



THE UNIVERSITY OF
MELBOURNE

Support Vector Machines

COMP90051 Statistical Machine Learning

Semester 2, 2020

QiuHong Ke

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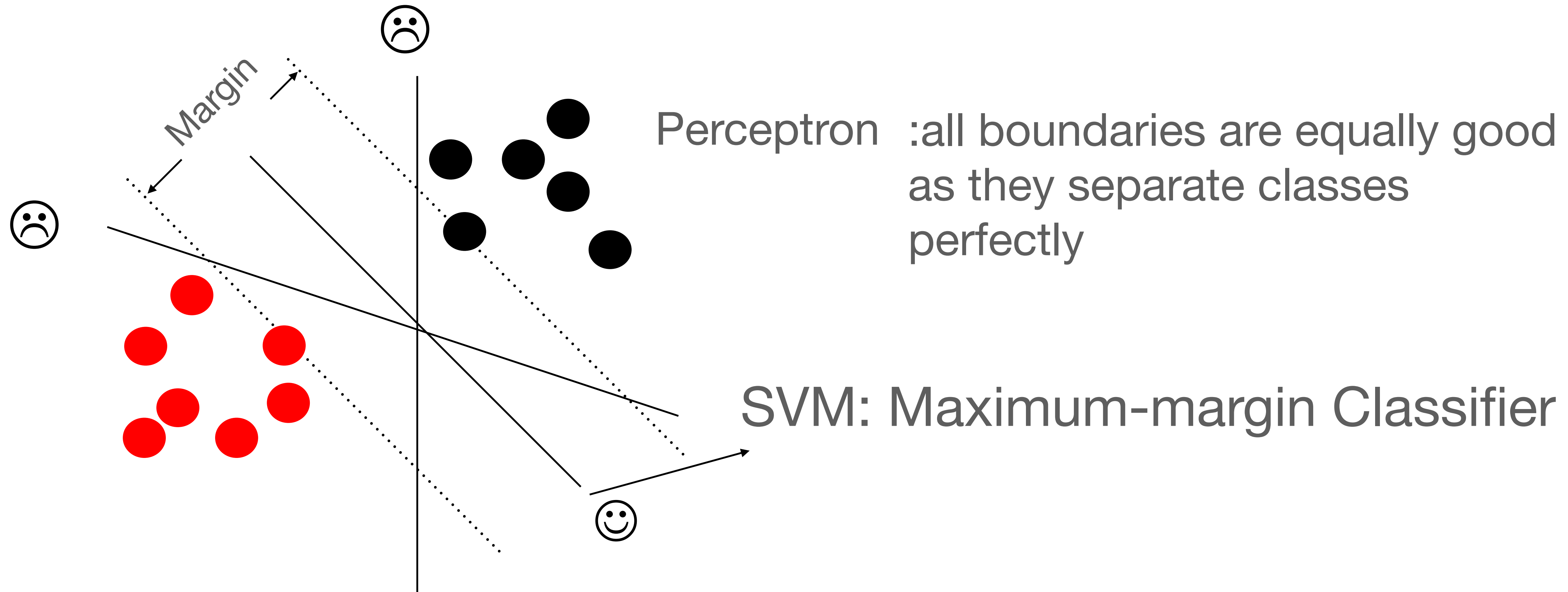
Before we start...

About me

- 2015.02-2018.04: PhD in UWA
- 2018.05-2019.12: Post-doc in MPII
- From 2020.01: Lecturer in UniMelb
- Research: Action recognition and prediction using machine learning
- Contact:
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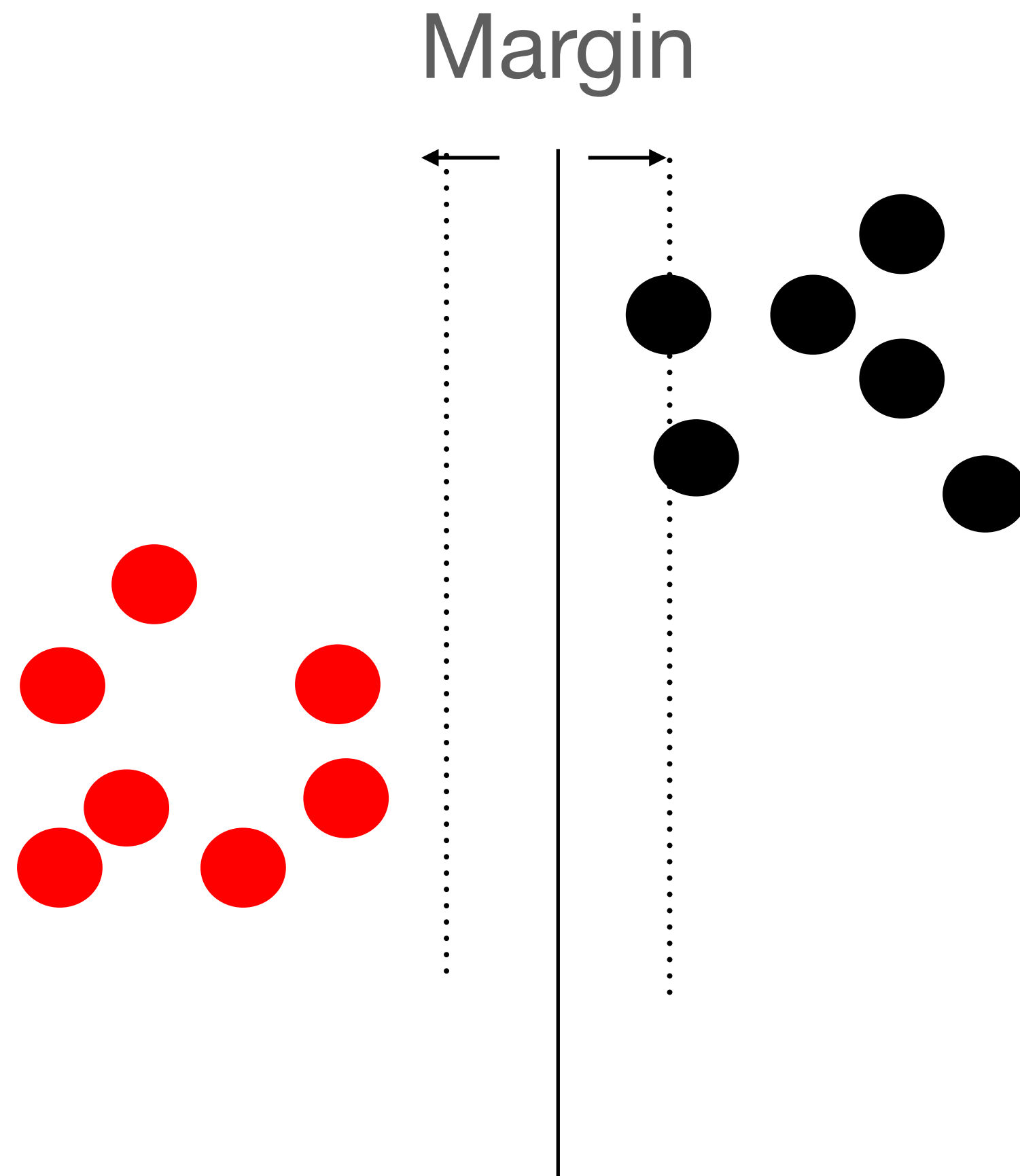
Binary Linear Classifier

SVM vs Perceptron



Binary Linear Classifier

SVM vs Perceptron



Margin: 2x minimum distance (boundary, data points)

Outline

- Margin
- Lagrange Duality
- Soft-margin SVM
- Kernels

Linear classifier

$$f(x) = w^T x + b$$

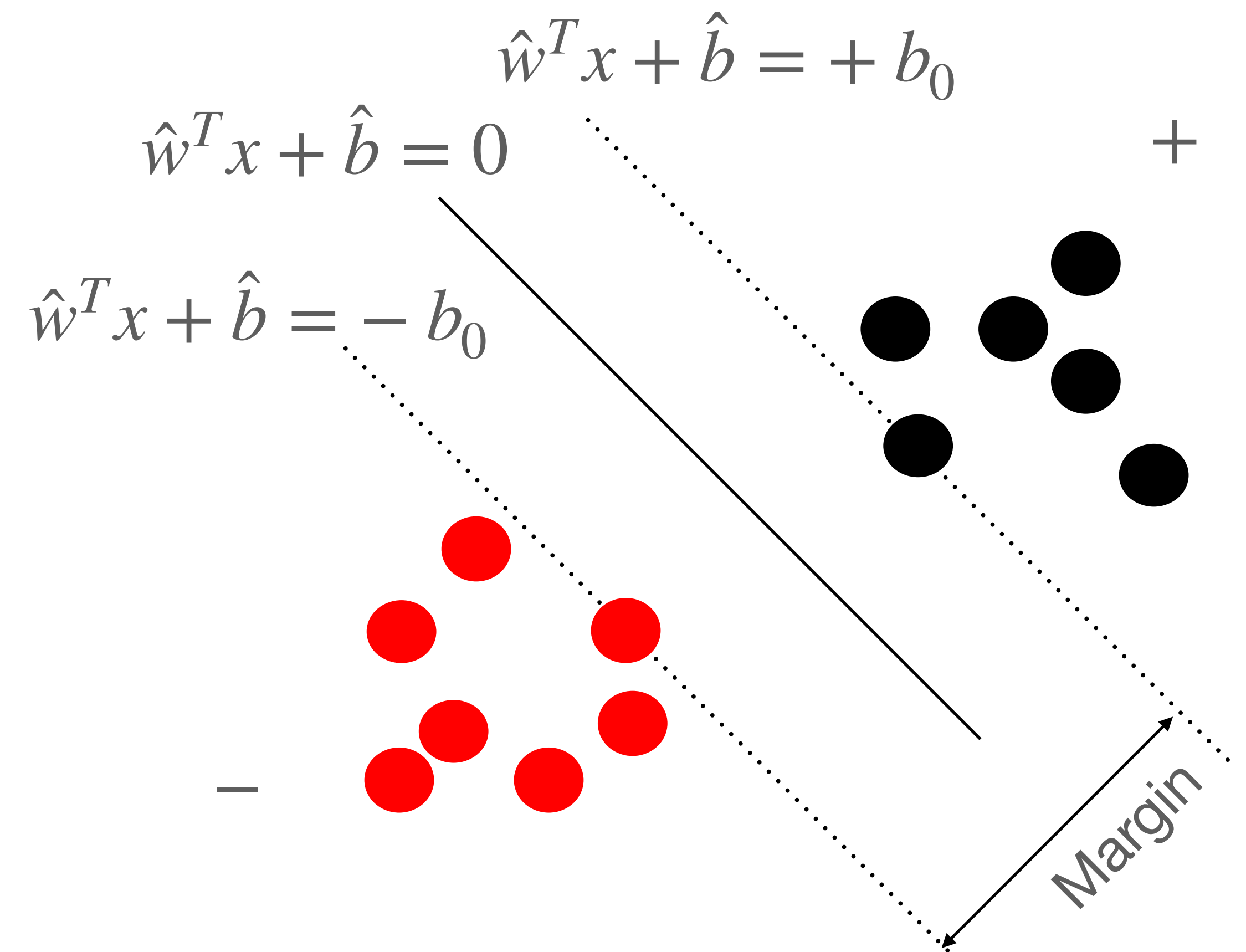
x : Feature vector (column)

w : Weight vector (column)

