)



**Thermocouple:**  
temperature change  
measured as change  
on resistance

## Light

(photoresistor,  
photodiode,  
phototransistors,  
photoconductors,  
charge coupled diodes)

## Linear/ Rotational

LVDT/RVDT, optical  
encoder, tachometer,  
hall-effect sensor,  
capacitive transducer...



**LVDT:**  
measure linear  
displacement as  
electrical current



**Photoresistor:**  
decrease  
resistance  
with light

# Sensor classification

Classified according to measurement objectives

## Force, torque, pressure

Strain gauge  
 dynamometer,  
 piezoelectric load cell,  
 tactile sensor, ultrasonic  
 stress sensor...



**Strain gauge:**  
 measure strain on  
 object from electrical  
 conductance

## Flow

(Pitot tube, orifice plate,  
 flow nozzle, rotameter,  
 turbine flow meter...)



**Pitot tube:**  
 measure difference  
 between stagnation  
 and static pressure

## Acceleration

Seismic accelerometer, piezoelectric  
 accelerometer

### Seismic accelerometer

charge is generated proportional  
 to the vibration of machine or  
 structure



## Proximity

(inductance, Eddy  
 current, hall effect...)



**Inductive sensor**



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# Systems Engineering



# Systems Engineering

An **interdisciplinary** approach and means to enable the successful realization of (complex) systems <sup>1</sup>

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<sup>1</sup>Systems Engineering Handbook, version 2a. INCOSE. 2004.

# Systems Engineering

An **interdisciplinary** approach and means to enable the successful realization of (complex) systems <sup>1</sup>

- Focuses on defining **user demands** and **functional requirements** early in the design cycle

Remember previous lecture... Design of Artificial Limb

- **User demands:** walk on two legs, no pain...
- **Functional requirements:** nervous system actuate leg, lifetime...

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# Systems Engineering

An **interdisciplinary** approach and means to enable the successful realization of (complex) systems <sup>1</sup>

- Focuses on defining **user demands** and **functional requirements** early in the design cycle
- **Integrates** several disciplines and specialized groups into a team effort

Remember previous lecture... Design of Artificial Limb

**Integrates** mechanical, electrical, biomedical engineers, robotics experts, doctors...

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# Systems Engineering

An **interdisciplinary** approach and means to enable the successful realization of (complex) systems <sup>1</sup>

- Focuses on defining **user demands** and **functional requirements** early in the design cycle
- **Integrates** several disciplines and specialized groups into a team effort
- Considers both the **business** and **technical** needs of the customers

Remember previous lecture... Design of Artificial Limb

- **Business:** market, cost, regulatory compliance
- **Technical:** biomechanics, ergonomics, safety, weight...

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# Main Ideas Systems Engineering

- Understand the **whole problem** before trying to solve it



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- Translate the problem into **measurable requirements**



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- Make sure the **total system life cycle** is being considered. Birth to death concept extends to maintenance, replacement and decommission.
- Make sure to **test** the **total system** before delivering it
- **Document** everything



