

MC-homework

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1 Statistics: MonteCarlo Methods

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1.1 1. Metropolis for hard disks

Two disks of radius R in a square box of side L which each walker is made of 4 coordinates. Start with several walkers and iterate checking the convergence of quantities such as the distance between them. Repeat for disks in a sphere of radius L

```
[230]: #Parameters
N <- 1000
L <- 1
R <- 0.2

#Function distance
d <- function(x1, x2, y1, y2){
  X <- (x2 - x1)^2
  Y <- (y2 - y1)^2
  return(sqrt(X + Y))
}

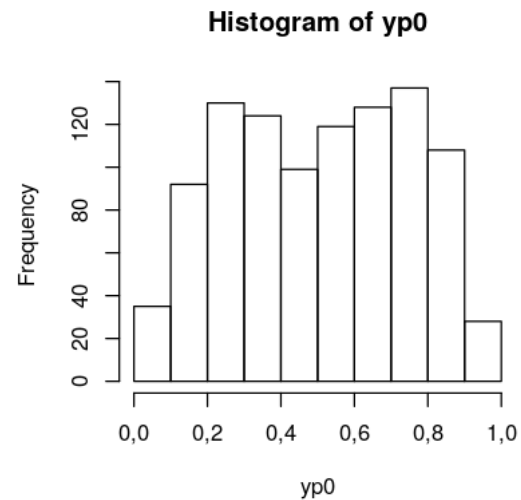
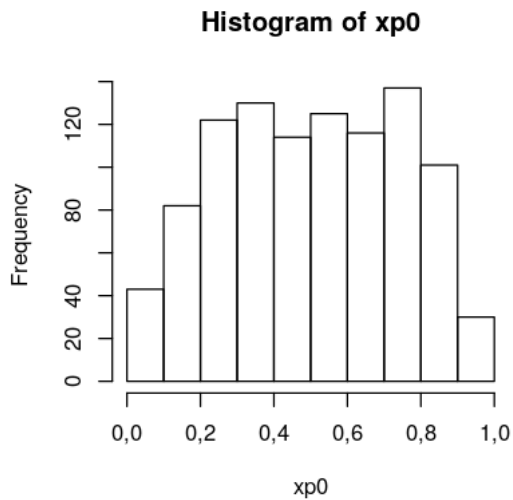
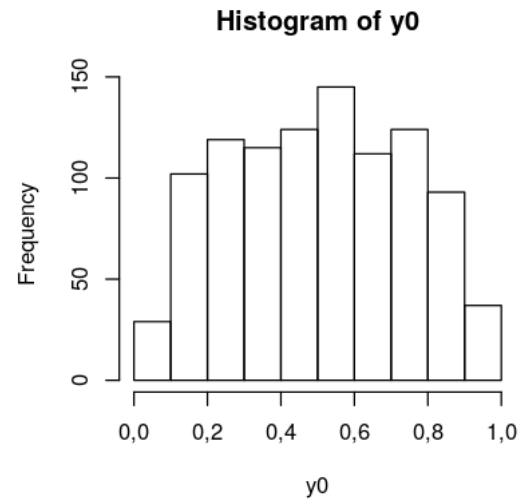
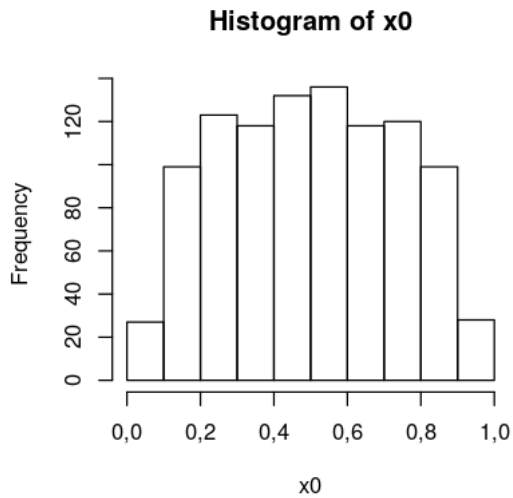
[274]: #Walkers
delta_x <- runif(N, 0, 0.2 * L)
delta_y <- runif(N, 0, 0.2 * L)
r0 <- runif(N, 0, 0.8 * L)
rp0 <- runif(N, 0, 0.8 * L)

#Initial positions
x0 <- ifelse(r0 < L, r0 + delta_x, r0) #This always be true since r0, rp0 max
  ↳ value is 0.8.
