

Advanced Data Science

Lecture 5: Introduction to Statistical Learning

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The course so far

Access how to get and combine the data-sources for a potential problem

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Access how to get and combine the data-sources for a potential problem

Assess things to do with data before you have a question

Address what you can do when you have data and a question to answer

Access

• ?

Assess

- Introduction to Probability (IA)
- Scientific Computing (IA)
- Cloud Computing (II)
-

Address

- ML and Real-world Data (IA)
- Data Science (IB)
- AI (IB)
- ML & Bayesian Inference (II)
- Deep NN (II)
- Randomised Algorithms (II)
-



Data centric thinking

You need to put Machine Learning in the context of data (and humans)

- Neil Lawrence

Reasons to use ML

- Tasks that are too hard to program
 - speech recognition
 - image understanding

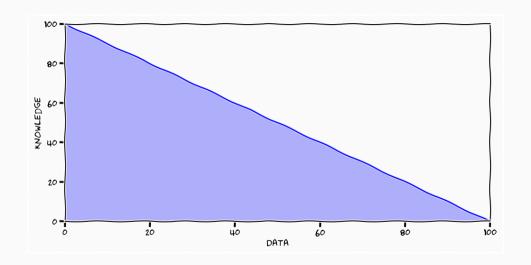
Reasons to use ML

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- Machine Learning bridges the knowledge gap by data

Task of Statistical Learning



Machine Learning and Knowledge

$$p(\theta \mid \mathcal{D}) = \frac{p(\mathcal{D} \mid \theta)p(\theta)}{p(\mathcal{D})}$$

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 access what data did I acquire?
 assess how did I prepare/treat the data?

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- Most knowledge is introduced before we apply ML access what data did I acquire?
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- The idea of the 80/20

Today

- what can machine learning actually do?
- what role does the "data scientist" play in the machine learning loop?
- put machine learning into context

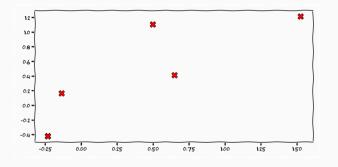
Statistical Learning

Statistical Learning

Learning is the process of converting experience into expertise or knowledge.

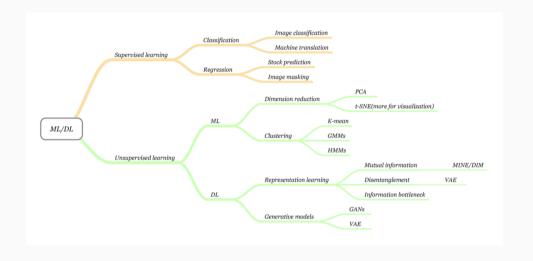
- Sha Ben-David

Machine Learning Paradigms



Supervised Learning $p(y \mid x)$ "Unsupervised" Learning p(y) Reinforcement Learning $p(\pi, f \mid \mathcal{L})$

Machine Learning Methods



Domain Set \mathcal{X} the set of measurements/objects that we want to label (input)

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Domain Set \mathcal{X} the set of measurements/objects that we want to label (input)

Label Set ${\mathcal Y}$ the set of outputs

Training Data ${\mathcal S}$ a finite sequence of pairs in ${\mathcal X} \times {\mathcal Y}$

Data Distribution ${\mathcal D}$ probability distribution governing the measurements

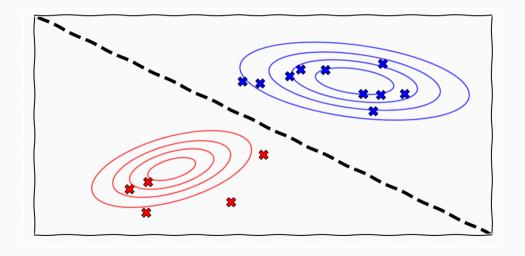
Data Distribution $\mathcal D$ probability distribution governing the measurements Data Generation $f:\mathcal X\to\mathcal Y$ the underlying generating process that we wish to recover

Data Distribution \mathcal{D} probability distribution governing the measurements

Data Generation $f: \mathcal{X} \to \mathcal{Y}$ the underlying generating process that we wish to recover

Prediction Rule $h: \mathcal{X} \to \mathcal{Y}$ what we wish to recover, the object that encodes the recovered knowledge

Classification



Measure of Success

$$L_{\mathcal{D},f}(h) := \mathcal{D}(\{x : h(x) \neq f(x)\})$$

• measure of success as probability of misclassified points (true risk)