T : Transpose

b : Bias

$$w^T x = \|w\| \|x\| \cos \theta$$



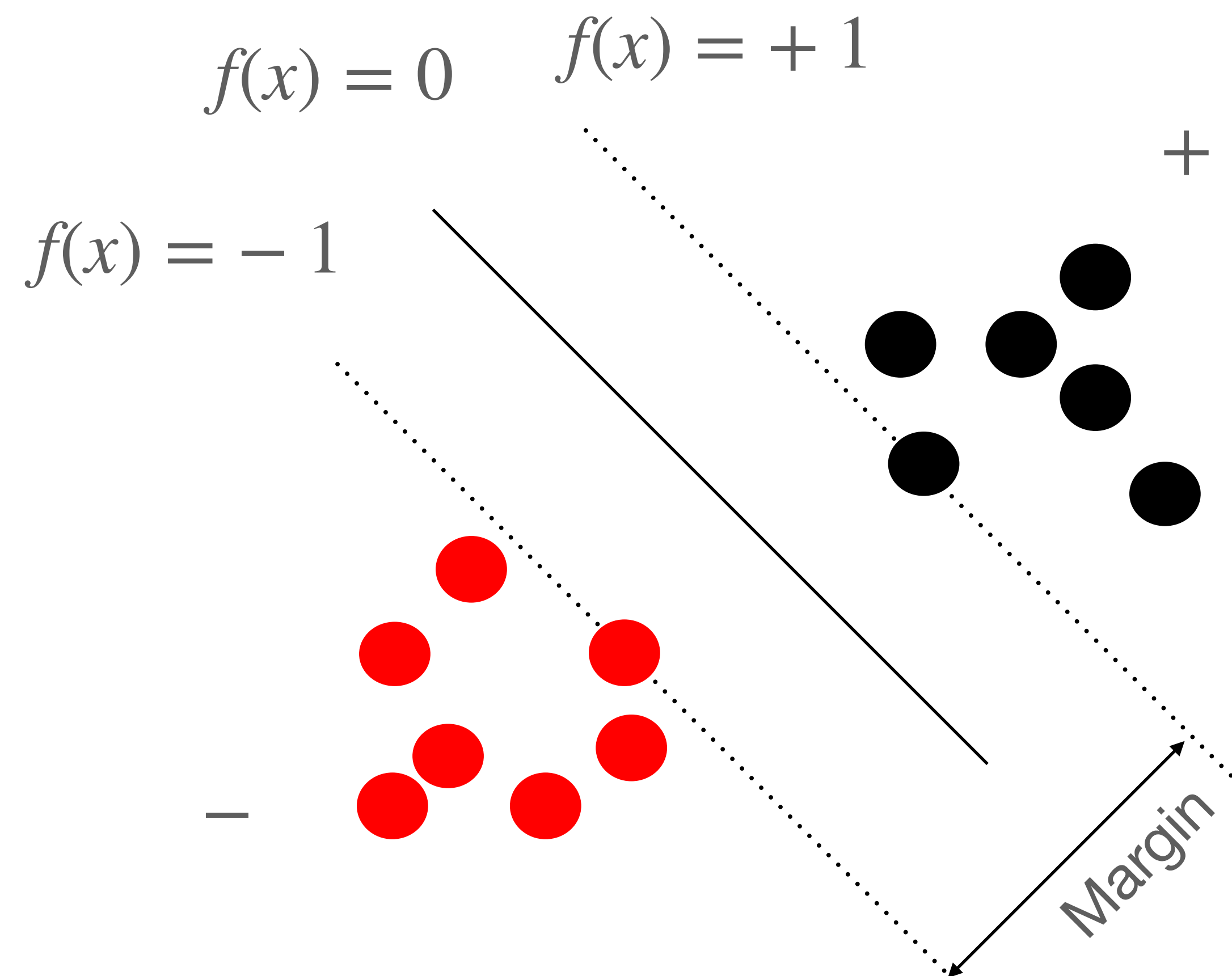
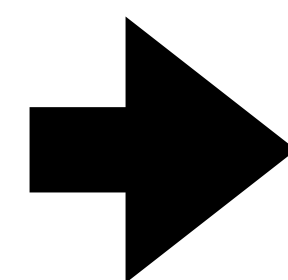
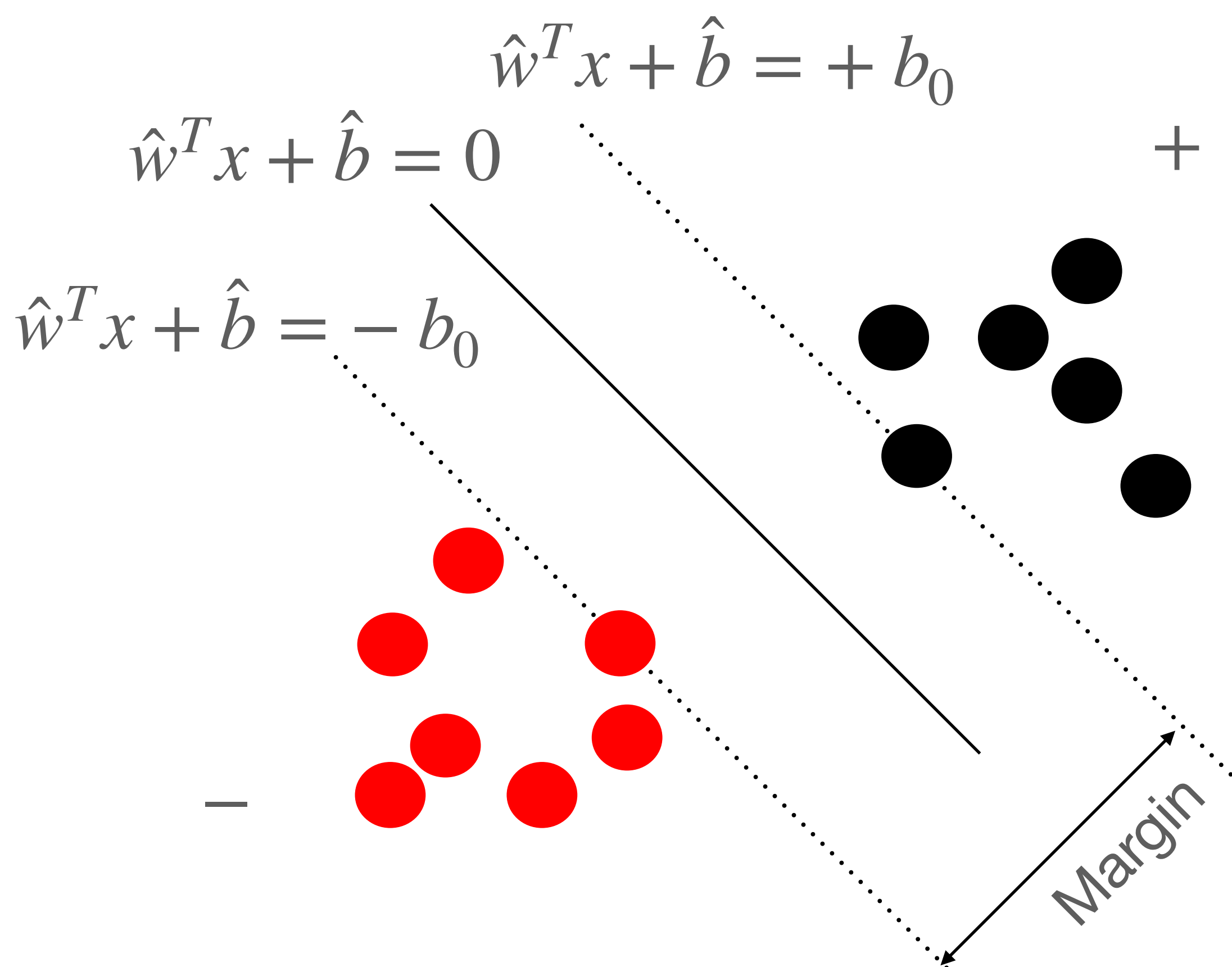
Margin