y0 <- ifelse(r0 < L, r0 + delta_y, r0)

xp0 <- ifelse(r0 < L, rp0 + delta_x, rp0)
```

```
yp0 <- ifelse(r0 < L , rp0 + delta_y, rp0)
```

```
[276]: par(mfrow=c(2,2))
hist(x0)
hist(y0)
hist(xp0)
hist(yp0)
```



```
[277]: # Disks' new positions
d0 <- d(x0, xp0, y0, yp0)

x1 <- ifelse(d0 > (2 * R) & x0 < L, x0+ delta_x, x0)
y1 <- ifelse(d0 > (2 * R) & y0 < L , y0+ delta_y, y0)
```

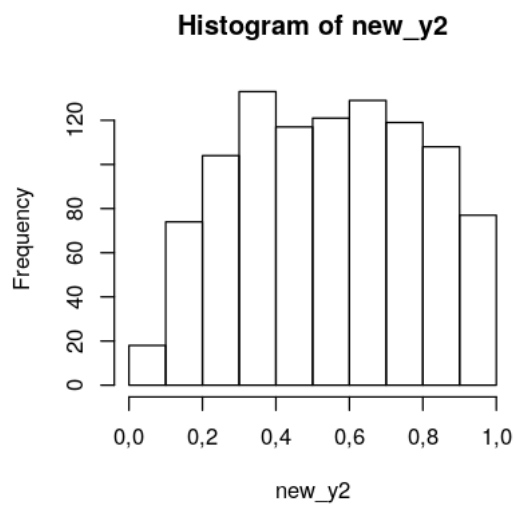
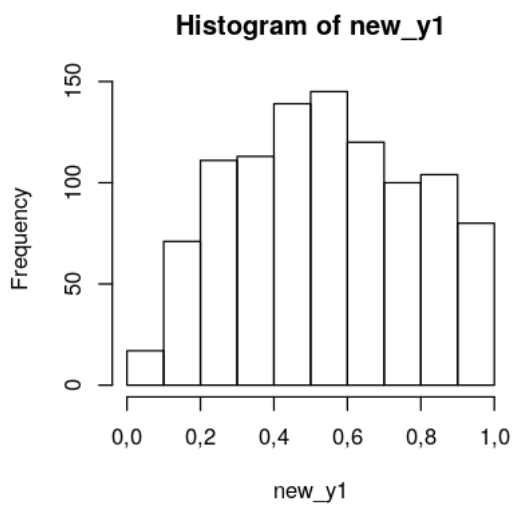
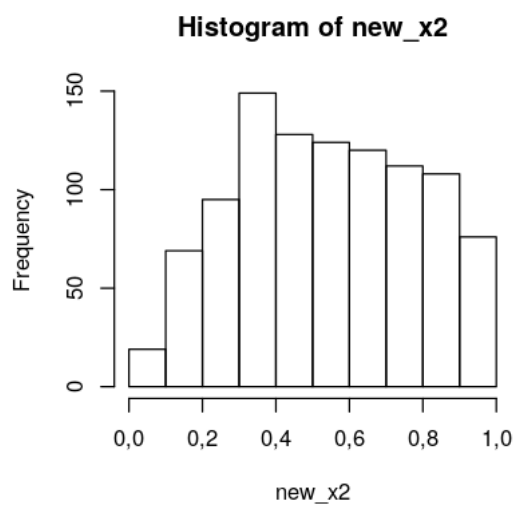
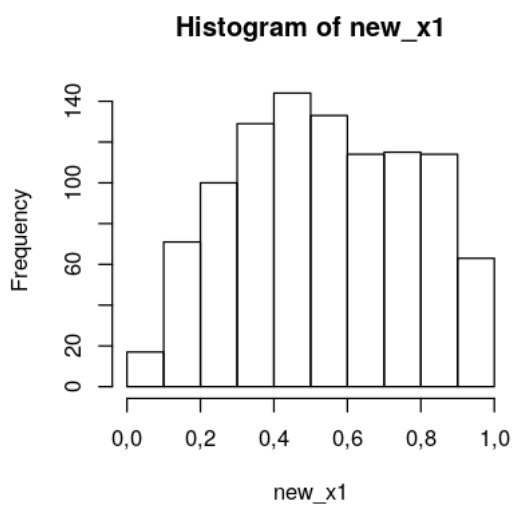
```
x2 <- ifelse(d0 > (2 * R) & xp0 < L , xp0+ delta_x, xp0)
y2 <- ifelse(d0 > (2 * R) & yp0 < L , yp0+ delta_y, yp0)