# Main Issues of Design

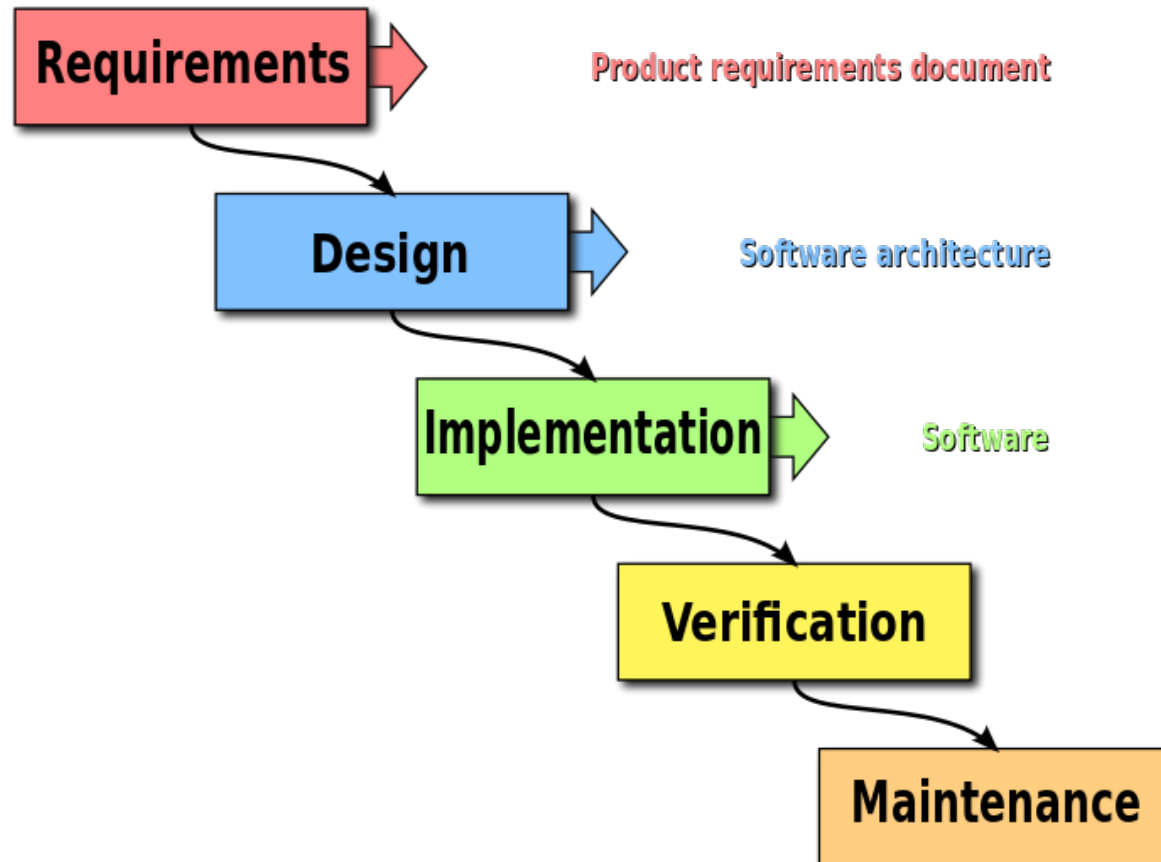
**Client** knows *partially or informally* what they want.