Lagrange Duality

Soft-margin SVM

Kernels

$$f(x) = w^T x + b \quad w = \frac{\hat{w}}{b_0} \quad b = \frac{\hat{b}}{b_0}$$



Margin formula

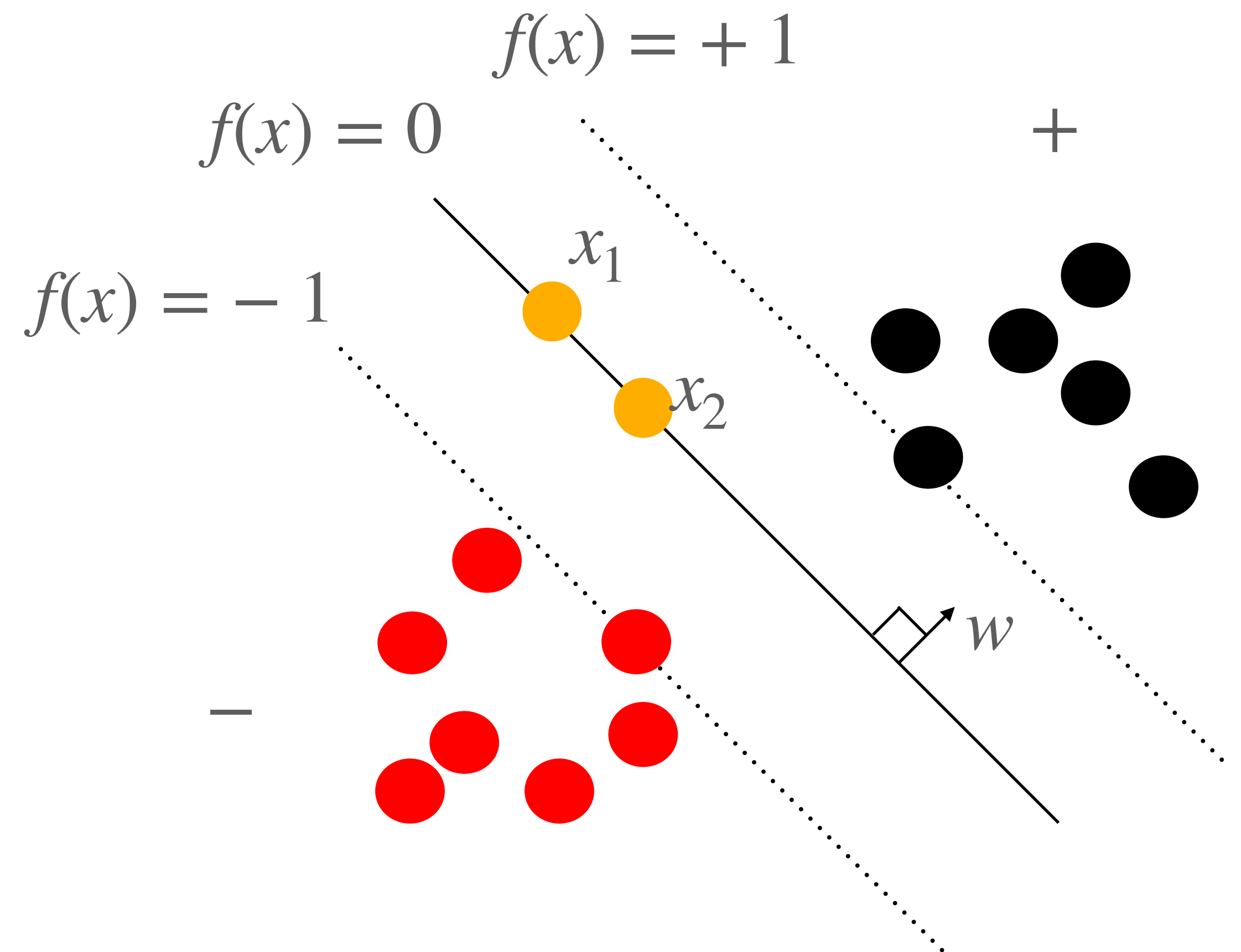
$$f(x) = w^T x + b$$

$$w^T x_1 + b = 0$$

$$w^T x_2 + b = 0$$

$$w^T (x_1 - x_2) = 0$$

$$\|w\| \|x_1 - x_2\| \cos\theta = 0$$



Margin formula

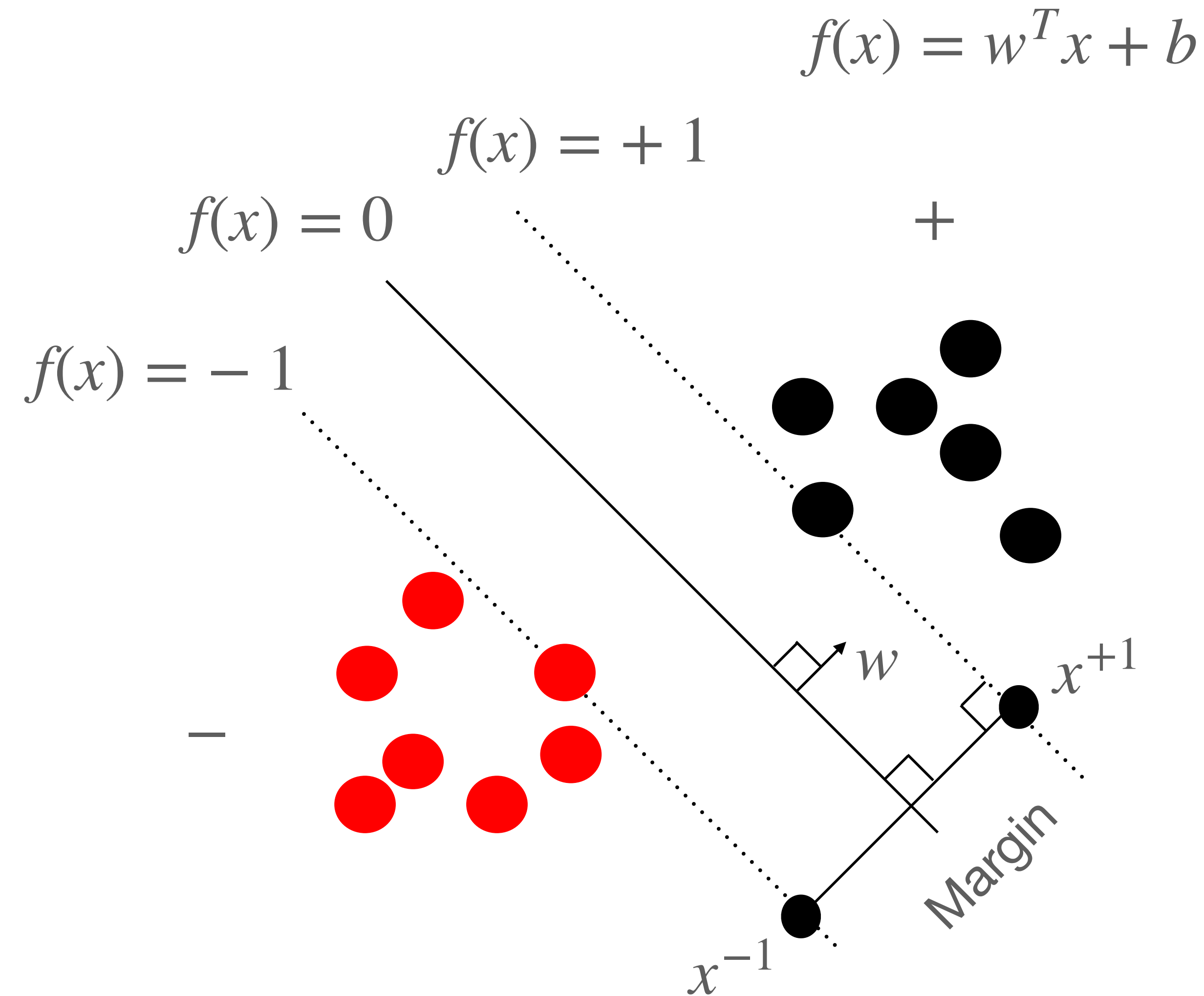
$$w^T x^{-1} + b = -1$$

$$w^T x^{+1} + b = 1$$

$$w^T (x^{+1} - x^{-1}) = 2$$

$$\|w\| \cdot \text{Margin} \cdot \cos\theta = 2$$

$$\text{Margin} = \frac{2}{\|w\|}$$

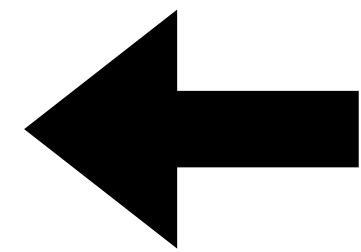


SVM: Constrained optimisation problem

$$\min_w \frac{\|w\|^2}{2}$$

s.t

$$1 - y^{(i)}(w^T x^{(i)} + b) \leq 0, \quad i = 1, \dots, n \text{ (data points)}$$



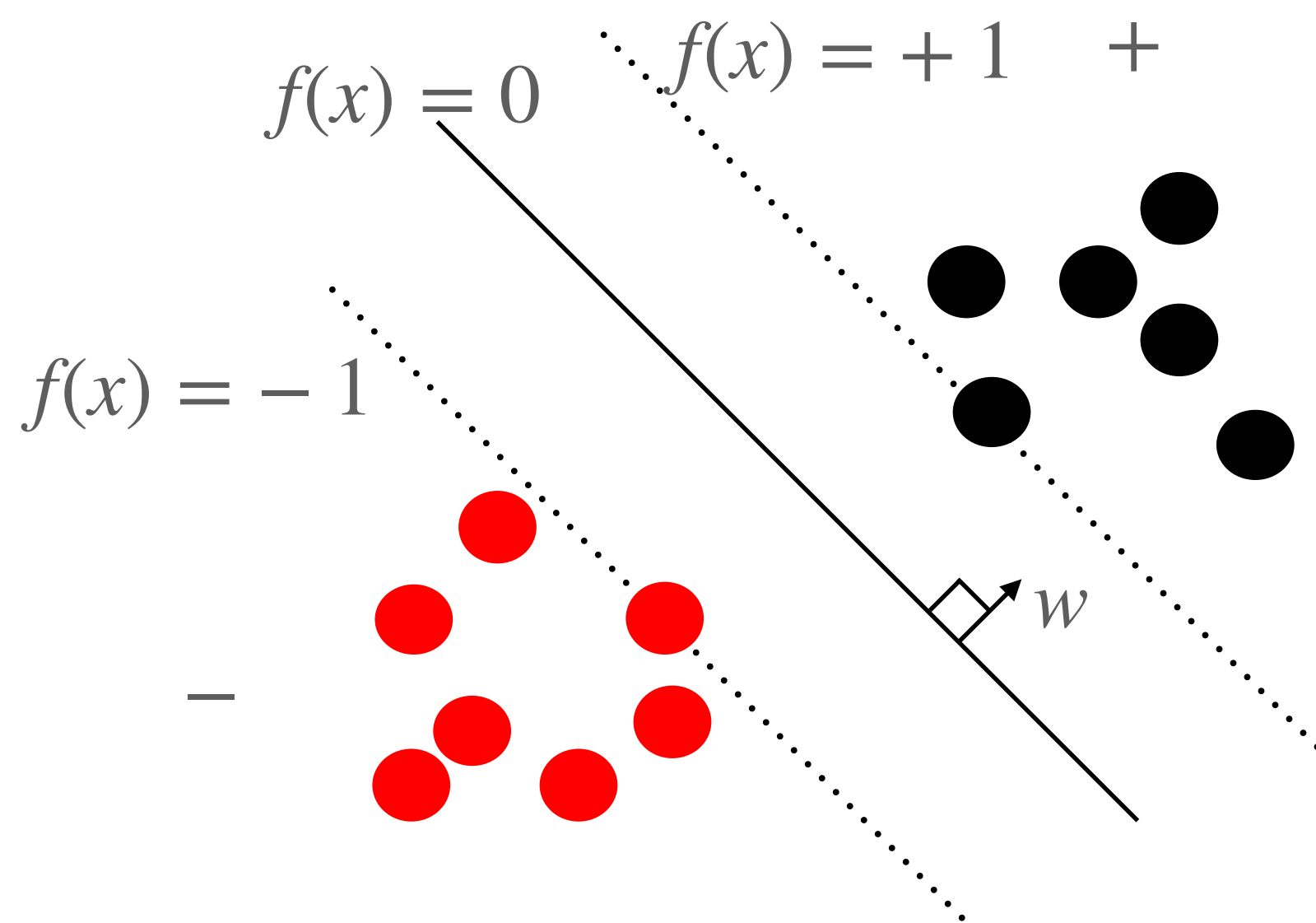
$$\max_w \frac{2}{\|w\|}$$

subject to

$$\text{if } y^{(i)} = +1 : f(x^{(i)}) = w^T x^{(i)} + b \geq +1$$

$$\text{if } y^{(i)} = -1 : f(x^{(i)}) = w^T x^{(i)} + b \leq -1$$

($i = 1, \dots, n$ data points)





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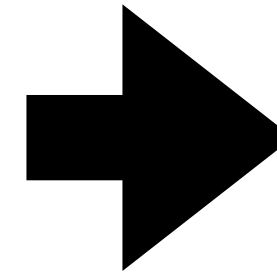
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Outline

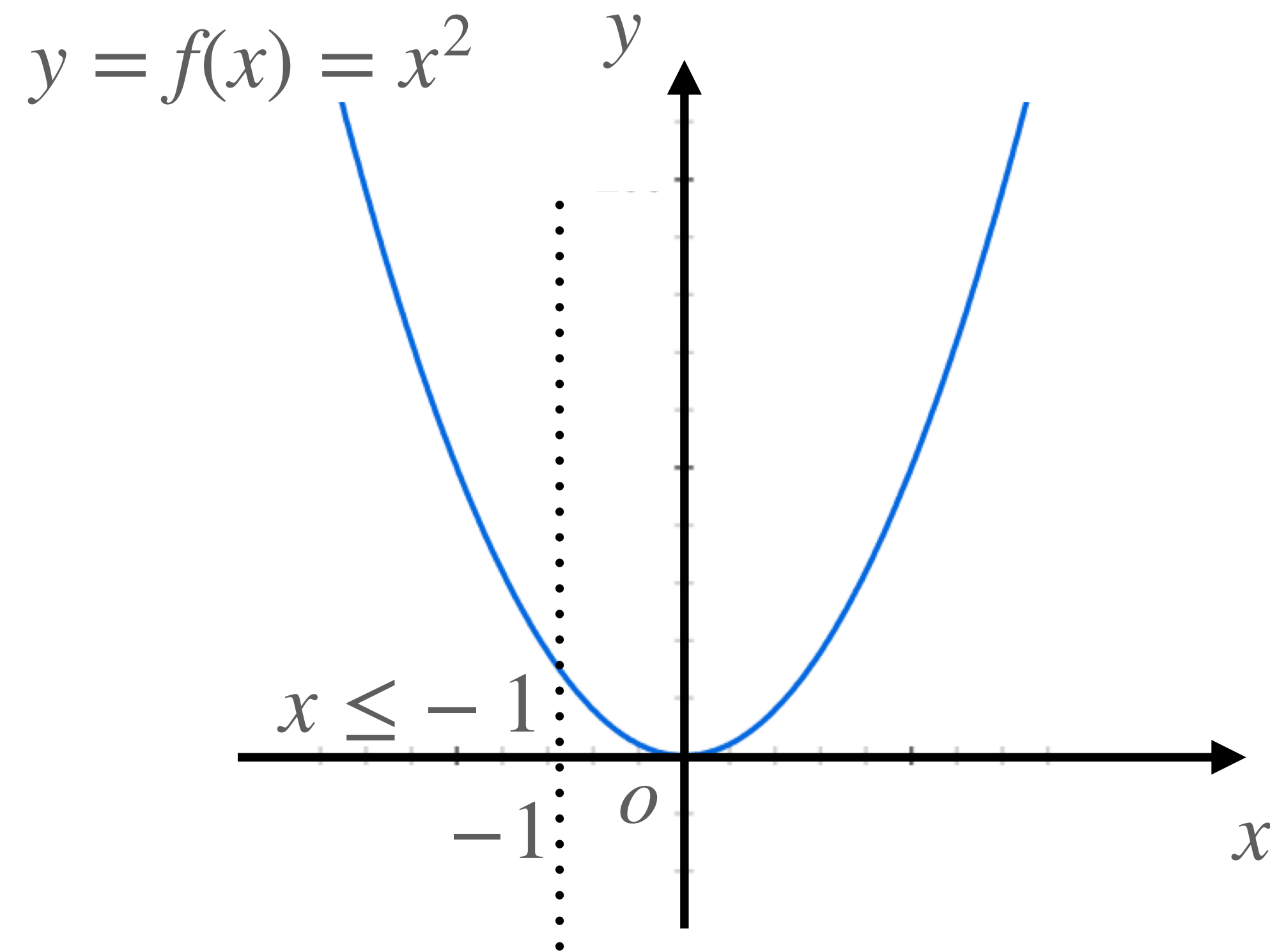
- Margin
- Lagrange Duality
- Soft-margin SVM
- Kernels

Primal problem

$$\begin{aligned} & \min_w \frac{\|w\|^2}{2} \\ & \text{s.t} \\ & 1 - y^{(i)}(w^T x^{(i)} + b) \leq 0, \quad i = 1, \dots, n \text{ (data points)} \end{aligned}$$

**Dual problem**

What's the dual problem?
**Why solving primal by
solving dual problem?**

Simple example

$$\begin{array}{ll} \min_x & x^2 \\ \text{s.t.} & x \leq -1 \end{array}$$

Primal problem

$$\min_x f(x)$$

$$\text{s.t. } g(x) = x + 1 \leq 0$$

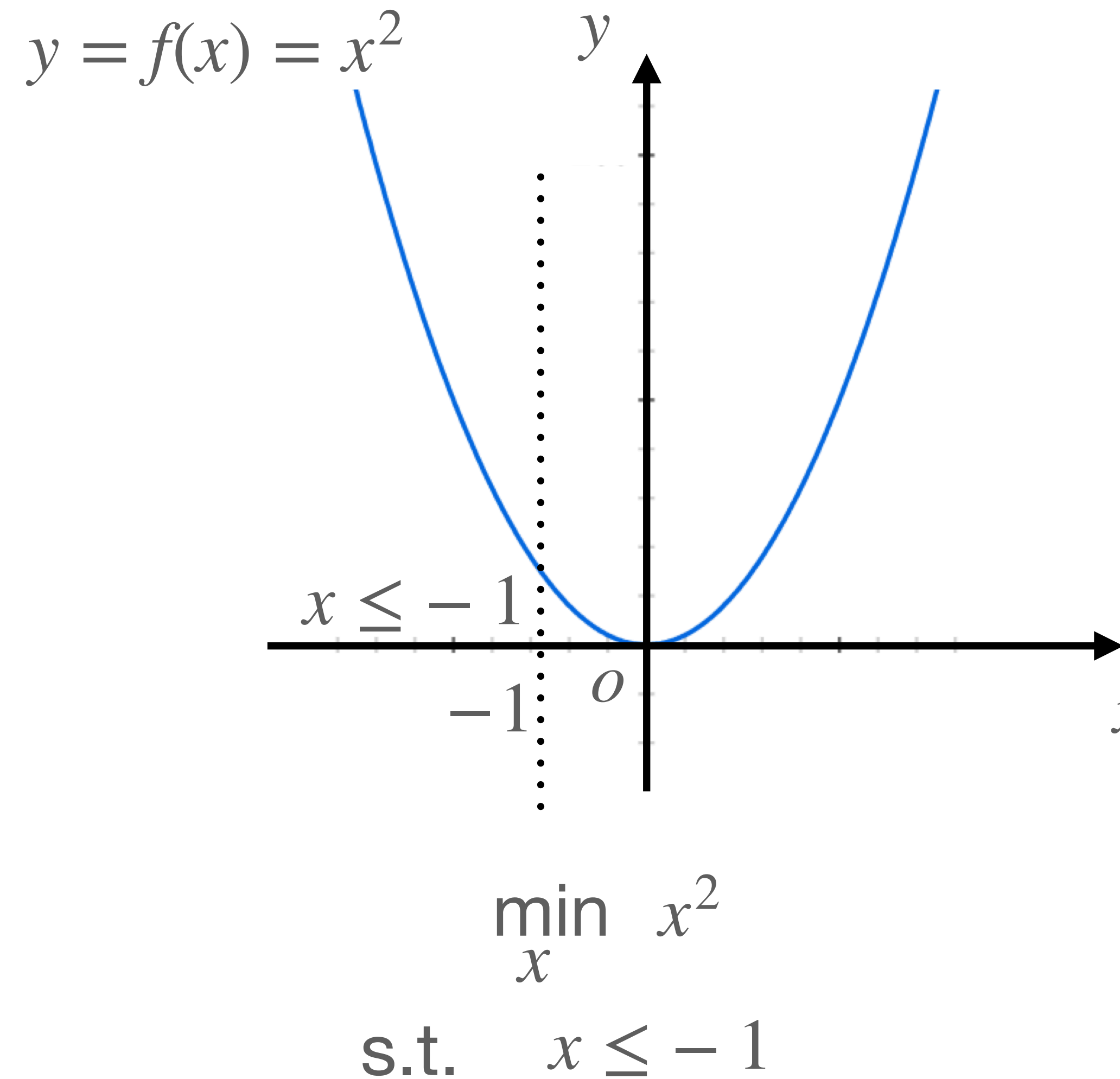
- Construct a function:

$$L(x, \lambda) = f(x) + \lambda g(x)$$

- Set $\lambda \geq 0$, calculate $\max_{\lambda} L(x, \lambda)$

$$g(x) > 0 : \max_{\lambda} L(x, \lambda) = \infty \text{ when } \lambda = \infty$$

$$g(x) \leq 0 : \max_{\lambda} L(x, \lambda) = f(x) \text{ when } \lambda = 0$$



Primal problem

$$\min_x f(x)$$

$$\text{s.t. } g(x) = x + 1 \leq 0$$

- Construct a function

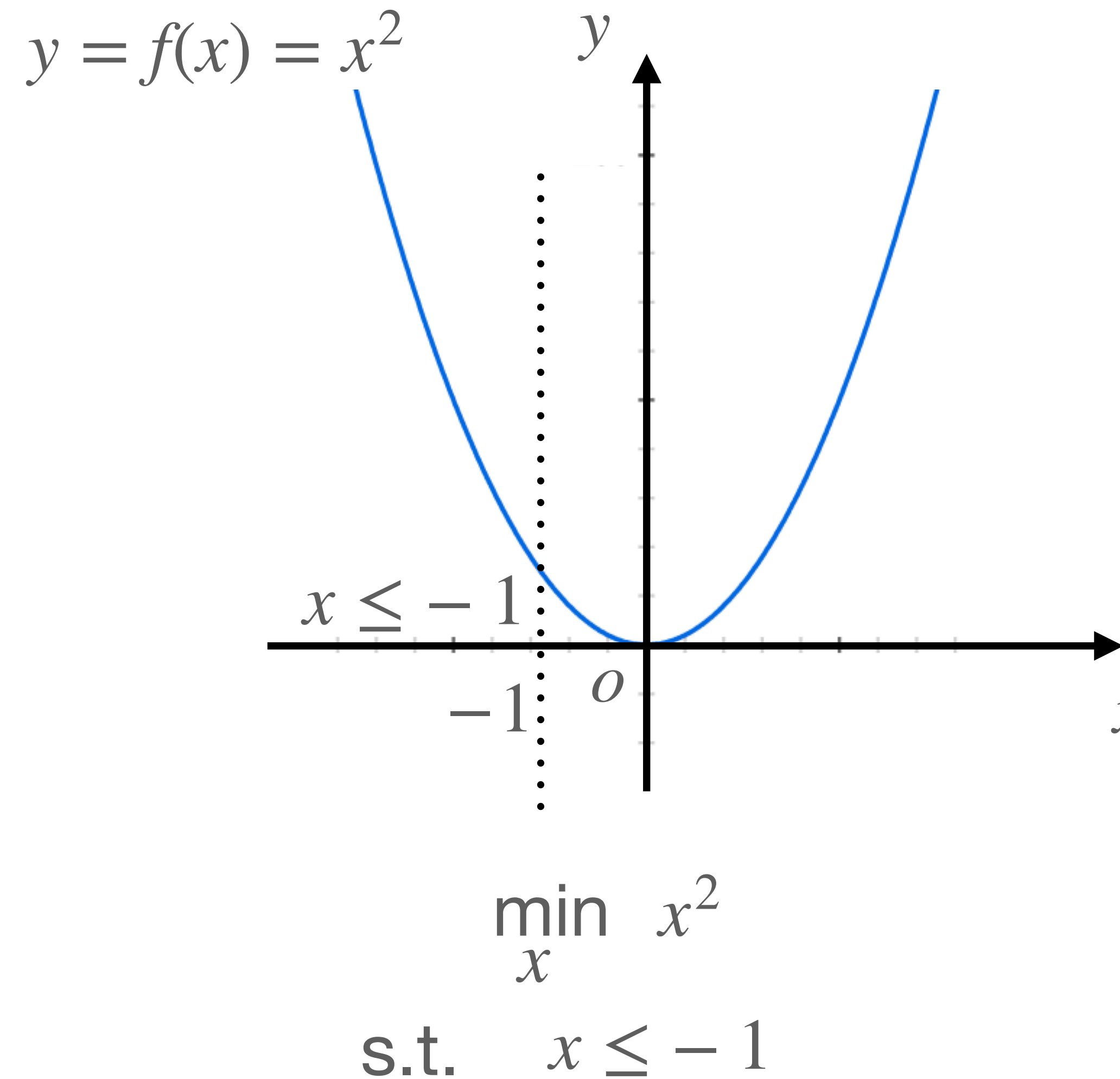
$$L(x, \lambda) = f(x) + \lambda g(x) : \quad \text{Lagrangian function}$$

$$\lambda \geq 0 : \quad \text{Lagrange multiplier}$$

- Primal function

$$\theta_p(x) = \max_{\lambda} L(x, \lambda) = f(x) \text{ if } g(x) \leq 0$$

$$\text{So: } \min_x f(x) = \min_x \theta_p(x) = \min_x \max_{\lambda} L(x, \lambda)$$