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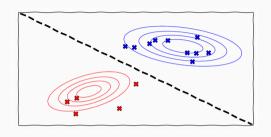
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- ullet we do not have access to ${\mathcal D}$
- ullet we do not have access to f

Empirical Risk Minimisation

$$L_{\mathcal{S}}(h) := \frac{|\{i \in [m] : h(x_i) \neq y_i\}|}{m}$$

- ullet We assume that $\mathcal{S} \sim \mathcal{D}$
- Empirical measure of risk

Overfitting

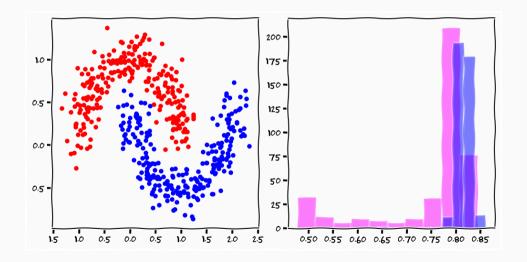


$$\mathcal{D} = \frac{1}{3} \mathcal{N}(\cdot, \cdot) + \frac{2}{3} \mathcal{N}(\cdot, \cdot)$$

$$h_{\mathcal{S}}(x) = \begin{cases} y_i & \text{if } \exists i \in [m] \text{s.t. } x_i = x \\ 0 & \text{otherwise} \end{cases}$$

- $L_{\mathcal{S}}(h_{\mathcal{S}}) = 0$ for all training data-sets
- if label 0 corresponds to red $L_{\mathcal{D}}(h_{\mathcal{S}}) = \frac{1}{3}$
- if label 0 corresponds to blue $L_{\mathcal{D}}(h_{\mathcal{S}}) = \frac{2}{3}$

True Risk is a Random Variable



Algorithm

$$L_{\mathcal{S}}(A(\mathcal{S})) := \frac{|\{i \in [m] : h(x_i) \neq y_i\}|}{m}$$

ullet We use an algorithm $A:\mathcal{S} o h$ to find a hypothesis

Finite Hypothesis Classes

$$h_{\mathcal{S}} \in \operatorname*{argmin}_{h \in \mathcal{H}} L_{\mathcal{S}}(h)$$

• We cannot parametrise all possible hypothesis

Statistical Learning Questions

m How much data do I need?

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 ${\cal A}$ How much does my solution depend on what I find?

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m How much data do I need?

 ${\cal A}$ How much does my solution depend on what I find?

 ${\cal H}$ How does my solution depend on the hypothesis class I choose?

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$$L_{\mathcal{D},f}(h_{\mathcal{S}}) \le \epsilon$$

• We are looking for a *hypothesis* that will be probably (with confidence $(1 - \delta)$) approximately (up to an error ϵ) correct.

Assumptions: I.I.D.

$$\mathcal{S} \sim \mathcal{D}^m$$

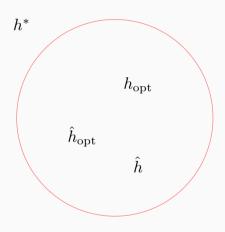
- each sample is *independent* from the other
- the *order* of samples does not effect the data distribution
- the sampling process does not effect the "world"

PAC Bounds [Shalev-Shwartz et al., 2014]

$$m \ge \frac{\log\left(\frac{|\mathcal{H}|}{\delta}\right)}{\epsilon}$$

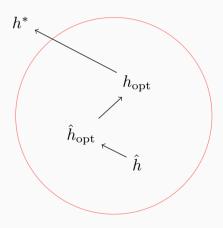
- PAC learning allows us to provide bounds on the learning procedure
- How much data do we need?
- How large hypothesis class can we allow?

The Bias-Complexity Trade-off



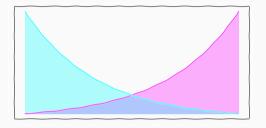
 h^* the optimal predictor $h_{ extbf{opt}}$ the optimal hypothesis on training data \hat{h} the hypothesis found by learning algorithm

The Bias-Complexity Trade-off



$$\begin{split} \epsilon(\hat{h}) - \epsilon(h^*) \\ = \underbrace{\epsilon(h_{\mathrm{opt}}) - \epsilon(h^*)}_{\text{Approximation}} \\ + \underbrace{\epsilon(\hat{h}_{\mathrm{opt}}) - \epsilon(h_{\mathrm{opt}})}_{\text{Estimation}} \\ + \underbrace{\epsilon(\hat{h}) - \epsilon(\hat{h}_{\mathrm{opt}})}_{\text{Optimisation}} \end{split}$$

The Bias-Complexity Trade-off



High Complexity low bias (ϵ_{app} small), but high risk of overfitting (ϵ_{est} large) **Low Complexity** high bias (ϵ_{app} large), low risk of overfitting (ϵ_{est} small)

Universal Learner







The No-Free Lunch Theorem [Shalev-Shwartz et al., 2014]

Theorem (The No-Free-Lunch Theorem) Let A be any learning algorithm fo the task of binary classification with respect to 0-1 loss over the domain \mathcal{X} . Let m be any number smaller than $\frac{|\mathcal{X}|}{2}$. Then there exists a distribution $\mathcal{D}(\{\mathcal{X} \times \{0,1\}\})$ such that.