but

**Designer requires** *detailed and complete* specifications.



# Classical waterfall design approach





# Classical waterfall design approach

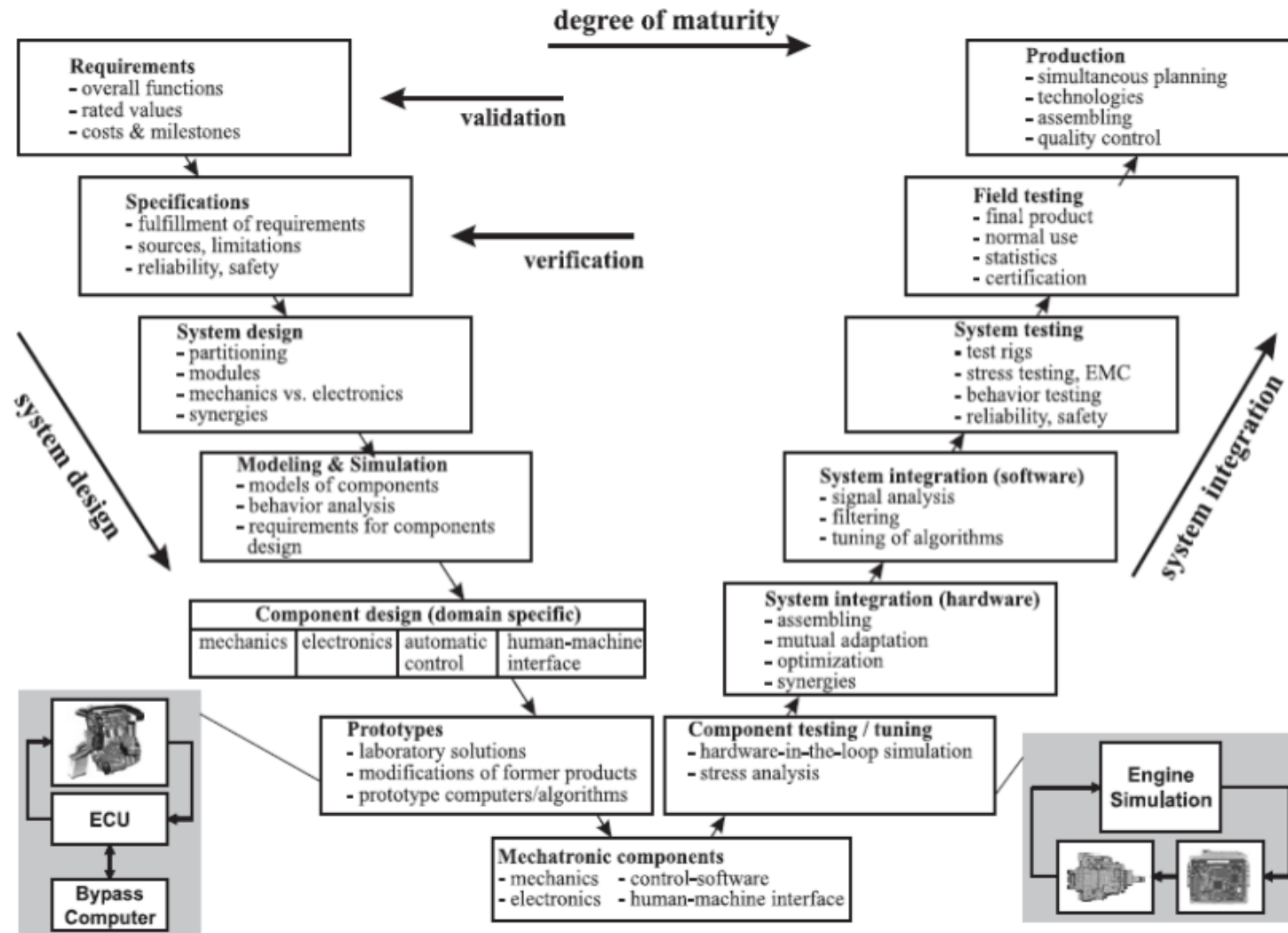
## Advantages:

- ✓ Natural, sequential Flow
- ✓ Simple structure
- ✓ Well identified schedules
- ✓ Easily explainable phases
- ✓ Easily identifiable milestones
- ✓ Suitable for projects with well established goals and clear technological needs

## Disadvantages:

- Clients usually do not have clear picture of their wants
- Distinct phases of the design may be unaware of needs of others
- Difficult to foresee future issues
- Major costs for late redesign and redevelopment

# Improved model: V-model of System Engineering Process





# V-model of System Engineering Process

Two key elements:

1. **Validation:** does the system/product/service **meet the needs** for customer or stakeholder?
2. **Verification:** are imposed requirements/specifications **fulfilled**?



# Mechatronics and its relationship with systems Engineering



# Design challenges in mechatronics

- Mechatronics **combines** all fields of **mechanical and electrical** engineering



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# Design challenges in mechatronics

- Mechatronics **combines** all fields of **mechanical and electrical** engineering
- Mechatronics systems are **employed in various fields**, including power systems, transportation, optical telecommunications and biomedical engineering
- **Preliminary design** of mechatronic systems is an extremely important step in the development process of multi-disciplinary products
- Great challenge lies in the **multidisciplinary optimization** of a complete system with various physical phenomena related to interacting heterogeneous subsystems





# Mechatronics...

- is highly **interdisciplinary**



# Mechatronics...

- is highly interdisciplinary
- is interactive



# Mechatronics...

- is highly **interdisciplinary**
- is **interactive**
- conveys expertise of **several fields**, each of which has its own set of 'toolboxes'



# Mechatronics...

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- conveys expertise of **several fields**, each of which has its own set of 'toolboxes'
- requires a **well defined** set of user and functional requirements and design **parameters**