From primal to dual problem

$$L(x, \lambda) = f(x) + \lambda g(x)$$

$$\lambda \geq 0$$

$$g(x) \leq 0$$

- Primal problem:

$$\min_x f(x) = \min_x \max_{\lambda} L(x, \lambda)$$

- Dual problem:

$$\max_{\lambda} \min_x L(x, \lambda) = \max_{\lambda} \theta_d(\lambda)$$

$$\text{Dual function: } \theta_d(\lambda) = \min_x L(x, \lambda)$$

$$\theta_d(\lambda) = \min_x L(x, \lambda) \leq L(x, \lambda) = f(x) + \lambda g(x) \leq f(x)$$

From primal to dual problem

- Primal problem:

$$\min_x f(x) = \min_x \max_{\lambda} L(x, \lambda)$$

- Dual problem:

$$\max_{\lambda} \min_x L(x, \lambda) = \max_{\lambda} \theta_d(\lambda)$$

Solutions:

x^* makes $f(x)$ minimum : $f(x^*) = p^*$

λ^* makes $\theta_d(\lambda)$ maximum : $\theta_d(\lambda^*) = d^*$

$$\theta_d(\lambda) = \min_x L(x, \lambda) \leq L(x, \lambda) = f(x) + \lambda g(x) \leq f(x)$$

From primal to dual problem

- Primal problem:

$$\min_x f(x) = \min_x \max_{\lambda} L(x, \lambda)$$

- Dual problem:

$$\max_{\lambda} \min_x L(x, \lambda) = \max_{\lambda} \theta_d(\lambda)$$

$$\theta_d(\lambda) = \min_x L(x, \lambda) \leq L(x, \lambda) = f(x) + \lambda g(x) \leq f(x)$$

$$d^* = \theta_d(\lambda^*) = \min_x L(x, \lambda^*) \leq L(x^*, \lambda^*) = f(x^*) + \lambda^* g(x^*) \leq f(x^*) = p^*$$

Under some conditions: $d^* = p^*$

?

Solutions:

$$f(x^*) = p^* = \min_x f(x)$$

$$\theta_d(\lambda^*) = d^* = \max_{\lambda} \theta_d(\lambda)$$

From primal to dual problem

$$d^* = \theta_d(\lambda^*) = \min_x L(x, \lambda^*) \leq L(x^*, \lambda^*) = f(x^*) + \lambda^* g(x^*) \leq f(x^*) = p^*$$

$$\text{if } \min_x L(x, \lambda^*) = L(x^*, \lambda^*) \text{ and } f(x^*) + \lambda^* g(x^*) = f(x^*)$$

$$d^* = p^*$$

KKT (Karush-Kuhn-Tucker) conditions :

$$g(x) \leq 0 \quad (\text{Primal feasibility})$$

$$\lambda \geq 0 \quad (\text{Dual feasibility})$$

$$\lambda g(x) = 0 \quad (\text{Complementary slackness})$$

$$\frac{\partial L}{\partial x} = 0 \quad (\text{Stationarity})$$

Dual problem of SVM

Primal problem $\min_w \frac{\|w\|^2}{2}$

s.t. $g_i(w, b) = 1 - y^{(i)}(w^T x^{(i)} + b) \leq 0, i = 1, \dots, n$ data points

(1) Lagrangian function:

$$L(w, b, \lambda) = \frac{\|w\|^2}{2} + \sum_{i=1}^n \lambda_i (1 - y^{(i)}(w^T x^{(i)} + b))$$

(2) dual function $\theta_d(\lambda) = \min_{w, b} L(w, b, \lambda) :$

$$\frac{\partial L}{\partial w_j} = 0 : w_j = \sum_{i=1}^n \lambda_i y^{(i)} x_j^{(i)}$$

$$\frac{\partial L}{\partial b} = 0 : \sum_{i=1}^n \lambda_i y^{(i)} = 0$$

Dual problem of SVM

Dual function

$$\theta_d(\lambda) = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \lambda_i \lambda_k y^{(i)} y^{(k)} (x^{(i)})^T x^{(k)}$$

Dual problem

$$\begin{aligned} & \max_{\lambda} \theta_d(\lambda) \\ \text{s.t.} \quad & \lambda_i \geq 0 \quad \text{and} \quad \sum_{i=1}^n \lambda_i g_i(x) = 0 \end{aligned}$$

Support vectors

$$\min \frac{\|w\|^2}{2} \quad \text{s.t.} \quad g_i(w, b) = 1 - y^{(i)}(w^T x^{(i)} + b) \leq 0, \quad i = 1, \dots, n \text{ data points}$$

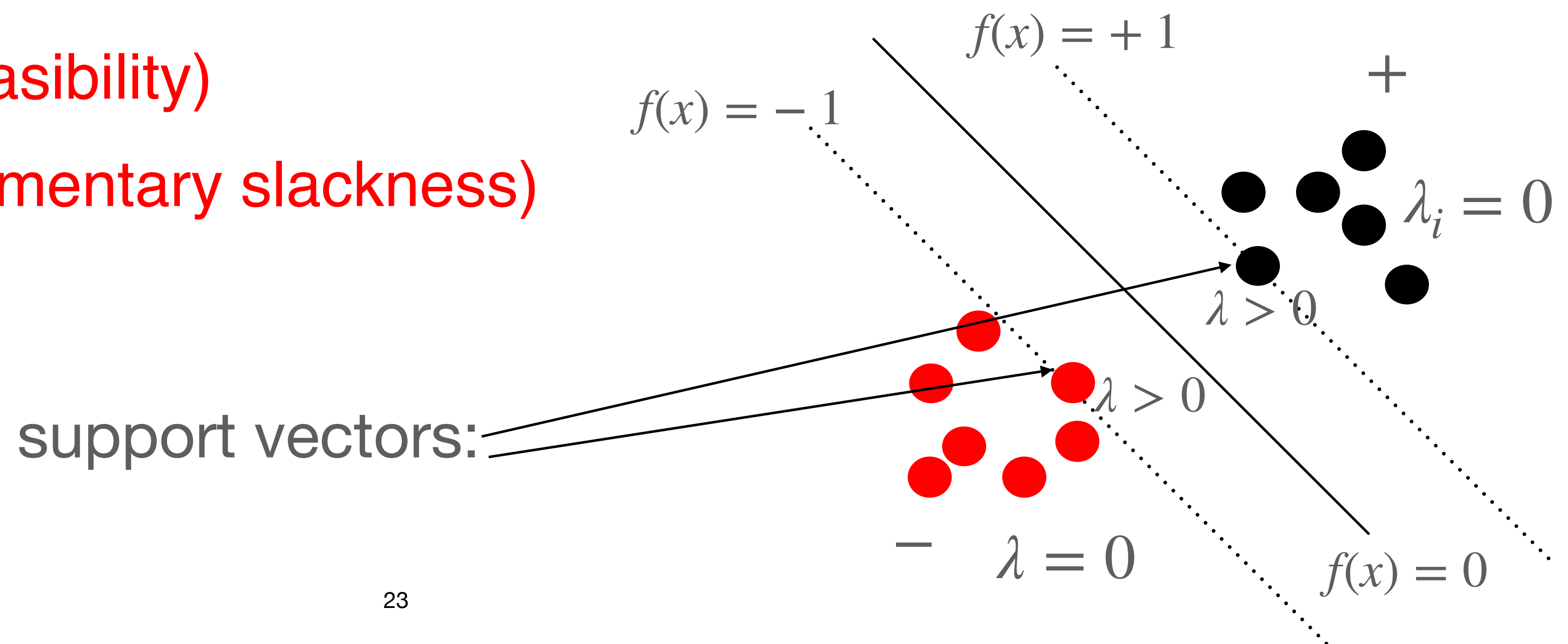
Lagrangian function:
$$L(w, b, \lambda) = \frac{\|w\|^2}{2} + \sum_{i=1}^n \lambda_i (1 - y^{(i)}(w^T x^{(i)} + b))$$

$$\lambda_i \geq 0$$

(Dual feasibility)

$$\lambda_i g_i(w, b) = 0$$

(Complementary slackness)



Primal vs Dual (Training)

- Primal problem: solve $d+1$ variables (w_j and b) (d : dimension of weight vector w)

$$\text{s.t.} \quad \min_w \frac{\|w\|^2}{2}$$

$$g_i(w, b) = 1 - y^{(i)}(w^T x^{(i)} + b) \leq 0, \quad i = 1, \dots, n \text{ data points}$$

- Dual problem: solve n variables (λ_i)

$$\begin{aligned} & \max_{\lambda} \theta_d(\lambda) \quad \theta_d(\lambda) = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \lambda_i \lambda_k y^{(i)} y^{(k)} (x^{(i)})^T x^{(k)} \\ & \text{s.t.} \quad \lambda_i \geq 0 \text{ and } \sum_{i=1}^n \lambda_i g_i(x) = 0 \end{aligned}$$

If data size n is large, ($n \gg d$) solving dual problem is slower than solving primal problem, and vice versa.

Primal vs Dual (Prediction)

- Primal form:

$$f(x) = w^T x + b \quad \begin{array}{l} f(x) > 0 : \text{positive class} \\ f(x) < 0 : \text{negative class} \end{array}$$

- Dual form:

$$w_j = \sum_{i=1}^n \lambda_i y^{(i)} x_j^{(i)}$$
$$f(x) = \sum_{i=1}^n \lambda_i y^{(i)} (x^{(i)})^T x + b$$

(b can be solved using support vectors: $f(x) = \pm 1$)

Why bother solving dual problem to solve primal problem

Training, solve:

$$\begin{aligned} \max_{\lambda} \quad & \theta_d(\lambda) \\ \text{s.t.} \quad & \lambda_i \geq 0 \text{ and } \sum_{i=1}^n \lambda_i g_i(x) = 0 \end{aligned} \quad \theta_d(\lambda) = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \lambda_i \lambda_k y^{(i)} y^{(k)} (x^{(i)})^T x^{(k)}$$

$$\text{Prediction: } f(x) = \sum_{i=1}^n \lambda_i y^{(i)} (x^{(i)})^T x + b$$

- Use only support vectors for prediction: Efficient in prediction
- Inner product: Kernel trick can be used to efficiently handle non-linearly separable data