```

```
[279]: # accepted positions
d1 <- d(x1, x2, y1, y2)

new_x1 <- ifelse(x1 < L & d1 > (2 * R), x1, x0)
new_y1 <- ifelse(y1 < L & d1 > (2 * R), y1, y0)

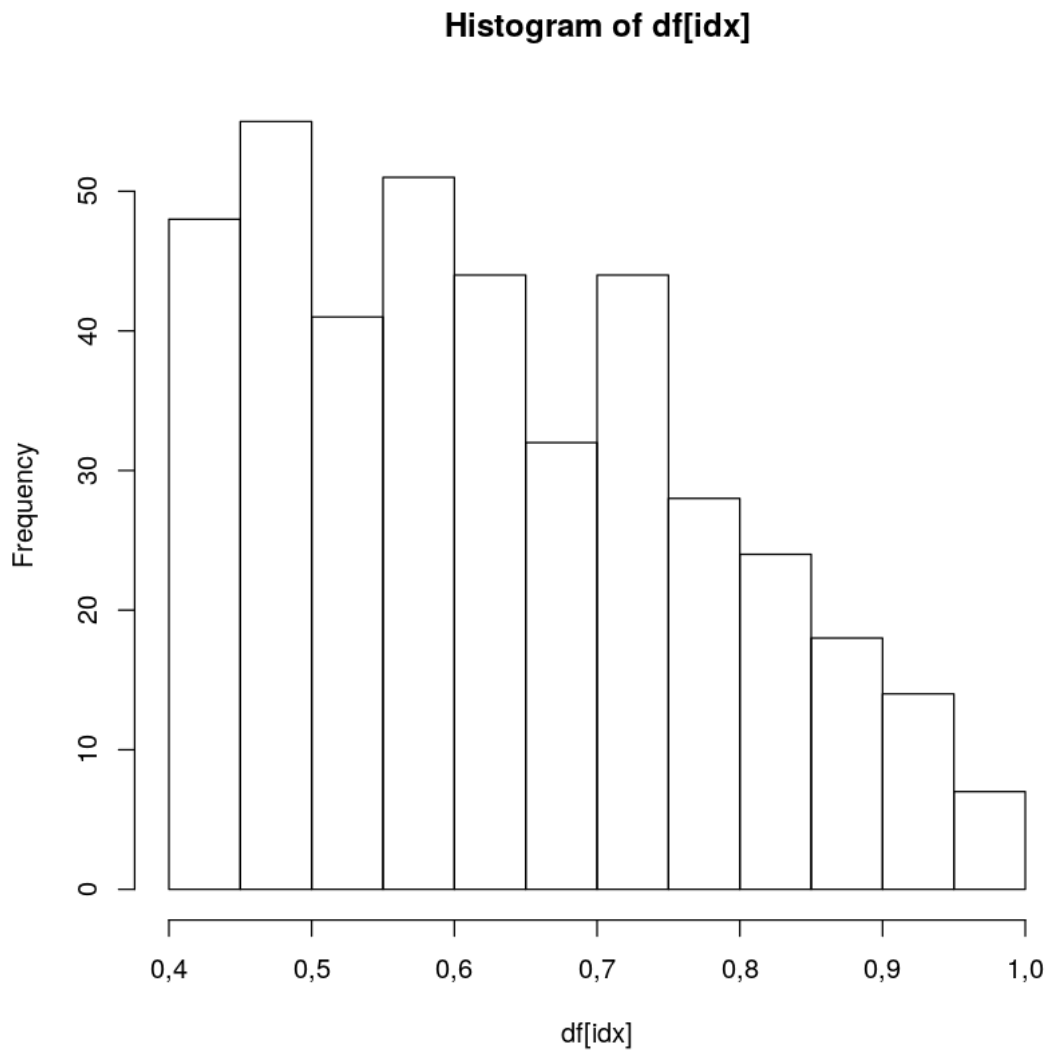
new_x2 <- ifelse(x2 < L & d1 > (2 * R), x2, xp0)
new_y2 <- ifelse(y2 < L & d1 > (2 * R), y2, yp0)
```

```
[280]: par(mfrow=c(2,2))
hist(new_x1)
hist(new_x2)
hist(new_y1)
hist(new_y2)
```



```
[281]: df <- d(new_x1, new_x2, new_y1, new_y2)
```

```
[282]: idx <- which(df > (2 * R) & df <= L)
hist(df[idx])
```



If the disks were in a circle of radius L

```
[291]: condition <- function(x, y, R){
  return(x^2 + y^2 < R^2)
}

