WHITEBOARD" Final PRESENTATION

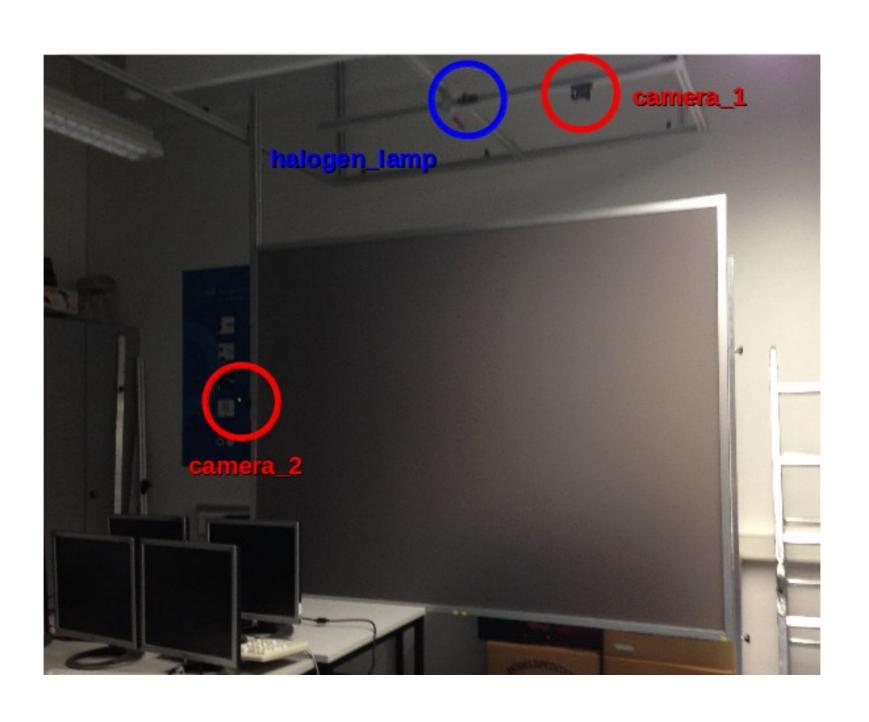
COMPUTER VISION ARGENTINA ORTEGA SAINZ NICOLAS LAVERDE ALFONSO Jan. 15 2015

Introduction

 Recognize the strokes made with a marker in a flat surface and to transform the strokes into drawings for later projection.

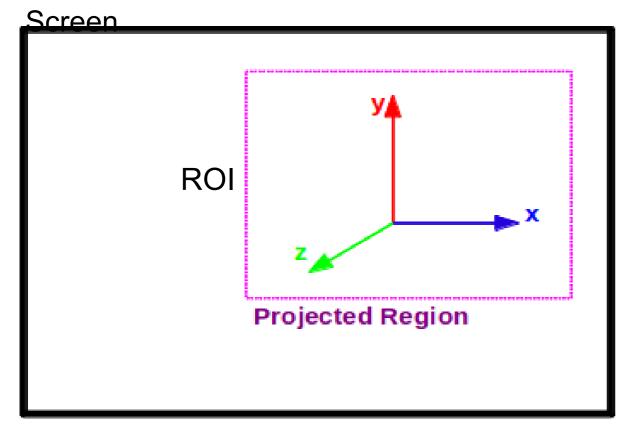
- Two synchronized cameras capture snapshots simultaneously.
- Process two snapshots from different perspectives to detect the position of a pre-defined marker.
- Draw detected strokes and project them into a screen for visualization.

