FashionStar串口总线舵机库-使用说明 (Windows)

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更新时间: 2021/06/12

C++开发环境配置

在Windows下配置C++的开发环境过程有些繁琐,同时也有很多需要配置的地方,以及技术常识。

配置过程详情见教程: cmake搭建C++编译调试

- Windows下配置C++的开发环境,安装mingw-w64, make, cmake
- 编译原理基础, 动态链接库的作用原理。(在底部附录部分)
- 如何自己生成一个动态链接库,以及动态链接库的使用方法。

物理接线

- 1. 安装USB转TTL模块的驱动程序。
- 2. 将串口舵机转接板跟USB转TTL模块通过杜邦线相连。

串口舵机转接板	USB转TTL模块
RX (串口舵机转接板RX 接收端)	Tx (USB转TTL模块的接收端)
TX(串口舵机转接板Tx 发送端)	Rx (USB转TTL模块的发送端)
GND	GND

安装依赖

CSerialPort

CSerialPort 是基于C++的轻量级开源跨平台串口类库,可以轻松实现跨平台多操作系统的串口读写。 FashionStar串口总线舵机,通信部分使用的是CSerialPort库。使用前需要编译安装。

CSerialPort - Github代码仓库地址

详情可以看这个库的WIKI,因为原仓库文件有些冗余,因此我做了删减版本的,放置到 fashionstaruart-servo-cpp/dependency/CSerialPort 文件夹下。

在 CSerial Port 文件夹下创建build文件夹,依次执行指令。

```
mkdir build
cd build
# 需要把`CMAKE_INSTALL_PREFIX` 里面的内容替换为你自己的C++库的安装路径.
cmake .. -D CMAKE_INSTALL_PREFIX="D:/Kylesoftware/CPP_LIBRARIES/"
make
sudo make install
```

注: 如果build为非空文件夹,每次cmake之前,需要清空build文件夹下的所有缓冲文件。

安装日志

```
Windows PowerShell
                                                                                                    ×
PS D:\Ky1eLab\FashionStar\fashionstar-uart-servo-cpp\dependency\CSeria1Port\bui1d> cmake
-D CMAKE_INSTALL_PREFIX="D:/Ky1eSoftware/CPP_LIBRARIES/"
-- Building for: MinGW Makefiles
 - The CXX compiler identification is GNU 8.1.0
- Detecting CXX compiler ABI info
- Detecting CXX compiler ABI info - done
 -- Check for working CXX compiler: D:/KyleSoftware/mingw64/bin/g++.exe - skipped
-- Detecting CXX compile features
-- Detecting CXX compile features - done
 -- CSerialPort CMake Info
 Operation System : Windows-10.0.19042
CPU Architecture : AMD64
        Build Type : Release
Shared Library : ON
        Build Examples
 - Build Test :
- -----
CMake Deprecation Warning at lib/CMakeLists.txt:1 (cmake_minimum_required):
Compatibility with CMake < 2.8.12 will be removed from a future version of
  Update the VERSION argument <min> value or use a ... <max> suffix to tell
  CMake that the project does not need compatibility with older versions.
 - Configuring done
 -- Generating done
 -- Build files have been written to: D:/KyleLab/FashionStar/fashionstar-uart-servo-cpp/depe
ndency/CSeria1Port/bui1d
PS D:\KyleLab\FashionStar\fashionstar-uart-servo-cpp\dependency\CSeria1Port\bui1d>
 Windows PowerShell
                                                                                                    -- Build files have been written to: D:/KyleLab/FashionStar/fashionstar-uart-servo-cpp/depe
ndency/CSerialPort/build
PS D:\KyleLab\FashionStar\fashionstar-uart-servo-cpp\dependency\CSeria1Port\build> make
  12%]
  25%]
  37%]
  50%]
[ 62%] Building CXX object lib/CMakeFiles/libcserialport.dir/_/src/SerialPortInfoWinBase.
  75%] Building CXX object lib/CMakeFiles/libcserialport.dir/_/src/SerialPortWinBase.cpp.
  87%]
โ100%โ
[100%] Built target libcserialport
PS D:\Ky1eLab\FashionStar\fashionstar-uart-servo-cpp\dependency\CSeria1Port\bui1d>
```

安装FashionStar串口总线舵机库

修改CMAKE配置文件

CMakeLists.txt

```
cmake_minimum_required(VERSION 3.00)
# 设置工程名称,设定版本
project(UART_DEMO VERSION 1.0)
# 动态链接库的安装路径
if(CMAKE HOST WIN32)
   # Windows
   # 注意事项: 这里需要改成自己的Windows下的动态链接库的安装路径
   # <<<<<< 改这里
   SET(CMAKE_INSTALL_PREFIX "D:/KyleSoftware/CPP_LIBRARIES/")
elseif(CMAKE_HOST_UNIX)
   # Linux
   # 注意事项: Linux下, CMake默认会将库安装到/usr/local, 需要注意的是,安装的时候需要sudo
权限
   # sudo make install
   SET(CMAKE_INSTALL_PREFIX "/usr/local/")
endif()
#添加依赖的.h文件路径(即hello.h所在的文件夹)
include_directories(${CMAKE_INSTALL_PREFIX}/include include)
#添加link文件夹
link_directories(${CMAKE_INSTALL_PREFIX}/bin)
# 构建源码文件
add_subdirectory(src)
```

```
mkdir build
cd build
cmake ..
make
sudo make install
```

注:如果build为非空文件夹,每次cmake之前,需要清空build文件夹下的所有缓冲文件.

安装日志

```
Windows PowerShell

-- Generating done
-- Build files have been written to: D:/KyleLab/FashionStar/fashionstar-uart-servo-cpp/build
PS D:\KyleLab\FashionStar\fashionstar-uart-servo-cpp\build> make

[ 33%] Building CXX object src/CMakeFiles/fsuartservo.dir/FashionStar_UartServoFrotocol.cpp.obj

[ 66%] Building CXX object src/CMakeFiles/fsuartservo.dir/FashionStar_UartServo.cpp.obj

[ 100%] Linking CXX shared library ..\lib\libfsuartservo.dll

[ 100%] Built target fsuartservo
PS D:\KyleLab\FashionStar\fashionstar-uart-servo-cpp\build>
```

```
[100%] Built target fsuartservo
PS D:\KyleLab\FashionStar\fashionstar-uart-servo-cpp\build> make install
Consolidate compiler generated dependencies of target fsuartservo
[100%] Built target fsuartservo
[100%] Built target fsuartservo-cpp\build> make install
Consolidate compiler generated dependencies of target fsuartservo
[100%] Built target fsuartservo-cpp\build>

Install the project...
-- Install configuration: ""
-- Install configuration: ""
-- Installing: D:/KyleSoftware/CPP_LIBRARIES/lib/libfsuartservo. dll. a
-- Installing: D:/KyleSoftware/CPP_LIBRARIES/bin/libfsuartservo. dll
-- Installing: D:/KyleSoftware/CPP_LIBRARIES/include/FashionStar/Uservo/FashionStar_UartServoProtocol.h
-- Up-to-date: D:/KyleSoftware/CPP_LIBRARIES/include/FashionStar/Uservo/FashionStar_UartServo.h
PS D:\KyleLab\FashionStar\fashionstar-uart-servo-cpp\build>
```

如何运行示例代码

iyleLab > FashionStar > fashionstar-uart-servo-cpp > example

名称

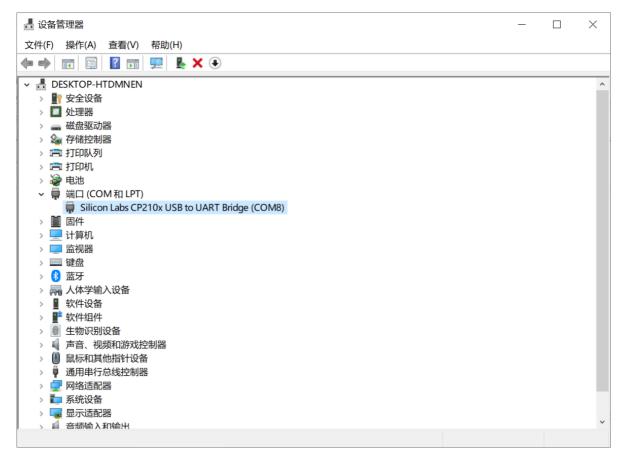
servo_calibration
servo_damping
servo_data_read
servo_ping
servo_query_angle
servo_query_angle
servo_query_angle_mturn
servo_set_angle
servo_set_angle_mturn
servo_set_angle_mturn
servo_torque
servo_wait

修改例程的CMake配置文件

servo_wheel_mode

CMakeLists.txt

```
cmake_minimum_required(VERSION 3.0)
# 设置工程名称,设定版本
project(SERVO_PING VERSION 1.0)
# 动态链接库的安装路径
if(CMAKE HOST WIN32)
   # Windows
   # 注意事项: 这里需要改成自己的Windows下的动态链接库的安装路径
   # <<<<<< 改这里
   SET(CMAKE_INSTALL_PREFIX "D:/KyleSoftware/CPP_LIBRARIES/")
elseif(CMAKE_HOST_UNIX)
   # Linux
   # 注意事项: Linux下, CMake默认会将库安装到/usr/local, 需要注意的是, 安装的时候需要sudo
权限
   # sudo make install
   SET(CMAKE_INSTALL_PREFIX "/usr/local/")
endif()
#添加依赖的.h文件路径(即hello.h所在的文件夹)
include_directories(${CMAKE_INSTALL_PREFIX}/include)
# # 添加link文件夹
link_directories(${CMAKE_INSTALL_PREFIX}/bin)
#添加可执行程序hello_demo
add_executable(servo_ping servo_ping.cpp)
# 添加动态链接库的路径
target_link_libraries(servo_ping fsuartservo cserialport)
```



修改源码里面的端口号名称。

servo_ping.cpp 节选。

举例来讲,舵机通信检测例程 servo_ping , 进入到工程目录下。

```
mkdir build
cd build
cmake ..
make
```

注: 如果build为非空文件夹,每次cmake之前,需要清空build文件夹下的所有缓冲文件。

执行编译出来的可执行文件:

```
.\servo_ping.exe
```