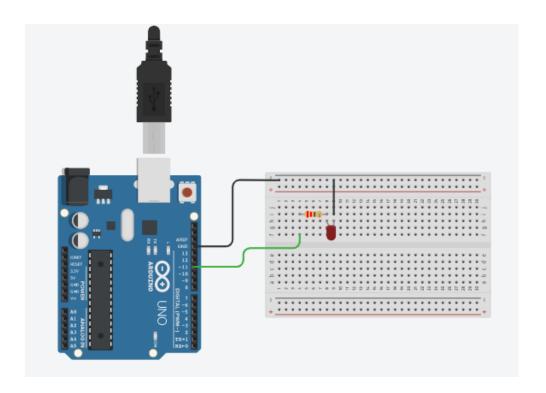
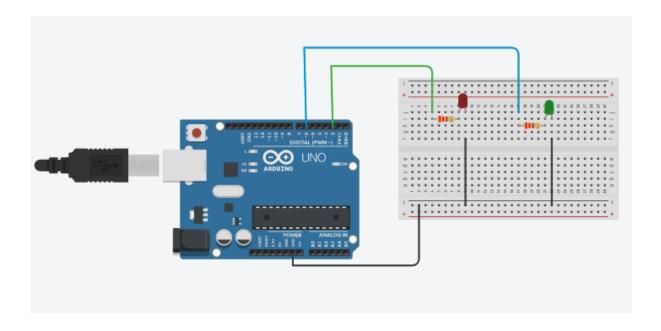
1.LED



```
void setup()
{
    pinMode(11, OUTPUT);
}

void loop()
{
    digitalWrite(11, HIGH);
    delay(1000); // Wait for 1000 millisecond(s)
    digitalWrite(11, LOW);
    delay(1000); // Wait for 1000 millisecond(s)
}
```

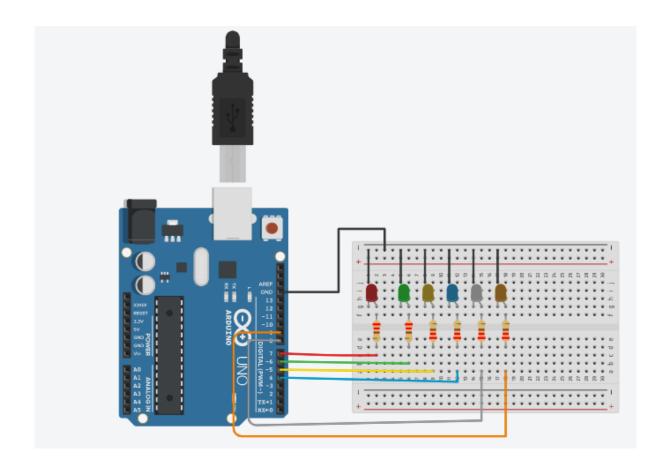
2. Alternate blinking of LEDS



```
void setup()
{
  pinMode(2, OUTPUT);
  pinMode(6, OUTPUT);
}

void loop()
{
  digitalWrite(2, HIGH);
  digitalWrite(6,LOW);
  delay(1000); // Wait for 1000 millisecond(s)
  digitalWrite(6,HIGH);
  delay(1000); // Wait for 1000 millisecond(s)
}
```

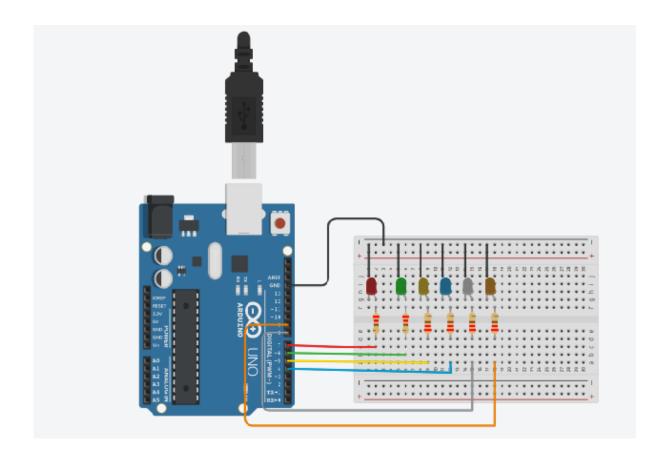
3. Forward blink of LEDS



```
void setup()
{
  pinMode(7, OUTPUT);
  pinMode(6, OUTPUT);
  pinMode(5, OUTPUT);
  pinMode(4, OUTPUT);
  pinMode(8, OUTPUT);
  pinMode(9, OUTPUT);
}
```

```
void loop()
{
 digitalWrite(7,HIGH);
 delay(100);
 digitalWrite(6,HIGH);
 digitalWrite(7,LOW);
 delay(100);
 digitalWrite(5,HIGH);
 digitalWrite(6,LOW);
 delay(100);
 digitalWrite(4,HIGH);
 digitalWrite(5,LOW);
 delay(100);
 digitalWrite(8,HIGH);
 digitalWrite(5,LOW);
 delay(100);
 digitalWrite(9,HIGH);
 digitalWrite(8,LOW);
 delay(100);
 digitalWrite(9,LOW);
 digitalWrite(8,HIGH);
 delay(100);
}
```