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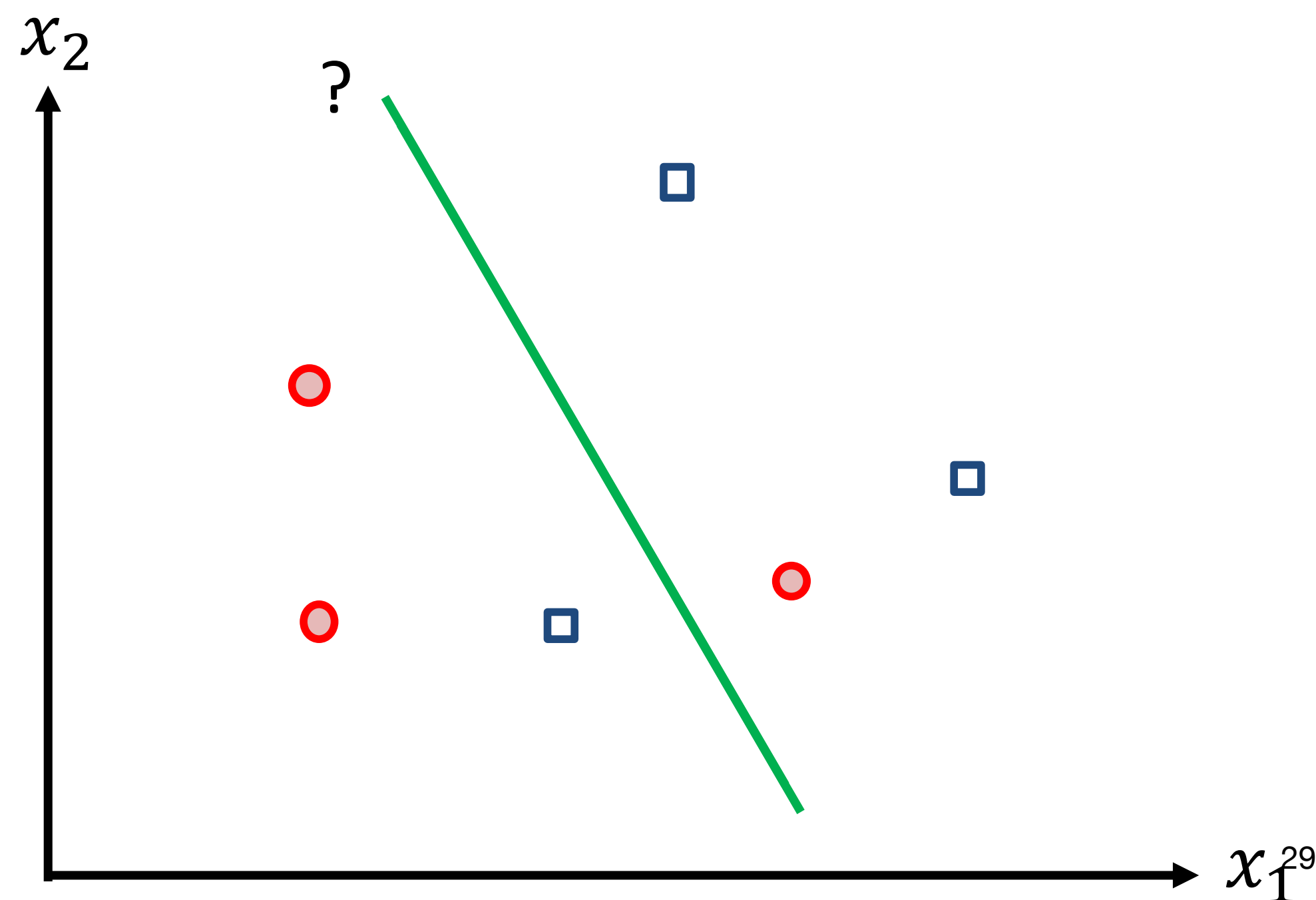
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Outline

- Margin
- Lagrange Duality
- **Soft-margin SVM**
- Kernels

Data not linearly separable

- Hard-margin loss is too stringent (*hard!*)
- Real data is unlikely to be linearly separable
- If the data is not separable, hard-margin SVMs are in trouble

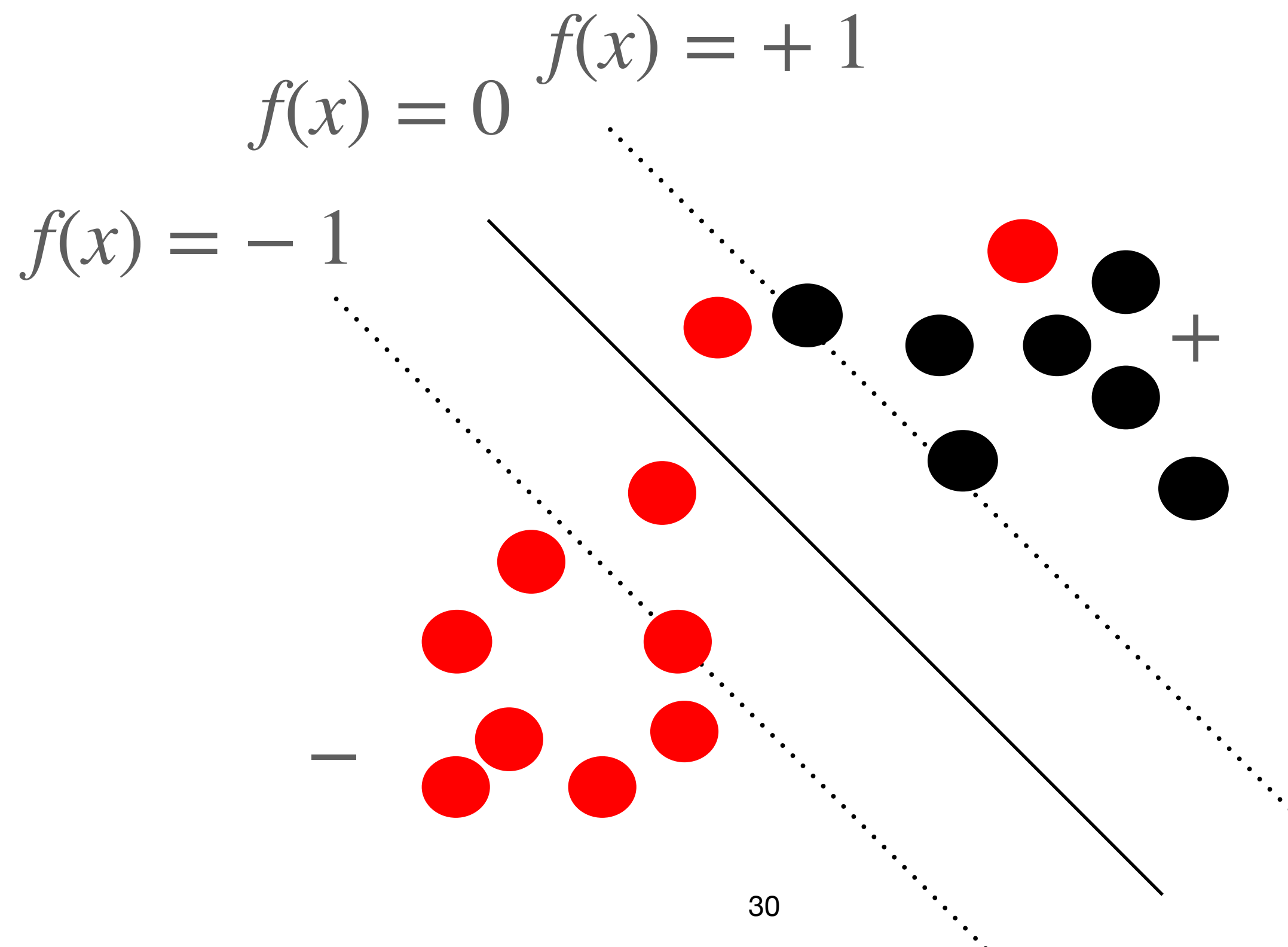


SVMs offer 3 approaches to address this problem:

1. *Relax* the constraints (soft-margin)
2. Still use hard-margin SVM, but *transform* the data (kernel)
3. The combination of 1 and 2 😊

Soft-margin SVM: 'soft' constraint

- Relax constraints to allow points to be **inside the margin** or even on the **wrong side** of the boundary



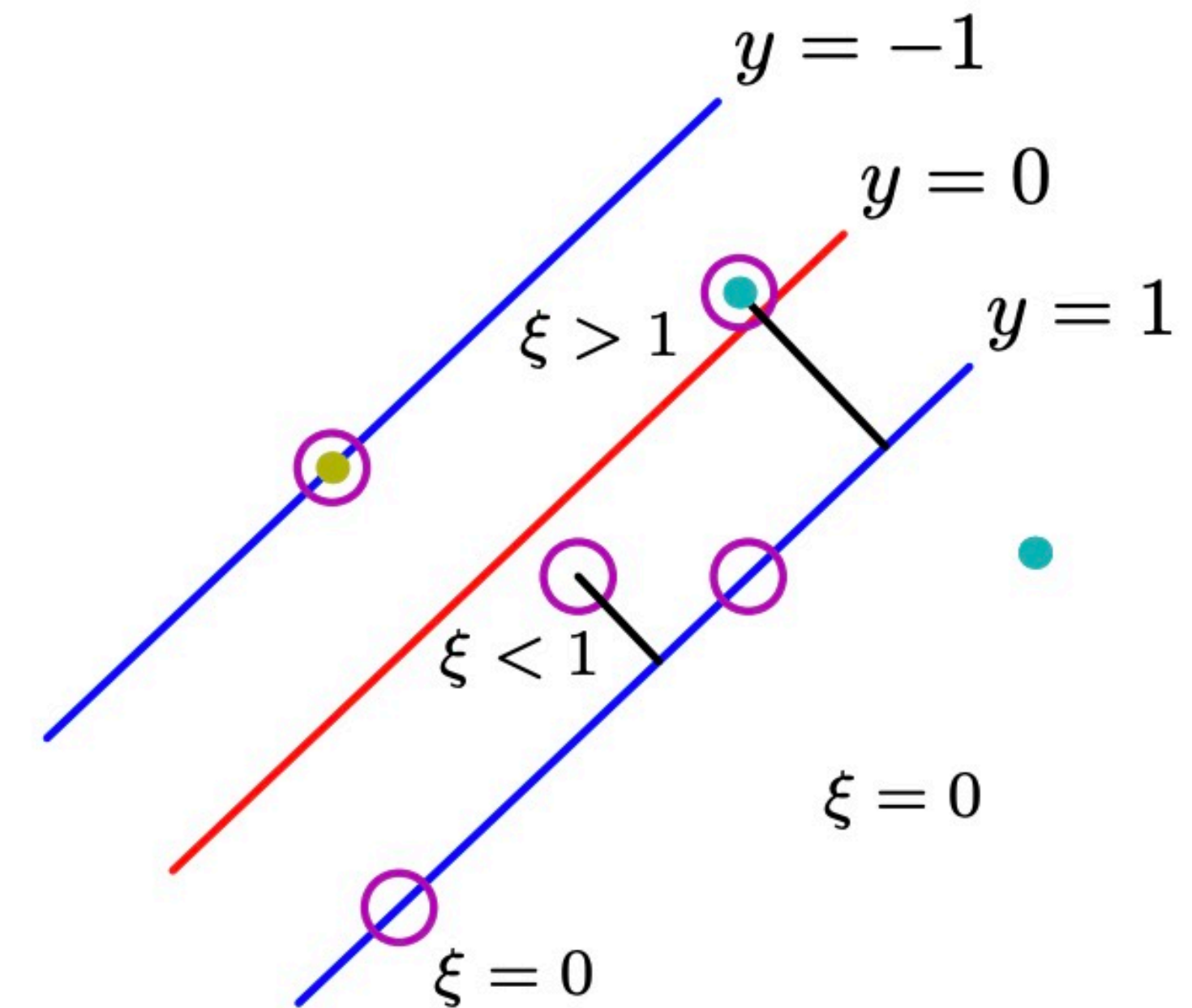
Objective of soft-margin SVM

$$\min_w \left(\frac{\|w\|^2}{2} + C \sum_{i=1}^n \xi_i \right) \quad \text{s.t.} \quad \begin{aligned} & y^{(i)}(w^T x^{(i)} + b) \geq 1 - \xi_i, \\ & \xi_i \geq 0 \quad (i = 1, \dots, n \text{ data points}) \end{aligned}$$

