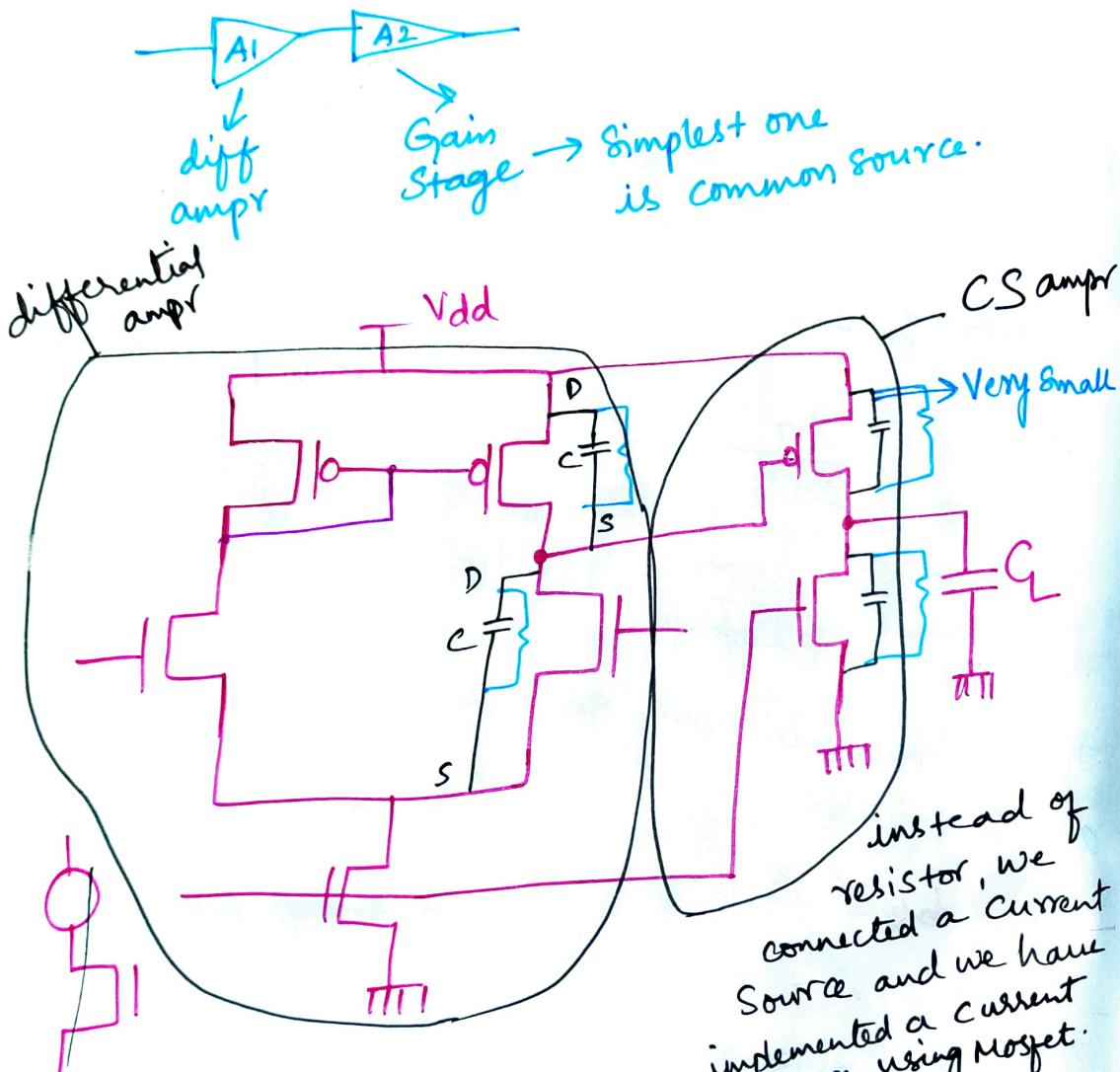
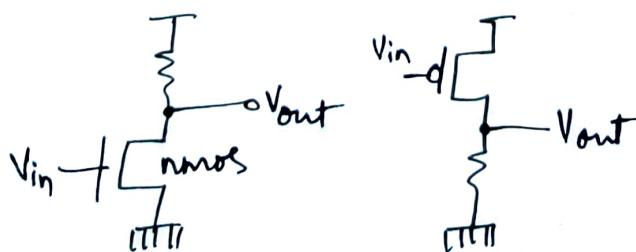


Two Stage opamp

A Single Stage opamp does not provide much gain.
We need two Stage op-amp



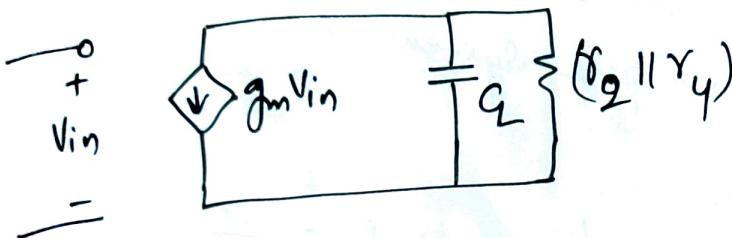
- CS can be either with pmos or nmos
- amplr



With nmos, the swing will be limited

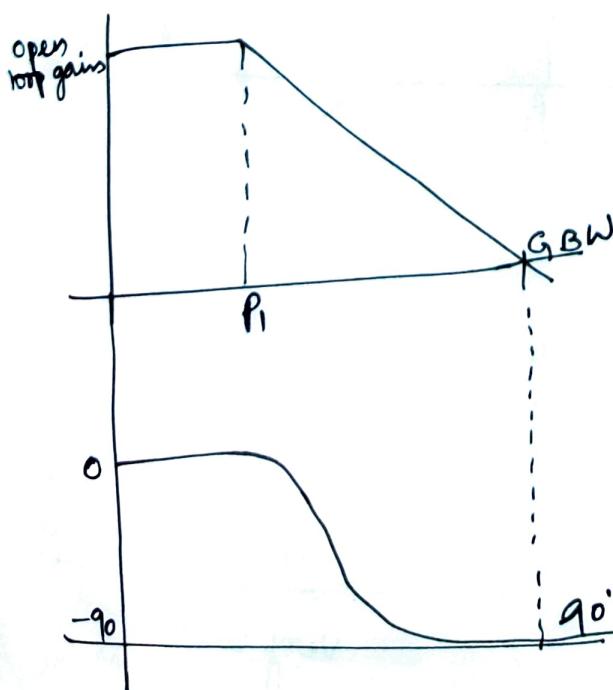
good swing will be obtained, if we connect this.