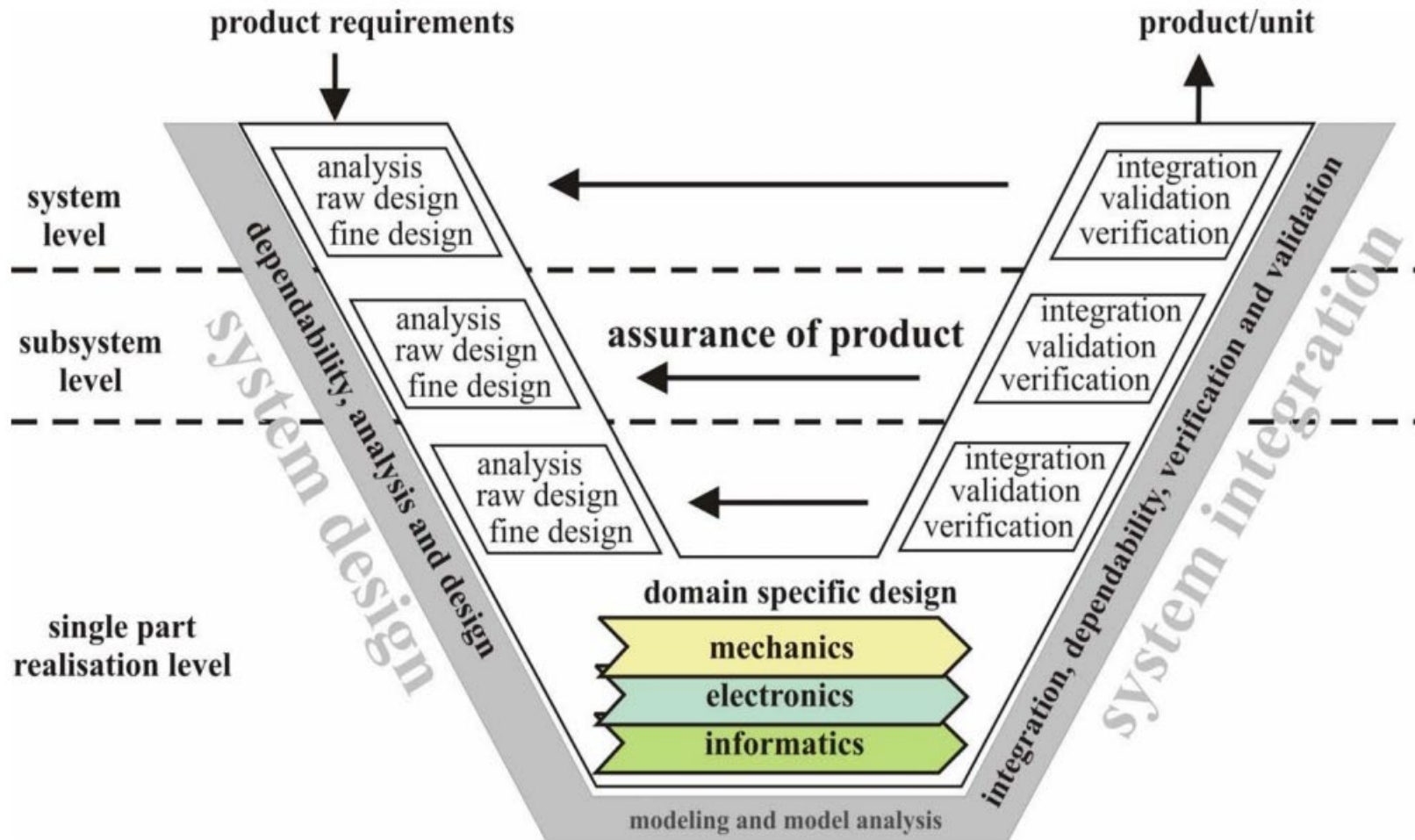
# Mechatronics...

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# Mechatronics...