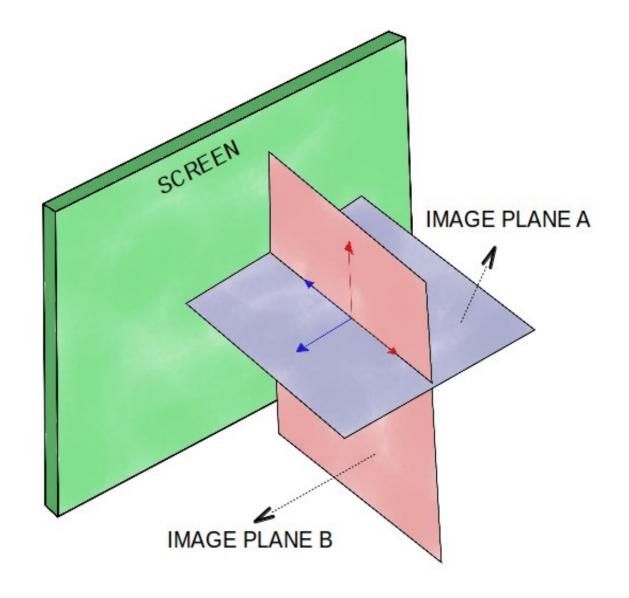
Description



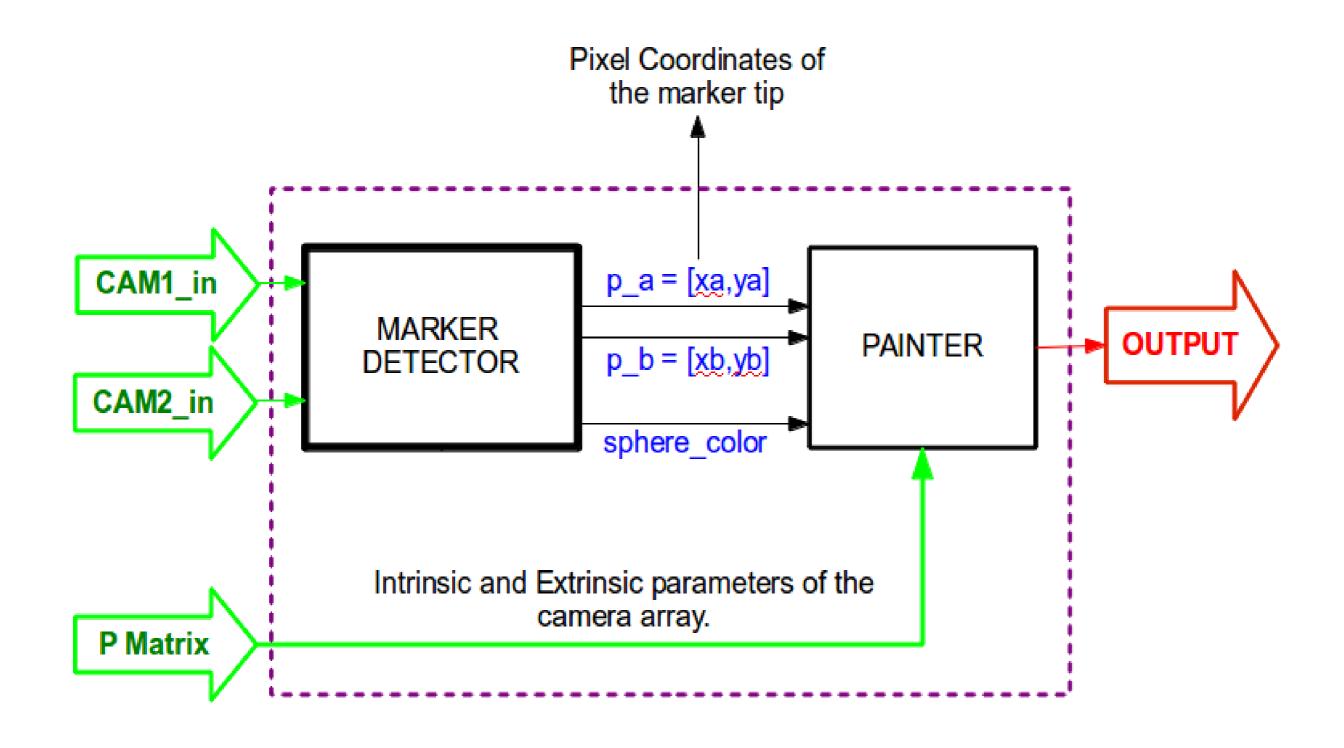
Description

Glass

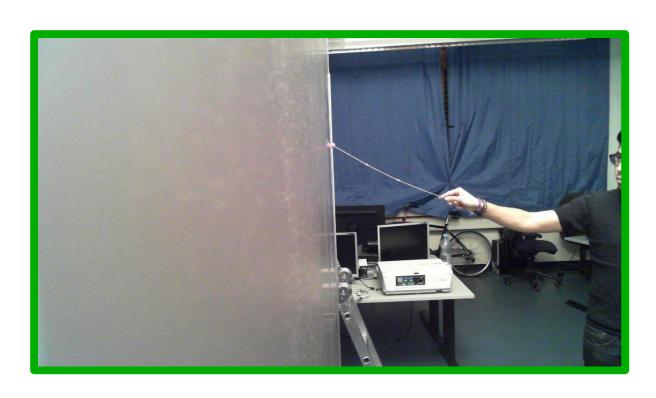


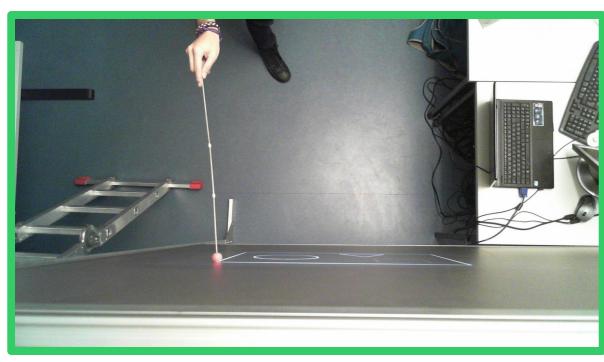


System Description



Input





Resolution: 1920x1080

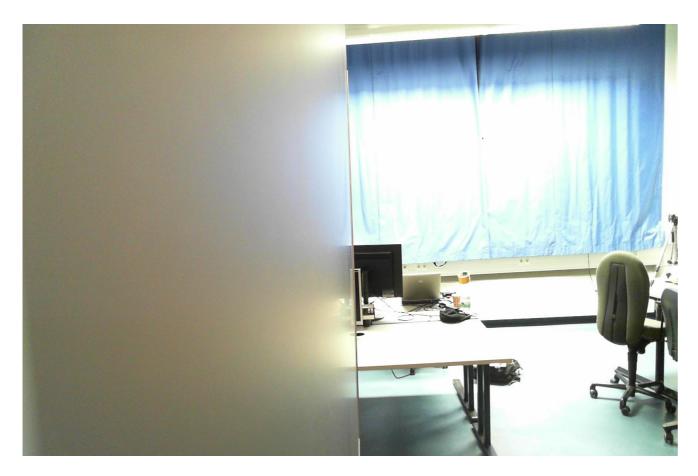
OFFLINE DESIGN:

50-100 frames (images) per view.

3 sessions "recorded", with three different colored markers (r,g,b).

