

Predictive Maintenance for Industries Using Flask and Big data

Abstract

In industries looking to maximize equipment longevity and minimize downtime, predictive maintenance is essential. This study examines the use of machine learning methods, particularly the Gradient Boosting Classifier (GBT), to forecast industrial machinery breakdowns based on sensor data. Other classification models, such Random Forest and Logistic Regression, are compared to see how well the model predicts machine failure. With an accuracy of 97.81%, the data demonstrate that GBT performs better than alternative models. In order to enable real-time failure predictions based on incoming sensor data, the model has been implemented as a component of an API system that uses Flask.

Introduction

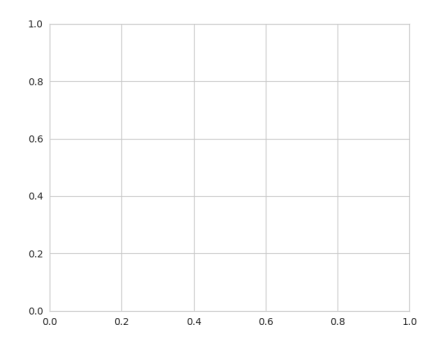
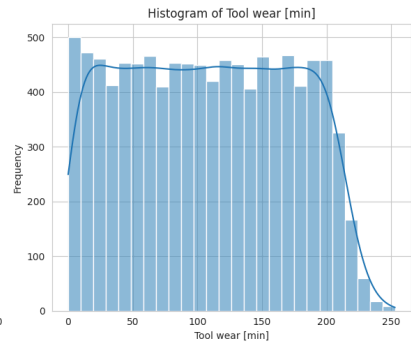
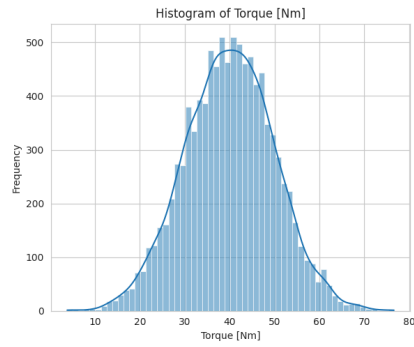
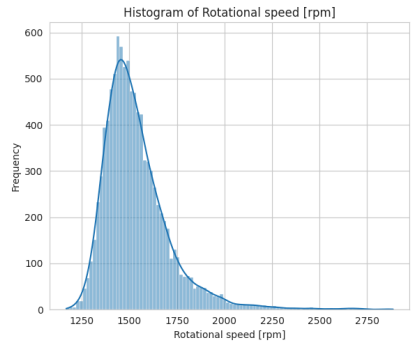
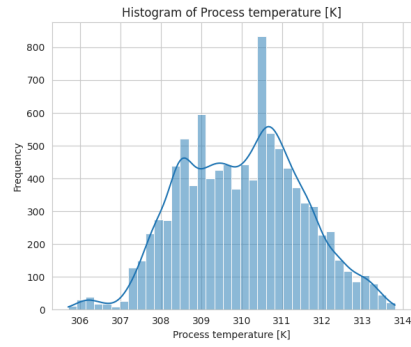
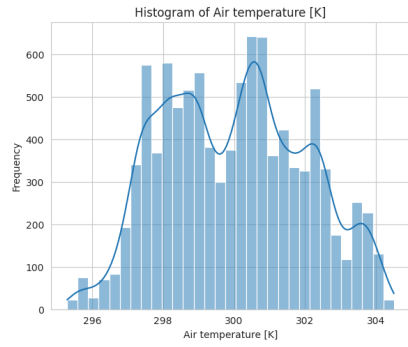
Using information from sensors mounted on equipment, predictive maintenance anticipates possible malfunctions before they happen. Predictive maintenance prolongs the life of vital equipment and lowers the costs of unscheduled downtime in sectors including manufacturing, oil and gas, and automotive. Predictive models can identify trends that point to a machine's risk of failure by using past data. In order to provide useful insights into the condition of machinery, this work investigates the application of machine learning models for failure prediction based on sensor data.

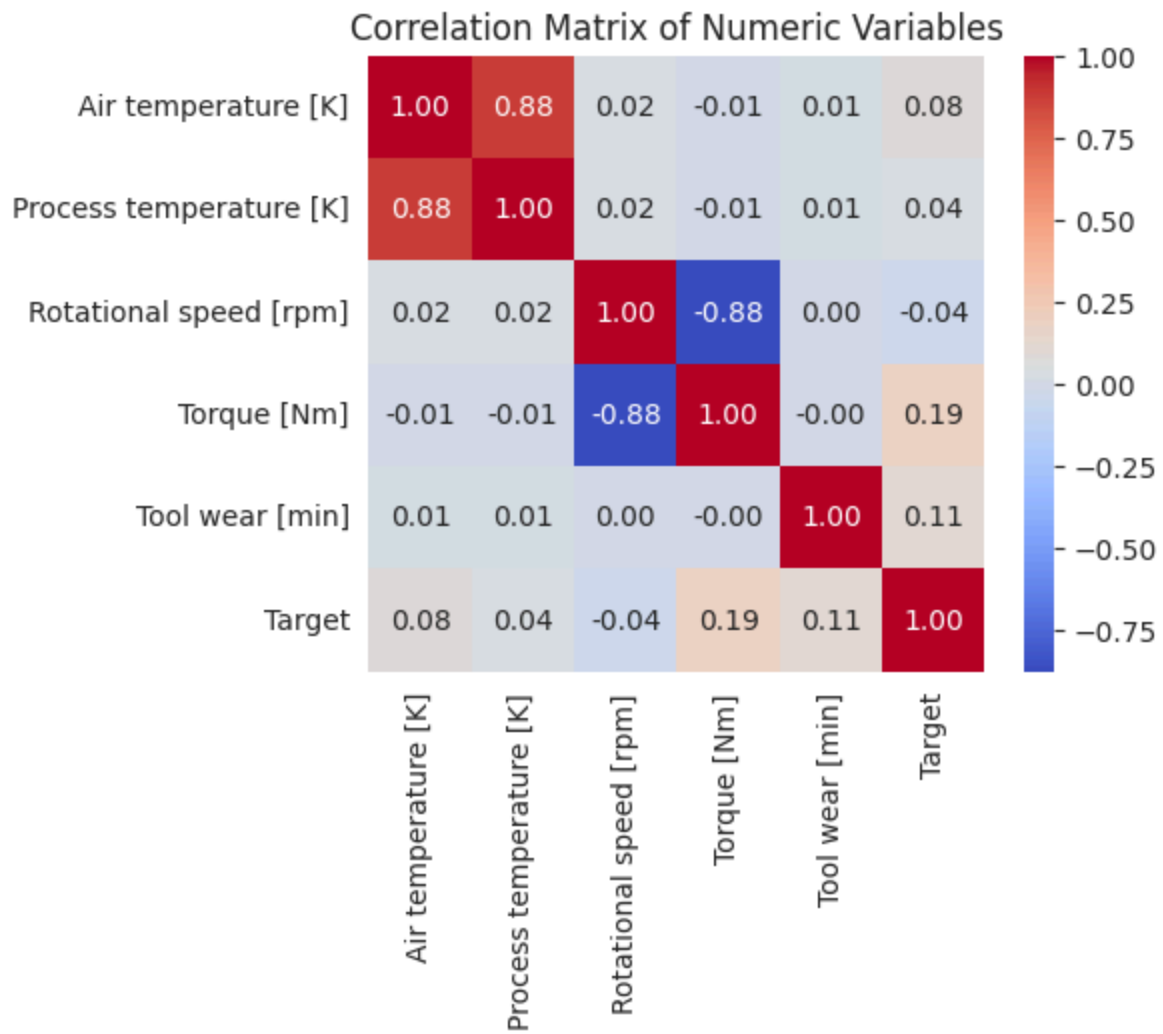
Exploratory Data Analysis:

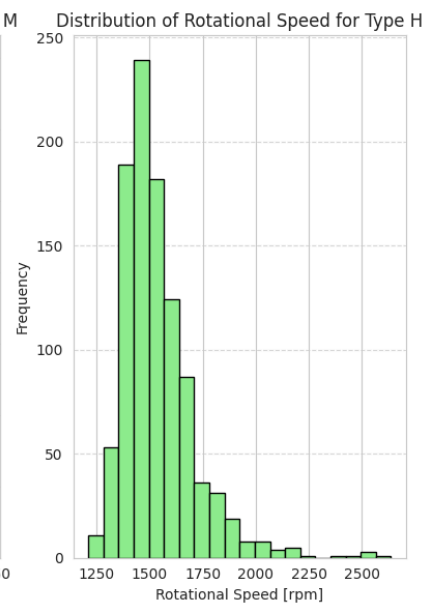
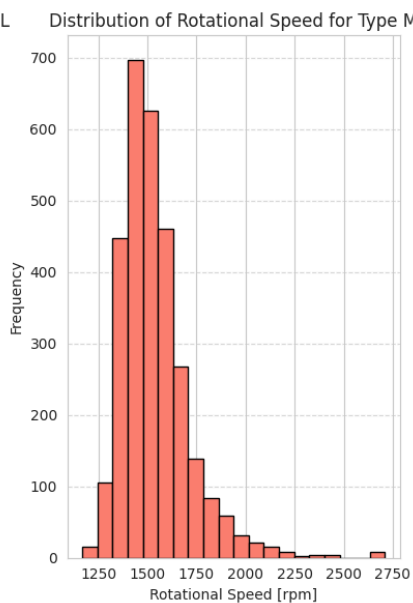
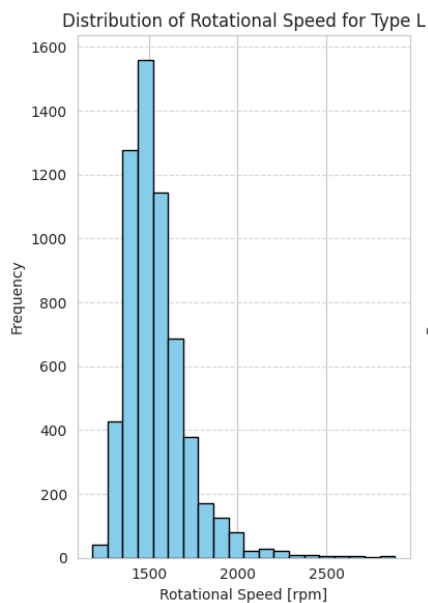
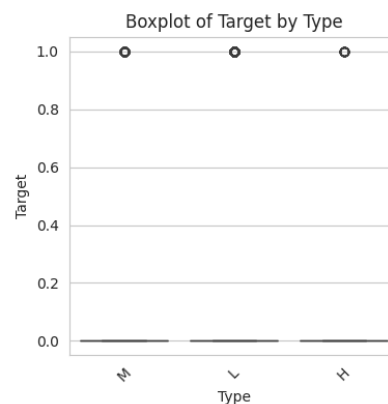
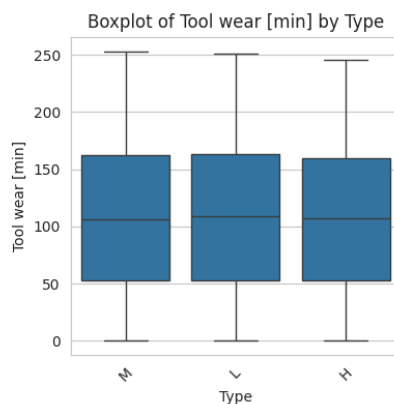
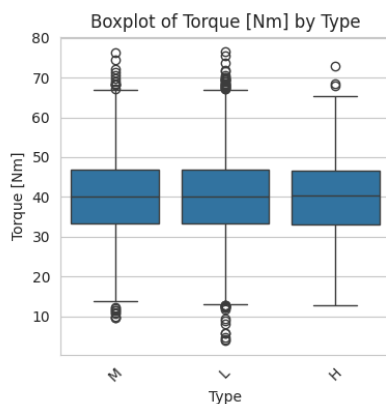
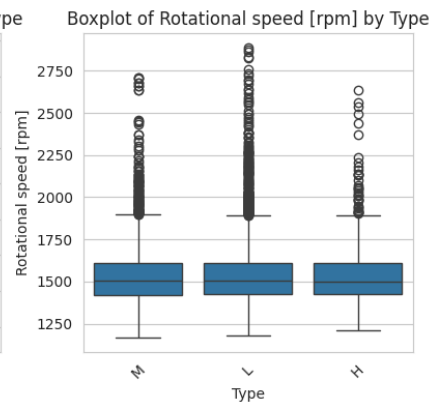
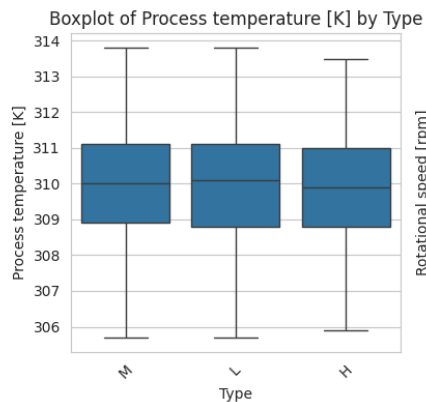
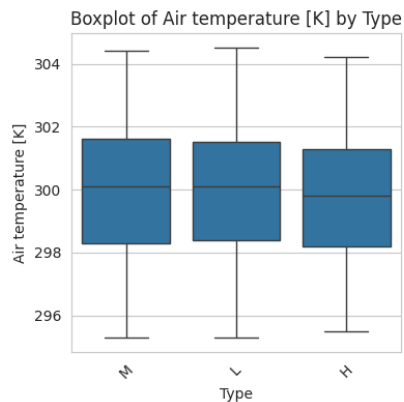
All the columns in our dataset are being displayed.

```
root
|-- UDI: integer (nullable = true)
|-- Product ID: string (nullable = true)
|-- Type: string (nullable = true)
|-- Air temperature [K]: double (nullable = true)
|-- Process temperature [K]: double (nullable = true)
|-- Rotational speed [rpm]: integer (nullable = true)
|-- Torque [Nm]: double (nullable = true)
|-- Tool wear [min]: integer (nullable = true)
|-- Target: integer (nullable = true)
|-- Failure Type: string (nullable = true)
```

	UDI	Product ID	Type	Air temperature [K]	Process temperature [K]	Rotational speed [rpm]	Torque [Nm]	Tool wear [min]	Target	Failure Type
count	10000	10000	10000	10000	10000	10000	10000	10000	10000	10000
mean	5000.5	NULL	NULL	300.00492999999875	310.00555999999995	1530.7761	39.986909999999995	107.951	0.0339	NULL
stddev	2886.8956799071675	NULL	NULL	2.0002586829161944	1.4837342191656513	179.28409591342677	9.968933725121323	63.65414663663629	0.180980842650654	NULL
min	1	H29424	H	295.3	305.7	1168	3.8	0	0	Heat Dissipation ...
max	10000	M24859	M	304.5	313.8	2886	76.6	253	1	Tool Wear Failure







Existing Methods

The paper makes use of the

For anomaly detection, the study assesses models such as One-Class SVM, Isolation Forest, Elliptic Envelope, and Local Outlier Factor (LOF).

Classifiers such as Gaussian Naive Bayes, SVM, Random Forests, K-Nearest Neighbors (KNN), Logistic Regression, and Decision Trees are used to forecast failures.

The following are a few popular machine learning techniques for predictive maintenance:

- Random Forest: A group technique that constructs several decision trees and combines their forecasts.
- For binary classification tasks, such as predicting failure or no failure, logistic regression is a straightforward yet powerful technique.
- Gradient Boosting Machines (GBM) are boosting algorithms that optimize speed by building trees one after the other.

Methodology/Algorithm

The following procedures are used in this project to create and assess the predictive maintenance model:

1. Data Collection: Sensor data from machinery was gathered, including torque, rotational speed, air temperature, process temperature, and tool wear.

Preprocessing Data:

2. addressing outliers and missing data.
3. Feature normalization with StandardScaler.
4. utilizing a mapping for machine kinds (L, M, and H) to encode category information.
5. Choosing a Model:
6. A number of models were assessed, such as Random Forest, Gradient Boosting Classifier (GBT), and Logistic Regression.
7. Train-test splits with an 80:20 ratio were used to train and validate the models.
8. Assessment of the Model:
9. The accuracy, precision, recall, and F1-score measures were used to evaluate each model's performance.
10. With the maximum accuracy of 97.81%, the Gradient Boosting Classifier was chosen as the top-performing model.

Results

Results as per the paper for failure prediction:

- Logistic Regression
 - 46.40% accuracy
 - 48.70% precision, 90.77% recall
 - 63.39% F1 score
- K-Nearest Neighbors (KNN)
 - 84.89% accuracy
 - 89.15% precision, 80.21% recall
 - 84.44% F1 score
- SVM with Linear Kernel
 - 51.12% accuracy
 - 51.12% precision, 100% recall
 - 67.66% F1 score
- SVM with RBF Kernel
 - 86.46% accuracy
 - 95.48% precision, 77.16% recall
 - 85.35% F1 score
- Gaussian Naive Bayes
 - 86.05% accuracy
 - 94.23% precision, 77.46% recall
 - 85.02% F1 score
- Decision Tree (with entropy criterion)
 - Best performer with 87.51% accuracy
 - 88.08% precision, 87.39% recall
 - 87.73% F1 score
- Random Forest (with entropy criterion, 10 estimators)
 - 84.35% accuracy
 - 88.28% precision, 80.00% recall
 - 83.94% F1 score

The following is a summary of the models' evaluation on our test set:

Accuracy of the Gradient Boosting Classifier (GBT): 97.81%

Accuracy of logistic regression: 96.72%

Random Forest: accuracy of 97.08%

Revision of Gradient Boosting: accuracy of 97.55%

Model	Accuracy	Precision	Recall	F1 Score
Gradient Boosting	0.9781	0.9761	0.9781	0.9766
Logistic Regression	0.9672	0.9594	0.9672	0.9596
Random Forest	0.9708	0.9686	0.9708	0.9624
Gradient Boosting	0.9755	0.9726	0.9755	0.9719
Decision Tree	0.9729	0.9689	0.9729	0.9690
Naive Bayes	0.9636	0.9284	0.9636	0.9457
Support Vector Machine	0.9636	0.9284	0.9636	0.9457

Anomalies detected: 5006
Best model saved.

When we compare both the results we can observe that our model has achieved best accuracies compared to the models achievement as per the paper.

We also used the user prompt such that user can enter all the details and our model predicts if their is failure or not.

Confusion Matrix and Classification Report for the GBT model:

- **Accuracy:** 97.81%
- **Precision:** Both classes (failure and no failure) have high precision.
- **Recall:** Both classes showed high recall, demonstrating the model's resilience in forecasting failures.

Comparison of Models:

- GBT was selected as the final model since it demonstrated the highest accuracy.
- In terms of accuracy, Random Forest and Logistic Regression fared similarly, albeit marginally worse than GBT.

Conclusion

Promising outcomes were shown when machine learning was applied to sectors for predictive maintenance. With an accuracy of 97.81%, the Gradient Boosting Classifier proved to be successful at forecasting equipment failures using sensor data. Predictive maintenance benefits greatly from the model's real-time predictions made possible by its distribution via a Flask-based API. Additional sensor data integration, model parameter adjustment, and the use of sophisticated algorithms could all lead to further advancements.

References

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2. T. Harsh, T. Kumar, A. Mohanty, and A. Pandey, "Predictive Maintenance of Industrial Machines using ML and IoT," presented at the *AI and IoT Conference 2024*. doi: 10.1109/aiiot58432.2024.10574756.
3. D. Patel and P. Kalgutkar, "Predictive Maintenance for Industrial Equipment Using Machine Learning," *International Journal of Advanced Research in Science, Communication and Technology*, 2024. doi: 10.48175/ijarsct-19379.
4. R. K. Mishra, S. Suman, and P. S. Bali, "Predictive Maintenance in Industrial Systems Using Machine Learning," *International Journal of Innovative Science and Research Technology*, 2024. doi: 10.38124/ijisrt/ijisrt24mar1367.