- There exists a function $f: \mathcal{X} \to \{0,1\}$ with $L_{\mathcal{D}}(f) = 0$
- With probability at least $\frac{1}{7}$ over the choice of $S \sim \mathcal{D}^m$ we have $L_{\mathcal{D}}(A(S)) > \frac{1}{9}$

The No-Free Lunch Theorem

- There exists no universal learner
- For every learner there exist a task on which it fails
- Every algorithm that learns something useful does so by assumptions

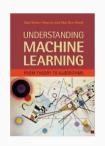
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- Every algorithm that learns something useful does so by assumptions
- There is no free lunch algorithm

Statistical Learning Summary

- We can never have sufficient data
- We can never find a method that will guarantee to find the right solution
- We can never be certain about the true risk of our outcome

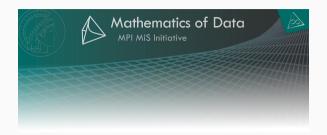
Statistical Learning Theory Further Reading



 Shai Shalev-Shwartz et al. (2014). Understanding Machine Learning: From Theory to Algorithms. New York, NY, USA: Cambridge University Press https:

//www.cs.huji.ac.il/~shais/UnderstandingMachineLearning/

Statistical Learning Theory Further Reading



O. Bousquet et al. (2004). "Introduction to Statistical Learning Theory". In: vol. Lecture Notes in Artificial Intelligence 3176. Heidelberg, Germany: Springer, pp. 169–207,

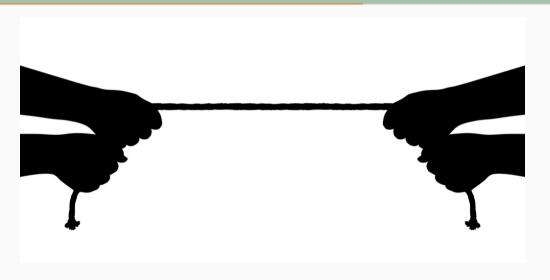
http://www.econ.upf.edu/~lugosi/mlss_slt.pdf



Explicit vs. Tacit Knowledge







Access enormous inductive bias in what data to acquire

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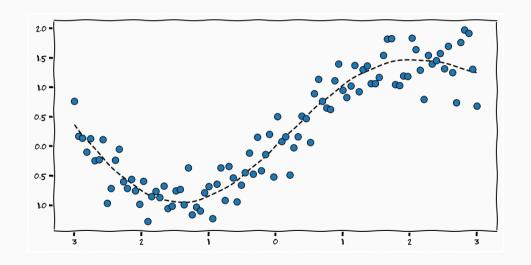
Assess human bias in what questions will probably be asked

Access enormous inductive bias in what data to acquire

Assess human bias in what questions will probably be asked

Address "it is just curve fitting"

Curve Fitting is Really Fun



Requirements for Data Science



This part of the course

Today/Mon Generalised Linear Models

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Wen Unsupervised Learning

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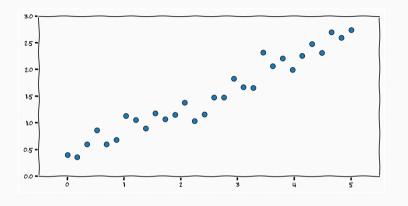
Fri Approximate Inference

Generalised Linear Models

Limited Hypothesis Classes

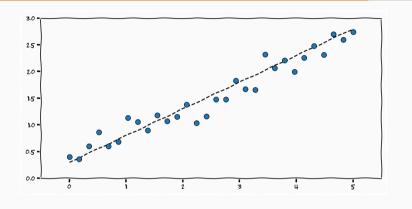


Formalism



 $\mathbf{x} \in \mathcal{X}$ explanatory variable $y \in \mathcal{Y}$ response variable Task explain the response by the explanatory variables

Linear Regression [Bishop, 2006]



$$y_i = \sum_{j=1}^d \beta_j x_{ij} + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2).$$