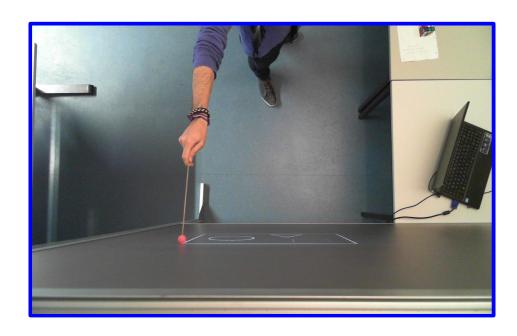
Calibration

Background

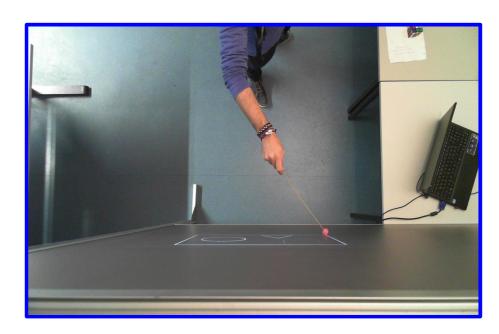




Calibration Corners

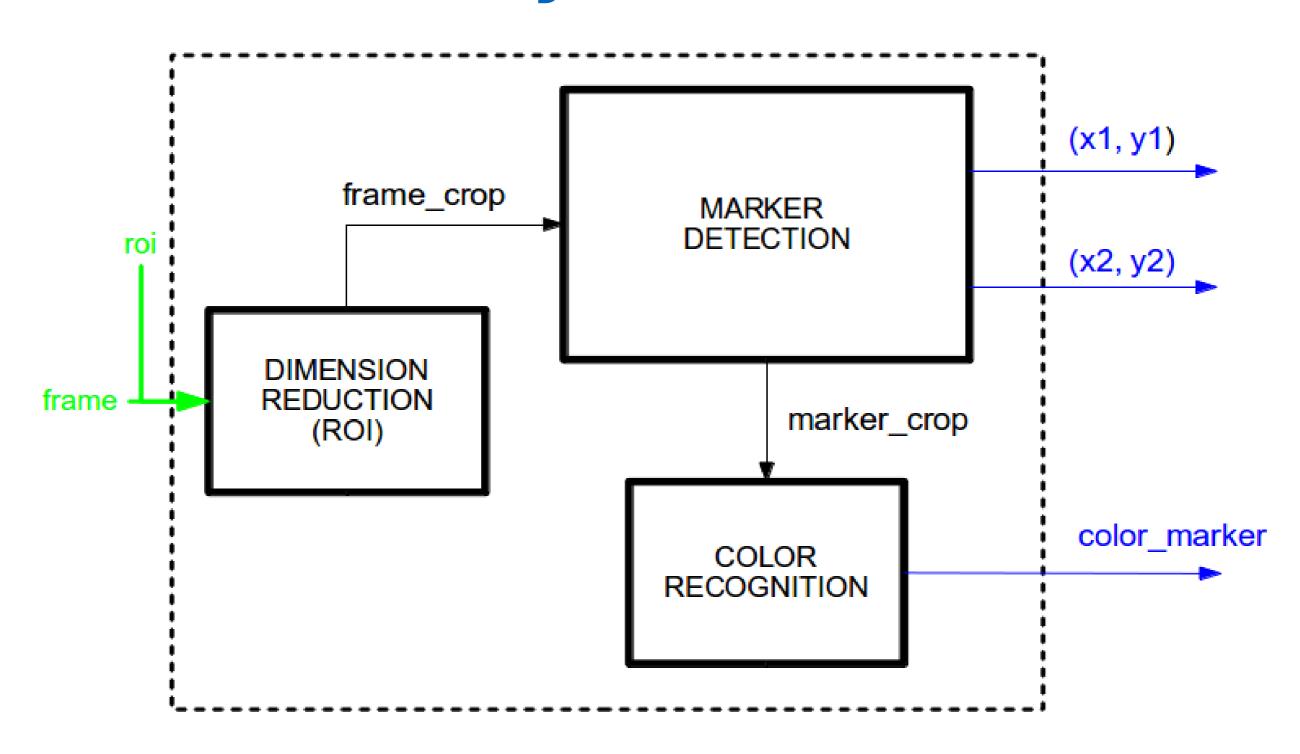