cx1 <- ifelse(d0 > (2 * R) & condition(x0,y0,L), x0+ delta_x, x0)
cy1 <- ifelse(d0 > (2 * R) & condition(x0,y0,L), y0+ delta_y, y0)

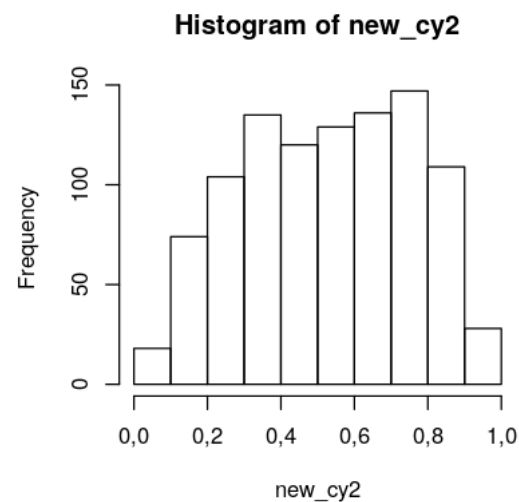
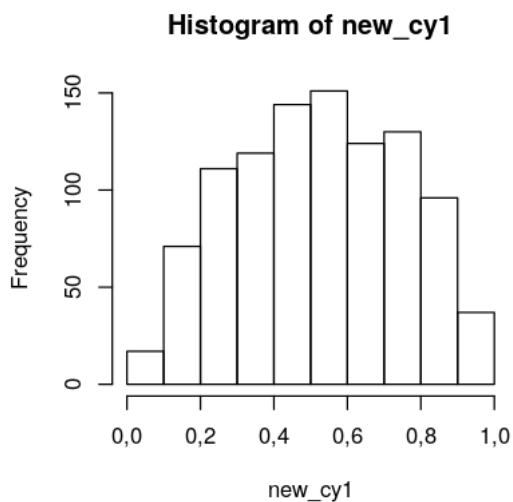
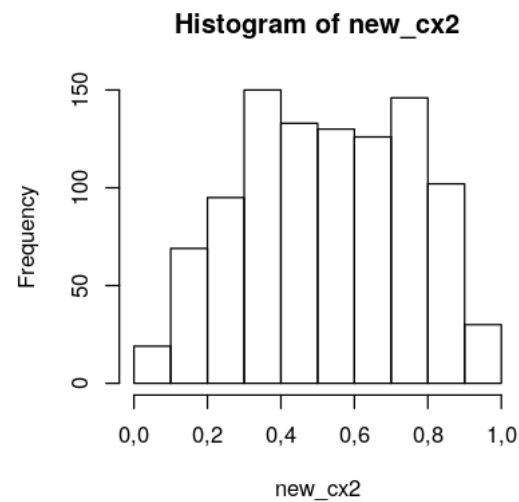
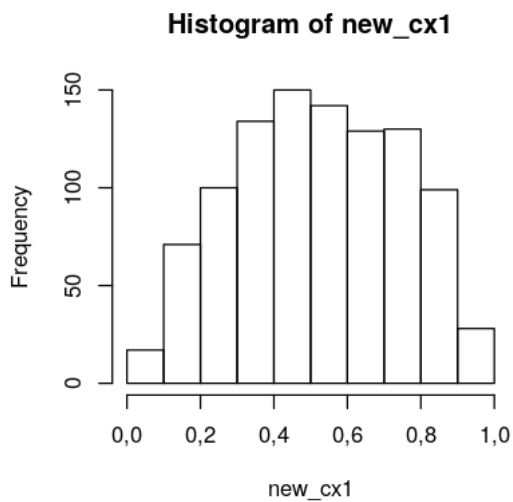
cx2 <- ifelse(d0 > (2 * R) & condition(xp0,yp0, L), xp0+ delta_x, xp0)
cy2 <- ifelse(d0 > (2 * R) & condition(xp0,yp0, L), yp0+ delta_y, yp0)
```

```
[292]: # accepted positions
dc1 <- d(cx1, cx2, cy1, cy2)

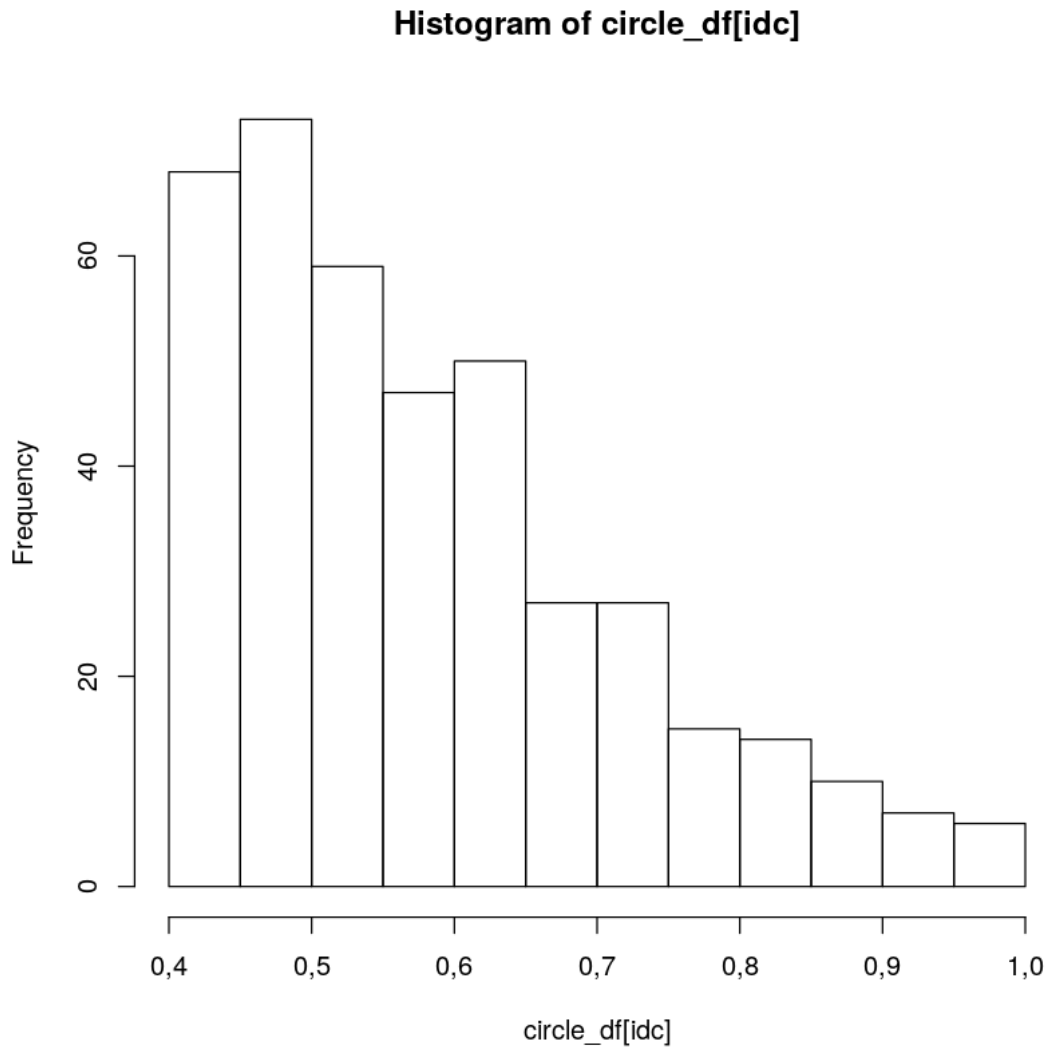
new_cx1 <- ifelse(condition(cx1,cy1,L) & dc1 > (2 * R), cx1, x0)
new_cy1 <- ifelse(condition(cx1,cy1, L) & dc1 > (2 * R), cy1, y0)