In single Stage op amp, we were not worried about Stability, phase Margin because it is a single pole System

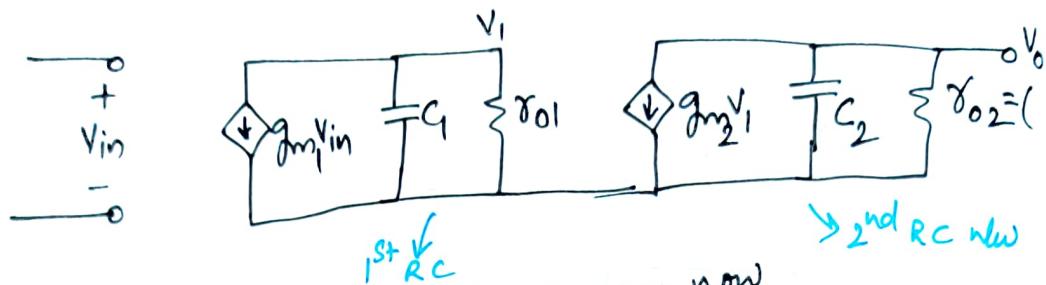
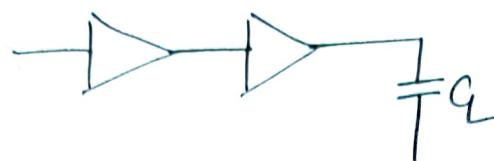


But in 2 stage op amp, we are connecting C_2 at output of CS ampl. So, the small signal model is no longer C_2 for 2 Stage op-amp but it is C_1 (say) The value of C_1 is very less as most of them are parasitics and gate cap.

for single stage op-amp



$90^\circ \rightarrow$ Phase Margin
 ↳ Safe as long as single op-amp is considered.

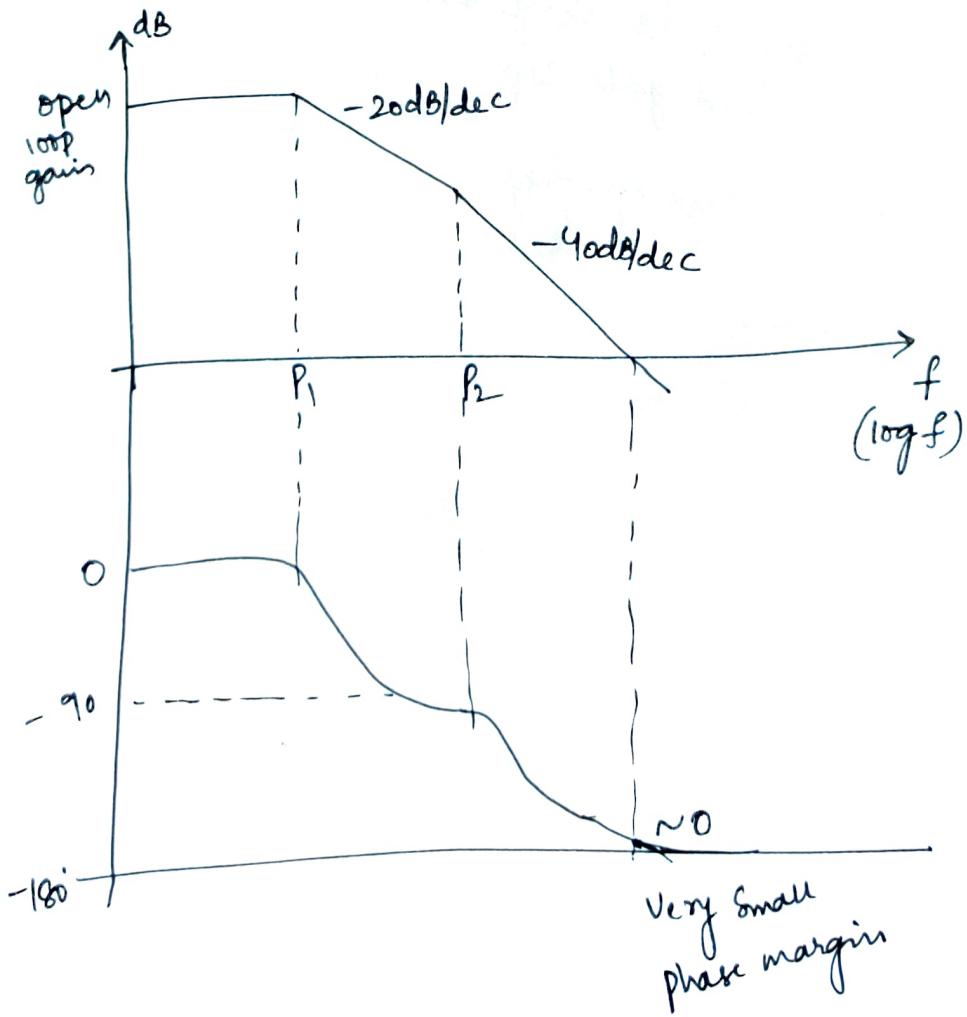


This is a two pole system now

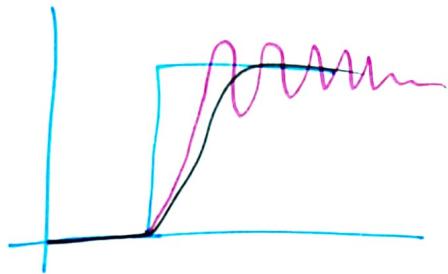
Roughly poles are

$$P_1 = \frac{1}{r_{o1} C_1} ; P_2 = \frac{1}{r_{o2} C_2}$$

Plotting Bode plot of this (for two pole system)



Initially for single pole system, the phase margin was good but now it is very small.
 What is the problem if the phase margin is very small?



If phase margin is good, we get good curve.

If P.M is small, we get ringing curves, which is not required.

To remove ringing and to get smooth curve, we need P.M, which should be minimum 45° (45°)

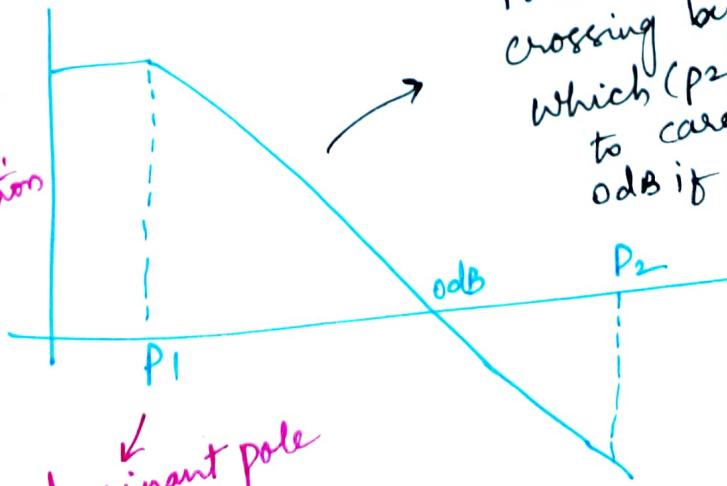
If 60° P.M \Rightarrow Very good.

- But here P.M is 0° .

We will apply dominant pole concept, and we move P_1 to left, such that the system looks like single pole system.

i.e. if P_1 is moved left then 0dB crosses the line before P_2 .

This process is called compensation.