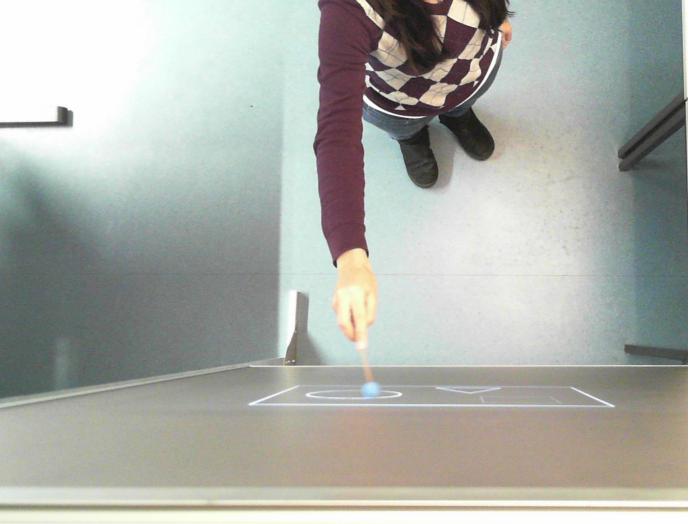


Marker Detector System

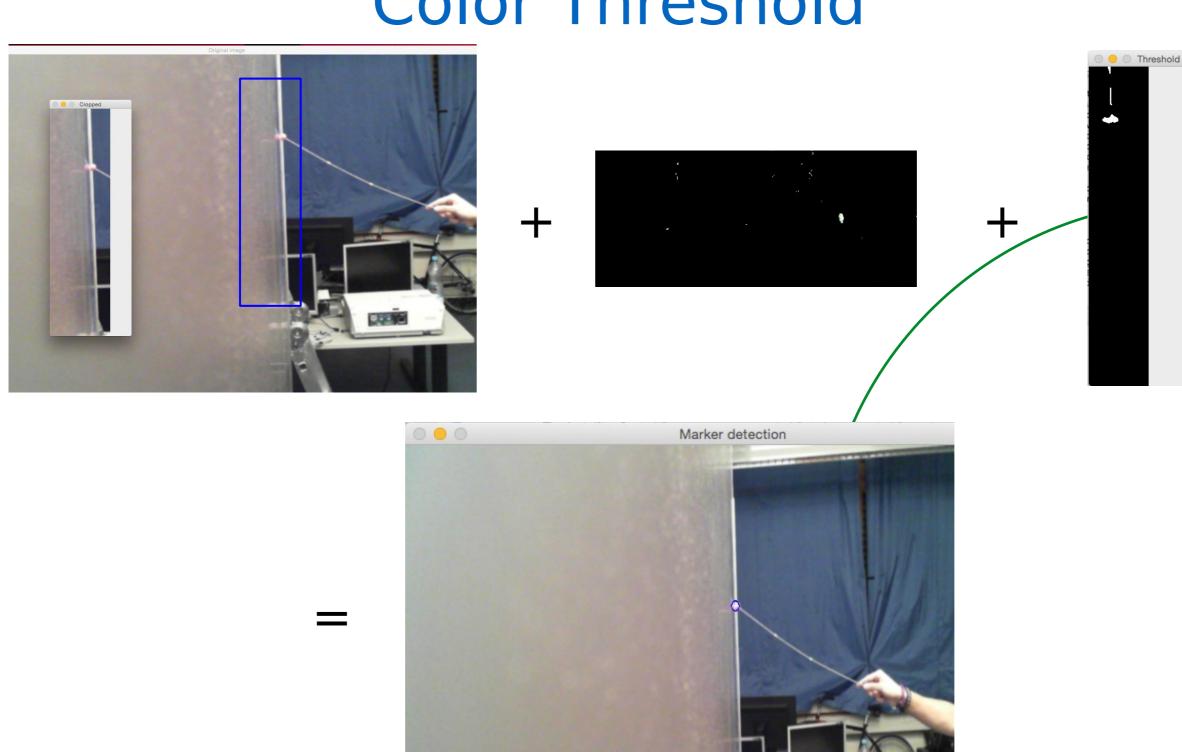


Results Data Synchronization





Marker Detection Color Threshold



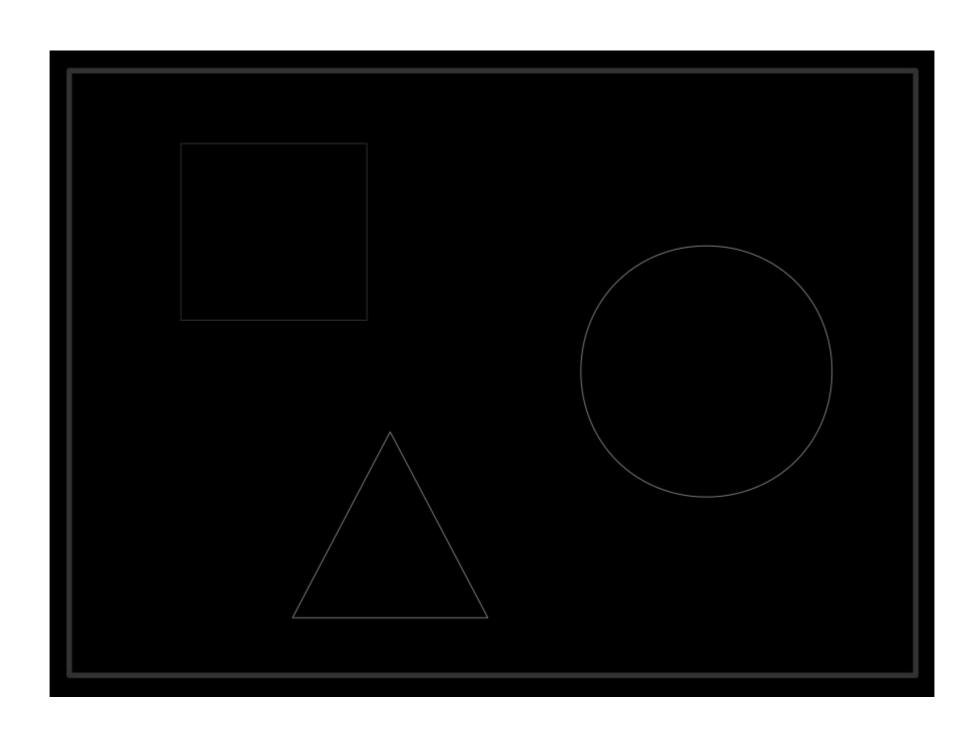