new_cx2 <- ifelse(condition(cx2,cy2,L) & dc1 > (2 * R), cx2, xp0)
new_cy2 <- ifelse(condition(cx2,cy2,L) & dc1 > (2 * R), cy2, yp0)
```

```
[293]: par(mfrow=c(2,2))
hist(new_cx1)
hist(new_cx2)
hist(new_cy1)
hist(new_cy2)
```



```
[295]: circle_df <- d(new_cx1, new_cx2, new_cy1, new_cy2)
      idc <- which(circle_df > (2 * R) & circle_df <= L)
      hist(circle_df[idc])
```



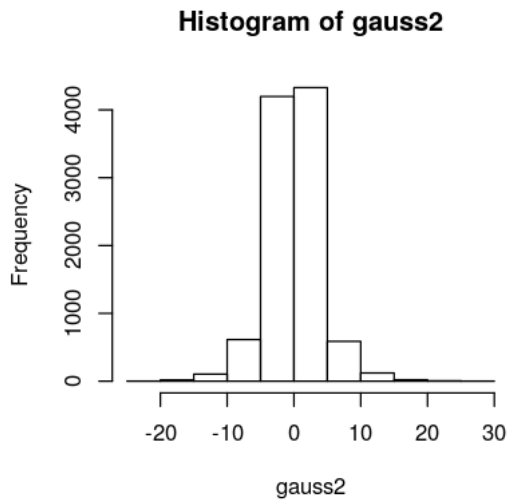
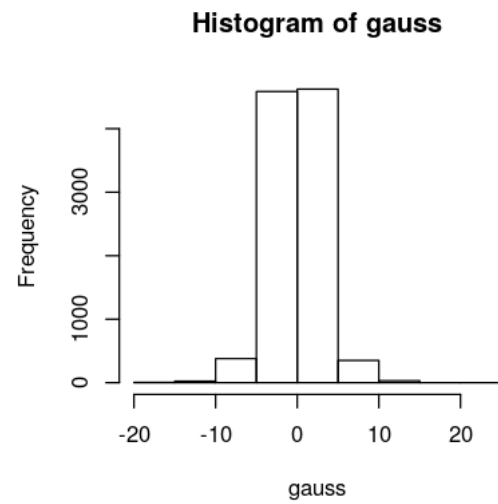
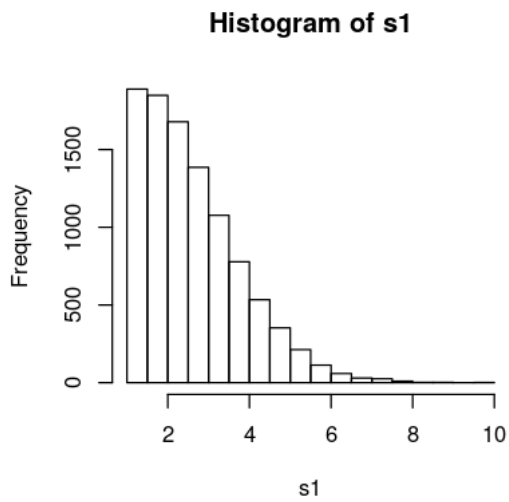
1.2 2. An example of MC-based interference

We have N measurements that follow a gaussian law whose σ is also gaussian $1 + |\mu| N(0,1)$. Use a KS to find the optimal μ

```
[21]: sigma2 <- function(N, nd){  
      return(1 + (abs(nd * rnorm(N, 0, 1))))  
    }
```

```
[41]: N <- 1e4  
      nd <- 2  
      s1 <- sigma2(N, nd)  
  
      gauss <- rnorm(N, 0, s1)  
  
      gauss2 <- rnorm(N, 0, sigma2(N, 3))
```

```
[42]: par(mfrow=c(2,2))  
      hist(s1)  
      hist(gauss)  
      hist(gauss2)
```

```
[43]: mean(gauss)
```

```
-0,0267861232716946
```

```
[44]: mean(gauss2)
```

```
0,0434642541848007
```

```
[45]: ks.test(gauss, gauss2)
```

```
Two-sample Kolmogorov-Smirnov test
```

```
data: gauss and gauss2
```

```
D = 0,0504, p-value = 1,859e-11
```

alternative hypothesis: two-sided

[]: