Multi class perceptron

In multi class perceptron our goal is to make a weight matrix W and then for each example we predict $r = argmax_r(Wx)_r$. In each update we use the update rule

$$W = W + U^t$$
 where
 $U_{r,i}^t = x_{ri}(1[y == r] - 1[y == r)$

Hinge Loss and mistake bound

Hinge loss

Hinge loss is defined by $I(W; (x, y)) = \max_{r \in k - y} [1 - (Wx)_y + (Wx)_r]_+$ Here we can define Loss of perceptron as $L = \sum_{1}^{T} I(W; (x, y))$

Complexity

complexity of a weight matrix is defined as 2 times the square of its L-2 norm

$$D=2\sum\sum W(i,j)^2$$

Mistake bound

The mistake bound for multiclass perceptron is $M < L + D + \sqrt{LD}$

Banditron

In our problem , we do not know what is the correct label in case our prediction is wrong so we cannot apply multi class perceptron . In this case similar to exp3 , we add a exploration factor. So first we construct a extimator for matrix ${\it U}$

$$\tilde{U}_{rj} = x_j (\frac{1(y == r)1(\tilde{y} == r)}{P(r)} - 1(y == r))$$

Here \tilde{y} is our prediction obtained from the probability vector $P(r)=(1-\gamma)1 (r==\hat{y}+\gamma/k$, here γ is our exploration constant.

Banditron algorithm

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for \mathbf{t}=1,2,...T: \hat{y}=argmax_r(W^tx)_r make the probability array P(r)=(1-\gamma)\mathbf{1}(r==\hat{y}+\gamma/k) sample \tilde{y} according to P make the update matrix \tilde{U}_{rj}=x_j(\frac{\mathbf{1}(y==r)\mathbf{1}(\tilde{y}==r)}{P(r)}-\mathbf{1}(y==r)) W=W+\tilde{U}
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Theorem 1

If our dataset satisfies $||x|| \le 1$, then the mistake bound of banditron will be and there are k classes,

$$E[M] \le L + \gamma T + 3 \max kD/\gamma, \sqrt{D\gamma T} + \sqrt{\frac{kDL}{\gamma}}$$

Lemma 5

$$E[||U||^2] \le 2||x_t||^2(k/\gamma 1||y \ne \hat{y}|| + \gamma 1||y \ne \hat{y}||)$$

Halving algorithm

Here we take a cover of hypothesis H and at every iteration remove the hypothesis that gave wrong answer H'. This only works for separable case as otherwise all the hypothesis will be removed

Theorem 7

There exists a deterministic algorithm (in the bandit setting), taking D as input, which makes at most $O(k^2d \ln(Dd))$ mistakes on any sequence (where $||x_t||1$) that is linearly separable.

Another trick to reduce the mistake bound is to remap x onto a lower dimension $d' = O(D \ln (T + k)/\delta)$. Here the algorithm will give a mistake bound of

 $O(k^2D\ln(T+k)/\delta(\ln D + \ln\ln(T+k)/\delta))$ with probability of $1-\delta$