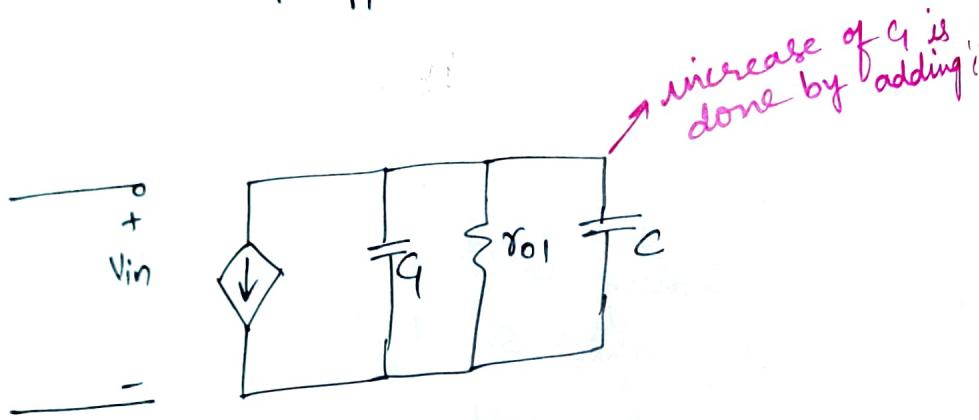


here we have two poles but 0dB is crossing before P_2 which (P_2) no need to care. i.e. after 0dB if a pole comes there will be no effect

We can move P_1 or P_2 , but if we move P_2 which is dependant on load capacitance becomes a problem, so P_2 cannot be moved.

$$P_1 = \frac{1}{r_{o1} C_1}$$

if we ↑ the value of $C_1 \Rightarrow r_{o1} C_1 \uparrow \Rightarrow$
i.e. P_1 is less \Rightarrow it can be moved left



$$P_1 = \frac{1}{r_{o1} C_1} \approx \frac{1}{r_1 (C_0 + C)}$$

to move the pole more towards left, the 'C' should be big.
To avoid that big 'C' value, we can use Miller effect.

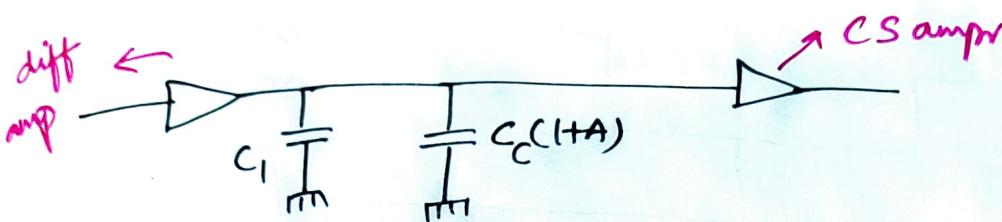
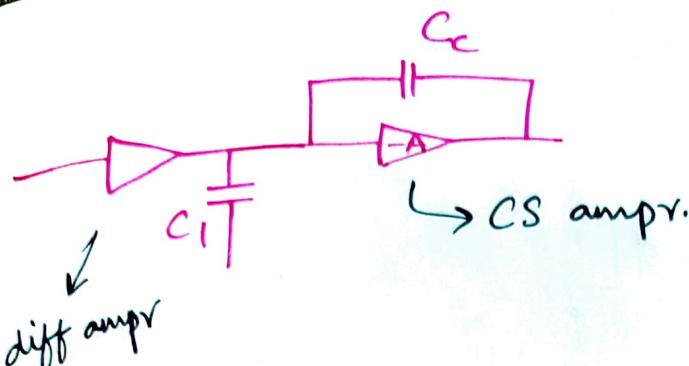
Miller Effect

To implement miller effect, we should have an amp.



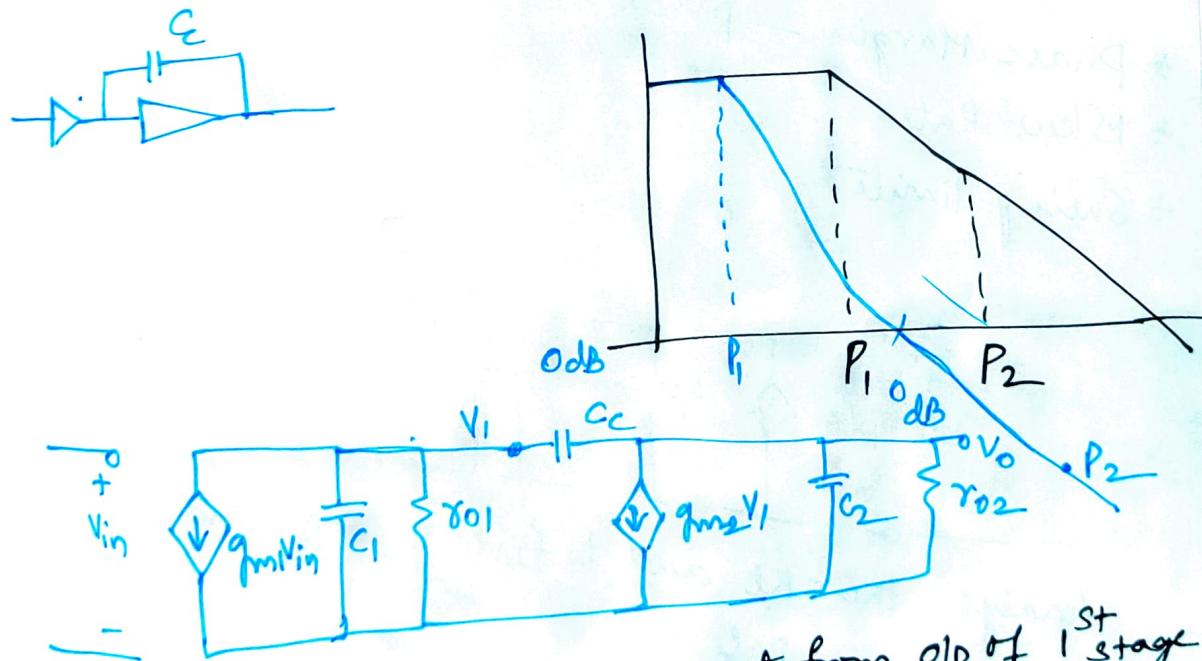
big 'C' value can be avoided because, $(1+A)$ is getting for $C \Rightarrow C'$ value increases.

$$C(1+A) \frac{1}{T} \quad \frac{1}{T} C \left(1 + \frac{1}{A}\right)$$



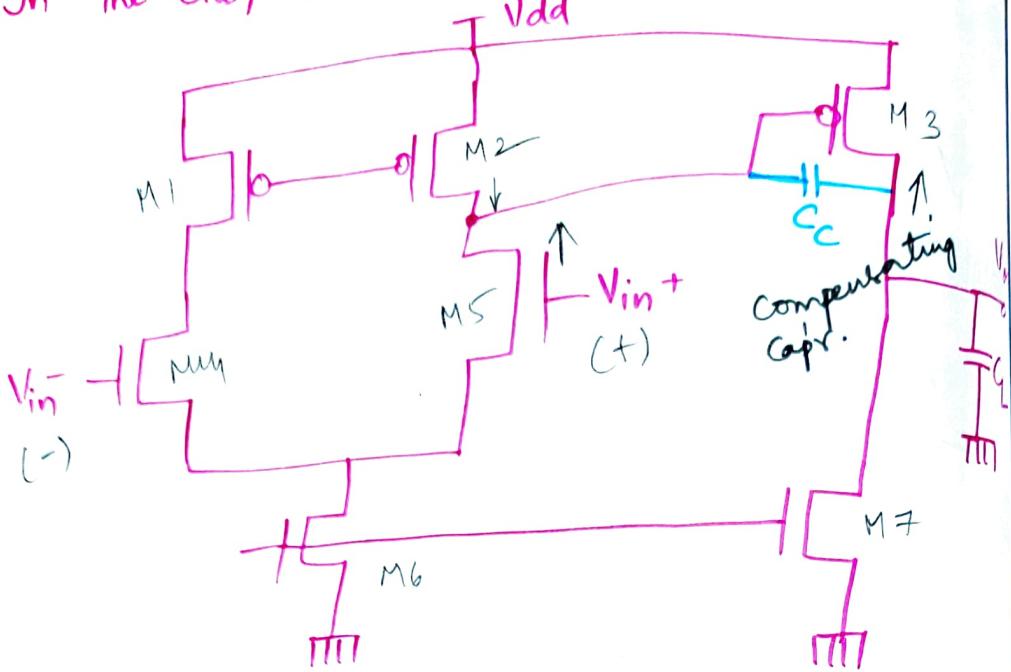
$$P_1 = \frac{1}{r_i [G + C_c(1+A)]}$$

The circuit is now.