Use slack variable to 'soft' constraint:
allow violation of the constraint

$$\xi_i = \begin{cases} 0, & y^{(i)}(w^T x^{(i)} + b) \geq 1, \\ 1 - y^{(i)}(w^T x^{(i)} + b), & \text{otherwise} \end{cases}$$

or $\xi_i = \max(0, 1 - y^{(i)}(w^T x^{(i)} + b))$ **hinge loss**

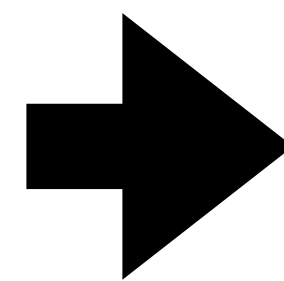


Objective of soft-margin SVM

$$\min_w \left(\frac{\|w\|^2}{2} + C \sum_{i=1}^n \xi_i \right) \quad \text{s.t.} \quad \begin{aligned} y^{(i)}(w^T x^{(i)} + b) &\geq 1 - \xi_i, \\ \xi_i &\geq 0 \end{aligned} \quad (i = 1, \dots, n \text{ data points})$$

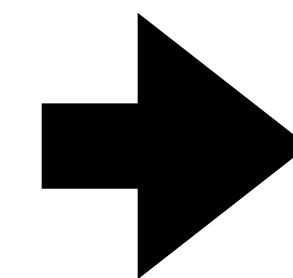
Slack penalty: $C > 0$

If $C = 0$: data is ignored



Underfitting

If $C = \infty$: data has to be correctly classified



Overfitting

KKT

$$L(w, b, \lambda, \beta, \xi) = \frac{\|w\|^2}{2} + C \sum_{i=1}^n \xi_i + \sum_{i=1}^n \lambda_i g_i(w, b, \xi) + \sum_{i=1}^n \beta_i (-\xi_i)$$

$$g_i(w, b, \xi) = 1 - \xi_i - y^{(i)}(w^T x^{(i)} + b) \leq 0 \quad -\xi_i \leq 0$$

Primal feasibility: $g_i(w, b, \xi) \leq 0 \quad -\xi_i \leq 0$

Dual feasibility $\lambda_i \geq 0 \quad \beta_i \geq 0$

Complementary slackness $\lambda_i g_i(w, b, \xi) = 0 \quad \beta_i \xi_i = 0$

Stationarity $\frac{\partial L}{\partial w_j} = 0 : w_j = \sum_{i=1}^n \lambda_i y^{(i)} x_j^{(i)} \quad \frac{\partial L}{\partial b} = 0 : \sum_{i=1}^n \lambda_i y^{(i)} = 0$

$$\frac{\partial L}{\partial \xi_i} = 0 : C - \lambda_i - \beta_i = 0$$

KKT

Primal feasibility: $g_i(w, b, \xi) = 1 - \xi_i - y^{(i)}(w^T x^{(i)} + b) \leq 0, \quad -\xi_i \leq 0$

Dual feasibility $\lambda_i \geq 0 \quad \beta_i \geq 0$

Complementary slackness $\lambda_i g_i(w, b, \xi) = 0 \quad \beta_i \xi_i = 0$

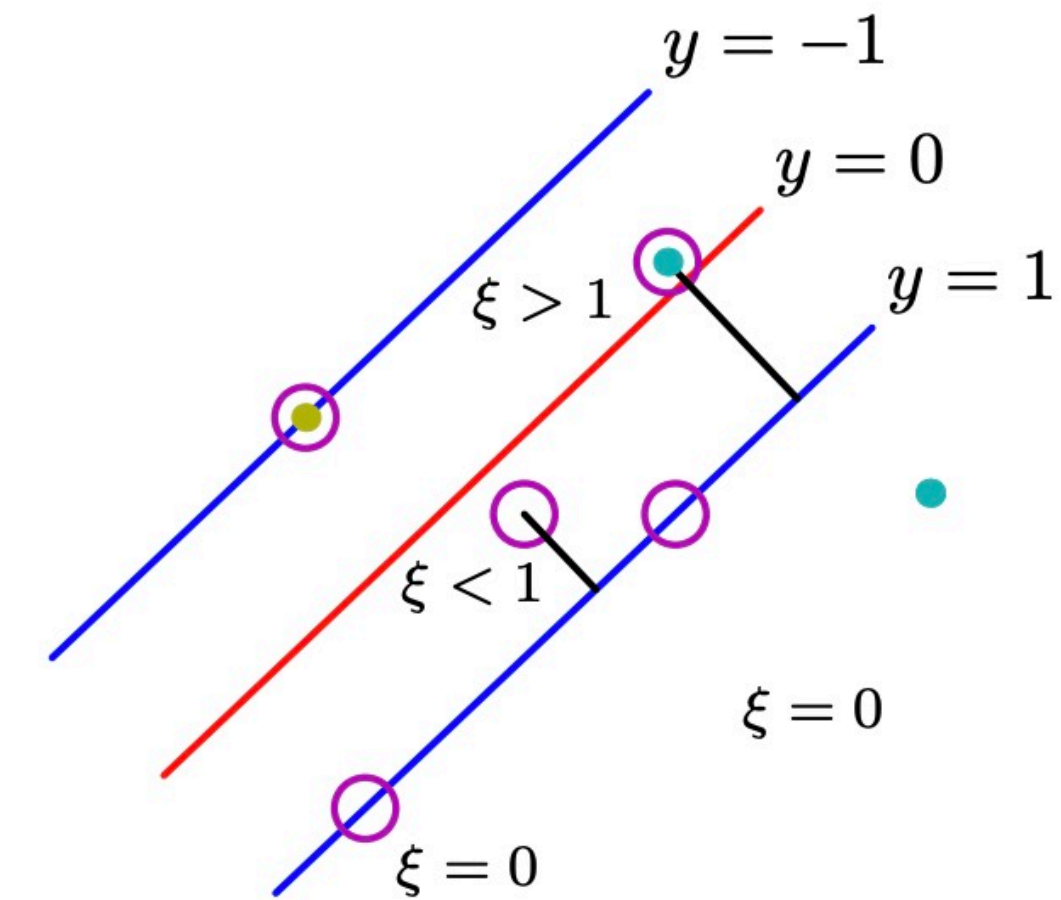
$$C - \lambda_i - \beta_i = 0 : \quad 0 \leq \lambda_i \leq C$$

$$\text{if } \lambda_i = 0 : \quad \beta_i = C, \xi_i = 0 \quad y^{(i)}(w^T x^{(i)} + b) \geq 1 - \xi_i = 1$$

$$\text{if } \lambda_i = C : \quad \beta_i = 0, -\xi_i \leq 0 \quad y^{(i)}(w^T x^{(i)} + b) = 1 - \xi_i \leq 1$$

$$\text{if } 0 < \lambda_i < C : \quad \xi_i = 0 \quad g_i(w, b, \xi) = 0 \quad y^{(i)}(w^T x^{(i)} + b) = 1 - \xi_i = 1$$

**The point is a
Support vector!**





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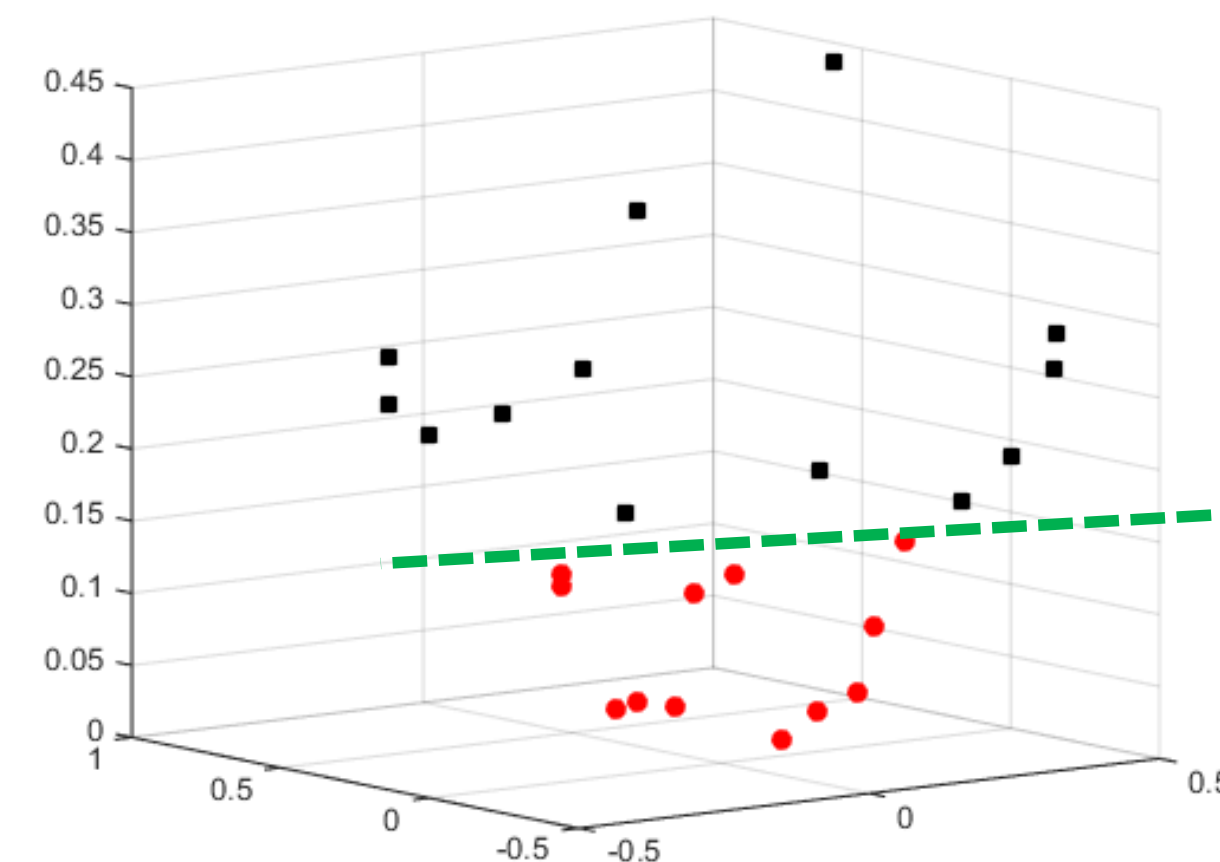
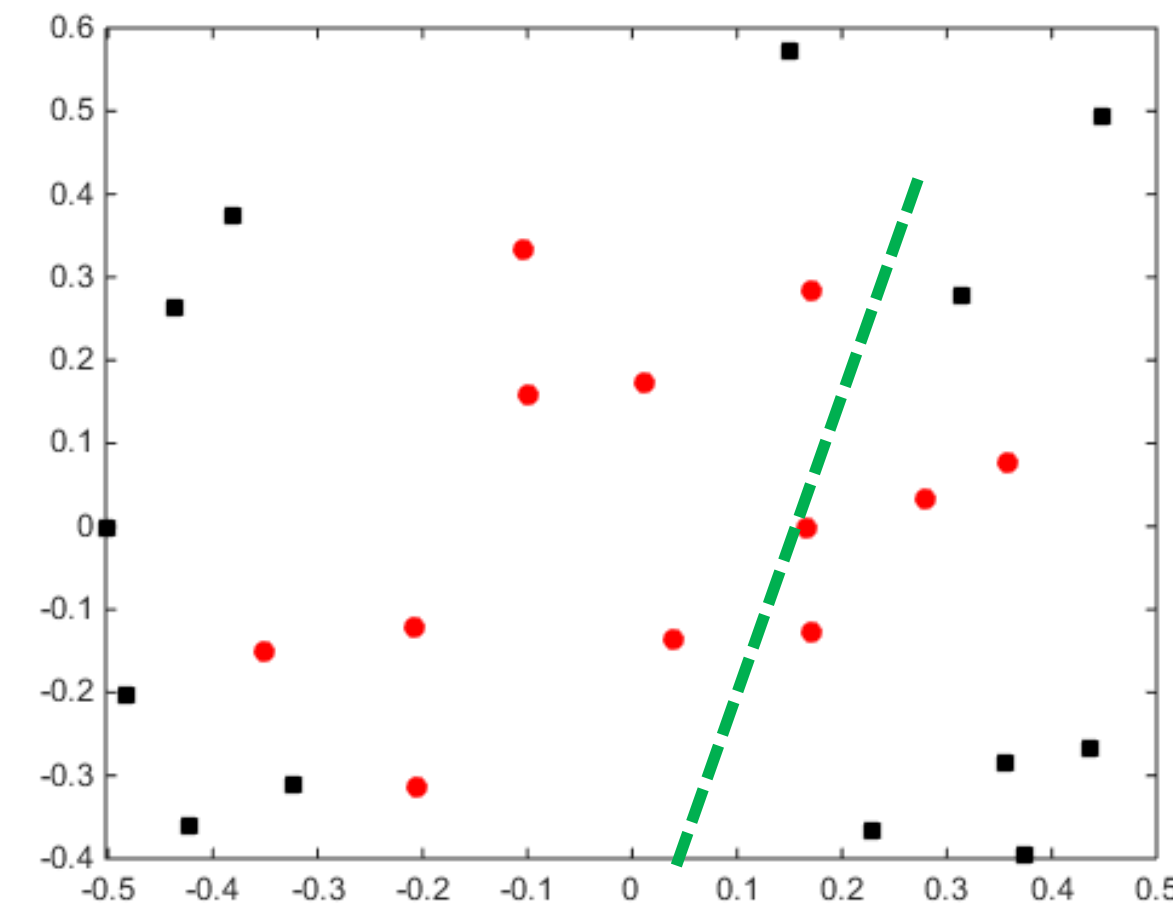
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- **Kernels**