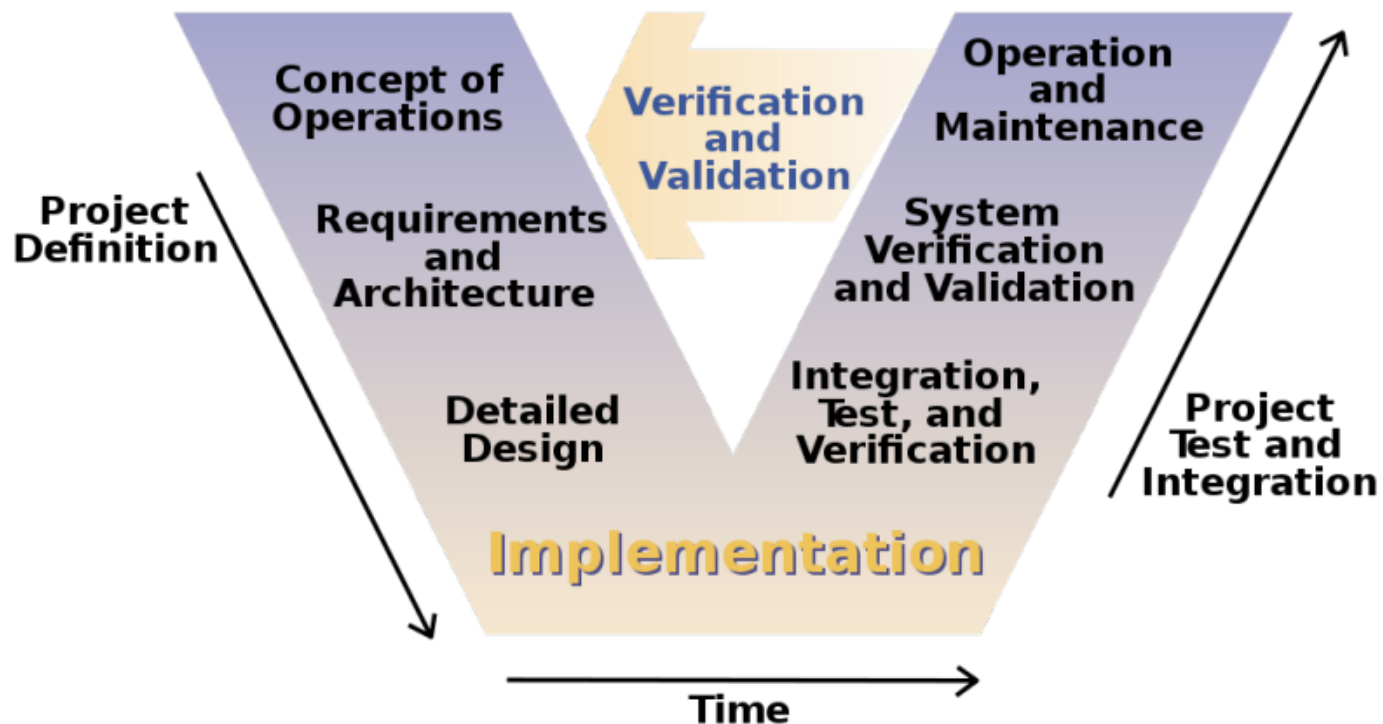
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- conveys expertise of **several fields**, each of which has its own set of 'toolboxes'
- requires a **well defined** set of user and functional requirements and design **parameters**
- is **flexible**
- looks for the **optimal** design and solution to a problem

# Mechatronics design cycle





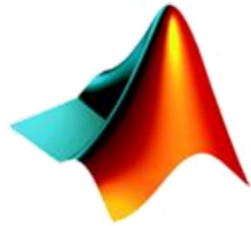
# Mechatronics design cycle







# Some computational tools



MATLAB®



*3D* **SOLIDWORKS**



# Some companies

**ASML**

**Rockwell  
Automation**



**ALLEN**



**BOSCH**

Technologie voor het leven



# Summary

- **Systems interacts** with its environment through **sensors** and **actuators** which are related to inputs and outputs of the system



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- In Systems Engineering the design process, the design methodology and the organizational structure are considered **simultaneously**
- The Systems Engineering approaches **eases the design of Mechatronic systems**



# Next

Next Lecture:

- Introduction to modeling of dynamical systems