C_c is present from o/p of 1st stage
to o/p of 2nd stage.

In the ckt, the two-stage op-amp is

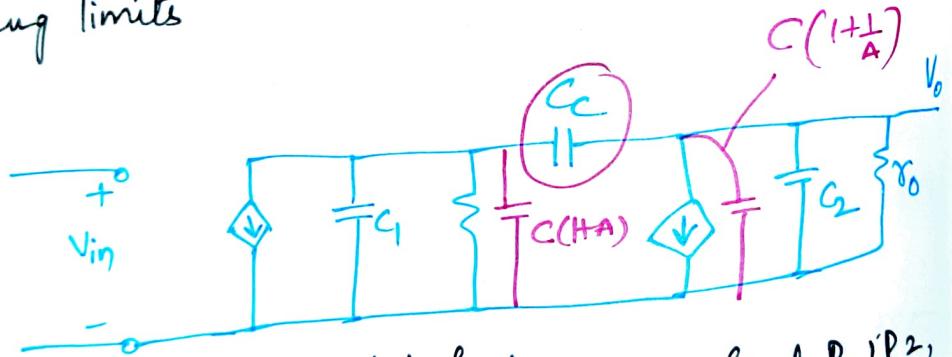


Let us see the terms

* Phase Margin - poles, zeros, GBW etc

* Skew Rate

* Swing limits

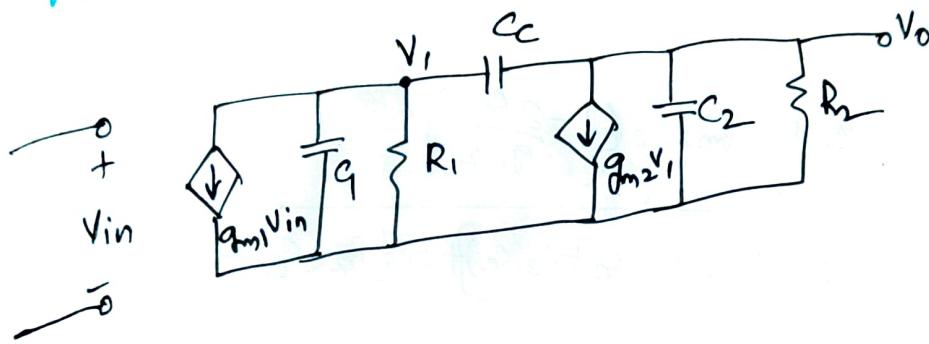


Analyse the ckt and to find
pole P_1
 P_2
GBW
PM.

To find P_1, P_2 ,
GBW, PM
find Transferf

This is miller theorem,
but we cannot do this b/c
of two reasons
1) pole splitting 2) zero

At high frequency, this capacitance may be short and the signal may flow from $\overset{\text{CC}}{\text{II}}$, but if we are splitting C in two, then the flow may be interrupted \rightarrow which is zero effect.
 - so solve the above small signal model, manually without splitting.



To find

$$\frac{V_o}{V_{in}} = \frac{V_1}{V_{in}} \cdot \frac{V_o}{V_1}$$

Node eqn at V_1 ,

$$\frac{V_1}{R_1} + \frac{V_1}{R_1} + g_{m1}V_{in} + \frac{V_1 - V_o}{SC_C} = 0.$$

$$V_1 \left(SC_1 + \frac{1}{R_1} + SC_C \right) + g_{m1}V_{in} - V_o S C_C = 0.$$

$$V_1 = \frac{V_o \cdot SC_C R_1 - g_{m1} \cdot R_1 V_{in}}{1 + SR_1(G + CC)}$$

— ①

Node eqn at V_o ,

$$\frac{V_o}{SC_2} + \frac{V_o}{R_2} + g_{m2}V_1 + \frac{V_o - V_1}{SC_C} = 0$$

$$V_o \left[s(C_2 + C_C) + \frac{1}{R_2} \right] = V_i (sC_C - g_{m2})$$

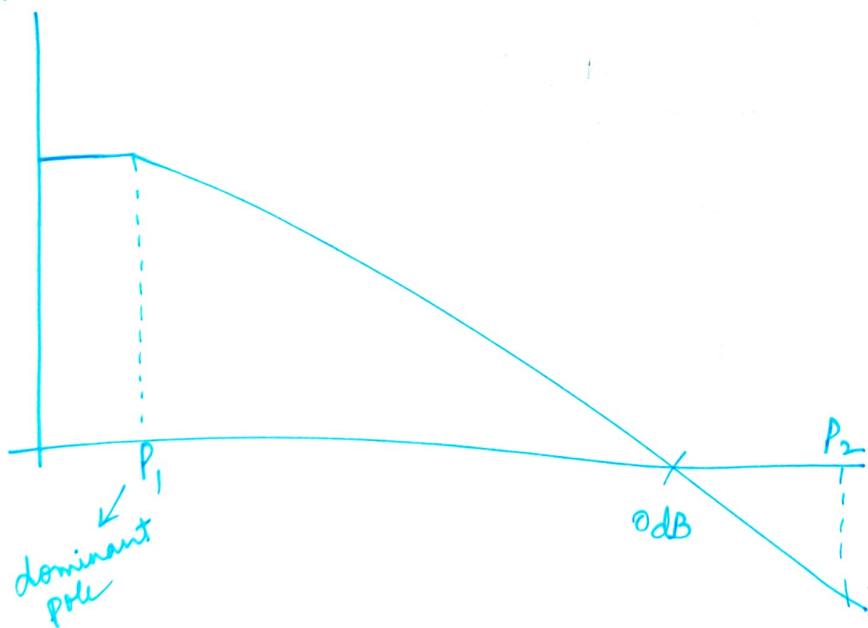
↓
Substitute ① here.

$$V_o \left[s(C_2 + C_C) + \frac{1}{R_2} \right] = \frac{(V_o sC_C R_1 - g_{m1} R_1 V_{in})(sC_C - g_{m2})}{1 + s(C_1 + C_C)R_1}$$

$$V_o [s(C_1 + C_C)R_2 + 1] [1 + s(C_1 + C_C)R_1] = (V_o sC_C R_1 - g_{m1} R_1 V_{in})(sC_C - g_{m2})$$

$$\frac{V_o}{V_{in}} = \frac{g_{m1} R_1 g_{m2} R_2 \left(1 - \frac{sC_C}{g_{m2}} \right)}{s^2 [C_1 R_2 (C_1 C_2 + C_1 C_C + C_2 C_C)] + s [R_2 (C_1 + C_2) + R_1 (C_C + C_1)] + \frac{C_C g_{m2} R_1 R_2}{2}}$$

Bode plot



at lower frequencies, what is significant is P_1 .
we have to make few assumptions like

$$D \rightarrow j\omega \text{ i.e } s = 0$$

if we put $s = 0$, we get

Dc gain

at lower frequencies, the coefficient of s is dominant

for two pole system, the standard transfer function
is

$$\frac{V_o}{V_{in}} = \frac{A_{DC} \left(1 - \frac{s}{Z} \right)}{\left(1 + \frac{s}{P_1} \right) \left(1 + \frac{s}{P_2} \right)}$$

from the obtained $\frac{V_o}{V_{in}}$, we need to find Z_1, P_1, P_2
by assumptions.

→
$$= \frac{A_{DC} \left(1 - \frac{s}{Z} \right)}{1 + s \left(\frac{1}{P_1} + \frac{1}{P_2} \right) + s^2 \left(\frac{1}{P_1 P_2} \right)}$$

from $\frac{V_o}{V_{in}}$ of opamp, it is required to find Z_1, P_1, P_2
 A_{DC} .

which is difficult as the eqn is longer.

$$S \text{ term} = \frac{1}{P_1} + \frac{1}{P_2} \approx \frac{1}{P_1}$$

$$S^2 \text{ term} = \frac{1}{P_1 P_2}$$

$$'S' \text{ term} = \frac{1}{P_1}$$

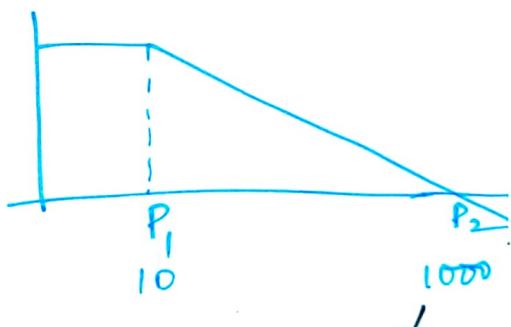
$\frac{1}{P_1} \rightarrow \text{coeff. of } 's'$

$$P_1 \approx \frac{1}{R_2(C_E + C_2) + R_1(C_E + C_1) + C_C g_m Z_2 Q}$$

R_1 is
also
large

dominating

gain of
single
stage
opamp



$$\frac{1}{P_1} + \frac{1}{P_2} \approx \frac{1}{P_1}$$

This can
be neglected

$$\frac{1}{10} + \frac{1}{1000}$$

$$0.1 + 1m$$

$$100m + 1m$$

$$\therefore P_1 \approx \frac{1}{g_m R_1 R_2 C_C}$$

To find P_2)

$$\text{Coeff of } s^2 = \frac{1}{P_1 P_2}$$

$$P_1 P_2 = \frac{1}{R_1 R_2 (G_C C_2 + G_C + C_2 C_C)}$$

$$P_2 = \frac{1}{R_1 R_2 (G_C C_2 + G_C + C_2 C_C)} \frac{g_m R_1 R_2 C_C}{g_m R_1 R_2 C_C}$$

$$P_2 = \frac{g_m C_C}{C_1 C_2 + G_C C_C + C_2 C_C}$$

big $\approx \frac{g_m C_C}{C_2 C_C}$

load capce.

gate capce & effective capce
parasitic capce. can be neglected

$$P_2 \approx \frac{g_m}{C_2}$$

Zero

on comparison,

$$Z = \frac{g_m}{C_C}$$

DC gain

\hookrightarrow when all 'S' terms are zero, what is remaining is DC gain.

$$A_{DC} = g_m_1 g_m_2 R_1 R_2$$

$$Z = \frac{g_m^2}{C_C}$$

$$P_1 = \frac{1}{g_m^2 R_1 R_2 C_C}$$

$$P_2 = \frac{g_m^2}{C_2}$$

$$A_{DC} = g_m R_1 \cdot g_m R_2 \cdot$$

Gain Bandwidth product

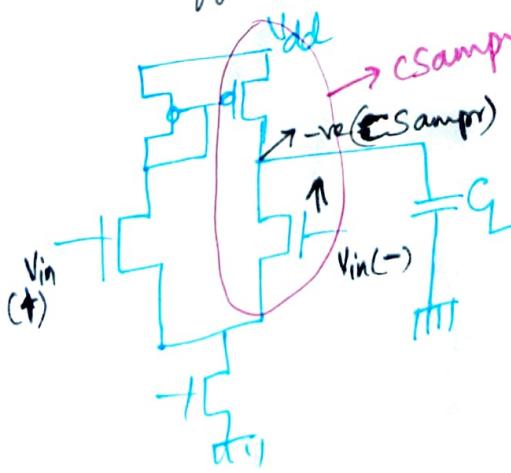
$$\begin{aligned} GBW &= DC\text{gain} * P_1 \\ &= g_m R_1 * g_m R_2 * \frac{1}{g_m^2 R_1 R_2 C_C} \end{aligned}$$

$$GBW = \frac{g_m}{C_C}$$

written
gain BW

Slew Rate:

S.R. is different for 2 Stage than Single stage
 S.R. is greater ($\because 180^\circ$ phase shift)



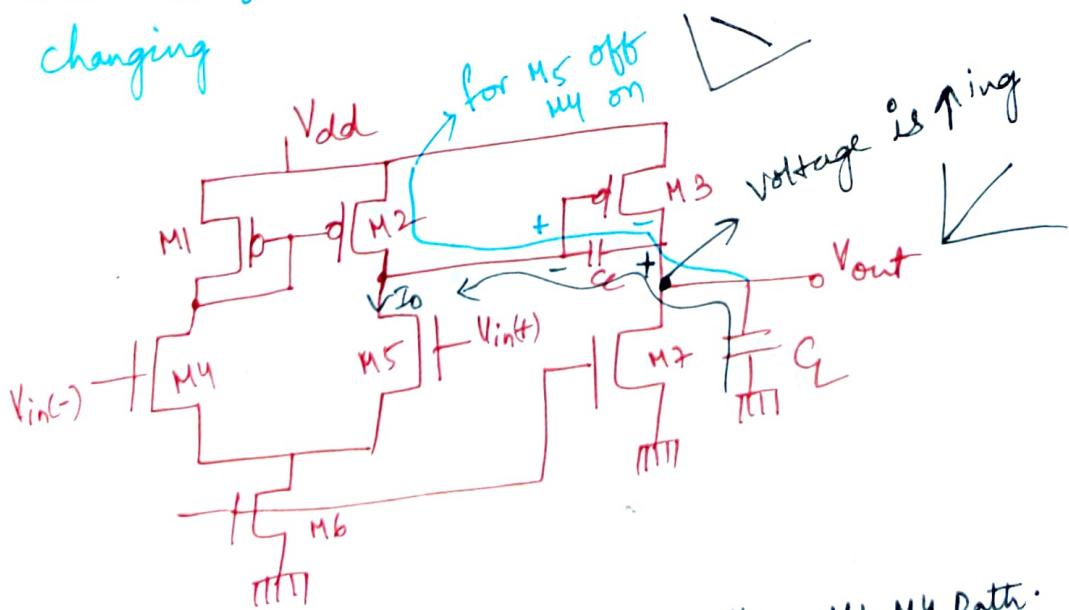
Slew rate is the rate of change of Voltage i.e. how quickly the voltage changes.

What are the limiting factors

Suppose if input at $V_{in(-)}$ is going up and if at $V_{in(+)}$ is going down, how quickly the Not-changing increasing/peak value max $V_{in(-)}$ can go till the mosfet is completely turned on and $V_{in(+)}$ mosfet is completely turned off. Then the ' I ' completely flows thru tail nmos. and this is coming from ' Q ' and all other transistors are off.

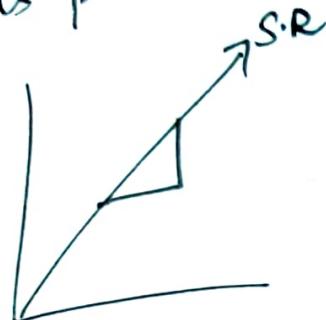
for 2 Stage Slew rate

when V_{in} of M_5 is ↑ing, how quickly my ilp is changing



When M_4 is off, no current flows thru M_1, M_4 path. As M_2 is current mirror of M_1 , ' I ' does not flow thru M_2 also. (M_2 OFF). All the ' I ' flows thru M_5 Mosfet, which is coming from Q thru E

Voltage at V_{out} is linearly rising b'coz of ϵ which is present and controlling the current



$$S.R = \frac{I_o}{C_C}$$

due to I_o & ϵ the Voltage is changing,

- If M_5 is off, M_4 is on, thus current flows thru M_1, M_4 path, $\because M_1$ is conduct, M_2 also conducts and reaches that current to V_{out} thru ϵ .

Here also I_o & ϵ are responsible for S.R

Phase Margin

The PM has to be like this for 2-Stage opamp.

- If P_2 is moving left, PM decreases. We should see P_2 is away from GBW

- Zero (Z_1) comes after long freq of GBW product

Generally, we assume

$$Z \geq 10 \text{ GBW}$$

We have to find out what condition gives 60° phase margin

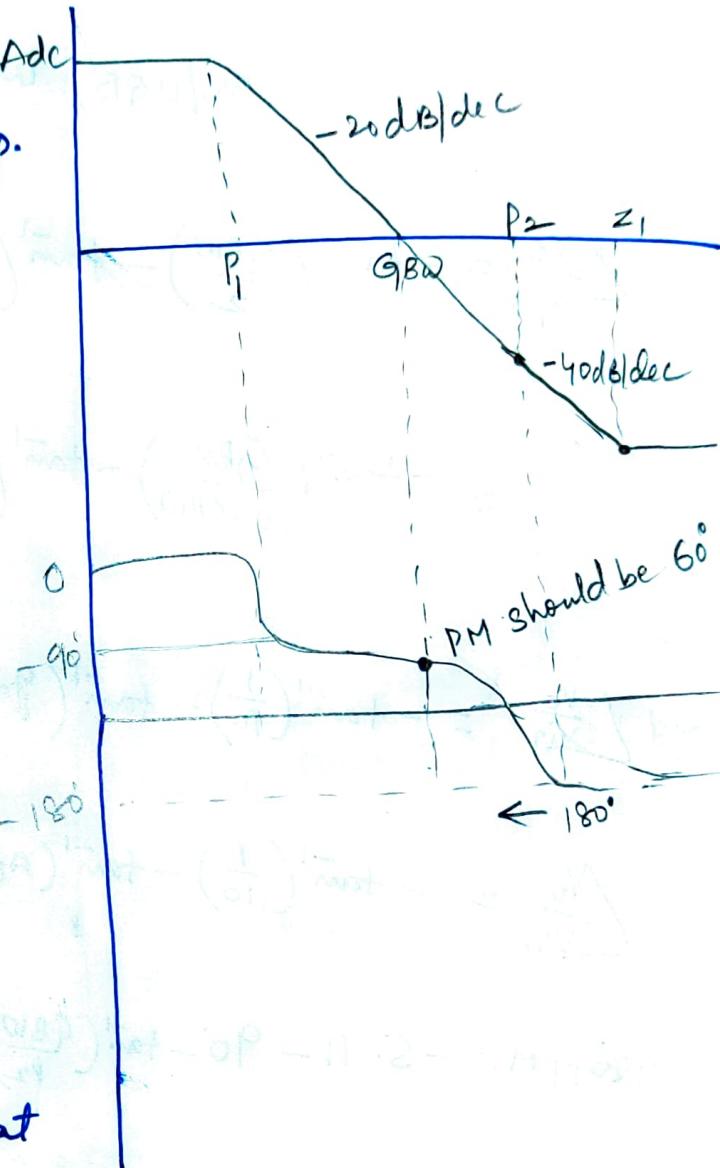
W.K.T from part 3,

$$= \frac{A_{DC} \left(1 - \frac{S}{Z} \right)}{1 + S \left(\frac{1}{P_1} + \frac{1}{P_2} \right) + S^2 \left(\frac{1}{P_1 P_2} \right)} \Leftarrow$$

$$\frac{A_{DC} \left(1 - \frac{S}{Z} \right)}{\left(1 + \frac{S}{P_1} \right) \left(1 + \frac{S}{P_2} \right)}$$

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1} \left(\frac{w}{Z} \right)$$

$$- \tan^{-1} \left(\frac{w}{P_1} \right) - \tan^{-1} \left(\frac{w}{P_2} \right)$$



PM should be 60° at GBW.

When f is at GBW/UGB, what is PM is our interest

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{G_{BW}}{2}\right) - \tan^{-1}\left(\frac{G_{BW}}{P_1}\right) - \tan^{-1}\left(\frac{G_{BW}}{P_2}\right)$$

$$= -\tan^{-1}\left(\frac{G_{BW}}{10 \cdot G_{BW}}\right) - \tan^{-1}\left(\frac{g_{m1} g_{m2} R_1 R_2 C_C}{C_C \cdot g_{m2}}\right) - \tan^{-1}\left(\frac{g_{m1} C_2}{C_C \cdot g_{m2}}\right)$$

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{1}{10}\right) - \tan^{-1}(g_{m1} g_{m2} R_1 R_2) - \tan^{-1}\left(\frac{g_{m1} C_2}{C_C \cdot g_{m2}}\right)$$

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{1}{10}\right) - \tan^{-1}(A_{DC}) - \tan^{-1}\left(\frac{G_{BW}}{P_2}\right)$$

$$-180^\circ + PM = -5.71 - 90^\circ - \tan^{-1}\left(\frac{G_{BW}}{P_2}\right) \quad (\text{All values are substituted from previous parts})$$