4. Forward - Reverse blinking of LEDS



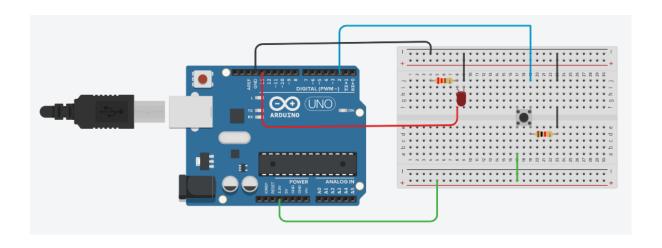
```
void setup()
{
  pinMode(7, OUTPUT);
  pinMode(6, OUTPUT);
  pinMode(5, OUTPUT);
  pinMode(4, OUTPUT);
  pinMode(8, OUTPUT);
  pinMode(9, OUTPUT);
}

void loop()
{
```

```
digitalWrite(7,HIGH);
delay(100);
digitalWrite(6,HIGH);
digitalWrite(7,LOW);
delay(100);
digitalWrite(5,HIGH);
digitalWrite(6,LOW);
delay(100);
digitalWrite(4,HIGH);
digitalWrite(5,LOW);
delay(100);
digitalWrite(8,HIGH);
digitalWrite(5,LOW);
delay(100);
digitalWrite(9,HIGH);
digitalWrite(8,LOW);
delay(100);
digitalWrite(9,LOW);
digitalWrite(8,HIGH);
delay(100);
digitalWrite(8,LOW);
digitalWrite(4,HIGH);
delay(100);
digitalWrite(4,LOW);
digitalWrite(5,HIGH);
delay(100);
digitalWrite(5,LOW);
digitalWrite(6,HIGH);
delay(100);
```

```
digitalWrite(6,LOW);
digitalWrite(7,HIGH);
delay(100);
digitalWrite(7,LOW);
delay(100);
}
```

5.Blink of LED using pushbutton

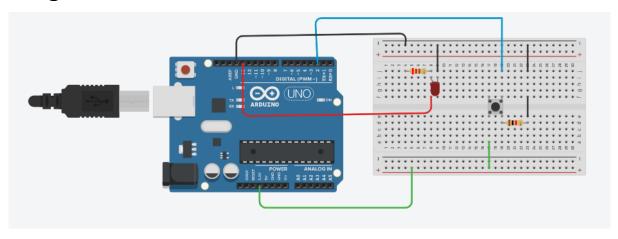


```
int led=13;
int pushbutton=2;
void setup()
{
    Serial.begin(9600);
    pinMode(pushbutton,INPUT);
    pinMode(led,OUTPUT);
}

void loop()
{
    int buttonState=digitalRead(pushbutton);
    Serial.println(buttonState);
```

```
if(buttonState ==HIGH)
{
    digitalWrite(led,HIGH);
}
else
{
    digitalWrite(led,LOW);
}
delay(100);
```

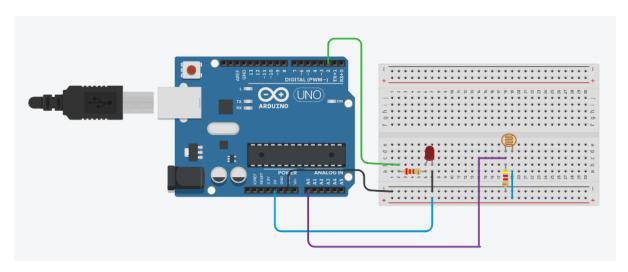
6. Changing the state of LED using pushbutton



```
int pinButton=2;
int LED=13;
int stateLED= LOW;
int stateButton;
int previous = LOW;
long time=0;
long debounce = 200;
void setup()
```

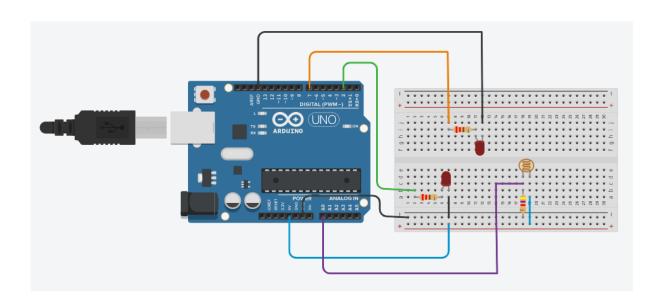
```
{
pinMode(pinButton, INPUT);
pinMode(LED, OUTPUT);
void loop()
stateButton = digitalRead(pinButton);
 if(stateButton == HIGH && previous == LOW && millis()- time > debounce){
  if(stateLED == HIGH){
   stateLED = LOW;
  else {
   stateLED = HIGH;
  time = millis();
  digitalWrite(LED, stateLED);
  previous == stateButton;
```

7. Changing the LED state using photoresistor



```
int sensorValue =0;
void setup()
 pinMode(A0, INPUT);
 Serial.begin(9600);
 pinMode(2, OUTPUT);
void loop()
 sensorValue = analogRead(A0);
 Serial.println(sensorValue);
 if(sensorValue>829)
  digitalWrite(2,LOW);
 else
  digitalWrite(2,HIGH);
```

8. Changing the states of LEDS using photoresistor



```
int sensorValue =0;
void setup()
 pinMode(A0, INPUT);
 Serial.begin(9600);
 pinMode(2, OUTPUT);
 pinMode(7,OUTPUT);
void loop()
 sensorValue = analogRead(A0);
 Serial.println(sensorValue);
 if(sensorValue<852)
  digitalWrite(2,HIGH);
      digitalWrite(7,HIGH);
 }
  else if(sensorValue<900)
  digitalWrite(2,HIGH);
  digitalWrite(7,LOW);
   }
 else
      digitalWrite(2, LOW);
      digitalWrite(7, LOW);
      }
}
```