Non-linearly separable data

- Consider a binary classification problem
- Each example has features $[x_1, x_2]$
- Not linearly separable
- Now 'add' a feature $x_3 = x_1^2 + x_2^2$
- Each point is now $[x_1, x_2, x_1^2 + x_2^2]$
- Linearly separable!



Naïve workflow

- Choose/design a linear model
- Choose/design a high-dimensional transformation $\varphi(\mathbf{x})$
 - * Hoping that after adding a lot of various features some of them will make the data linearly separable
- For each training example, and for each new instance compute $\varphi(\mathbf{x})$
- Train classifier/Do predictions

Hard-margin SVM in feature space

Training, solve:

$$\begin{array}{ll} \max_{\lambda} & \theta_d(\lambda) \\ \text{s.t.} & \lambda_i \geq 0 \text{ and } \sum_{i=1}^n \lambda_i g_i(x) = 0 \end{array} \quad \theta_d(\lambda) = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \lambda_i \lambda_k y^{(i)} y^{(k)} (x^{(i)})^T x^{(k)}$$

Prediction:
$$f(x) = \sum_{i=1}^n \lambda_i y^{(i)} (x^{(i)})^T x + b$$

We just need the dot product!

Observation: Kernel representation

- Both parameter estimation and computing predictions depend on data only in a form of a **dot product**
 - * In original space $\mathbf{u}'\mathbf{v} = \sum_{i=1}^m u_i v_i$
 - * In transformed space $\varphi(\mathbf{u})'\varphi(\mathbf{v}) = \sum_{i=1}^l \varphi(\mathbf{u})_i \varphi(\mathbf{v})_i$
- **Kernel** is a function that can be expressed as a dot product in some feature space $K(\mathbf{u}, \mathbf{v}) = \varphi(\mathbf{u})'\varphi(\mathbf{v})$

Benefits:

- no need to find the mapping function.
- no need to do transformation.
- no need to do dot product.

Kernel as shortcut

- For *some* $\varphi(\mathbf{x})$'s, **kernel is faster to compute** directly than first mapping to feature space then taking dot product.
- For example, consider two vectors $\mathbf{u} = [u_1]$ and $\mathbf{v} = [v_1]$ and transformation $\varphi(\mathbf{x}) = [x_1^2, \sqrt{2c}x_1, c]$, some c
 - * So $\varphi(\mathbf{u}) = [u_1^2, \sqrt{2c}u_1, c]'$ and $\varphi(\mathbf{v}) = [v_1^2, \sqrt{2c}v_1, c]'$
 - * Then $\varphi(\mathbf{u})' \varphi(\mathbf{v}) = (u_1^2 v_1^2 + 2cu_1 v_1 + c^2)$
- This can be alternatively **computed directly** as
$$\varphi(\mathbf{u})' \varphi(\mathbf{v}) = (u_1 v_1 + c)^2$$
 - * Here $K(\mathbf{u}, \mathbf{v}) = (u_1 v_1 + c)^2$ is the corresponding kernel

Hard-margin SVM in feature spaceTraining: solve

$$\max_{\lambda} L(\lambda) \quad L(\lambda) = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \lambda_i \lambda_k y^{(i)} y^{(k)} \overbrace{(\varphi(x^{(i)}))^T \varphi(x^{(k)})}^{K(x^{(i)}, x^{(k)})}$$

Making predictions:

$$f(x) = w^T x + b = \sum_{i=1}^n \lambda_i y^{(i)} \overbrace{(\varphi(x^{(i)}))^T \varphi(x)}^{K(x^{(i)}, x)} + b$$

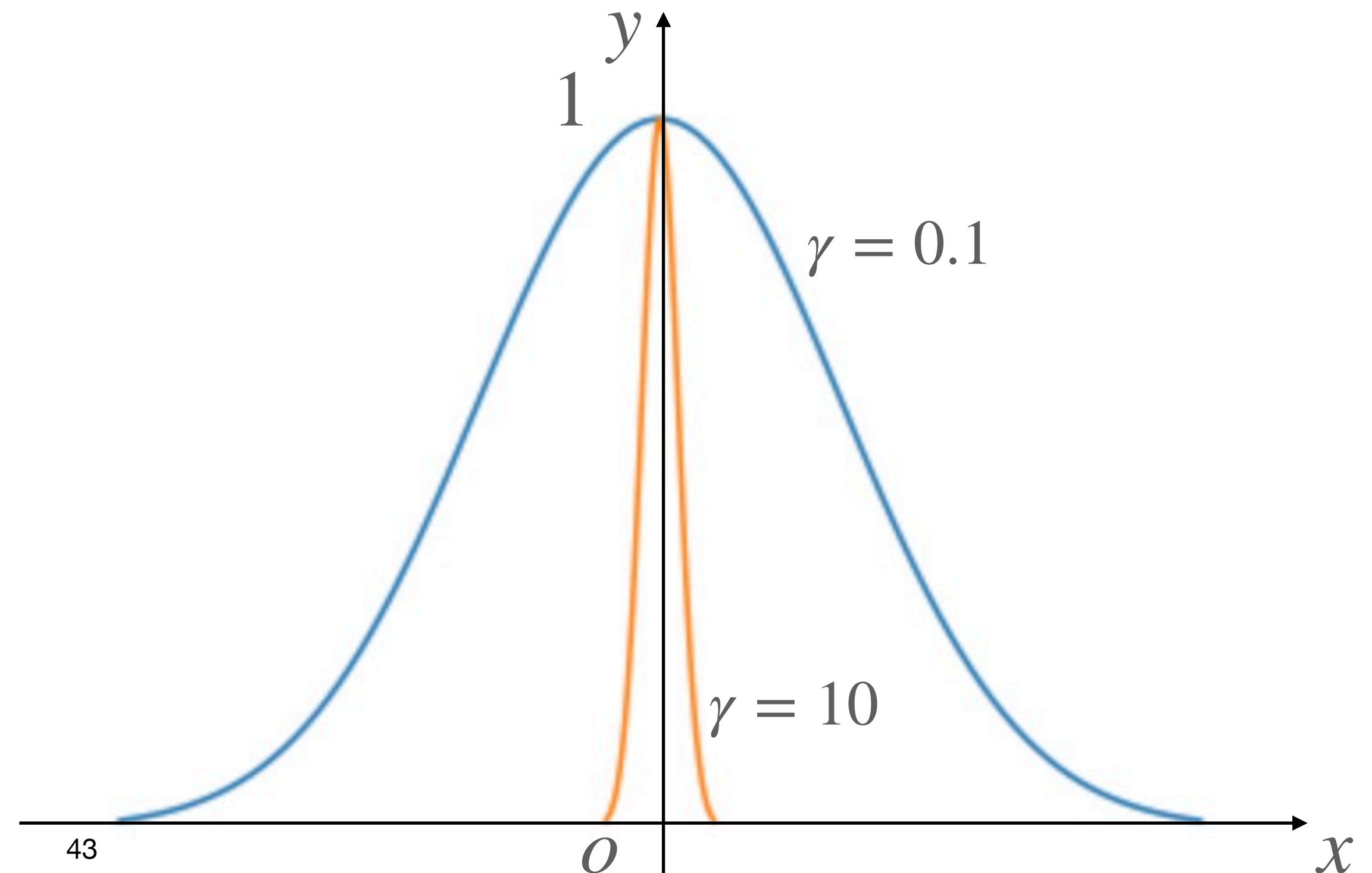
Radial Basis Function (RBF) kernel

$$K(u, v) = \exp(-\gamma \|u - v\|^2)$$

γ is too small : underfitting

γ is too large : overfitting

$$y = \exp(-\gamma x^2) = \exp\left(-\frac{x^2}{2\sigma^2}\right)$$



Identify new kernels

Mercer's theorem:

Consider a finite sequences of vectors x_1, \dots, x_n

Construct $n \times n$ matrix A (Gram matrix) of pairwise values

$K(x_i, x_j)$ is a valid kernel if this matrix is positive semi-definite, and this holds for all possible sequences

$$A = \begin{bmatrix} K(x_1, x_1) & K(x_1, x_2) & \dots & K(x_1, x_n) \\ K(x_2, x_1) & K(x_2, x_2) & \dots & K(x_2, x_n) \\ \vdots & \vdots & \vdots & \vdots \\ K(x_n, x_1) & K(x_n, x_2) & \dots & K(x_n, x_n) \end{bmatrix}$$

Identify new kernels

Positive semi-definite matrix: a square symmetric matrix satisfies $v^T A v \geq 0$
 $v \in \mathbb{R}^{n \times 1}$ any non-zero vector (column), $A \in \mathbb{R}^{n \times n}$, $A = A^T$

$$A = \begin{bmatrix} K(x_1, x_1) & K(x_1, x_2) & \dots & K(x_1, x_n) \\ K(x_2, x_1) & K(x_2, x_2) & \dots & K(x_2, x_n) \\ \vdots & \vdots & \vdots & \vdots \\ K(x_n, x_1) & K(x_n, x_2) & \dots & K(x_n, x_n) \end{bmatrix}$$

Identify new kernels

Let $K_1(u, v)$, $K_2(u, v)$ be kernels, $c > 0$ be a constant, and $f(x)$ be a real-valued function.

Then each of the following is also a kernel:

1) $K(u, v) = K_1(u, v) + K_2(u, v)$

2) $K(u, v) = c K_1(u, v)$

3) $K(u, v) = f(u) K_1(u, v) f(v)$

Summary

- What are the objective and constraints of hard-margin, soft-margin SVM
- What are KKT conditions?
- What are support vectors?
- What are Slack variables & slack penalty of soft-margin SVM?
- What is Kernel?
- How do parameters γ , C influence performance of SVM?
- How to identify new kernels?