$$\text{if } A_{DC} = 100 \Rightarrow \tan^{-1}(100) = 89.4$$

$$1000 = 89.94$$

$$10000 = 89.99$$

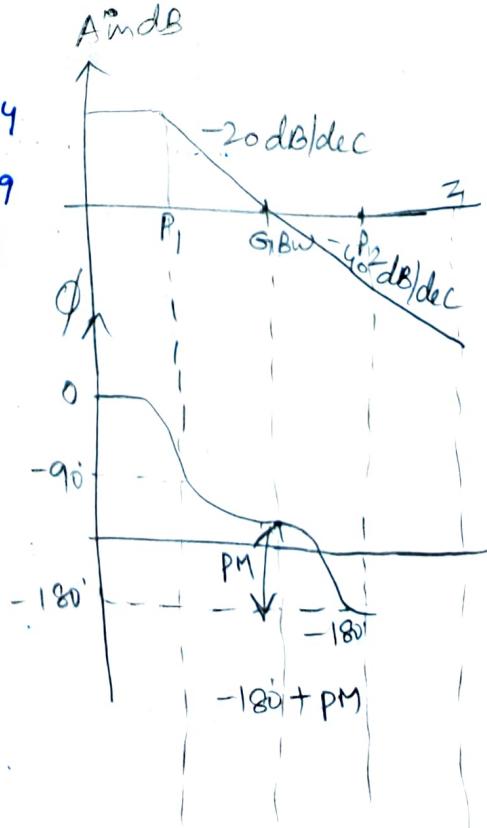
$$(\approx 90)$$

$$PM = 180 - 5.71 - 90 - \tan^{-1}\left(\frac{G_{BW}}{P_2}\right)$$

$$PM = 84.29 - \tan^{-1}\left(\frac{G_{BW}}{P_2}\right)$$

Let us calculate for $PM = 60^\circ \&$

$$PM = 45^\circ$$



$$60^\circ = 84.29 - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

$$\tan^{-1}\left(\frac{GBW}{P_2}\right) = 24.29$$

$$\frac{GBW}{P_2} = \tan(24.29)$$

$$\frac{GBW}{P_2} = 0.4513$$

$$P_2 = \frac{GBW}{0.4513}$$

$$P_2 = 2.2 GBW$$

If we want PM to be

$$> 60^\circ \text{ Then } P_2 \geq 2.2 GBW$$

$$45^\circ = 84.29 - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

$$\tan^{-1}\left(\frac{GBW}{P_2}\right) = 39.29$$

$$\frac{GBW}{P_2} = \tan(39.29)$$

$$= 0.8181$$

$$P_2 = \frac{GBW}{0.8181}$$

$$P_2 = 1.22 GBW$$

\therefore If we want PM to be
 $> 45^\circ$ then P_2 should be
 $\geq 1.22 GBW$

$$P_2 \geq 1.22 GBW$$

Let us consider $P_2 \geq 2.2 GBW$

WKT P_2, GBW

$$\frac{g_{m2}}{C_2} \geq 2.2 \frac{g_{m1}}{C_1} \quad - \textcircled{A}$$

$C_2 = C_L$
 \downarrow
 because C_2 is o/p of 2nd stage \rightarrow load cap.

We assumed $Z = 10 \cdot GBW$

$$\frac{g_{m2}}{C_L} = 10 \cdot \frac{g_{m1}}{Z}$$

$$g_{m2} = 10 \cdot g_{m1} \quad - \textcircled{B}$$

Substitute ③ in ①

$$\frac{10g_m}{C_L} \geq 2 \cdot 2 \frac{g_m}{C_C}$$

$$\frac{10}{C_L} \geq \frac{2 \cdot 2}{C_C}$$

$$C_C \geq \frac{2 \cdot 2}{10} C_L$$

$$C_C \geq 0.22 C_L$$

In the circuit, to get PM as 60° , we should make
sure that $C_C \geq 0.22 C_L$.

Design of two stage opamp

Specifications

$$\text{DC gain} = 1000 \Rightarrow 20 \log 1000 \\ = 60 \text{dB}$$

$$f_{\text{BW}} = 30 \text{ MHz}$$

$$\text{PM} \geq 60^\circ$$

$$\text{Slew rate} = 20 \text{ V}/\mu\text{sec}$$

$$I_{\text{CMR} (+)} = 1.6 \text{ V}$$

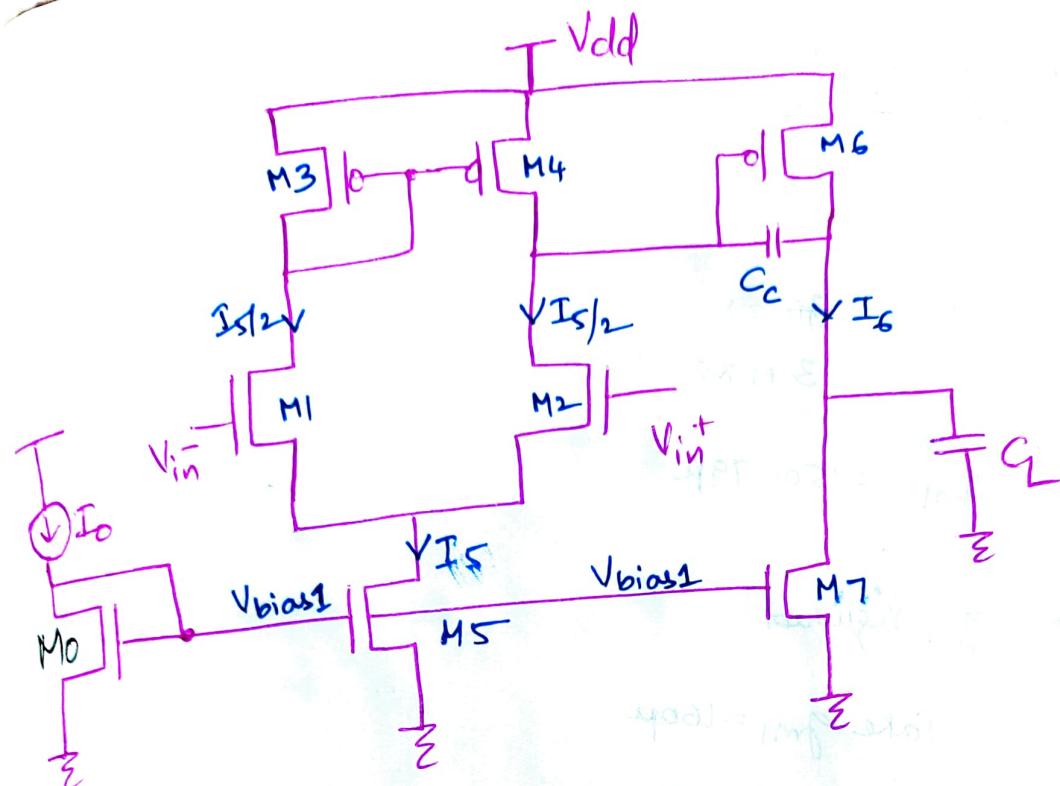
$$I_{\text{CMR} (-)} = 0.8$$

$$Q = 2 \text{ pF}$$

$$\text{Power dissipation} \leq 300 \mu\text{W}$$

$$V_{dd} = 1.8 \text{ V}$$

$$\text{Process} = 28 \text{ nm}$$



$M_3, M_4 - ICMR(+)$ $I_S - \text{Slew-rate}$

$M_1, M_2 - GBW$ $C_C - P.M.$

$M_5 - ICMR(-)$

$M_6 - \text{Gain} \propto M_3, M_4 \text{ design}$

$$\textcircled{1} \quad L = 500\text{nm}$$

$$C_L = 2\text{pF} \text{ (given)}$$

$$\textcircled{2} \quad C_C \geq 0.22 C_L$$

$$C_C \geq 0.22 \times 2\text{pF}$$

$$C_C \geq 0.44\text{pF}$$

$$\approx 440\text{fF}$$

We take $C_C = 800\text{fF}$ in ckt

$$\textcircled{3} \quad SR = \frac{I_S}{C_C}$$

$$I_S = SR * C_C$$

$$= \frac{20\mu\text{A}}{\mu\text{s}} \times 800\text{fF} \Rightarrow 16\mu\text{A}$$

$$I_S = 20\mu\text{A}$$

Design of M1, M2

$$g_{m1} = GB \times C \times 2\pi$$

$$g_{m1} = \cancel{GB \times C} \\ 30M \times 800f \times 2\pi$$

$$g_{m1} = 150 \cdot 79\mu$$

min g_{m1} required

$$\text{Take } g_{m1} = 160\mu$$

W.K.T

$$I_D = \mu n \cos \frac{\omega}{2L} (V_{GS} - V_T)^2$$

$$g_m = \frac{\partial I_D}{\partial V_{GS}} = \frac{\mu n \cos \left(\frac{\omega}{L} \right)}{2} 2(V_{GS} - V_T)$$

$$g_m = \mu n \cos \left(\frac{\omega}{L} \right) (V_{GS} - V_T)$$

$$g_{m1} = \sqrt{2I_D \mu n \cos \left(\frac{\omega}{L} \right)}$$

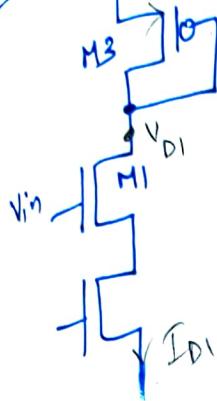
$$\left(\frac{\omega}{L} \right)_1 = \frac{g_{m1}^2}{\mu n \cos (2I_{D1})} = \frac{g_{m1}^2}{\mu n \cos (I_S)}$$

$$\frac{I_S}{2} = I_{D1}$$

$$I_S = 2I_{D1}$$

$$\left(\frac{\omega}{L} \right)_1 = \frac{(160\mu)^2}{300 \times 20} = 4.26$$

Design of M₃, M₄



- M₃ will be always in S.R because it is diode connected
- If V_{in} is fed, M₁ may enter into linear region.

To have M₁ in S.R,

$$V_{D1} > V_{g1} - V_{t1}$$

$$V_{DD} - V_{SG3} - V_{D1} = 0$$

$$V_{D1} = V_{DD} - V_{SG3}$$

$$V_{g1} < V_{D1} + V_{t1}$$

$$V_{in} \leq V_{D1} + V_{t1}$$

$$\text{max } V_{in} \leq V_{D1} + V_{t1}$$

W.L.K.T

$$V_{gs} = \sqrt{\frac{2 I_D}{B}} + |V_{t1}| \quad (\because \text{from } I_D \text{ eqn in S.R})$$

$$V_{gs} = \sqrt{\frac{2 I_{D3}}{\beta P_3}} + |V_{t3}|$$

$$V_{D1} = V_{DD} - \left[\sqrt{\frac{2 I_{D3}}{\beta P_3}} + |V_{t3}| \right]$$

$$V_{in \text{ max}} \leq V_{D1} + V_{t1}$$

$$I_{CMR(+)} \leq V_{D1} + V_{t1 \text{ min}}$$

$$I_{CMR(+)} \leq V_{DD} - \left[\sqrt{\frac{2 I_{D3}}{\beta P_3}} + |V_{t3}| \right] + V_{t1}$$

$$V_{DD} - \sqrt{\frac{2 I_{D3}}{\beta P_3}} - |V_{t3}| + V_{t1}$$

$$\beta = \mu n \alpha \frac{W}{L}$$

$$\left(\frac{W}{L} \right)_{3,4} = \frac{2 \times 10 \mu}{60 \mu [1.8 - 1.6 - 0.51 + 0.47]^2}$$

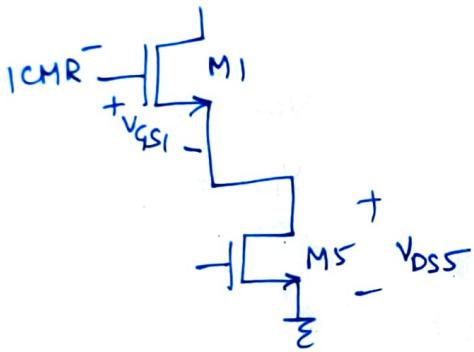
$$V_{t3 \text{ max}} = 0.51$$

$$V_{t1 \text{ min}} = 0.47$$

$$\left(\frac{w}{l}\right)_{3,4} = 13.02$$

$$\text{use } \left(\frac{w}{l}\right)_{3,4} = 14$$

Design of MS:



$$ICMR^- - V_{GS1} - V_{DSS} = 0$$

$$ICMR^- = V_{GS1} + V_{DSS}$$

$$V_{GS1} = V_t + \sqrt{\frac{2I_D}{\mu n C_o (\frac{w}{l})}},$$

$$V_{GS1} = 0.47 + \sqrt{\frac{2(10\mu)}{300\mu \times 4.26}}$$

$$V_{GS1} = 0.59V \approx 0.6V$$

$$V_{DS} = 10.5MV$$

$$I_{DS5} = \frac{1}{2} \mu n C_o \left(\frac{w}{l}\right) \left(V_{DSS}\right)^2$$

$$\left(\frac{w}{l}\right)_5 = 12$$

Design of M6

for 60° P.M

$$g_{m6} \geq 10 \cdot g_{my}$$

$$g_{m6} \geq 10 \times 160 \mu$$

$$\geq 1600 \mu$$

$$V_{DS_{m3}} = V_{DS_{my}} \approx V_{DS_{m6}}$$

$$V_{GS_{m3}} = V_{GS_{my}} = V_{GS_{m6}} \quad (\text{from mirroring})$$

W.K.

$$\left(\frac{w}{L}\right)_y = 14$$

$$g_{m6} = 1600 \mu$$

$$\frac{\left(\frac{w}{L}\right)_6}{\left(\frac{w}{L}\right)_y} = \frac{g_{m6}}{g_{my}}$$

$$g_{my} = \sqrt{\mu_p \cdot \ln \left(\frac{w}{L}\right)_y \cdot 2 I_D}$$

$$= \sqrt{60 \mu \times 14 \times 2(10 \mu)}$$

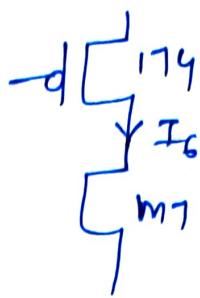
$$g_{my} = 129.61 \mu$$

$$\left(\frac{w}{L}\right)_6 = \frac{1600 \mu}{129.61 \mu} \times 14$$

$$\left(\frac{w}{L}\right)_6 = 172.82 \approx 173.$$

Design of M7

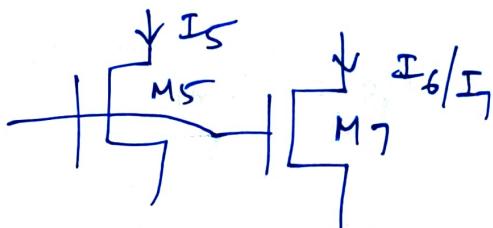
$$\frac{I_b}{I_4} = \frac{(\omega/L)_6}{(\omega/L)_4}$$



$$I_b = \frac{174}{19} \times 10\mu$$

$$I_b = 124.28\mu \approx 125\mu A. = I_7.$$

$$\frac{I_7}{I_5} = \frac{(\omega/L)_7}{(\omega/L)_5}$$



$$(\omega/L)_7 = \frac{125\mu}{20\mu} \times 12$$

$$(\omega/L)_7 = 75.$$

$$I_5 = 20\mu$$

$$c_c = 800fF$$

$$(\omega/L)_{M1, M2} = 6 \rightarrow \frac{3\mu}{500n}$$

$$(\omega/L)_{M3, M4} = 14 \rightarrow \frac{7\mu}{500n}$$

$$(\omega/L)_{M5} = 12 \rightarrow \frac{6\mu}{500n}$$

$$(\omega/L)_{M6} = 174 \rightarrow \frac{87\mu}{500n}$$

The W/L denoted in black are instance numbers in tool

$$M_7 = 75 \Rightarrow \frac{37.5\mu}{500n}$$

$$I_b, I_7 = 125\mu$$