Marker Detection Background Difference





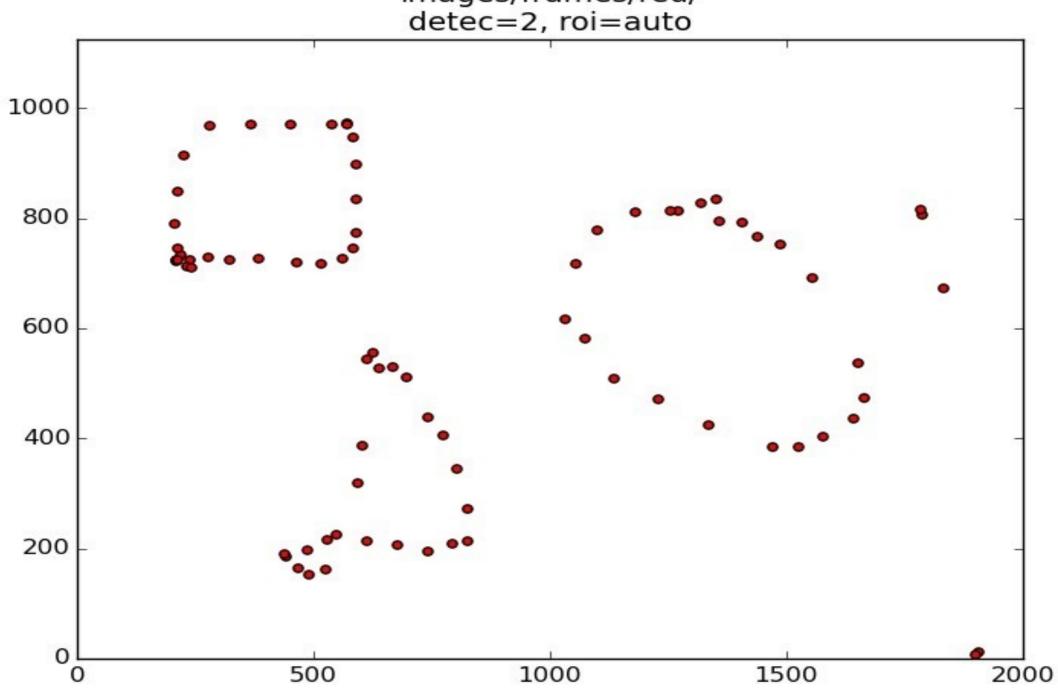


Guideline (Evaluation)



Results

images/frames/red/ detec=2, roi=auto



Results