Linear Regression Prediction

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$$= \sum_{j=1}^d \beta_j x_{ij} + 0.$$

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$$\hat{y}_i \sim \mathcal{N}(y_i, \sigma^2) = \mathcal{N}\left(\sum_{j=1}^d \beta_j x_{ij}, \sigma^2\right),$$

Generalised Linear Models [McCullagh et al., 1989]

$$g(\mathbb{E}[y_i \mid \mathbf{x}_i]) = \sum_{j=1}^d \beta_j x_{ij},$$

 $g(\cdot)$ link function $y \sim \mathcal{D} \ \ \text{Exponential Dispersion Family}$ $\sum_{j=1}^d \beta_j x_{ij} \ \ \text{Linear predictor}$

Generalised Linear Models [McCullagh et al., 1989]

$$\mathbb{E}[y_i \mid \mathbf{x}_i] = g^{-1}(\sum_{j=1}^d \beta_j x_{ij}),$$

- The inverse of the *link* maps the linear predictor to the first moment of the response
- Linear regression the link is identity

¹https://towardsdatascience.com/ glms-part-iii-deep-neural-networks-as-recursive-generalized-linear-URL

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- Looks an awful lot like a neural network¹

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Exponential Dispersion Family ²

$$f(y; \theta, \phi) = e^{\frac{\theta y - b(\theta)}{a(\phi)} + c(y, \phi)},$$

- θ location parameter
- ϕ scale parameter

 $^{^{2} \}verb|https://en.wikipedia.org/wiki/Exponential_dispersion_model|$

Gaussian

$$f(y; \mu, \sigma^2) = e^{\frac{\mu y - \frac{1}{2}\mu^2}{\sigma^2} - \frac{y^2}{2\sigma^2} - \frac{1}{2}\ln(2\pi\sigma^2)}$$

$$\bullet \ \theta = \mu$$

•
$$\phi = \sigma^2$$

•
$$b(\theta) = \frac{1}{2}\mu^2$$

•
$$a(\phi) = \sigma^2$$

•
$$c(y,\phi) = \frac{y^2}{2\sigma^2} - \frac{1}{2}\ln(2\pi\sigma^2)$$

$$\mathbb{E}[y \mid \mathbf{x}] = \frac{\partial}{\partial \theta} b(\theta)$$

$$\mathbb{V}[y \mid \mathbf{x}] = a(\phi) \frac{\partial^2}{\partial \theta^2} b(\theta).$$

 Through a consistent parametrisation we can generalise the moment calculations

Model	Response Variable	Link	Explanatory Variable
Linear Regression	Normal	Identity	Continuous
Logistic Regression	Binomial	Logit	Mixed
Poisson Regression	Poisson	Log	Mixed
ANOVA	Normal	Identity	Categorical
ANCOVA	Normal	Identity	Mixed
Loglinear	Poisson	Log	Categorical
Multinomial response	Multinomial	Generalized Logit	Mixed

- Brief introduction to statistical learning theory
- Take home
 - ML models and algorithms is only a small part of the story
 - we are doing a lot better than we should be
 - we are not sure what we are doing but it somehow works

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- Take home
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 - we are not sure what we are doing but it somehow works
 - it is not explicit knowledge that pushes data-science forward, it is tacit and implicit

- Generalised Linear Models
 - "main" tool for statisticians
 - very well studied, excellent literature
 - linearity provides means of interpretability
 - excellent software packages statsmodels

The rest

Monday (22/11) Lecture: Generalised Linear Models

Tuesday (23/11) Lab: Generalised Linear Models

Wendesday (24/11) Lecture: Unsupervised Learning/Visualisation

Thursday (25/11) Tick: Generalised Linear Models

Friday (26/11) Lecture: Statistical Inference

eof

References

- Bishop, Christopher M. (2006). Pattern Recognition and Machine Learning (Information Science and Statistics). Secaucus, NJ, USA: Springer-Verlag New York, Inc.
- Bousquet, O., S. Boucheron, and G. Lugosi (2004). "Introduction to Statistical Learning Theory". In: vol. Lecture Notes in Artificial Intelligence 3176. Heidelberg, Germany: Springer, pp. 169–207.
- McCullagh, P. and J. A. Nelder (1989). Generalized Linear Models. London, UK: Chapman Hall / CRC: Chapman Hall / CRC.
- Shalev-Shwartz, Shai and Shai Ben-David (2014). *Understanding Machine Learning: From Theory to Algorithms*. New York, NY, USA: Cambridge University Press.